

△ Problem setting

$$\min_{x \in X} \hat{f}(x) := p(x) + h(x)$$

where h is a proper lower-semicontinuous convex function

X is a nonempty convex set

$$p(x) := \max_{y \in Y} \Phi(x, y), \forall x \in X$$

Y is a nonempty compact convex set

Φ , for some scalar $m > 0$ and open set $\Omega \supset X$, is such that

(i) $\Phi \in C(\Omega \times Y)$ (ii) $-\Phi(x, \cdot): Y \rightarrow \mathbb{R}$ is lower-semicontinuous and convex for every $x \in X$ (iii) for every $y \in Y$, $\Phi(\cdot, y) + \frac{m}{2} \|\cdot\|^2$ is convex, differentiable and its gradient is Lipschitz continuous on $X \times Y$

△ Smooth approximation

$$P_{\bar{z}}(x) := \max_{y \in Y} \left\{ \bar{\Phi}_{\bar{z}}(x, y) := \bar{\Phi}(x, y) - \frac{1}{2\bar{z}} \|y - y_0\|^2 \right\} \quad \forall x \in X$$

for some $y_0 \in Y$

△ Algorithms

(i) ACC (accelerated composite gradient)

Input: $(\mu, L) \in \mathbb{R}_{++}^2$, a function pair (ψ_n, ψ_s) , an initial point $z_0 \in \text{dom } \psi_n$

(b) set $y_0 = z_0$, $A_0 = 0$, $\Gamma_0 \stackrel{(\alpha_0 = \beta_0 = 0)}{=} 0$ and $j = 0$

$$(1) \quad A_{j+1} = A_j + \frac{1}{2L} (\mu A_j + 1 + \sqrt{(\mu A_j + 1)^2 + 4L(\mu A_j + 1)A_j})$$

$$\tilde{z}_j = \frac{A_j}{A_{j+1}} z_j + \frac{A_{j+1} - A_j}{A_{j+1}} y_j$$

$$\Gamma_{j+1}(y) = \alpha_{j+1} + \langle y, \beta_{j+1} \rangle, \forall y$$

$$\text{where } \begin{cases} \alpha_{j+1} = \frac{A_j}{A_{j+1}} \alpha_j + \frac{A_{j+1} - A_j}{A_{j+1}} [\psi_s(\tilde{z}_j) - \langle \nabla \psi_s(\tilde{z}_j), \tilde{z}_j \rangle] \\ \beta_{j+1} = \frac{A_j}{A_{j+1}} \beta_j + \frac{A_{j+1} - A_j}{A_{j+1}} \nabla \psi_s(\tilde{z}_j) \end{cases}$$

$$y_{j+1} = \operatorname{argmin}_y \left\{ T_{j+1}(y) + \psi_n(y) + \frac{1}{2A_{j+1}} \|y - y_0\|^2 \right\} \rightarrow \text{needs extra care}$$

$$z_{j+1} = \frac{A_j}{A_{j+1}} z_j + \frac{A_{j+1} - A_j}{A_{j+1}} y_{j+1}$$

$$(2) \quad u_{j+1} = (y_0 - y_{j+1}) / A_{j+1}$$

$$\varepsilon_{j+1} = \psi(z_{j+1}) - T_{j+1}(y_{j+1}) - \psi_n(y_{j+1}) - \langle u_{j+1}, z_{j+1} - y_{j+1} \rangle$$

$$(3) \quad j = j+1 \text{ and go to (1)}$$

(ii) AIPP (Accelerated inexact proximal point method)

Input: a function pair (f, h) , $(m, M) \in \mathbb{R}_{++}^2$ satisfying (P2), $\lambda \in (0, \frac{1}{2m}]$,

$\sigma \in (0, 1)$, an initial point $x_0 \in \operatorname{dom} h$, a tolerance $\bar{\rho} > 0$

Output: $(\bar{x}, \bar{u}) \in \operatorname{dom} h \times X$ satisfying $\bar{u} \in \nabla f(\bar{x}) + \partial h(\bar{x})$, $\|\bar{u}\| \leq \bar{\rho}$

$$(0) \text{ set } k=1, \hat{\rho} := \frac{\bar{\rho}}{4}, \hat{\varepsilon} := \bar{\rho}^2 / (32(M + \frac{1}{\lambda})), M_\lambda := M + \frac{1}{\lambda}$$

(1) call ACG with inputs $z_0 = x_{k-1}$, $(\mu, L) = (\frac{1}{2}, \lambda M + \frac{1}{2})$, $\psi_s = \lambda f + \frac{1}{4} \|\cdot - x_{k-1}\|^2$ and $\psi_n = \lambda h + \frac{1}{4} \|\cdot - x_{k-1}\|^2$ in order to obtain a triple $(x, u, \varepsilon) \in X \times X \times \mathbb{R}_+$ satisfying $u \in \partial_\varepsilon(\lambda \phi + \frac{1}{2} \|\cdot - x_{k-1}\|^2)(x)$, $\|u\|^2 + 2\varepsilon \leq \sigma \|x_{k-1} - x + u\|^2$ (*)

stop condition

(2) if $\|x_{k-1} - x + u\| \leq \lambda \hat{\rho} / 5$, then go to (3);

otherwise set $(x_k, \tilde{u}_k, \tilde{\varepsilon}_k) = (x, u, \varepsilon)$, $k = k+1$ and go to (1)

(3) restart the previous call to ACG in step 1 to find a triple $(\tilde{x}, \tilde{u}, \tilde{\varepsilon})$ such that $\tilde{\varepsilon} \leq \hat{\varepsilon} \lambda$ and $(x, u, \varepsilon) = (\tilde{x}, \tilde{u}, \tilde{\varepsilon})$ satisfies (*)

$$(4) \quad \bar{x} := \operatorname{argmin}_{x' \in X} \left\{ \langle \nabla f(x), x' - x \rangle + h(x') + \frac{M_\lambda}{2} \|x' - x\|^2 \right\}$$

$$\bar{u} := M_\lambda (x - \bar{x}) + \nabla f(x) - \nabla f(\bar{x})$$

(iii) AIPP-S

Input: $(m, L_x, L_y) \in \mathbb{R}_{++}^3$ satisfying (A3), a smoothing constant $\xi > 0$

an initial point $(x_0, y_0) \in X \times Y$, a tolerance $\rho > 0$

Output: $(x, u) \in X \times X$

(0) $L_z = L_y Q_z + L_x$, where $Q_z = z L_y + \sqrt{z(Lx+m)}$

$\sigma = \frac{1}{z}, \lambda = \frac{1}{4m}$

$P_z(x) := \max_{y \in Y} \{ \Phi_z(x, y) := \Phi(x, y) - \frac{1}{2z} \|y - y_0\|^2 \} \quad \forall x \in X$

(1) apply AIPP with inputs $(m, L_z), (P_z, h), \lambda, \sigma, x_0$ and f to obtain a pair (x, u) satisfying $u \in \nabla P_z(x) + \partial h(x), \|u\| \leq \rho$

(2) output the pair (x, u)