Figure 313

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Check interpretation of coefficients in anisotropic CRS formula

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Define working folder, add links to Library and SeisLab

```
clear; close all; clc;
mlibfolder = '/home/zmaw/u250128/Desktop/MLIB';
path(path, mlibfolder);
addmypath;
```

Introduction

```
% Note:
% Accuracy of traveltime 10e-12
% Accuracy of attributes 10e-10

model = 64:64
    acquisition = 4;

model =
64
```

Get model parameters

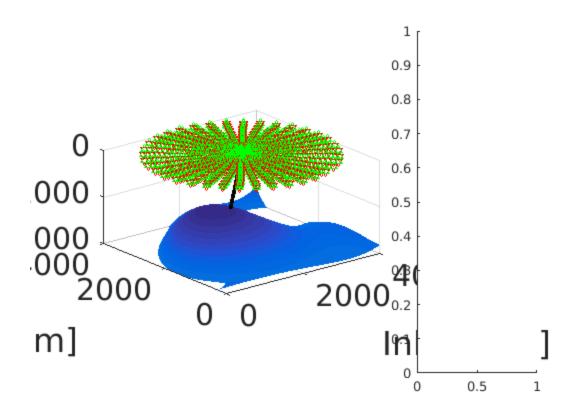
```
Get_model_parameters;
```

Get acquisition geometry

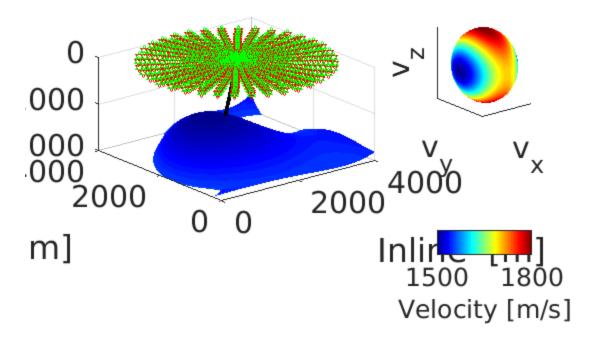
Get_model_acquisition_geometry;

Plot acquisition geometry

```
x0 = [2000; 2000; 0];
             [~, xref ] = Get_model_exact_traveltime(X0, X0, 64);
             figure(1)
             subplot(1,3,[1 2])
             [XX, YY] = meshgrid(G.xx, G.yy);
             [ZZ, ind] = Get_model_surface(XX,YY,model);
             h = surf(XX, YY, ZZ);
   set(h,'FaceColor','interp','EdgeColor','none','DiffuseStrength',.8)
             plot3(Xs(1,:),Xs(2,:),Xs(3,:), 'rv');
             plot3(Xg(1,:),Xg(2,:),Xg(3,:), 'g^');
             plot3(X0(1),X0(2),X0(3), 'b*');
   plot3(linspace(XO(1),xref(1),200),linspace(XO(2),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),200),linspace(XO(3),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xref(2),xre
black', 'LineWidth',3);
             axis([G.x0, G.mx, G.y0, G.my, G.z0, G.mz]);
             xlabel('Inline [m]', 'Fontsize', 24);
             ylabel('Crossline [m]', 'Fontsize', 24);
             zlabel('Depth [m]', 'Fontsize', 24);
             set(gca,'xtick',[0 2000 4000])
             set(gca,'ytick',[0 2000 4000])
             set(gca,'ztick',[0 1000 2000])
             view(-39,19);
             set(gca, 'ZDir', 'reverse')
             set(gca,'FontSize',24)
             axis('equal')
             axis([0 4000 0 4000 0 2000])
             subplot(1,3,3)
```



```
[x, y, z] = ellipsoid(0,0,0,sqrt(All),sqrt(A22),sqrt(A33),30);
   subplot(1,3,3)
  c = sqrt(x.^2 + y.^2 + z.^2);
  surf(x, y, z,c)
  xlabel('v_x', 'Fontsize', 24);
  ylabel('v_y', 'Fontsize', 24);
   zlabel('v_z', 'Fontsize', 24);
   c = colorbar('southoutside', 'Ticks', [1500,1800], 'Fontsize',
20);
   c.Label.String = 'Velocity [m/s]';
   set(gca,'xtick',[])
   set(gca,'ytick',[])
   set(gca,'ztick',[])
  axis equal
  view(-39,19);
   %colormap(makeColorMap([0 0 1],[1 1 1],[1 0 0],100));
   colormap('jet')
   shading interp
```



