

6

5

4

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D

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B

A

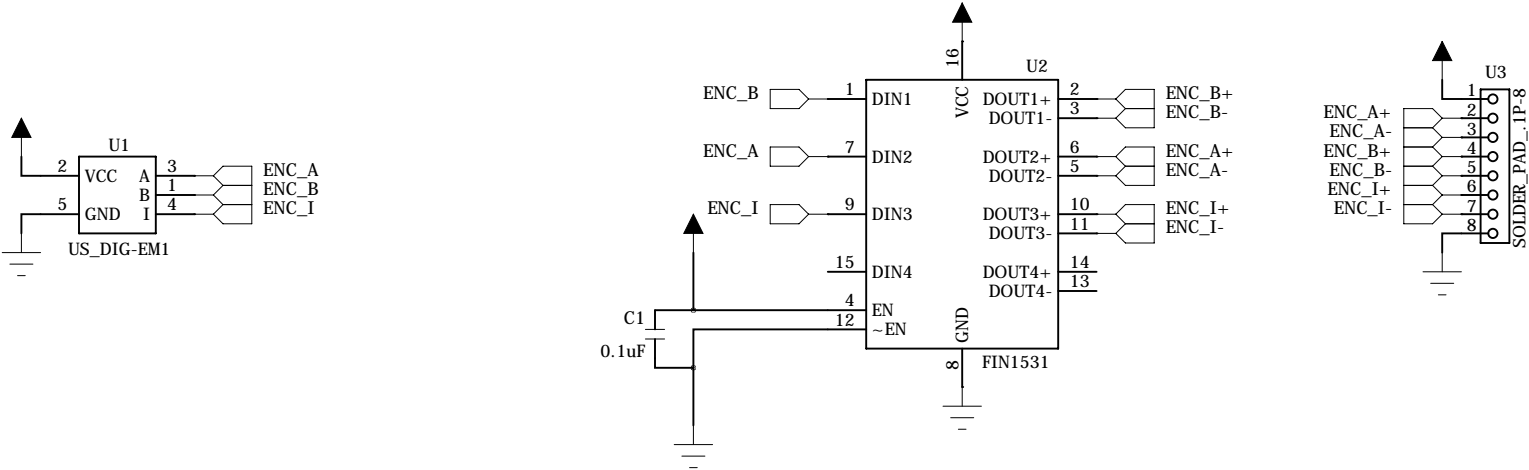
D

C

B

A

REVISION RECORD			
LTR	ECO NO:	APPROVED:	DATE:



COMPANY: OSU Dynamic Robotics Laboratory			
TITLE: ATRIAS 2.1 Encoder Differential Driver			
CODE:	SIZE: B	DRAWING NO:	REV:
SCALE:		SHEET: 1 of 1	

DRAWN: Kit Morton	DATED:
CHECKED:	DATED:
QUALITY CONTROL:	DATED:
RELEASED:	DATED: