



# Logic Synthesis – Part 1

## Technology-Independent Optimization

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Courtesy: Prof. Jing-Yang Jou

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1

## Outline

- Synthesis overview
- RTL synthesis
- Two-level logic optimization
- Multi-level logic optimization
- Technology mapping
- Timing analysis
- Timing optimization
- Synthesis for low power

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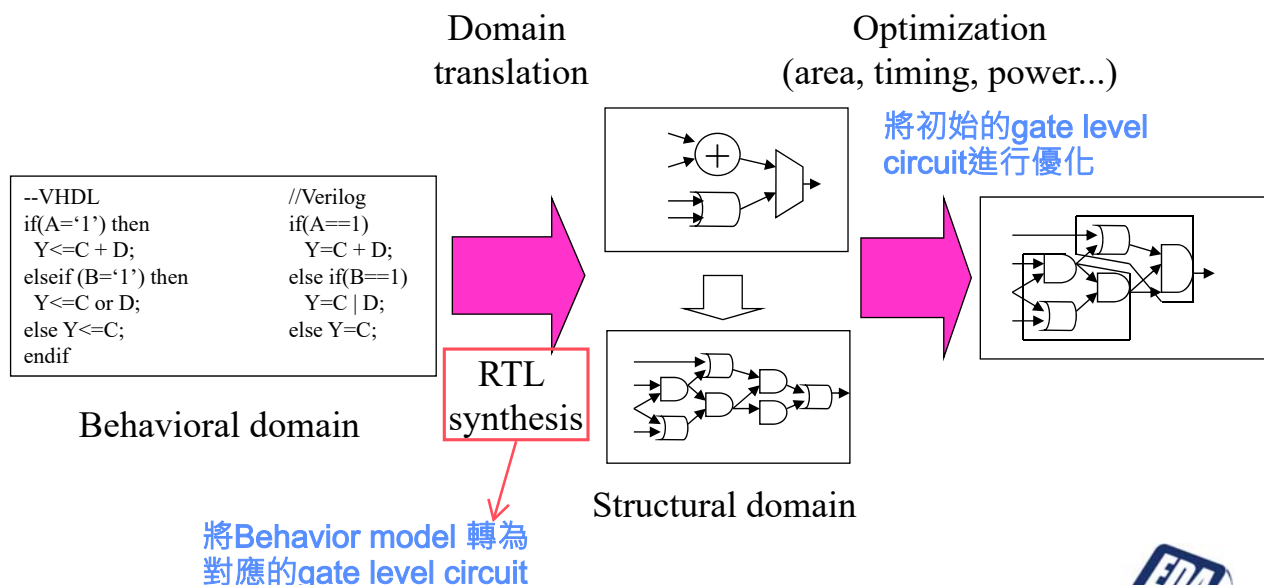
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# HDL Synthesis

