ELEC2146

Electrical Engineering Modelling and Simulation

Simulation Programming and MATLAB

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Overview

- Programming vs. simulation programming
- Programming principles
- How MATLAB works
- Debugging
- Good programming practise

Simulation Programming

Most programming:

- Uses a variety of data structures
- Need to declare all variables ('strongly typed')
- Often need to worry about memory allocation of variables
- Visual component = GUI
- Few pre-defined functions

Simulation programming:

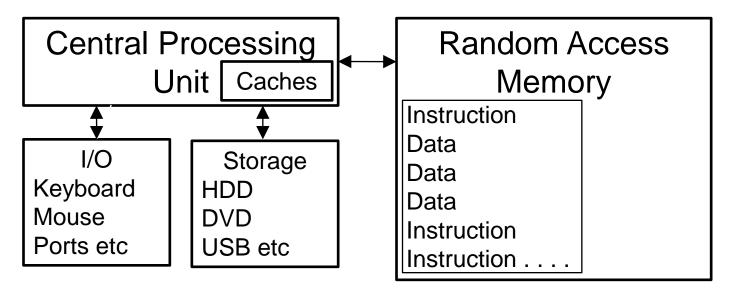
- Often uses just numbers, arrays and matrices
- Visual component = plots (GUI possible)
- MATLAB
 - No need to worry about declaring variables or memory allocation
- Nearly every function is predefined

Simulation Programming

Comparing programming languages

Doodobility	<u>MATLAB</u>
 Readability 	OK
Writability	Good
 Reliability 	
Everything except memory managementMemory management	Good Bad
Cost	
Writing/debugging code	Good
Execution time	Not great
Portability	Bad
Generality	Bad

How computers are organised



- Programs are a set of instructions on data, executed by the CPU
- Data exists in storage (slow), RAM (fast) or in a CPU cache (fastest)

Top-down design

- In procedural languages, code development is based on a step-wise refinement of the abstract function that the code is required to perform
- Breaks a problem into sub-problems
 - And from there into sub-sub-problems
 - Deals with each sub-problem separately

– Example:

```
% Problem: Get to UNSW
DoINeedToGo(date, timetable);
CheckSocialSchedule(date, timetable);
WhatDoINeed(date, timetable);
CheckGearNeeded(date, timetable);
Raining(windowCam);
HotCold(temperature);

GetThere(homeGPS, UNSWGPS);
DrivingHassle(date, trafficCond);
NextBus(date, time);
NextTrain(date, time);
```

Top-down design

- Start solution to sub-problems by writing pseudocode
 - Comments containing code-like statements or even just text descriptions of the function being performed
- Wherever possible, find generic pieces of the problem and write them as functions
 - Should be as independent and self-contained as possible
 - Typically have one entry and one exit point
 - Usually short
 - Makes code easier to read; improves underlying logic
 - Makes code easier to test
 - Large projects: can split up work
 - MATLAB: can start new file for function or include it as part of a script file
 function b = sqrt(a)

Data structures: MATLAB

- Most common type of variable: double
 - 64-bit double-precision floating-point
 - Can hold real, imaginary and complex numbers
- Arrays
 - The fundamental data type of MATLAB
 - 1-D, e.g. array = [1 3 2 4];
 - 2-D (matrix), e.g. A = [1 3; 2 4];
 - 3-D and beyond, e.g. B(2,1,4) = 16;
- Characters (not used much in this course)
- Cell arrays (not used much in this course)
 - Generic containers very handy
 - ExampleCell $\{1\}$ = $[1 \ 3 \ 2 \ 4]$; ExampleCell $\{2\}$ = 56;

- MATLAB detaches developer from memory management
 - Dynamic variable size

- Growing an array within a loop

$$B=0$$
; for $k=1:100$; $B(k)=100-k$; end

High level language

- Huge amount of abstraction from the machine-level instructions
- Programming languages don't come much higher level than this

