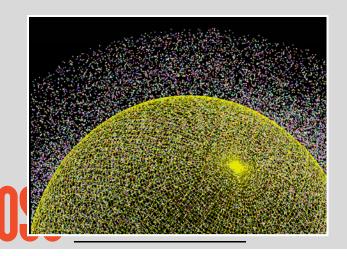
How to Use and Teach OpenGL Compute Shaders

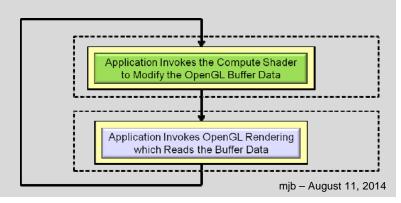
Mike Bailey

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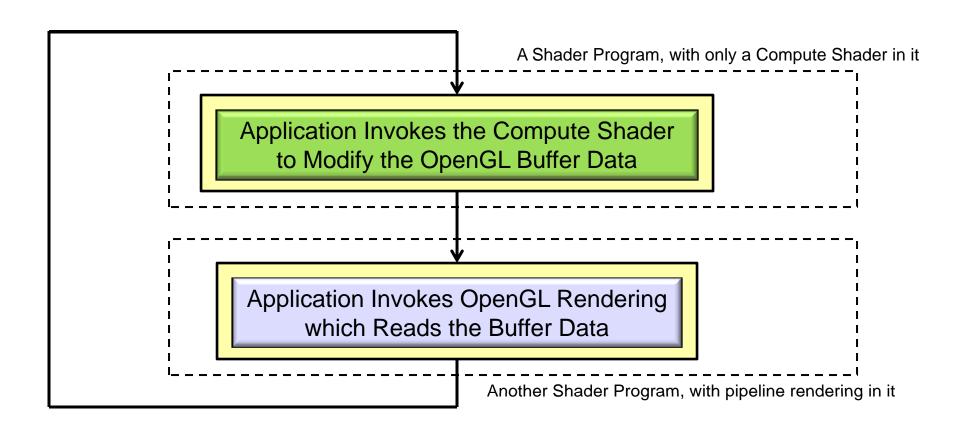
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OpenGL Compute Shader – the Basic Idea



Why Not Just Use OpenCL Instead?

OpenCL is *great*! It does a super job of using the GPU for general-purpose data-parallel computing. And, OpenCL is more feature-rich than OpenGL compute shaders. So, why use Compute Shaders *ever* if you've got OpenCL? Here's what I think:

- OpenCL requires installing a separate driver and separate libraries. While this is not a huge deal, it does take time and effort. When everyone catches up to OpenGL 4.3, Compute Shaders will just "be there" as part of core OpenGL.
- Compute Shaders use the GLSL language, something that all OpenGL programmers should already be familiar with (or will be soon).
- Compute shaders use the same context as does the OpenGL rendering pipeline. There is no need to acquire and release the context as OpenGL+OpenCL must do.
- I'm assuming that calls to OpenGL compute shaders are more lightweight than calls to OpenCL kernels are. (true?) This should result in better performance. (true? how much?)
- Using OpenCL is somewhat cumbersome. It requires a lot of setup (queries, platforms, devices, queues, kernels, etc.). Compute Shaders look to be more convenient. They just kind of flow in with the graphics.

The bottom line is that I will continue to use OpenCL for the big, bad stuff. But, for lighter-weight data-parallel computing that interacts with graphics, I will use the Compute Shaders.

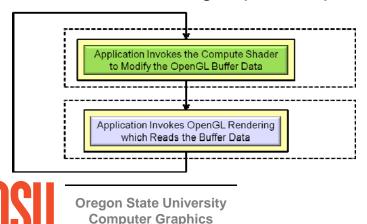


I suspect that a good example of a lighter-weight data-parallel graphics-related application is a **particle system**. This will be shown here in the rest of these notes. I hope I'm right.

If I Know GLSL, What Do I Need to Do Differently to Write a Compute Shader?

