# Rebuttal

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## 1 Proof for Question 2: Why Our Error Rate Holds

We now explain why the O(1/M) rate applies to our time-inhomogeneous MJD SDEs, structured in three steps:

### 1.1 Step 1: Results on Time-Homogeneous MJD SDEs

For time-homogeneous MJD SDEs, the error term  $\epsilon_t^E$  of the standard EM method is O(1/M), with an exponential growth term  $O(e^t)$ . This is supported by the following: (a) Theorem 2.2 in [PT97] establishes the O(1/M) rate; (b) Sec. 4-5 of [PT97] and Theorem 2.1 of [Bic81] shows that  $\epsilon_t^E$  grows exponentially regarding time with a big-O factor  $O(e^t)$ . Particularly, the time-dependent term in the error bound  $e^{K_p(t)}$  used in the proof of [PT97] is rooted in their Lemma 4.1, which is proven in a more general setting in [Bic81], e.g., Eq. (2.16) in [Bic81] discusses concrete forms of  $K_p(t)$  which can be absored into  $O(e^t)$ .

#### 1.2 Step 2: Results on Time-Inhomogeneous MJD SDEs

Our paper considers time-inhomogeneous MJD SDEs, with parameters fixed within each interval  $[\tau-1,\tau)$  ( $\tau\in\mathbb{N},\,\tau\geq1$ ). This happens to align with the Euler-Peano scheme for general time-inhomogeneous SDEs approximation. As a specific case of time-varying Lévy processes, our MJD SDEs retain the same big-O bounds as the time-homogeneous case. This can be justified by extending Section 5 of [PT97] that originally proves the EM's weak convergence for time-homogeneous Lévy processes. Specifically, the core technique lies in the Lemma 4.1 of [PT97], which, based on [Bic81], is applicable to both time-homogeneous and Euler-Peano-style inhomogeneous settings (see Remark 3.3.3 in [Bic81]). Therefore, equivalent weak convergence bounds could be attained by extending Lemma 4.1 of [PT97] with proofs from [Bic81] thanks to the Euler-Peano formulation.

#### 1.3 Step 3: Restarted EM Solver Error Bound

We now discuss the error bound for the restarted EM solver,  $\epsilon_t^R$ . Thanks to explicit solutions for future states  $\{S_1, S_2, \dots, S_{T_f}\}$ , we can analytically compute their mean  $\mathbb{E}[S_{\tau}]$ ,  $\tau \geq 1$ , based on Eq. (13), which greatly simplifies the analysis.

Using the restart mechanism in line 10 of Algorithm 2, we ensure that  $\mathbb{E}[\bar{S}\tau]$  from our restarted EM solver closely approximates  $\mathbb{E}[S\tau]$  at restarting times.  $\epsilon_t^R$  is significantly reduced when restart happens, then it grows again at the same rate as the standard EM method until the next restart timestep. This explains the  $O(e^{t-\rho_t})$  difference in the error bounds of  $\epsilon_t^R$  and  $\epsilon_t^E$ , where  $\rho_t$  is the last restart time

### References

- [Bic81] Klaus Bichteler. "Stochastic integrators with stationary independent increments". In: Zeitschrift für Wahrscheinlichkeitstheorie und Verwandte Gebiete 58.4 (1981), pp. 529–548.
- [PT97] Philip Protter and Denis Talay. "The Euler scheme for Lévy driven stochastic differential equations". In: *The Annals of Probability* 25.1 (1997), pp. 393–423.