Find stacking parameters

w3, M3 and N3 are stacking parameters. They could be transformed to wavefield attributes

- V phase velocity
- alpha, beta phase angles
- theta, phi group angles

Case 1. Isotropic homogeneous overburden:

```
model = 61;
[ t0, w3, M3, N3 ] = Get_model_stacking_parameters( X0, model );

V0 = 2/norm(w3);
[ alpha, beta, KNIP, KN ] = my_A3P(V0, w3, M3, N3);

KNIP = KNIP
KN = KN
clear alpha beta KNIP KN v0 w3 M3 N3 model
KNIP =
```

```
1.0e-03 *
   0.8573
            0.0000 -0.0000
  -0.0000
            0.8573
                    0.0000
   -0.0000
            0.0000
                      0.0000
KN =
  1.0e-03 *
   0.3485
          -0.0077
                      0.0000
  -0.0077
            0.3873
                      0.0000
  -0.0000
             0.0000
                      0.0000
```

Case 2. Isotropic inhomogeneous overburden:

```
model = 63;
    CRS_param = MLD([mlibfolder '/CRS/models/model_'
num2str(model) '_CRS_param.mat']);
   X0 = CRS_param.x0;
   t0 = CRS_param.t0;
   v0 = CRS_param.v0;
   w3 = CRS_param.w;
   M3 = CRS_param.M;
   N3 = CRS_param.N;
   V0 = 2/norm(w3);
    [ alpha, beta, KNIP, KN ] = my_A3P(V0, w3, M3, N3);
   KNIP = KNIP
   KN = KN
KNIP =
   1.0e-03 *
   0.7597
            -0.0000 -0.0000
            0.7676
   -0.0000
                      -0.0000
   -0.0000
            -0.0000 -0.0000
KN =
  1.0e-03 *
   0.2660 -0.0060
                       0.0000
```

```
    -0.0060
    0.3176
    0.0000

    -0.0000
    -0.0000
    -0.0000
```

Case 3. Anisotropic homogeneous overburden:

```
model = 64;
               [ t0, w3, M3, N3 ] = Get_model_stacking_parameters( X0, model );
              V0 = 2/norm(w3);
               [ alpha, beta, KNIP, KN ] = my_A3P(V0, w3, M3, N3);
              KNIP = KNIP
              KN = KN
KNIP =
              0.0011
                                               0.0001 -0.0001
                                               0.0010 -0.0000
              0.0001
            -0.0001 -0.0000
                                                                                      0.0000
KN =
           1.0e-03 *
              0.3637
                                                   0.0084
                                                                                     -0.0244
              0.0084
                                                 0.4106 -0.0093
           -0.0244
                                               -0.0093
                                                                                        0.0018
               theta = atan( sqrt((A11*cos(beta))^2 + (A22*sin(beta))^2)/
A33*tan(alpha));
              phi = atan(A22/A11*tan(beta));
              v = 1/sqrt((sin(theta)*cos(phi))^2/Al1 + (sin(theta)*sin(phi))^2/Al1 + (sin(theta)*sin(phi))^2
A22 + (\cos(theta))^2/A33);
              vacq = v*([sin(theta)*cos(phi); sin(theta)*sin(phi); cos(theta)]);
              R = Get_Rmatrix_3x3(alpha, beta);
              vwoc = R'*vacq
              KNIP*vwoc;
              KN*vwoc
              KNIP'*vwoc
              KN'*vwoc
              w = w3(1:2, 1);
              N = N3(1:2, 1:2);
              M = M3(1:2, 1:2);
```

```
vwoc =
   1.0e+03 *
    0.1188
    0.0378
    1.7843
ans =
   1.0e-04 *
    0.3991
   -0.7623
   -0.1058
ans =
   1.0e-05 *
    0.0163
   -0.1028
   -0.0501
ans =
   1.0e-05 *
   -0.2553
    0.0257
   -0.9377
```