Procedural language

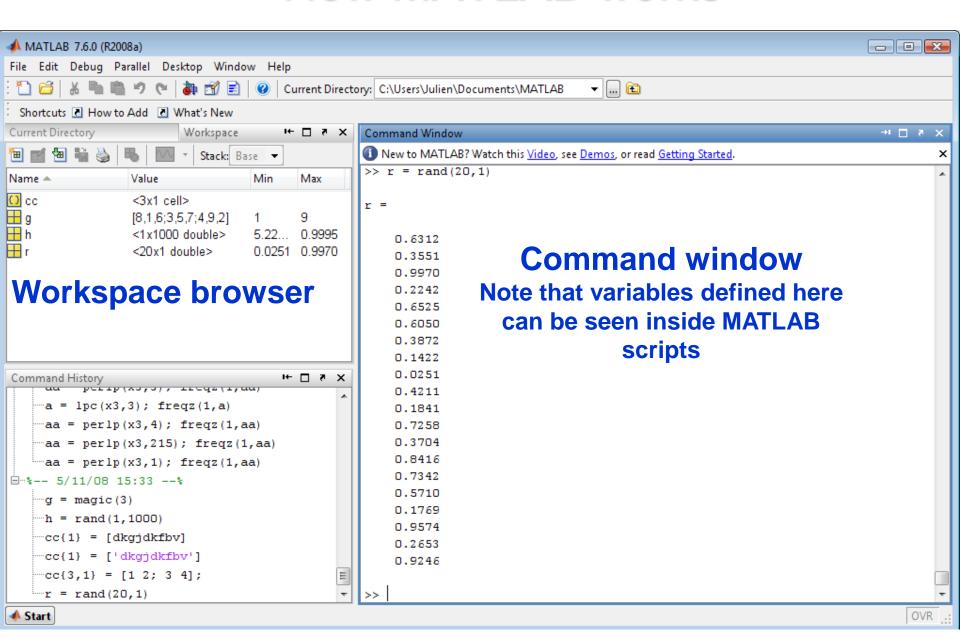
 Complex problems can be decomposed into a hierarchy of functions

Interpreted language

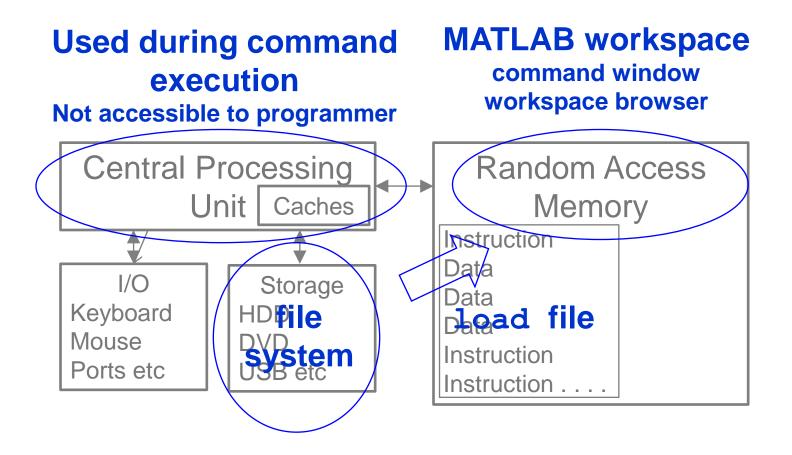
- Each line of code is decoded as the compiler reaches it
 - Slower than compiled languages. MATLAB now has a compiler

Based on fast numerical methods

- LINPACK, EISPACK
- Like an advanced calculator



Where data is stored in memory



Scripts

- A list of commands, stored in exampleScript.m
- Execute by running exampleScript in the command window
- Think of scripts as identical to the command window

Functions

- Should always be used in preference to scripts, where possible to produce generic, reusable code
- Take inputs, produce outputs
- Execute in command window by running e.g.

```
c = dist(a,b);
function d = dist(x,y)
d = sqrt(sum((x-y).^2));
```

Built-in functions

- Lots of them
- Very useful
- Functions are "overloaded"
 - Same function can different inputs or produce different outputs depending on how it is called

Some MATLAB tips

- If your code is slow, avoid for loops
 - Try to use vectors and matrices MATLAB is fast for these
 - Other languages: for loops are fine
- If your code is slow, work out where the problem is
 - Use the profiler: help profile
- If your code is slow, reduce your memory usage

Debugging

- Writing code is the easy part
- Figuring out why it doesn't work is the hard part Some advice:
- Understand the big objective of debugging: Systematically isolating the point of error
 - Try to eliminate parts of the code that could not have produced the error
- Work out what should have happened where the bug occurred
 - Try the code using a simpler input

Debugging

- MATLAB will usually locate the problem line of code
- Try executing the code in the command window (if using a script or function)
- Try leaving the ";" off the end of the command
 - Prints output to command window

```
>> g(1,:) = r
??? Subscripted assignment dimension mismatch.
```

Check the dimensions of g and r

Debugging

- Typical problem:
 - "I built it and it doesn't work"
- Understand exactly what "working" means
- Break "it" up into smaller subsections
- Test each subsection
 - With the simplest possible test you can construct
- Better still:
 - Do this as you create the code
 - Test as you go

Why ?

