

---

# Check the idea that n-CRS sews two solutions: CRS and DSR

## Table of Contents

Introduction .....	1
Define working folder, add links to Library and SeisLab .....	1
Define model parameters (See table 4.1): .....	1
Set offset and midpoint displacement .....	2
Part I: Calculate traveltimes of PP waves .....	2
Part II: Find traveltime approximation for PP and PS waves .....	2
Part III Compare approximations .....	2
Part IV Compare approximations .....	3
Part V Compare approximations .....	4

## Introduction

**Author:** Abakumov Ivan

**Publication date:** 10th August 2016

## Define working folder, add links to Library and SeisLab

```
clear; close all; clc;
mlibfolder = '/home/zmaw/u250128/Desktop/MLIB';
path(path, mlibfolder);
addmypath;
current_folder = pwd;
```

## Define model parameters (See table 4.1):

```
Rmin = 0.0001; % min radius of curvature (0.1 m)
Rmax = 10000; % max radius of curvature (10000 km)
R = logspace(log(Rmin)/log(10), log(Rmax)/log(10), 50);
TePP = zeros(size(R));
TePS = zeros(size(R));
T_CRS = zeros(size(R));
T_nCRS = zeros(size(R));
T_DSR = zeros(size(R));
T_MF = zeros(size(R));
T_iCRS = zeros(size(R));
T_DSR_PS = zeros(size(R));
```

```
T_CRS_PS = zeros(size(R));
T_nCRS_PS = zeros(size(R));

for i=1:length(R)

    alpha = pi/6;                % radian
    Rnip = 1.0;                  % km
    Rn = Rnip + R(i);           % km
    Vp = 3.2;                   % km/s
    Vs = 1.8;                   % km/s
    modelPP = [alpha, Rnip, Rn, Vp, Vp];
    modelPS = [alpha, Rnip, Rn, Vp, Vs];
```

## Set offset and midpoint displacement

```
m = 0.2;
h = 0.4;
[M,H]=meshgrid(m,h);
```

## Part I: Calculate traveltimes of PP waves

```
TePP(i) = Get_traveltime_2D_exact(M,H,modelPP);
TePS(i) = Get_traveltime_2D_exact(M,H,modelPS);
```

## Part II: Find traveltime approximation for PP and PS waves

```
% PP approximations
T_CRS(i) = Get_traveltime_2D_CRS(M, H, modelPP);
T_nCRS(i) = Get_traveltime_2D_nCRS(M, H, modelPP);
T_DSR(i) = Get_traveltime_2D_DSR_PS(M, H, modelPP);
T_MF(i) = Get_traveltime_2D_MF(M, H, modelPP);
T_iCRS(i) = Get_traveltime_2D_iCRS(M, H, modelPP);

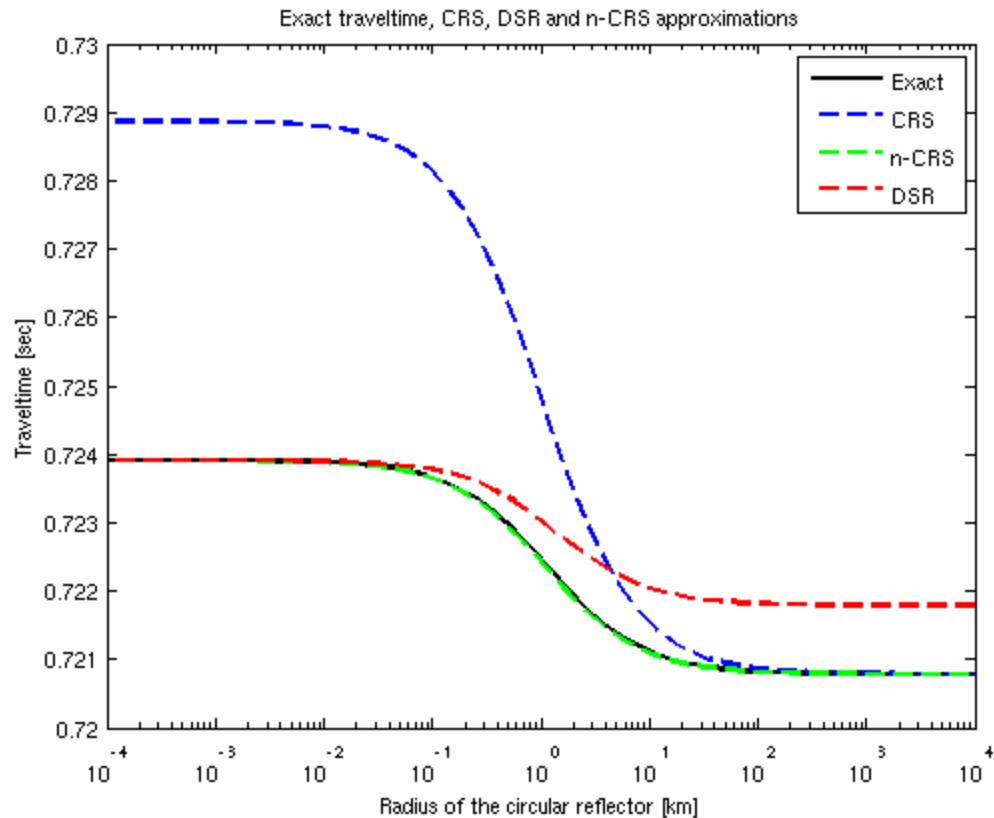
% PS approximations
T_DSR_PS(i) = Get_traveltime_2D_DSR_PS(M, H, modelPS);
T_CRS_PS(i) = Get_traveltime_2D_CRS_PS(M, H, modelPS);
T_nCRS_PS(i) = Get_traveltime_2D_nCRS_PS(M, H, modelPS);

end
```