Not much:

- 1. A Compute Shader is created just like any other GLSL shader, except that its type is GL_COMPUTE_SHADER (duh...). You compile it and link it just like any other GLSL shader program.
- 2. A Compute Shader must be in a shader program all by itself. There cannot be vertex, fragment, etc. shaders in there with it. (why?)
- 3. A Compute Shader has access to uniform variables and buffer objects, but cannot access any pipeline variables such as attributes or variables from other stages. It stands alone.
- 4. A Compute Shader needs to declare the number of work-items in each of its work-groups in a special GLSL *layout* statement.



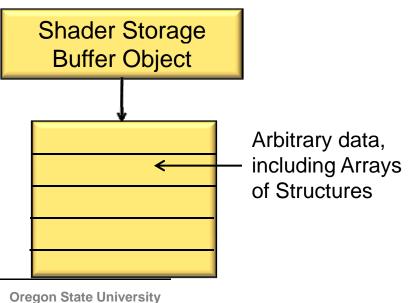
More information on items 3 and 4 are coming up . . .

Passing Data to the Compute Shader Happens with a Cool New Buffer Type – the *Shader Storage Buffer Object*

The tricky part is getting data into and out of the Compute Shader. The trickiness comes from the specification phrase: "In most respects, a Compute Shader is identical to all other OpenGL shaders, with similar status, uniforms, and other such properties. It has access to many of the same data as all other shader types, such as textures, image textures, atomic counters, and so on."

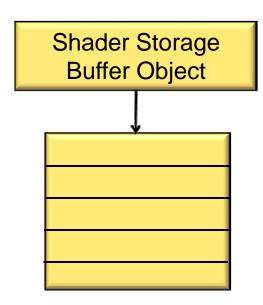
OpenCL programs have access to general arrays of data, and also access to OpenGL arrays of data in the form of buffer objects. Compute Shaders, looking like other shaders, haven't had *direct* access to general arrays of data (hacked access, yes; direct access, no). But, because Compute Shaders represent opportunities for massive data-parallel computations, that is exactly what you want them to use.

Thus, OpenGL 4.3 introduced the **Shader Storage Buffer Object**. This is very cool, and has been needed for a long time!

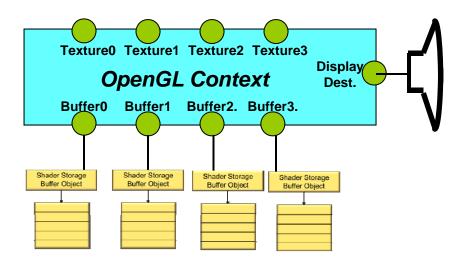


Shader Storage Buffer Objects are created with arbitrary data (same as other buffer objects), but what is new is that the shaders can read and write them in the same C-like way as they were created, including treating parts of the buffer as an array of structures – perfect for dataparallel computing!

Passing Data to the Compute Shader Happens with a Cool New Buffer Type – the *Shader Storage Buffer Object*

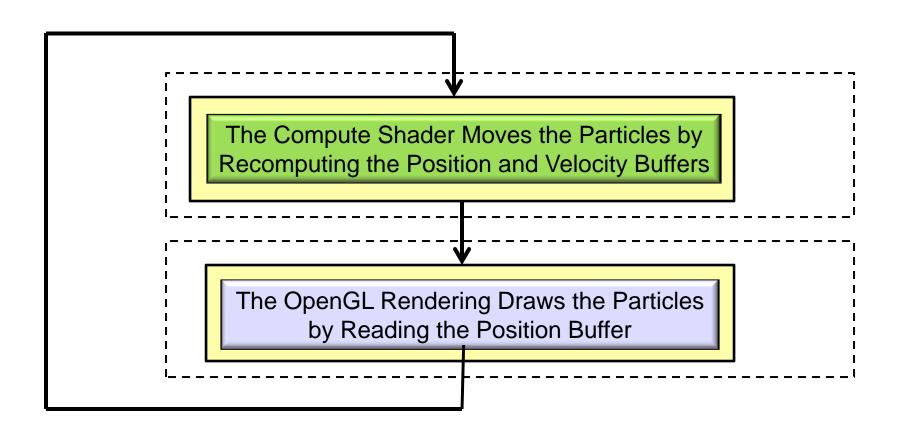


And, like other OpenGL buffer types, Shader Storage Buffer Objects can be bound to indexed binding points, making them easy to access from inside the Compute Shaders.