CRS, n-CRS and i-CRS errors for CMP and ZO acquisition

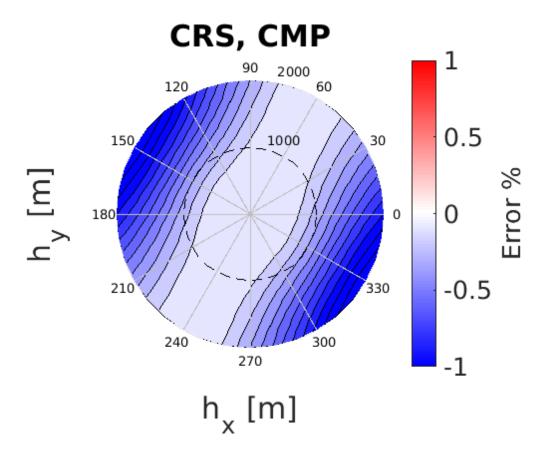
```
% Load CMP acquisition
acquisition = 4;
Get_model_acquisition_geometry;

% Compute exact traveltimes

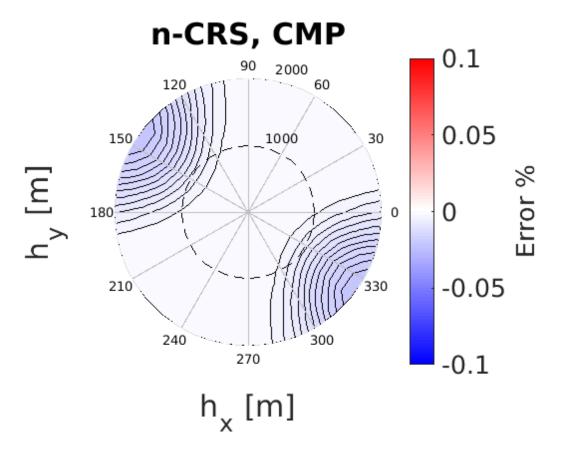
%tti_ex_CMP = Get_model_exact_traveltime(Xs, Xg, model);
%save([mlibfolder '/CRS/models/model_' num2str(model)
'_traveltimes_for_acq_' num2str(acquisition) '.mat'], 'tti_ex_CMP');
   tti_ex_CMP = MLD([mlibfolder '/CRS/models/model_'
num2str(model) '_traveltimes_for_acq_' num2str(acquisition) '.mat']);
```

```
% Compute traveltime approximations
   HH = (Xg(1:2, :) - Xs(1:2,:))/2;
   MM = (Xg(1:2, :) + Xs(1:2,:))/2;
   MM(1,:) = MM(1,:) - XO(1);
   MM(2,:) = MM(2,:) - XO(2);
   of_CMP = offset;
   az CMP = azimuth;
   [OF, AZ] = meshgrid(of_CMP,az_CMP);
   XX = OF.*cos(AZ);
   YY = OF.*sin(AZ);
   tti crs CMP = Get traveltime 3D CRS (MM, HH, t0, w, M, N);
   tti_ncrs_CMP = Get_traveltime_3D_nCRS(MM, HH, t0, w, M, N);
   tti_icrs_CMP = Get_traveltime_3D_iCRS_el_LIA(MM, HH, t0, V0, w, M,
N, 3);
   dt_crs_CMP
                  = reshape((tti_crs_CMP -tti_ex_CMP)./
tti_ex_CMP*100,length(az_CMP),length(of_CMP));
   dt_ncrs_CMP = reshape((tti_ncrs_CMP -tti_ex_CMP)./
tti_ex_CMP*100,length(az_CMP),length(of_CMP));
   dt icrs CMP
                = reshape((tti_icrs_CMP(3,:) -tti_ex_CMP)./
tti_ex_CMP*100,length(az_CMP),length(of_CMP));
    % Load ZO acquisition
   acquisition = 5;
   Get_model_acquisition_geometry;
   % Compute exact traveltimes
   %tti_ex_ZO = Get_model_exact_traveltime(Xs, Xg, model);
    %save([mlibfolder '/CRS/models/model_' num2str(model)
 '_traveltimes_for_acq_' num2str(acquisition) '.mat'], 'tti_ex_ZO');
    tti_ex_ZO = MLD([mlibfolder '/CRS/models/model_'
num2str(model) '_traveltimes_for_acq_' num2str(acquisition) '.mat']);
    % Compute traveltime approximations
   HH = (Xg(1:2, :) - Xs(1:2,:))/2;
   MM = (Xg(1:2, :) + Xs(1:2,:))/2;
   MM(1,:) = MM(1,:) - XO(1);
   MM(2,:) = MM(2,:) - XO(2);
   of_ZO = offset;
   az_Z0 = azimuth;
   tti crs ZO = Get traveltime 3D CRS (MM, HH, t0, w, M, N);
   tti_ncrs_ZO = Get_traveltime_3D_nCRS(MM, HH, t0, w, M, N);
   tti_icrs_ZO = Get_traveltime_3D_iCRS_el_LIA(MM, HH, t0, V0, w, M,
N, 3);
   dt_crs_Z0
                 = reshape((tti_crs_ZO -tti_ex_ZO)./
tti_ex_ZO*100,length(az_ZO),length(of_ZO));
   dt_ncrs_Z0
                = reshape((tti_ncrs_ZO -tti_ex_ZO)./
tti_ex_ZO*100,length(az_ZO),length(of_ZO));
```