## Part III Compare approximations

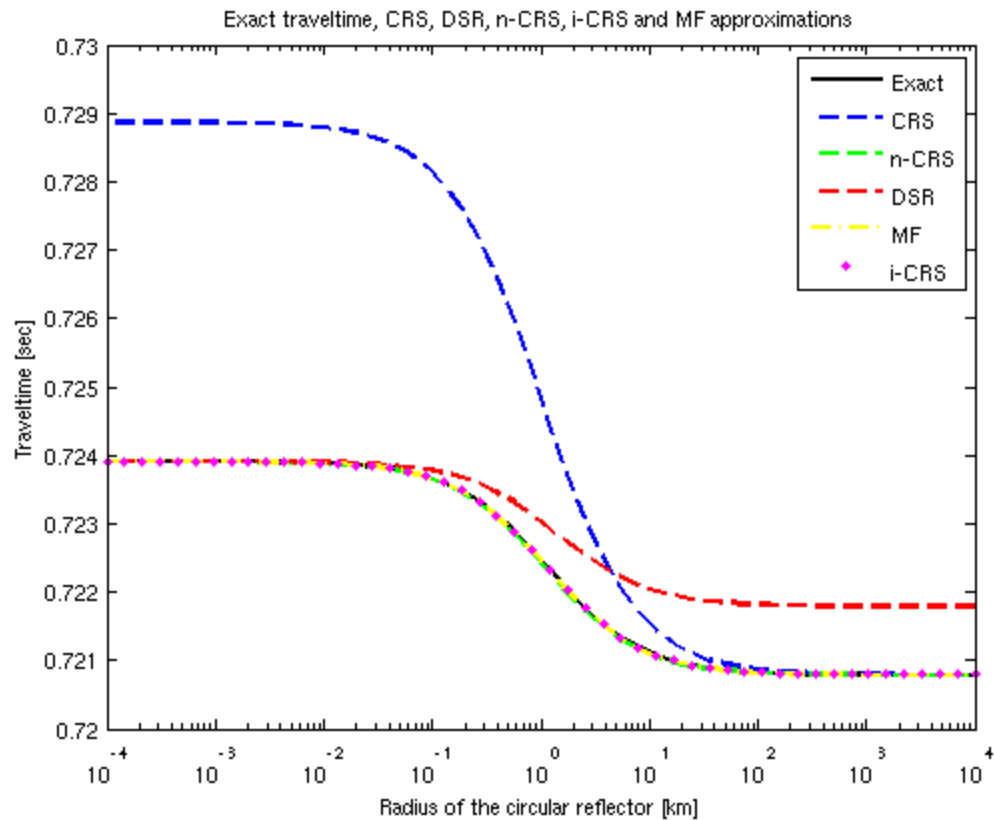
```
figure(1)
semilogx(R, TePP, '-black', 'LineWidth',2);
hold on
semilogx(R, T_CRS, '--blue', 'LineWidth',2);
semilogx(R, T_nCRS, '--g', 'LineWidth',2);
semilogx(R, T_DSR, '--r', 'LineWidth',2);
```

```
legend('Exact', 'CRS', 'n-CRS', 'DSR','Location','NorthEast');  
% axis([0, 1.35, 0.35, 1.35]);  
xlabel('Radius of the circular reflector [km]')  
ylabel('Traveltime [sec]')  
title('Exact traveltimes, CRS, DSR and n-CRS approximations')  
  
% Add manually  
%point diffractor limit  
%plane reflector limit
```



