

NOTE: The dimentions indicated with 'MAX' are the maximum dimentions allowable for installation on ATRIAS 2.0.

All other dimentions shown are what work in the SolidWorks model of the robot. These do not nessesaraly need tobe replicated in the final board layout.

UNLESS OTHERWISE SPECIFIED:		NAME	DATE	D ' D 1 .'		
DIMENSIONS ARE IN INCHES TOLERANCES: FRACTIONAL: ±1/16" ANGULAR: MACH±0.5 DECIMAL: TWO PLACE: ±0.010" THREE PLACE: ±0.005" MIN: +0.010" MAX: -0.010"	DRAWN	DRAWN BY	DRAW DATE	Dynamic Robbites		
	CHECKED	CHECKED	BYHECK DAT			
	ENG APPR.			Laboratory		
	MFG APPR.			File Name:		
	Q.A.			ATRIAS 2.0 Amp Stack		
	COMMENTS	:		Material:		
PROPRIETARY AND CONFIDENTIAL				Finish:		
THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF THE DYNAMIC ROBOTICS LAB. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF DRL IS PROHIBITED.				SIZE DWG. NO.	REV	
				SCALE: 3:2 WEIGHT: SHEE	T 1 OF 1	