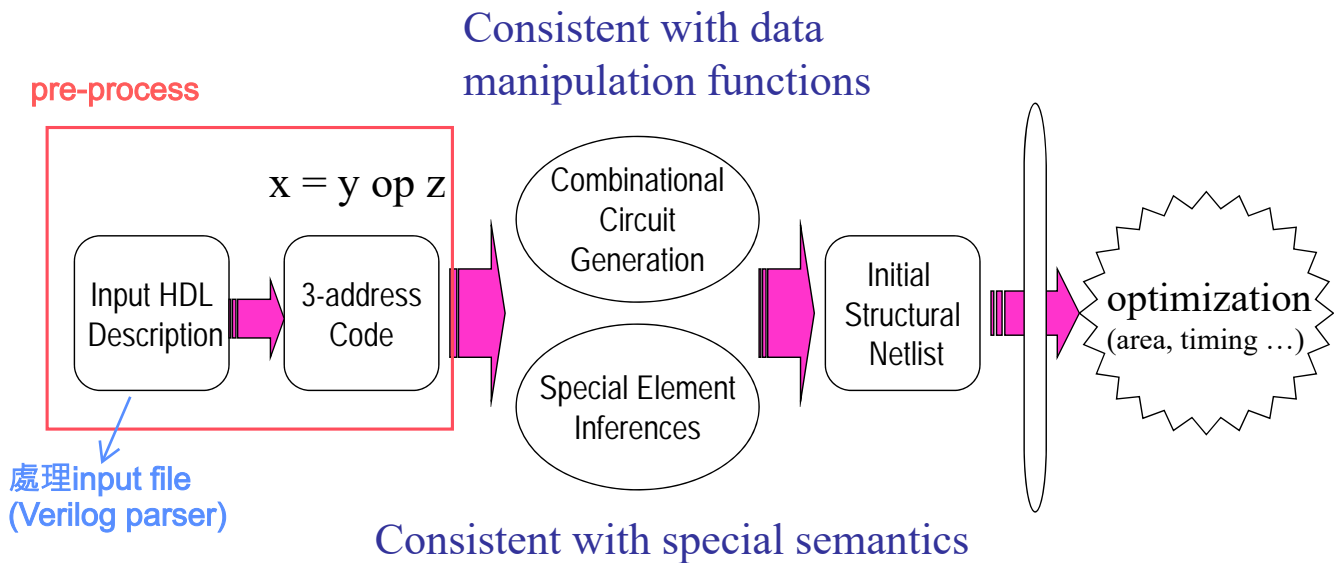
- **Logic synthesis** programs transform Boolean expressions or **register-transfer level (RTL)** description (in Verilog/VHDL/C) into logic gate networks (netlist) in a particular library.
- Advantages
  - Reduce time to generate netlists
  - Easier to retarget designs from one technology to another
  - Reduce debugging effort
- Requirement
  - **Robust** HDL synthesizers

## Synthesis Procedure

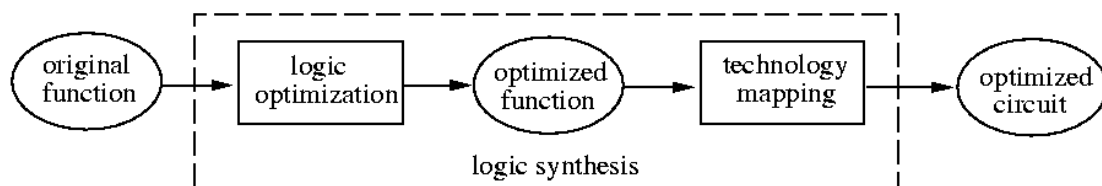
**Synthesis = Domain Translation + Optimization**



# Domain Translation



## Optimization



- **Technology-independent** optimization: **logic optimization**

- Work on Boolean expression equivalent
- Estimate size based on # of literals
- Use **simple delay models** 較不準確

- **Technology-dependent** optimization: **technology mapping/library binding**

- Map Boolean expressions into a particular cell library 將Boolean expression對應到指定的製程檔
- May perform some optimizations in addition to simple mapping 有用的資訊更多，可以進一步做最佳化
- Use **more accurate delay models** based on cell structures

# Technology-Independent Logic Optimization

- **Two-level:** minimize the # of product terms.

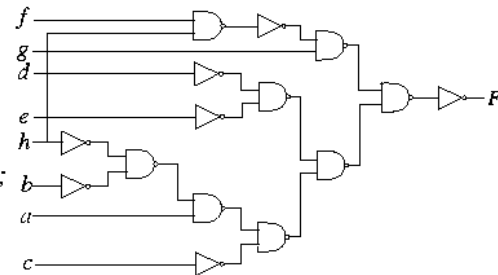
$$F = \bar{x}_1\bar{x}_2\bar{x}_3 + \bar{x}_1\bar{x}_2x_3 + x_1\bar{x}_2\bar{x}_3 + x_1\bar{x}_2x_3 + x_1x_2\bar{x}_3 \Rightarrow F = \bar{x}_2 + x_1\bar{x}_3.$$

- **Multi-level:** minimize the #'s of literals, variables.