(Any resemblance this diagram has to a mother sow is accidental, but not entirely inaccurate...)

The Example We Are Going to Use Here is a *Particle System*



Setting up the Shader Storage Buffer Objects in Your C Program

```
#define NUM PARTICLES
                                  1024*1024
                                                         // total number of particles to move
#define WORK GROUP SIZE
                                                         // # work-items per work-group
                                          128
struct pos
                                  // positions
           float x, y, z, w;
};
struct vel
           float vx, vy, vz, vw; // velocities
};
struct color
           float r, g, b, a;
                                  // colors
};
// need to do the following for both position, velocity, and colors of the particles:
GLuint posSSbo;
GLuint velSSbo
GLuint colSSbo:
```



Note that .w and .vw are not actually needed. But, by making these structure sizes a multiple of 4 floats, it doesn't matter if they are declared with the std140 or the std430 qualifier. I think this is a good thing. (is it?)

Setting up the Shader Storage Buffer Objects in Your C Program

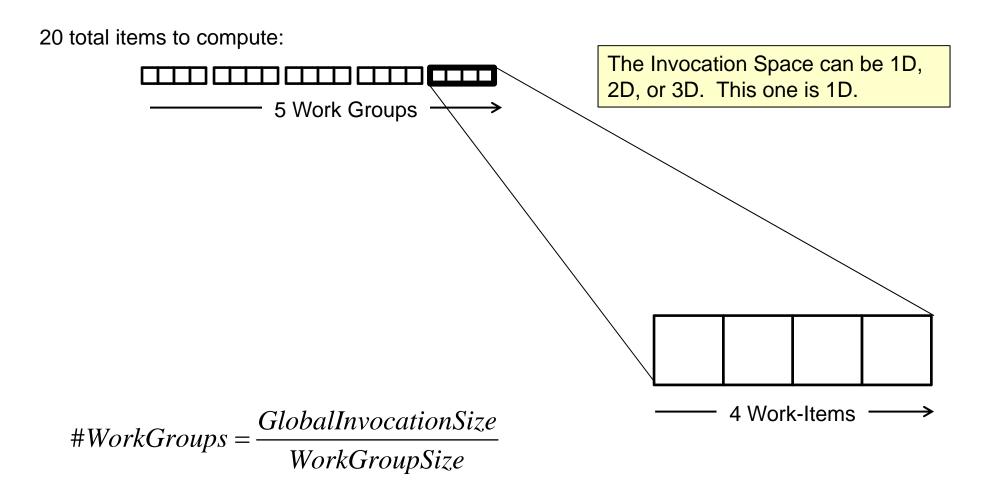
```
glGenBuffers( 1, &posSSbo);
glBindBuffer(GL_SHADER_STORAGE_BUFFER, posSSbo);
glBufferData( GL SHADER STORAGE_BUFFER, NUM_PARTICLES * sizeof(struct pos), NULL, GL_STATIC_DRAW );
GLint bufMask = GL MAP WRITE BIT | GL MAP INVALIDATE BUFFER BIT ;
                                                                           // the invalidate makes a big difference when re-writing
struct pos *points = (struct pos *) glMapBufferRange( GL_SHADER_STORAGE_BUFFER, 0, NUM_PARTICLES * sizeof(struct pos), bufMask );
for(int i = 0; i < NUM PARTICLES; i++)
                                                Shader Storage
                                                 Buffer Object
         points[ i ].x = Ranf( XMIN, XMAX );
         points[ i ].y = Ranf( YMIN, YMAX );
         points[ i ].z = Ranf( ZMIN, ZMAX );
         points[ i ].w = 1.;
glUnmapBuffer(GL_SHADER_STORAGE_BUFFER);
glGenBuffers(1, &velSSbo);
glBindBuffer(GL SHADER STORAGE BUFFER, velSSbo);
glBufferData( GL_SHADER_STORAGE_BUFFER, NUM_PARTICLES * sizeof(struct vel), NULL, GL_STATIC_DRAW );
struct vel *vels = (struct vel *) glMapBufferRange( GL SHADER STORAGE BUFFER, 0, NUM PARTICLES * sizeof(struct vel), bufMask );
for(int i = 0; i < NUM PARTICLES; i++)
                                                     Shader Storage
                                                      Buffer Object
         vels[ i ].vx = Ranf( VXMIN, VXMAX );
         vels[ i ].vy = Ranf( VYMIN, VYMAX );
         vels[ i ].vz = Ranf( VZMIN, VZMAX );
         vels[i].vw = 0.:
glUnmapBuffer(GL_SHADER_STORAGE_BUFFER);
```

