

Problem 22

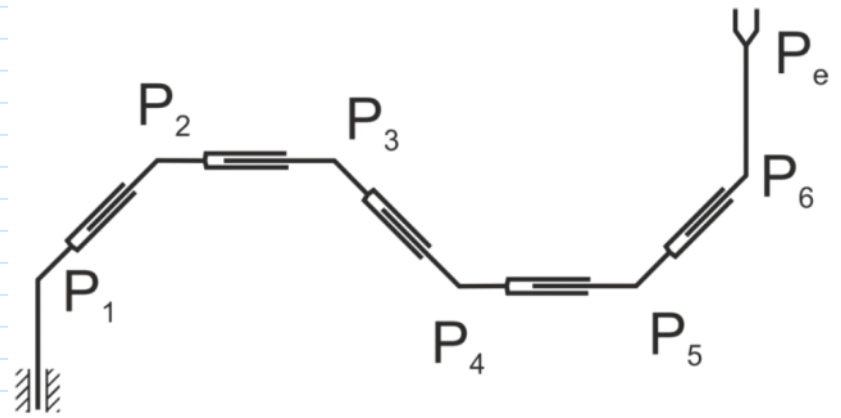
$$P_i = (x_i, y_i, r_i)^T$$

$$P_0 = \vec{0}$$

for $i=1$ to n

$$P_i = P_{i-1} + fct(\vec{q}_i)$$

end



$$P_e = \text{RecursivePosition}(\vec{q})$$

$$fct \ P = \text{RecursivePosition}(\vec{q})$$



PassiveDyn
amicWalker