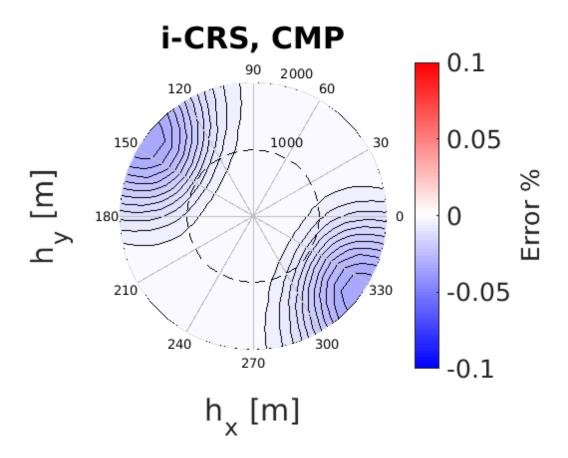
```
dt_icrs_Z0
               = reshape((tti_icrs_ZO(3,:) -tti_ex_ZO)./
tti ex ZO*100,length(az ZO),length(of ZO));
    [OF, AZ] = meshgrid(of_CMP,az_CMP);
   XX = OF.*cos(AZ);
   YY = OF.*sin(AZ);
   figure(21)
   %subplot(2,3,1)
   h = polar(azimuth, 2000*ones(size(azimuth)), '-black');
   hold on
   contourf(XX,YY,dt_crs_CMP,11);
   for a = 0:pi/6:pi
       hold on
       x1 = (-2000:10:2000)*cos(a);
       x2 = (-2000:10:2000)*sin(a);
       plot(x1,x2,'Color',[0.75 0.75 0.75])
   polar(azimuth,1000*ones(size(azimuth)),'--black');
   text(250,1100,'1000')
   c = colorbar('Ticks', [-1,-0.5 0, 0.5, 1], 'Fontsize', 20);
   c.Label.String = 'Error %';
   caxis([-1 1])
   colormap(makeColorMap([0 0 1],[1 1 1],[1 0 0],100));
   xlabel('h_x [m]','Fontsize', 24)
   ylabel('h_y [m]', 'Fontsize', 24)
   title('CRS, CMP', 'Fontsize', 24)
```



```
figure(22)
%subplot(2,3,2)
h = polar(azimuth,2000*ones(size(azimuth)), '-black');
hold on
contourf(XX,YY,dt_ncrs_CMP,11);
for a = 0:pi/6:pi
    hold on
    x1 = (-2000:10:2000)*cos(a);
    x2 = (-2000:10:2000)*sin(a);
    plot(x1,x2,'Color',[0.75 0.75 0.75])
end
polar(azimuth,1000*ones(size(azimuth)),'--black');
text(250,1100,'1000')
c = colorbar('Ticks', [-0.1,-0.05 0, 0.05, 0.1], 'Fontsize', 20);
c.Label.String = 'Error %';
caxis([-0.1 0.1])
colormap(makeColorMap([0 0 1],[1 1 1],[1 0 0],100));
xlabel('h_x [m]','Fontsize', 24)
ylabel('h_y [m]', 'Fontsize', 24)
title('n-CRS, CMP', 'Fontsize', 24)
```