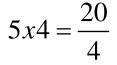


The same would possibly need to be done for the color shader storage buffer object

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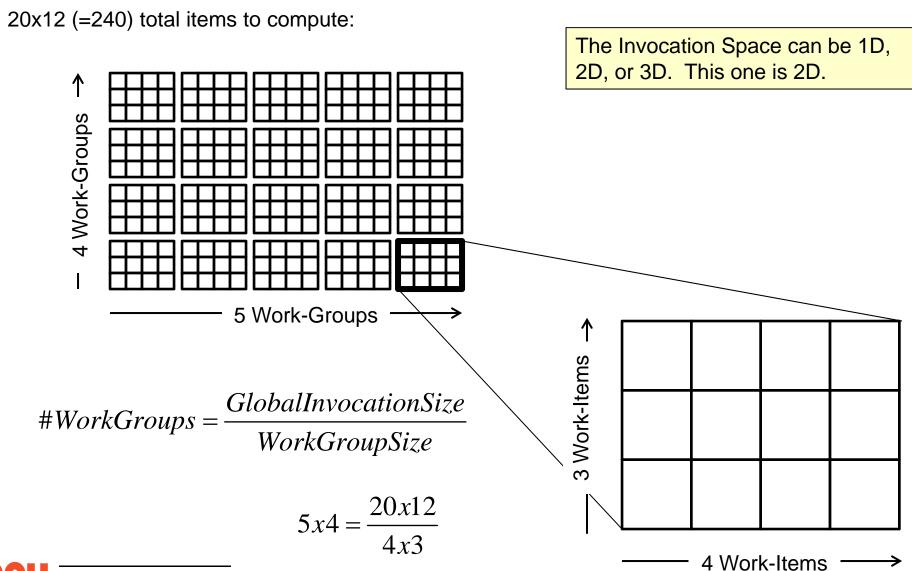
The Data Needs to be Divided into Large Quantities call *Work-Groups*, each of which is further Divided into Smaller Units Called *Work-Items*





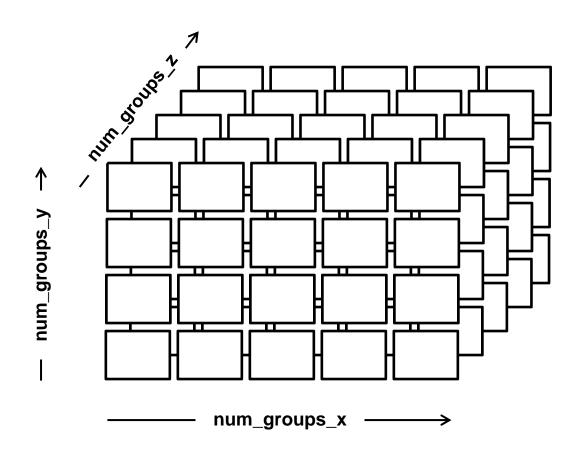


The Data Needs to be Divided into Large Quantities call Work-Groups, each of which is further Divided into Smaller Units Called Work-Items



Running the Compute Shader from the Application

void glDispatchCompute(num_groups_x, num_groups_y, num_groups_z);



If the problem is 2D, then num_groups_z = 1

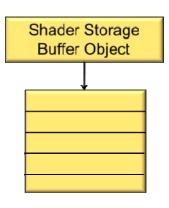
If the problem is 1D, then num_groups_y = 1 and num_groups_z = 1

