Bare Demo of IEEERev.cls for IEEE Journals

Yuchen Jin, *Member, IEEE,* and Yuchen Jin II, *Member, IEEE*

***Abstract*—The abstract goes here.**

***Index Terms*—IEEE, IEEEtran, journal, LaTeX, paper, template.**

I. Show Homework

sadfasf, sdfdsf, sdf.

Test citations:

[1–3].

A. Show Floats

Test figures and example block which is shown in Example 1.

Example 1: Show figures

Test inner subgraphs, i.e. Figure 1(a) and Figure 1(b):

(a) D = 1

Here could be graphs.

(b) D = 0.5

Fig. 1. Test graphs.

□

Test subequations and the theorem block which is shown in Theorem 1.

Theorem 1: Example Theorem

Here we show a simple example of subequations in (1-1):

$$\frac{\partial \mathcal{L}(\mathbf{w},\ b)}{\partial \mathbf{w}} = \mathbf{w} + C\sum_i \frac{\partial \ell_i}{\partial \mathbf{w}}, \tag{1-1}$$

$$\frac{\partial \mathcal{L}(\mathbf{w},\ b)}{\partial b} = C\sum_i \frac{\partial \ell_i}{\partial b}, \tag{1-2}$$

Test table, which is shown in Table I:

TABLE I
Parameters of *Daubechies*'s filter.

n	h[n]	g[n]
0	0.3327	-0.0352
1	0.8069	-0.0854
2	0.4599	0.1350
3	-0.1350	0.4599
4	-0.0854	-0.8069
5	0.0352	0.3327

Test equations in (2):

$$\begin{aligned} I(\Omega) &= \mathrm{Re}\left\{\frac{e^{-x}}{j\Omega}e^{j\Omega x}\Big|_0^1 + o\left(\frac{1}{\Omega}\right)\right\} \approx \mathrm{Re}\left\{\frac{e^{-x}}{j\Omega}e^{j\Omega x}\Big|_0^1\right\} \\ &= \mathrm{Re}\left\{\frac{e^{j\Omega-1}-1}{j\Omega}\right\} = \frac{1}{\Omega e}\cos\left(\Omega-\frac{\pi}{2}\right) = \frac{1}{\Omega e}\sin\Omega. \end{aligned} \tag{2}$$

B. Show Algorithm

Test Algorithm in Algorithm 1:

Algorithm 1 DWT Algorithm

Input: Sequence $\mathbf{x}$ in time domain

Output: Sequence $\hat{\mathbf{x}}$ in wavelet domain

1: $N = \lfloor \log_2(\mathrm{length}(\mathbf{x})) \rfloor$;
2: $\mathbf{c}_N = \mathbf{x}$, $\hat{\mathbf{x}} = \varnothing$;
3: **for** i from 1 to N **do**
4: $\quad \mathbf{c}_{N-i}$, $\mathbf{d}_{N-i}$ = analysis_filter($\mathbf{c}_{N-i+1}$);
5: $\quad$ insert $\mathbf{d}_{N-i}$ at the beginning of $\hat{\mathbf{x}}$.
6: **end for**

Test codings:

Yuchen Jin was with the Department of Electrical and Computer Engineering, University of Houston, TX, 77004 USA e-mail: cainmagi@gmail.com.

Yuchen Jin II was with the Department of Electrical and Computer Engineering, University of Houston, TX, 77004 USA e-mail: cain.king@foxmail.com.

```
# HyperPlate of SVM. It contains variables including w and b, and convert input x vector to a single value y(+-1).
with tf.name_scope('SVMPlate'): #Noted that the dimension of y must be 1, so the constants should be 1 dimensional.
    self.constrain = tf.constant(SVMPrimalSolution.Domain, dtype=tf.float32, shape=[1], name='Constrain')
    self.w = self.weight_variable([1, self.xDim], name='Weight')
    bias = self.bias_variable([1], name='Bias')
    self.subjection = tf.multiply(self.y, tf.matmul(self.w, self.x) + bias)
    tf.add_to_collection('Weight', self.w)
    tf.add_to_collection('Bias', bias)

@staticmethod
def weight_variable(shape, name=None):
    '''weight_variable generates a weight variable of a given shape.'''
    initial = tf.truncated_normal(shape, stddev=0.1)
    if name is not None:
        return tf.Variable(initial, name=name)
    else:
        return tf.Variable(initial)

@staticmethod
def bias_variable(shape, name=None):
    ''''bias_variable generates a bias variable of a given shape.'''
    initial = tf.constant(0.1, dtype=tf.float32, shape=shape)
    if name is not None:
        return tf.Variable(initial, name=name)
    else:
        return tf.Variable(initial)
```

APPENDIX A
PROOF OF THE FIRST ZONKLAR EQUATION

Appendix one text goes here.

APPENDIX B

Appendix two text goes here.

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The authors would like to thank...

REFERENCES

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[2] J. Yang, Z. Wang, Z. Lin, S. Cohen, and T. Huang, "Coupled dictionary training for image super-resolution," *IEEE Transactions on Image Processing*, vol. 21, no. 8, pp. 3467–3478, Aug 2012.

[3] C. Dong, C. C. Loy, K. He, and X. Tang, "Image super-resolution using deep convolutional networks," *IEEE Transactions on Pattern Analysis and Machine Intelligence*, vol. 38, no. 2, pp. 295–307, Feb 2016.

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Yuchen Jin Biography text here.

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Yuchen Jin II Biography text here.