– E.g., equations are optimized using a smaller number of literals.

尋找是否有元件可以共用

$$\begin{array}{l} t1 = a + b \cdot c; \\ t2 = d + e; \\ t3 = a \cdot b + d; \\ t4 = t1 \cdot t2 + f \cdot g; \\ t5 = t4 \cdot h + t2 \cdot t3; \\ F = t5'; \end{array} \xrightarrow{\text{logic optimization}} \begin{array}{l} t1 = d + e; \\ t2 = b + h; \\ t3 = a \cdot t2 + c; \\ t4 = t1 \cdot t3 + f \cdot g \cdot h; \end{array}$$



subject graph for the optimized equations

- Methods/CAD tools: **Quine-McCluskey** method (exponential-time exact algorithm), Espresso (heuristics for two-level logic), MIS (heuristics for multi-level logic), Synopsys, etc.

Espresso的團隊就是新思的創辦團隊



## Technology Mapping

- Goal: translation of a technology independent representation (e.g. Boolean networks) of a circuit into a circuit in a given technology (e.g. standard cells) with optimal cost

- Optimization criteria:

- Minimum area
- Minimum delay
- Meeting specified timing constraints
- Meeting specified timing constraints with minimum area

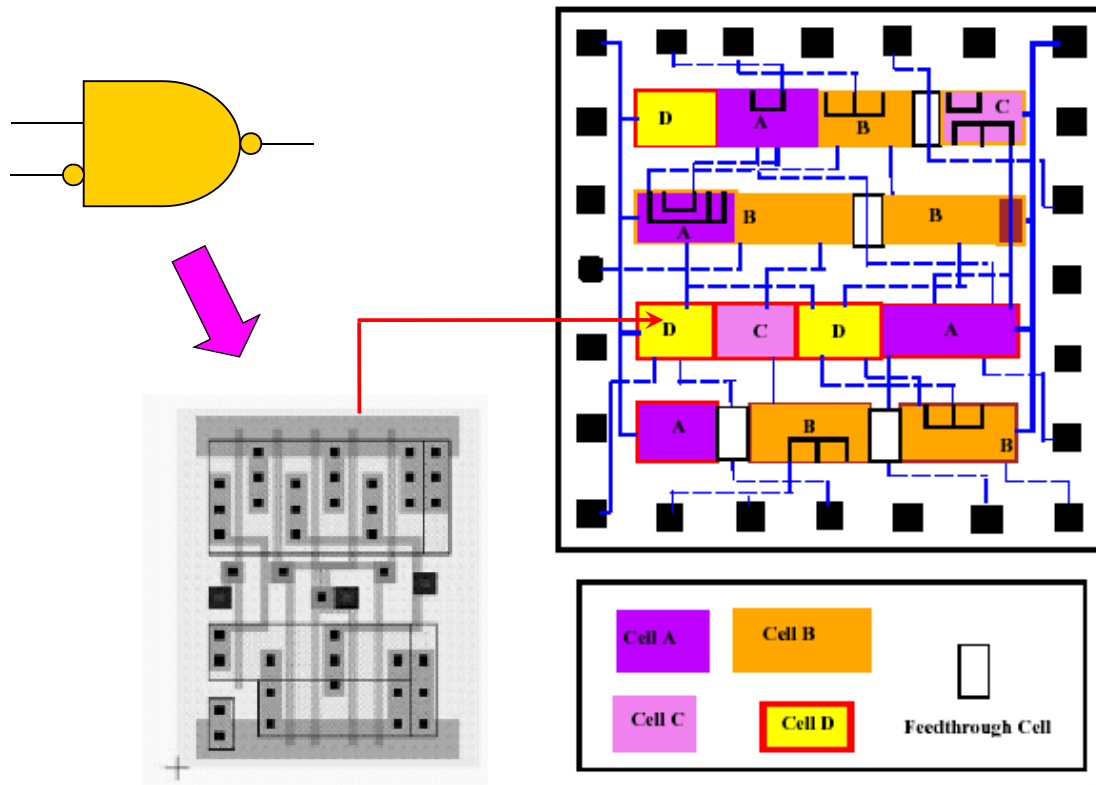
Optimization時需要考慮PPA，但是通常area與performance是trade off的關係，因此在此階段就會去嘗試各種不同的製程、cell library