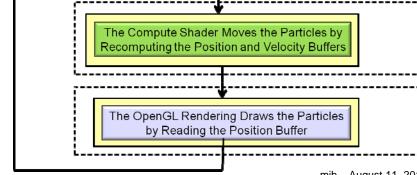


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Invoking the Compute Shader in Your C Program

```
glBindBufferBase(GL SHADER STORAGE BUFFER, 4, posSSbo);
qlBindBufferBase( GL_SHADER_STORAGE_BUFFER, 5, velSSbo );
glBindBufferBase(GL SHADER STORAGE BUFFER, 6, colSSbo);
glUseProgram( MyComputeShaderProgram );
glDispatchCompute( NUM PARTICLES / WORK GROUP SIZE, 1, 1);
glMemoryBarrier(GL_SHADER_STORAGE_BARRIER_BIT);
glUseProgram( MyRenderingShaderProgram );
glBindBuffer(GL_ARRAY_BUFFER, posSSbo);
glVertexPointer(4, GL FLOAT, 0, (void *)0);
glEnableClientState( GL_VERTEX_ARRAY );
glDrawArrays(GL POINTS, 0, NUM PARTICLES);
glDisableClientState( GL_VERTEX_ARRAY );
glBindBuffer(GL_ARRAY_BUFFER, 0);
```







Special Pre-set Variables in the Compute Shader

```
Same numbers as in the qlDispatchCompute call
in
      uvec3
                     gl_NumWorkGroups;
                                                  Same numbers as in the layout local_size_*
const uvec3
                     gl_WorkGroupSize;
                                                  Which workgroup this thread is in
                     gl_WorkGroupID;
in
      uvec3
                                                  Where this thread is in the current workgroup
                     gl_LocalInvocationID;
in
      uvec3
                                                  Where this thread is in all the work items
                     gl_GlobalInvocationID;
      uvec3
in
                     gl LocalInvocationIndex;
                                                  1D representation of the gl_LocalInvocationID
in
      uint
                                                  (used for indexing into a shared array)
```

```
0 ≤ gl_WorkGroupID ≤ gl_NumWorkGroups − 1

0 ≤ gl_LocalInvocationID ≤ gl_WorkGroupSize − 1

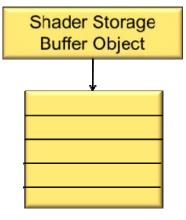
gl_GlobalInvocationID = gl_WorkGroupID * gl_WorkGroupSize + gl_LocalInvocationID

gl_LocalInvocationIndex = gl_LocalInvocationID.z * gl_WorkGroupSize.y * gl_WorkGroupSize.x + gl_LocalInvocationID.y * gl_WorkGroupSize.x + gl_LocalInvocationID.x
```



The Particle System Compute Shader -- Setup

```
#version 430 compatibility
#extension GL ARB compute shader:
                                                  enable
#extension GL_ARB_shader_storage_buffer_object: enable;
layout( std140, binding=4 ) buffer Pos
                                                                        You can use the empty
                                                                        brackets, but only on the
           vec4 Positions[ ]; ← // array of structures
                                                                        last element of the buffer.
};
                                                                        The actual dimension will be
                                                                        determined for you when
layout( std140, binding=5 ) buffer Vel
                                                                        OpenGL examines the size
           vec4 Velocities[ ]; ←
                                                                        of this buffer's data store.
                                             // array of structures
};
layout( std140, binding=6 ) buffer Col
           vec4 Colors[ ]: <
                                             // array of structures
};
layout(local size x = 128, local size y = 1, local size z = 1) in;
```





The Particle System Compute Shader – The Physics

```
const vec3 G = vec3(0., -9.8, 0.);
const float DT = 0.1;
     . . .
uint gid = gl_GlobalInvocationID.x;
                                                // the .y and .z are both 1 in this case
                                              Shader Storage
                                               Buffer Object
vec3 p = Positions[ gid ].xyz;
vec3 v = Velocities[ gid ].xyz;
                                                             p' = p + v \cdot t + \frac{1}{2}G \cdot t^{2}
v' = v + G \cdot t
vec3 pp = p + v*DT + .5*DT*DT*G;
vec3 vp = v + G*DT;
Positions[ gid ].xyz = pp;
Velocities[ gid ].xyz = vp;
```

