

## HW2

### Problem 1

(a) Since there are 6 vectors in  $\mathbb{R}^3$  (can be represented by 3 linear independent basis), they must be linearly dependent.

(b)  $\{I, A, A^2\}$  is not a linearly independent set in  $\mathbb{R}^{3 \times 2}$ ,

Cayley-Hamilton Theorem says that a matrix satisfies its own C.E.

$$\Delta S = \det(SI - A) = \begin{vmatrix} S & -2 \\ -1 & S-1 \end{vmatrix} = S(S-1) - 2 = S^2 - S - 2 = 0$$

$$\Rightarrow A^2 - A - 2I = 0, \text{ i.e. } A^2 = A + 2I$$

which shows  $A^2$  can be written as a linear combination of  $A$  and  $I$ , so they are not linearly independent.

### Problem 2

(a) 1-norm:

$$\|x_1\|_1 = \sum_{i=1}^n |x_{1i}| = 2+3+1=6$$

$$\|x_2\|_1 = \sum_{i=1}^n |x_{2i}| = 1+1+1=3$$

2-norm:

$$\|x_1\|_2 = \sqrt{2^2 + (-3)^2 + 1^2} = \sqrt{14}$$

$$\|x_2\|_2 = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}$$

$\infty$ -norm:

$$\|x_1\|_\infty = \max_i |x_{1i}| = 3$$

$$\|x_2\|_\infty = \max_i |x_{2i}| = 1$$

(b) Applying the Gram-Schmidt process

① Normalize  $x_1$ ,

$$x_1 := \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} \Rightarrow q_1 := \frac{x_1}{\|x_1\|_2} = \frac{1}{\sqrt{14}} \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$$

② Project  $x_2$  onto  $x_1$  and subtract

$$x_2 := \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \Rightarrow u_2 := \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \left( \left[ \frac{2}{\sqrt{14}}, \frac{-3}{\sqrt{14}}, \frac{1}{\sqrt{14}} \right] \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right) \cdot \begin{bmatrix} \frac{2}{\sqrt{14}} \\ \frac{-3}{\sqrt{14}} \\ \frac{1}{\sqrt{14}} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} \frac{2}{\sqrt{14}} \\ \frac{-3}{\sqrt{14}} \\ \frac{1}{\sqrt{14}} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \Rightarrow q_2 := \frac{u_2}{\|u_2\|_2} = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}$$

Therefore, we find an orthonormal basis for the space spanned by  $x_1$  and  $x_2$ .

$$q_1 := \frac{1}{\sqrt{14}} \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}, \quad q_2 := \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}$$

### Problem 3

(a) Since the second row of  $A_1$  is all zeros,  $\text{rank}(A_1) = 2$ .

Nullity of  $A_1$  is  $V(A_1) = 3 - 2 = 1$ .

Perform row reduction to  $A_2$

$$A_2 = \begin{bmatrix} 4 & 1 & 0 & -1 \\ 3 & 2 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 3 & 0 & -1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 0 & -1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

All three rows are linearly independent,  $\text{rank}(A_2) = 3$ .

$$V(A_2) = 3 - 3 = 0.$$

(b) For  $A_1$ :

$$\text{Basis for range space: } a_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad a_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Basis for null space: Solve for  $A_1 x = 0$

$$\Rightarrow n_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

For  $A_2$ :

$$\text{Basis for range space: } a_1 = \begin{bmatrix} 4 \\ 3 \\ 1 \end{bmatrix}, \quad a_2 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \quad a_3 = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}$$

Since  $V(A_2) = 0$ , we can't find null space (or  $n_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ )

(c) For  $A_1$ :

$$\|A_1\|_1 = |1| + |0| + |0| = 1$$

$$|\lambda I - A_1^T A_1| = \begin{vmatrix} \lambda & 0 & 0 \\ 0 & \lambda-1 & 0 \\ 0 & 0 & \lambda-1 \end{vmatrix} = \lambda(\lambda-1)^2 \Rightarrow \lambda_{\max} = 1 \quad \text{Thus, } \|A_1\|_2 = \sqrt{1} = 1$$

$$\|A_1\|_\infty = |0| + |1| + |0| = 1$$

For  $A_2$ :

$$\|A_2\|_1 = |4| + |3| + |1| = 8$$

$$|\lambda I - A_2^T A_2| = \begin{vmatrix} \lambda-26 & -11 & 4 \\ -11 & \lambda-6 & 1 \\ 4 & 1 & \lambda-1 \end{vmatrix} = \lambda^3 - 33\lambda^2 + 50\lambda - 1 = 0 \Rightarrow \lambda_{\max} = 31.409 \quad \text{Thus, } \|A_2\|_2 = \sqrt{31.409} \approx 5.604$$

$$\|A_2\|_\infty = |4| + |1| + |1| = 6$$

#### Problem 4

(a)  $|\lambda I - B_1| = \begin{vmatrix} \lambda-1 & -4 & -10 \\ 0 & \lambda-2 & 0 \\ 0 & 0 & \lambda-3 \end{vmatrix} = (\lambda-1)(\lambda-2)(\lambda-3) \Rightarrow \lambda_1=1, \lambda_2=2, \lambda_3=3$

for  $\lambda_1=1$ ,  $v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ; for  $\lambda_2=2$ ,  $v_2 = \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix}$ ; for  $\lambda_3=3$ ,  $v_3 = \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}$