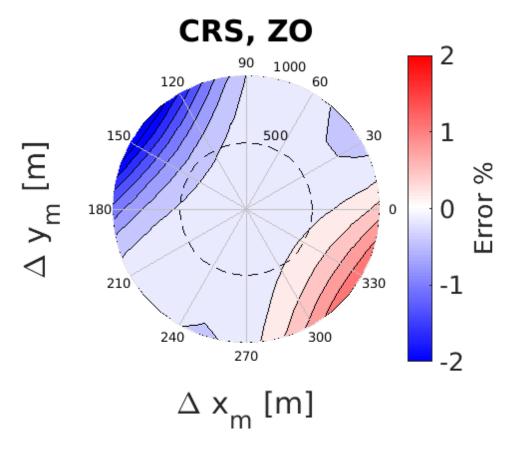


```
figure(23)
%subplot(2,3,3)
h = polar(azimuth,2000*ones(size(azimuth)), '-black');
hold on
contourf(XX,YY,dt_icrs_CMP,11);
for a = 0:pi/6:pi
    hold on
    x1 = (-2000:10:2000)*cos(a);
    x2 = (-2000:10:2000)*sin(a);
    plot(x1,x2,'Color',[0.75 0.75 0.75])
end
polar(azimuth,1000*ones(size(azimuth)),'--black');
text(250,1100,'1000')
c = colorbar('Ticks', [-0.1,-0.05 0, 0.05, 0.1], 'Fontsize', 20);
c.Label.String = 'Error %';
caxis([-0.1 0.1])
colormap(makeColorMap([0 0 1],[1 1 1],[1 0 0],100));
xlabel('h_x [m]','Fontsize', 24)
ylabel('h_y [m]', 'Fontsize', 24)
title('i-CRS, CMP', 'Fontsize', 24)
```