The Particle System Compute Shader – How About Introducing a Bounce?

```
const vec4 SPHERE = vec4( -100., -800., 0., 600. ); // x, y, z, r
                                                      // (could also have passed this in)
vec3
Bounce(vec3 vin, vec3 n)
    vec3 vout = reflect( vin, n );
                                          in
                                                                      out
     return vout;
vec3
BounceSphere(vec3 p, vec3 v, vec4 s)
    vec3 n = normalize(p - s.xyz);
     return Bounce( v, n );
bool
IsInsideSphere( vec3 p, vec4 s )
{
    float r = length(p - s.xyz);
     return ( r < s.w );
```

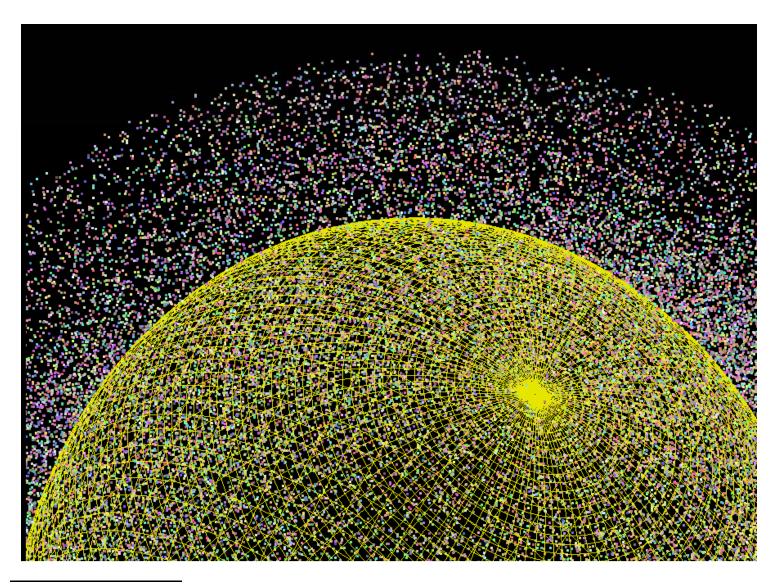


The Particle System Compute Shader – How About Introducing a Bounce?

```
uint gid = gl GlobalInvocationID.x;
                                                 // the .y and .z are both 1 in this case
vec3 p = Positions[ gid ].xyz;
                                                           p' = p + v \cdot t + \frac{1}{2}G \cdot t^{2}
v' = v + G \cdot t
vec3 v = Velocities[ gid ].xyz;
vec3 pp = p + v*DT + .5*DT*DT*G;
vec3 vp = v + G*DT;
if( IsInsideSphere(pp, SPHERE))
                                                    Graphics Trick Alert: Making the bounce
                                                    happen from the surface of the sphere is
     vp = BounceSphere(p, v, SPHERE);
                                                    time-consuming. Instead, bounce from the
                                                    previous position in space. If DT is small
     pp = p + vp*DT + .5*DT*DT*G;
                                                    enough, nobody will ever know...
Positions [gid] xyz = pp;
Velocities[ gid ].xyz = vp;
```

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The Bouncing Particle System Compute Shader – What Does It Look Like?





Personally, I Think this is a Better Way of Dispatching the Compute Shader from the Application

In your C/C++ code, replace:

```
void glDispatchCompute(
     num_groups_x, num_groups_y, num_groups_z );
```

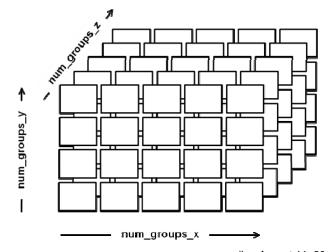
with:

And, in your shader code, replace:

```
layout( local_size_x = 128, local_size_y = 1, local_size_z = 1) in;
```

with:

layout(local_size_variable) in





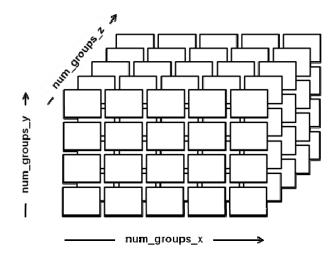
Personally, I Think this is a Better Way of Dispatching the Compute Shader from the Application

I like this better because you can experiment with changing work group sizes by changing a value in only one place, not two:

```
#define NUMPARTICLES
#define WORK_GROUP_SIZE
#define NUMGROUPS

Run your timing experiments by
changing this one number
128

(NUMPARTICLES / WORK_GROUP_SIZE )
```



In the other way of dispatching a compute shader, you would have modified the parallel parameters by changing values in *both* the *C/C++* code *and* in the shader code.