Thus,  $T = [v_1 \ v_2 \ v_3] = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\tilde{B}_1 = T^{-1} B_1 T = \begin{bmatrix} 1 & -4 & -5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 4 & 10 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$(b) |\lambda I - B_2| = \begin{vmatrix} \lambda & -1 & 0 \\ 0 & \lambda & -1 \\ -8 & 12 & \lambda - 6 \end{vmatrix} = \lambda^3 - 6\lambda^2 + 12\lambda - 8 = (\lambda - 2)^3$$

$\Rightarrow \lambda = 2$ , multiplicity 3

for  $\lambda_1 = 2$ ,

$$[B_2 - \lambda_1 I] v_1 = \begin{bmatrix} -2 & 1 & 0 \\ 0 & -2 & 1 \\ 8 & -12 & 4 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \\ v_{13} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow v_1 = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}$$

for  $\lambda_2 = 2$ ,

$$[B_2 - \lambda_2 I] v_2 = v_1 \Rightarrow \begin{bmatrix} -2 & 1 & 0 \\ 0 & -2 & 1 \\ 8 & -12 & 4 \end{bmatrix} \begin{bmatrix} v_{21} \\ v_{22} \\ v_{23} \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} \Rightarrow v_2 = \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix}$$

for  $\lambda_3 = 2$ ,

$$[B_2 - \lambda_3 I] v_3 = v_2 \Rightarrow \begin{bmatrix} -2 & 1 & 0 \\ 0 & -2 & 1 \\ 8 & -12 & 4 \end{bmatrix} \begin{bmatrix} v_{31} \\ v_{32} \\ v_{33} \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix} \Rightarrow v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Thus, } T = [v_1 \ v_2 \ v_3] = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 4 & 4 & 1 \end{bmatrix}$$

$$\tilde{B}_2 = T^{-1} B_2 T = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 4 & -4 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & -12 & 6 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 4 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

Problem 5

(a) C.E.  $|sI - C| = \begin{vmatrix} s-1 & -1 & 0 \\ 0 & s & -1 \\ 0 & 0 & s-1 \end{vmatrix} = s(s-1)^2$ , and  $f(\lambda) = \lambda^{10}$

$\Rightarrow s_1 = 0, s_2 = 1$  of multiplicity 2. Set  $h(\lambda) = \beta_0 + \beta_1 \lambda + \beta_2 \lambda^2$

for  $s_1 = 0$ , we have  $f(0) = h(0)$

$$\Rightarrow 0^{10} = \beta_0 \Rightarrow \beta_0 = 0$$

for  $s_2 = 1$ , we have  $\begin{cases} f(1) = h(1) \\ f'(1) = h'(1) \end{cases} \Rightarrow \begin{cases} 1^{10} = \beta_0 + \beta_1 + \beta_2 \\ 10 \cdot 1^9 = \beta_1 + 2\beta_2 \cdot 1 \end{cases} \Rightarrow \begin{cases} \beta_1 = -8 \\ \beta_2 = 9 \end{cases}$

Thus,  $h(\lambda) = -8\lambda + 9\lambda^2$

$$C^{100} = -8C + 9C^2 = -8 \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} + 9 \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 9 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

(b) Set  $f(\lambda) = \lambda^{100}$

for  $s_1 = 0$ , we have  $f(0) = h(0) \Rightarrow 0^{100} = \beta_0 \Rightarrow \beta_0 = 0$

for  $s_2 = 1$ , we have  $\begin{cases} f(1) = h(1) \\ f'(1) = h'(1) \end{cases} \Rightarrow \begin{cases} 1^{100} = \beta_0 + \beta_1 + \beta_2 \\ 100 \cdot 1^{99} = \beta_1 + 2\beta_2 \cdot 1 \end{cases} \Rightarrow \begin{cases} \beta_1 = -98 \\ \beta_2 = 99 \end{cases}$