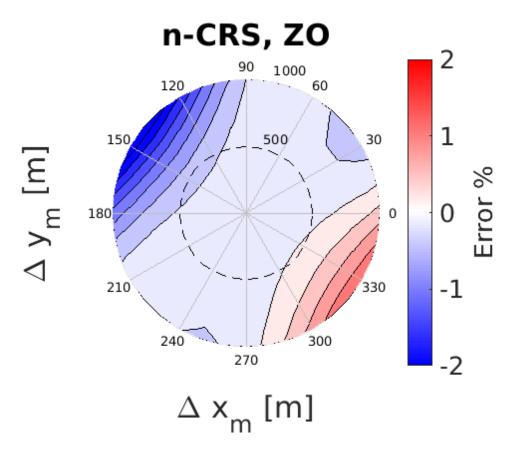
```
[OF, AZ] = meshgrid(of_ZO,az_ZO);
XX = OF.*cos(AZ);
YY = OF.*sin(AZ);
figure(24)
%subplot(2,3,4)
h = polar(azimuth,1000*ones(size(azimuth)), '-black');
hold on
contourf(XX,YY,dt_crs_ZO,11);
for a = 0:pi/6:pi
    hold on
   x1 = (-1000:10:1000)*cos(a);
    x2 = (-1000:10:1000)*sin(a);
    plot(x1,x2,'Color',[0.75 0.75 0.75])
end
polar(azimuth,500*ones(size(azimuth)),'--black');
text(125,550,'500')
c = colorbar('Ticks', [-2,-1 0, 1, 2], 'Fontsize', 20);
```

```
c.Label.String = 'Error %';
caxis([-2 2])
colormap(makeColorMap([0 0 1],[1 1 1],[1 0 0],100));
xlabel('\Delta x_m [m]','Fontsize', 24)
ylabel('\Delta y_m [m]', 'Fontsize', 24)
title('CRS, ZO', 'Fontsize', 24)
```

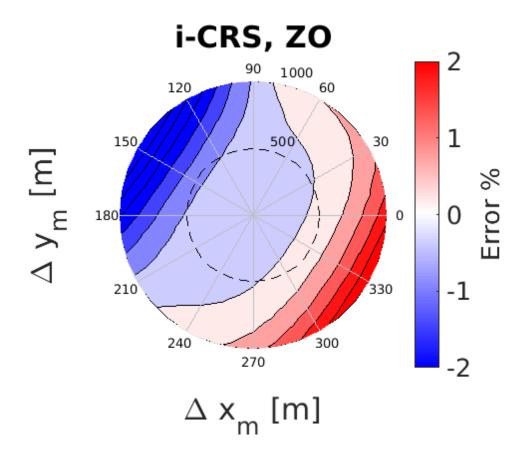


```
figure(25)
%subplot(2,3,5)
h = polar(azimuth,1000*ones(size(azimuth)), '-black');
hold on
contourf(XX,YY,dt_ncrs_ZO,11);
for a = 0:pi/6:pi
   hold on
    x1 = (-1000:10:1000)*cos(a);
    x2 = (-1000:10:1000)*sin(a);
    plot(x1,x2,'Color',[0.75 0.75 0.75])
end
polar(azimuth,500*ones(size(azimuth)),'--black');
text(125,550,'500')
c = colorbar('Ticks', [-2,-1 0, 1, 2], 'Fontsize', 20);
c.Label.String = 'Error %';
caxis([-2 2])
colormap(makeColorMap([0 0 1],[1 1 1],[1 0 0],100));
xlabel('\Delta x_m [m]','Fontsize', 24)
```

```
ylabel('\Delta y_m [m]', 'Fontsize', 24)
title('n-CRS, ZO', 'Fontsize', 24)
```