- Good programming is about communication
- Well-written code is more likely to have fewer errors
- Well-written code is easier to debug
- Well-written code is more extensible and re-usable
- Well-written code is easier for someone else to understand
 - Very important in industry

- Code formatting
 - A new level of indentation should be used for every nested statement

```
for k = 1:N,
    if array[k] > threshold,
        disp('above');
    else
        disp('below');
    end
end
```

- MATLAB has "smart indent" - use it

Variables

Newly declared variables should have a comment explaining their use

```
VC = zeros(1,100); % Array of capacitor voltages
```

- Use meaningful, descriptive variable names
 - E.g. VC or CapVolt or CapacitorVoltage for a capacitor voltage
- Don't change the value of loop variables within a loop
- Avoid use of global variables
 - Easy if you use functions
- Pre-allocate arrays to some fixed length
 - Not critical for MATLAB (no need to declare arrays), but faster and good practise
- Avoid using i, j MATLAB complex numbers

Function headers

- All useful functions/subroutines/scripts/methods have headers
- Should give:
 - The name of the function
 - Its purpose
 - Description of all inputs
 - Description of all outputs
 - Author, date
 - Version number (if you create more than one version)

```
% function C = lbg(data,csize)
%
LBG algorithm for codebook design
% data : matrix with training vectors in rows
% csize : desired codebook size (must be a power of 2)
% C : codebook with csize rows
%
% Author: Julien Epps Date: A few years ago
% Reference: Linde, Y., Buzo, A., and Gray, R. M. (1980). "An algorithm for vector quantiser design", IEEE Trans. Commun., vol. COM-28, no. 1, pp. 84-95, January.
```

Use pseudocode

```
% linfilt - plots various quantities for a digital filter
% Define filter
NumCoeff = [1 -2 1] % numerator coefficients
DenCoeff = 1; % denominator coefficients
% Plot frequency response
freqz(NumCoeff, DenCoeff);
% Plot pole-zero diagram
figure;
zplane (NumCoeff, DenCoeff);
% Plot impulse response
figure;
stem(NumCoeff); % filter is FIR
% Plot step response
figure;
Step = [zeros(1,100) ones(1,100)];
y = filter(NumCoeff, DenCoeff, Step);
plot(y);
```

- Keep your code modular
 - Use functions
- Bad:

```
for k = 1:N,

if sqrt(sum((x(k,:)-y).^2)) < min,

d(k) = sqrt(sum((x(k,:)-z).^2));

end

end
```

Good:

```
for k = 1:N,

if dist(x(k,:),y) < min,

d(k) = dist(x(k,:),z);
end

end

New function dist created by the programmer
```

```
function [c, lags] = xcorr(x, varargin)
%XCORR Cross-correlation function estimates.
    C = XCORR(A,B), where A and B are length M vectors (M>1), returns
ş
    the length 2*M-1 cross-correlation sequence C. If A and B are of
ş
    different length, the shortest one is zero-padded. C will be a
    row vector if A is a row vector, and a column vector if A is a
ş
ş.
    column vector.
ş
    XCORR produces an estimate of the correlation between two random
ş
÷
    (jointly stationary) sequences:
ş
           C(m) = E[A(n+m) *conj(B(n))] = E[A(n) *conj(B(n-m))]
    It is also the deterministic correlation between two deterministic
ş
ş
    signals.
ş
    XCORR(A), when A is a vector, is the auto-correlation sequence.
ş
÷
    XCORR(A), when A is an M-by-N matrix, is a large matrix with
ş
    2*M-1 rows whose N^2 columns contain the cross-correlation
ş
    sequences for all combinations of the columns of A.
    The zeroth lag of the output correlation is in the middle of the
ş
    sequence, at element or row M.
÷
ş
ş
    XCORR(..., MAXLAG) computes the (auto/cross) correlation over the
ş.
    range of lags: -MAXLAG to MAXLAG, i.e., 2*MAXLAG+1 lags.
    If missing, default is MAXLAG = M-1.
ş
ş
ş
    [C,LAGS] = XCORR(...) returns a vector of lag indices (LAGS).
ş
    XCORR(...,SCALEOPT), normalizes the correlation according to SCALEOPT:
ş
ş
       'biased' - scales the raw cross-correlation by 1/M.
       'unbiased' - scales the raw correlation by 1/(M-abs(lags)).
ş
       'coeff' - normalizes the sequence so that the auto-correlations
ş
ş
                   at zero lag are identically 1.0.
ş
      'none' - no scaling (this is the default).
ş
    See also XCOV, CORRCOEF, CONV, CCONV, COV and XCORR2.
```