Thus,  $h(\lambda) = -98\lambda + 99\lambda^2$

$$C^{100} = -98C + 99C^2 = -98 \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} + 99 \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 99 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} = 8A_1 + 8A_2 + 8A_3 = 8$$

$$\begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} = 2A_1$$

$$(c) \text{ Set } f(\lambda) = e^{\lambda t}, \quad f'(\lambda) = te^{\lambda t}$$

for  $S_1 = 0$ , we have  $f(0) = h(0) \Rightarrow 1 = \beta_0$

$$\text{for } S_2 = 1, \text{ we have } \begin{cases} f(1) = h(1) \\ f'(1) = h'(1) \end{cases} \Rightarrow \begin{cases} e^t = \beta_0 + \beta_1 + \beta_2 \\ te^t = \beta_1 + 2\beta_2 \end{cases} \Rightarrow \begin{cases} \beta_1 = 2e^t - te^t - 2 \\ \beta_2 = te^t - e^t + 1 \end{cases}$$

$$\text{Thus, } h(\lambda) = 1 + (2e^t - te^t - 2)s + (te^t - e^t + 1)s^2$$

$$e^{ct} = \beta_0 I + \beta_1 E + \beta_2 C$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + (2e^t - te^t - 2) \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} + (te^t - e^t + 1) \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{vmatrix} 2e^t - te^t - 2 + 1 + te^t - e^t + 1 & 2e^t - te^t - 2 + te^t - e^t + 1 & te^t - e^t + 1 \\ 0 & 1 & 2e^t - te^t - 2 + te^t - e^t + 1 \end{vmatrix}$$

$$= \begin{bmatrix} e^t & 0 & e^t - 1 & te^t - e^t + 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & e^t - 1 \\ 0 & 0 & 0 & e^t \end{bmatrix}$$

### Problem 6

(a) C.E

$$|S\lambda - A| = \begin{vmatrix} S+1 & -1 & 0 \\ 4 & S+2 & 5 \\ -5+S & 2 & S-6 \end{vmatrix} = S^3 - 3S^2 - 2S - 1$$

Thus, we know  $\alpha_0 = -1$ ,  $\alpha_1 = -2$ ,  $\alpha_2$

We can construct matrix  $\mathcal{Q} = [q_1 \ q_2 \ q_3]$

$$\text{which } q_3 = B = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}, \quad q_2 = AB + \alpha_2 B = \begin{bmatrix} -1 \\ -3 \\ 4 \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix},$$

$$q_1 = A^2 B + \alpha_2 AB + \alpha_1 B = \begin{bmatrix} -2 \\ -10 \\ 13 \end{bmatrix} \begin{bmatrix} -1 & -3 & 4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$\Rightarrow Q = \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & -1 \\ -1 & 1 & 1 \end{bmatrix}$$

$$T = Q^{-1} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$\bar{x} = T^{-1}x, x = T\bar{x}$$

$$(b) \tilde{A} = TAT^{-1} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 \\ -4 & -2 & -5 \\ 5 & 2 & 6 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & -1 \\ -1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 2 & 3 \end{bmatrix}$$

$$\tilde{B} = TB = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

(c) CCF:

$$\dot{\bar{x}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 2 & 3 \end{bmatrix} \bar{x} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

Set  $\bar{u} = k_1 \bar{x}_1 + k_2 \bar{x}_2 + k_3 \bar{x}_3$ , plug it into CCF

$$\dot{\bar{x}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 2 & 3 \end{bmatrix} \bar{x} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} [k_1 \ k_2 \ k_3] \begin{bmatrix} \bar{x}_1 \\ \bar{x}_2 \\ \bar{x}_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1+k_1 & 2+k_2 & 3+k_3 \end{bmatrix} \begin{bmatrix} \bar{x}_1 \\ \bar{x}_2 \\ \bar{x}_3 \end{bmatrix}$$

$$\det(sI - \tilde{A}) = \begin{vmatrix} s & -1 & 0 \\ 0 & s & -1 \\ -1-k_1 & -2-k_2 & s-3-k_3 \end{vmatrix} = s^3 - (3+k_3)s^2 - (2+k_2)s - (1+k_1) = 0$$

place all poles at -2

$$\text{Since } (s+2)^3 = s^3 + 6s^2 + 12s + 8$$

$$\text{Compare } \begin{cases} -(3+k_3) = 6 \\ -(2+k_2) = 12 \\ -(1+k_1) = 8 \end{cases} \Rightarrow \begin{cases} k_3 = -9 \\ k_2 = -14 \\ k_1 = -9 \end{cases}$$

$$\text{Thus, } \bar{u} = [-9 \ -14 \ -9] \bar{x}$$

$$(d) \bar{x} = Tx, \bar{u} = K\bar{x}$$

$$\Rightarrow u = KTx = \begin{bmatrix} -9 & -14 & -9 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} x = \begin{bmatrix} -18 & -23 & -32 \end{bmatrix} x$$

This is the control law for the original system

$$A \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + B \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} x = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} x = x$$

$$0 = (A+B) - 2(A+E) - 2(E+F) - F = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = (A-I_3)$$

$\lambda = 0$  is a pole

$$\lambda = 2, \lambda = 1, \lambda = -1, \lambda = 0$$