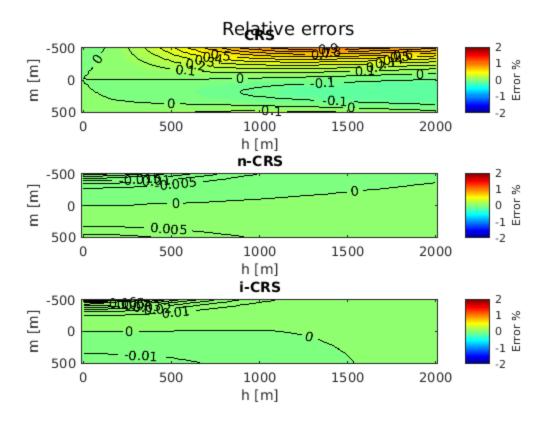
```
figure(26)
%subplot(2,3,6)
h = polar(azimuth,1000*ones(size(azimuth)), '-black');
contourf(XX,YY,dt_icrs_ZO,11);
for a = 0:pi/6:pi
   hold on
    x1 = (-1000:10:1000)*cos(a);
    x2 = (-1000:10:1000)*sin(a);
    plot(x1,x2,'Color',[0.75 0.75 0.75])
end
polar(azimuth,500*ones(size(azimuth)),'--black');
text(125,550,'500')
c = colorbar('Ticks', [-2,-1 0, 1, 2], 'Fontsize', 20);
c.Label.String = 'Error %';
caxis([-2 2])
colormap(makeColorMap([0 0 1],[1 1 1],[1 0 0],100));
xlabel('\Delta x_m [m]', 'Fontsize', 24)
ylabel('\Delta y_m [m]', 'Fontsize', 24)
title('i-CRS, ZO', 'Fontsize', 24)
```



CRS, n-CRS and i-CRS errors for 2D line

```
% Load CMP acquisition
acquisition = 2;
Get_model_acquisition_geometry;
% Compute exact traveltimes
%tti_ex_2D = Get_model_exact_traveltime(Xs, Xg, model);
%save([mlibfolder '/CRS/models/model_' num2str(model)
 '_traveltimes_for_acq_' num2str(acquisition) '.mat'], 'tti_ex_2D');
tti_ex_2D = MLD([mlibfolder '/CRS/models/model_'
num2str(model) '_traveltimes_for_acq_' num2str(acquisition) '.mat']);
% Compute traveltime approximations
HH = (Xg(1:2, :) - Xs(1:2,:))/2;
MM = (Xg(1:2, :) + Xs(1:2,:))/2;
MM(1,:) = MM(1,:) - XO(1);
MM(2,:) = MM(2,:) - XO(2);
tti_crs_2D = Get_traveltime_3D_CRS (MM, HH, t0, w, M, N);
tti_ncrs_2D = Get_traveltime_3D_nCRS(MM, HH, t0, w, M, N);
tti_icrs_2D = Get_traveltime_3D_iCRS_el_LIA(MM, HH, t0, V0, w, M, N,
 3);
```

```
texac = reshape(tti ex 2D,81,41);
tcrs = reshape(tti_crs_2D,81,41);
tncrs = reshape(tti ncrs 2D,81,41);
ticrs = reshape(tti_icrs_2D(end,:),81,41);
m = -500:25:500;
h = 0:25:2000;
figure(3)
suptitle('Relative errors')
subplot(3,1,1)
data = (tcrs - texac)./texac*100;
imagesc(h,m',flipud(data'))
xlabel('h [m]');
ylabel('m [m]');
title('CRS')
colorbar
colormap('Jet');
caxis([-2 2])
hold on
contour(h,m',flipud(data'),'color','k','ShowText','on')
c = colorbar('Ticks', [-2, -1 0, 1, 2]);
c.Label.String = 'Error %';
subplot(3,1,2)
data = (tncrs - texac)./texac*100;
imagesc(h,m',flipud(data'))
xlabel('h [m]');
ylabel('m [m]');
title('n-CRS')
colorbar
colormap('Jet');
caxis([-2 2])
hold on
contour(h,m',flipud(data'),'color','k','ShowText','on')
c = colorbar('Ticks', [-2, -1 0, 1, 2]);
c.Label.String = 'Error %';
subplot(3,1,3)
data = (ticrs - texac)./texac*100;
imagesc(h,m',flipud(data'))
xlabel('h [m]');
ylabel('m [m]');
title('i-CRS')
colorbar
colormap('Jet');
caxis([-2 2])
hold on
contour(h,m',flipud(data'),'color','k','ShowText','on')
c = colorbar('Ticks', [-2,-1 0, 1, 2]);
c.Label.String = 'Error %';
```



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