- %

```
Author(s): R. Losada
   Copyright 1988-2004 The MathWorks, Inc.
ş
    $Revision: 1.16.4.4 $ $Date: 2007/12/14 15:06:38 $
ş
ş
ş
   References:
      S.J. Orfanidis, "Optimum Signal Processing. An Introduction"
÷
ş
      2nd Ed. Macmillan, 1988.
error(nargchk(1,4,nargin,'struct'));
[x,nshift] = shiftdim(x);
[xIsMatrix,autoFlag,maxlag,scaleType,msg] = parseinput(x,varargin{:});
if ~isempty(msg), error(generatemsgid('SigErr'),msg); end
if xIsMatrix,
   [c,M,N] = matrixCorr(x);
else
    [c, M, N] = vectorXcorr(x, autoFlag, varargin(:));
end
Force correlation to be real when inputs are real
c = forceRealCorr(c,x,autoFlag,varargin(:));
lags = -maxlag:maxlag;
% Keep only the lags we want and move negative lags before positive lags
if maxlag >= M,
    c = [zeros(maxlag-M+1,N^2);c(end-M+2:end,:);c(1:M,:);zeros(maxlag-M+1,N^2)];
else
   c = [c(end-maxlag+1:end,:);c(1:maxlag+1,:)];
end
$ Scale as specified
```

```
% Scale as specified
 [c,msg] = scaleXcorr(c,xIsMatrix,scaleType,autoFlag,M,maxlag,lags,x,varargin{:});
 if ~isempty(msq), error(generatemsqid('SigErr'),msq); end
% If first vector is a row, return a row
-c = shiftdim(c,-nshift);
function [c,M,N] = matrixCorr(x)
 Compute all possible auto- and cross-correlations for a matrix input
 [M,N] = size(x);
X = fft(x, 2^nextpow2(2*M-1));
Xc = conj(X);
 [MX,NX] = size(X);
C = zeros(MX,NX*NX);
for n = 1:N.
    C(:,(((n-1)*N)+1):(n*N)) = repmat(X(:,n),1,N).*Xc;
-end
-c = ifft(C);
 $-----
function [c,M,N] = vectorXcorr(x,autoFlag,varargin)
% Compute auto- or cross-correlation for vector inputs
x = x(:);
 [M,N] = size(x);
 if autoFlag,
    % Autocorrelation
```

In this course:

- 10% of lab and assignment marks allocated to good code formatting and programming practise
 - Plenty of examples exist, see
 http://www.datatool.com/downloads/matlab_style_guidelines.pdf
- 5% of lab and assignment marks allocated to correct use of plotting
 - Correctly labelled axes
 - Axis ranges selected to show interesting part of plot
 - Good use of MATLAB plotting functions to visualise simulation results
 - e.g. Use of hold for comparing two curves
 - Only the key essential information shown (not plot after plot of similar results)

Object-Oriented Programming

```
classdef date
% write a description of the class here.
   properties
    % define the properties of the class here, (like fields of a struct)
        minute = 0:
        hour:
        day;
       month:
        vear;
    end
   methods
   % methods, including the constructor are defined in this block
        function obj = date(minute,hour,day,month,year)
        % class constructor
            if(nargin > 0)
              obj.minute = minute;
              obj.hour = hour;
              obj.dav = dav;
              obj.month = month;
              obj.year = year;
            end
        end
        function obj = rollDay(obj,numdays)
            obj.day = obj.day + numdays;
                                          see e.g.
        end
                                           http://www.cs.ubc.ca/~mdunham/tutorial/
    end
                                           objectOriented.html
end
```

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