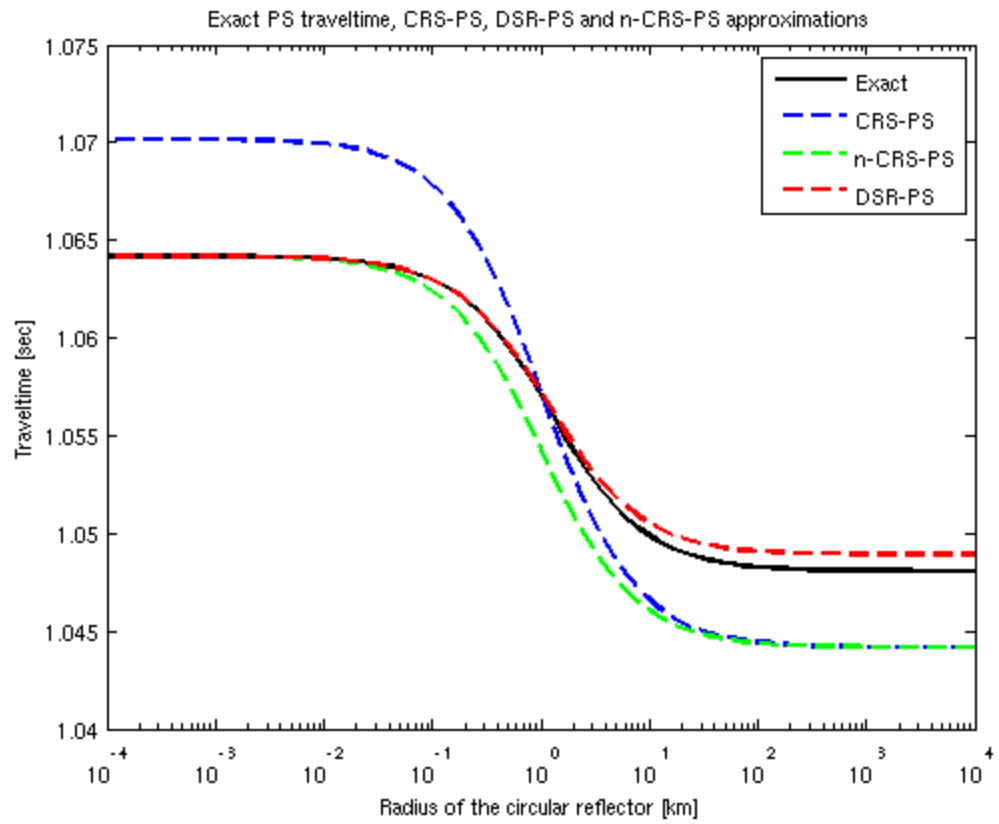
## Part IV Compare approximations

```
figure(2)  
semilogx(R, TePP, '-black', 'LineWidth',2);  
hold on  
semilogx(R, T_CRS, '--blue', 'LineWidth',2);  
semilogx(R, T_nCRS, '--g', 'LineWidth',2);  
semilogx(R, T_DSR, '--r', 'LineWidth',2);  
semilogx(R, T_MF, '-.yellow', 'LineWidth',2);  
semilogx(R, T_iCRS, '.m', 'LineWidth',2);  
legend('Exact', 'CRS', 'n-CRS', 'DSR','MF','i-CRS','Location','NorthEast');  
% axis([0, 1.35, 0.35, 1.35]);  
xlabel('Radius of the circular reflector [km]')  
ylabel('Traveltime [sec]')  
title('Exact traveltimes, CRS, DSR, n-CRS, i-CRS and MF approximations')
```



## Part V Compare approximations

```
figure(3)
semilogx(R, TePS, '-black', 'LineWidth',2);
hold on
semilogx(R, T_CRS_PS, '--blue', 'LineWidth',2);
semilogx(R, T_nCRS_PS, '--g', 'LineWidth',2);
semilogx(R, T_DSR_PS, '--r', 'LineWidth',2);
legend('Exact', 'CRS-PS', 'n-CRS-PS', 'DSR-PS', 'Location', 'NorthEast');
% axis([0, 1.35, 0.35, 1.35]);
xlabel('Radius of the circular reflector [km]')
ylabel('Traveltimes [sec]')
title('Exact PS traveltimes, CRS-PS, DSR-PS and n-CRS-PS approximations')
```



*Published with MATLAB® R2013a*