

Some Notes on Object-Oriented Programming

## Implementing a coordinate system in software

Data

$A_{ic}$   
 $\tilde{\omega}_{ic}$   
 color  
 3D-info  
 env  
 $\dot{A}_{ic}$

Functionality

$T\vec{u} = \text{transform}(A_{ic}, \tilde{u})$   
 $\dot{A}_{ic} = \text{derivative}(A_{ic}, \tilde{\omega}_{ic})$   
 3D-info = create3D-info( $A_{ic}$ )  
 showCoSys(color, 3D-info, env)  
 $\dot{A}_{ic}$

Object C combines data & functionality (state & behavior)

Create  
Delete

"Constructor"  
"Destructor"

O = (classname (vars) → initialize  
O.delete() → clean-up

Members

→ can interact

	<u>Data</u>	<u>Methods</u>
Public	$A_{ic}$ $\tilde{\omega}_{ic}$ color	constructor( $A_{ic}$ , env, color) destructor() set( $A_{ic}$ ), set( $\tilde{\omega}_{ic}$ ), ... transform( $\tilde{\omega}_{ic}$ ) getDerivative()
Private	env 3D-info $\dot{A}_{ic}$	create3Dinfo() showCoSys() computeDerivative()

```

classdef MyCLASS < handle
    properties (SetAccess = public, GetAccess = public)
        myVariable % a public variable
    end
    methods % no arguments means 'public'
        function obj = MyCLASS(initialValue) % constructor
            obj.myVariable = initialValue; % initialize variable
        end
        function showVariable(obj) % 'obj' is always first variable
            disp(obj.myVariable) % access 'myVariable' of this object
        end
    end
end
end
    
```

```

% Construct object and initialize with 42:
obj1 = MyCLASS(42);
% Construct another object with 17
obj2 = MyCLASS(17);

obj1.showVariable(); % Output is 42
showVariable(obj1); % (Alternative syntax)
obj2.showVariable(); % Output is 17

obj1.myVariable = 23; % Change state
obj1.showVariable(); % Output is 23
    
```