Other Useful Stuff – Copying Global Data to a Local Array Shared by the Entire Work-Group

There are some applications, such as image convolution, where threads within a work-group need to operate on each other's input or output data. In those cases, it is usually a good idea to create a local shared array that all of the threads in the work-group can access. You do it like this:

```
layout( std140, binding=6 ) buffer Col
          vec4 Colors[];
layout( shared ) vec4 rgba[ gl_WorkGroupSize.x ];
uint gid = gl GlobalInvocationID.x;
uint lid = gl LocalInvocationID.x;
rgba[ lid ] = Colors[ gid ];
memory barrier shared();
          << operate on the rgba array elements >>
Colors[ gid ] = rgba[ lid ];
```



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Other Useful Stuff – Getting Information Back Out

There are some applications it is useful to be able to return some numerical information about the running of the shader back to the application program. For example, here's how to count the number of bounces:

```
glGenBuffers( 1, &countBuffer);
glBindBufferBase( GL_ATOMIC_COUNTER_BUFFER, 7, countBuffer);
glBufferData(GL_ATOMIC_COUNTER_BUFFER, sizeof(GLuint), NULL, GL_DYNAMIC_DRAW);

GLuint zero = 0;
glBufferSubData(GL_ATOMIC_COUNTER_BUFFER, 0, sizeof(GLuint), &zero);
```

```
layout( std140, binding=7 ) buffer { atomic_uint bounceCount };

if( IsInsideSphere( pp, SPHERE ) )
{
```

```
if( IsInsideSphere( pp, SPHERE ) )
{
    vp = BounceSphere( p, v, SPHERE );
    pp = p + vp*DT + .5*DT*DT*G;
    atomicCounterIncrement( bounceCount );
}
```

Application Program

```
glBindBuffer( GL_SHADER_STORAGE_BUFFER, countBuffer );
GLuint *ptr = (GLuint *) glMapBuffer( GL_SHADER_STORAGE_BUFFER, GL_READ_ONLY );
GLuint bounceCount = ptr[ 0 ];
glUnmapBuffer( GL_SHADER_STORAGE_BUFFER );
fprintf( stderr, "%d bounces\n", bounceCount );
```

Other Useful Stuff – Getting Information Back Out

Another example would be to count the number of fragments drawn so we know when all particles are outside the viewing volume, and can stop animating:

```
glGenBuffers( 1, &particleBuffer);
glBindBufferBase( GL_ATOMIC_COUNTER_BUFFER, 8, particleBuffer);
glBufferData(GL_ATOMIC_COUNTER_BUFFER, sizeof(GLuint), NULL, GL_DYNAMIC_DRAW);

GLuint zero = 0;
glBufferSubData(GL_ATOMIC_COUNTER_BUFFER, 0, sizeof(GLuint), &zero);
```

Fragment Shader

```
layout( std140, binding=8 ) buffer { atomic_uint particleCount };
atomicCounterIncrement( particleCount );
```

Application Program



Other Useful Stuff – Getting Information Back Out

While we are at it, there is a cleaner way to set all values of a buffer to a preset value. In the previous example, we cleared the *countBuffer* by saying:

Application Program

```
glBindBufferBase( GL_ATOMIC_COUNTER_BUFFER, 7, countBuffer);
GLuint zero = 0;
glBufferSubData(GL_ATOMIC_COUNTER_BUFFER, 0, sizeof(GLuint), &zero);
```

We could have also done it by using a new OpenGL 4.3 feature, *Clear Buffer Data*, which sets all values of the buffer object to the same preset value. This is analogous to the C function *memset()*.

Application Program

```
glBindBufferBase( GL_ATOMIC_COUNTER_BUFFER, 7, countBuffer);
GLuint zero = 0;
glClearBufferData( GL_ATOMIC_COUNTER_BUFFER, GL_R32UI, GL_RED, GL_UNSIGNED_INT, &zero );
```

Presumably this is faster than using *glBufferSubData*, especially for *large-sized* buffer objects (unlike this one).

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