- Usage:

- Technology mapping after technology independent logic optimization
- Technology translation

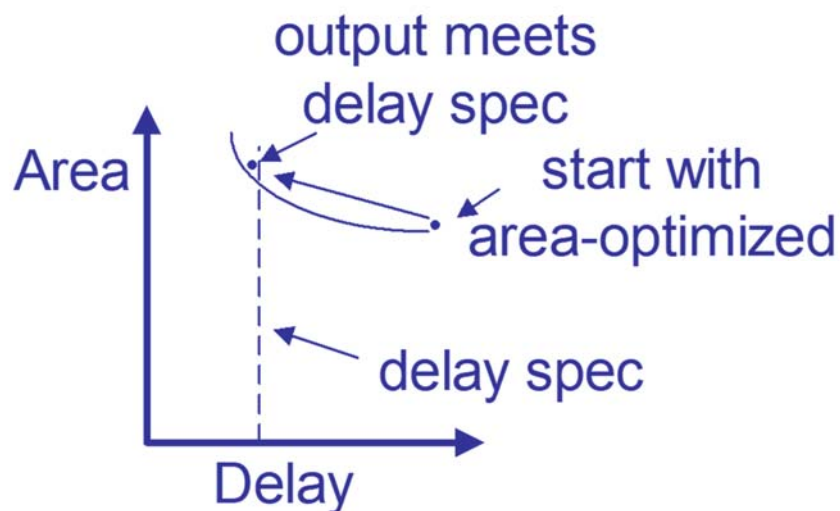


# Standard Cells for Design Implementation



## Timing Optimization

- There is always a trade-off between area and delay
- Optimize timing to meet delay spec. with minimum area



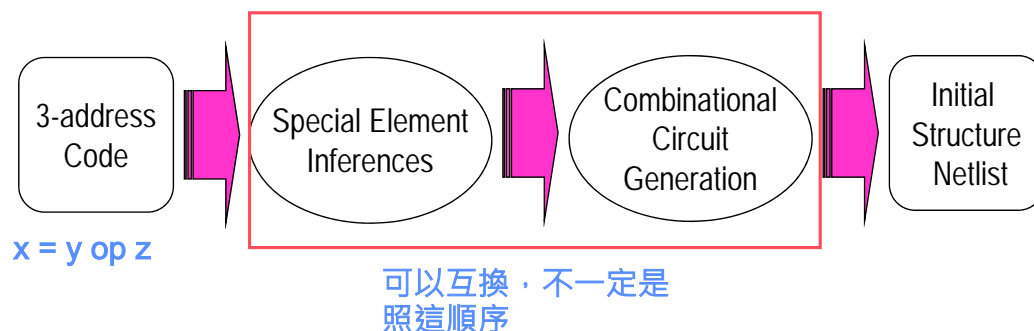
## Outline

- Synthesis overview
- **RTL synthesis**
  - Combinational circuit generation
  - Special element inferences
- Two-level logic optimization
- Multi-level logic optimization
- Technology mapping
- Timing analysis
- Timing optimization
- Synthesis for low power



## Typical Domain Translation Flow

- Translate original HDL code into 3-address format
- Conduct special element inferences before combinational circuit generation
- Conduct special element inferences process by process (local view)



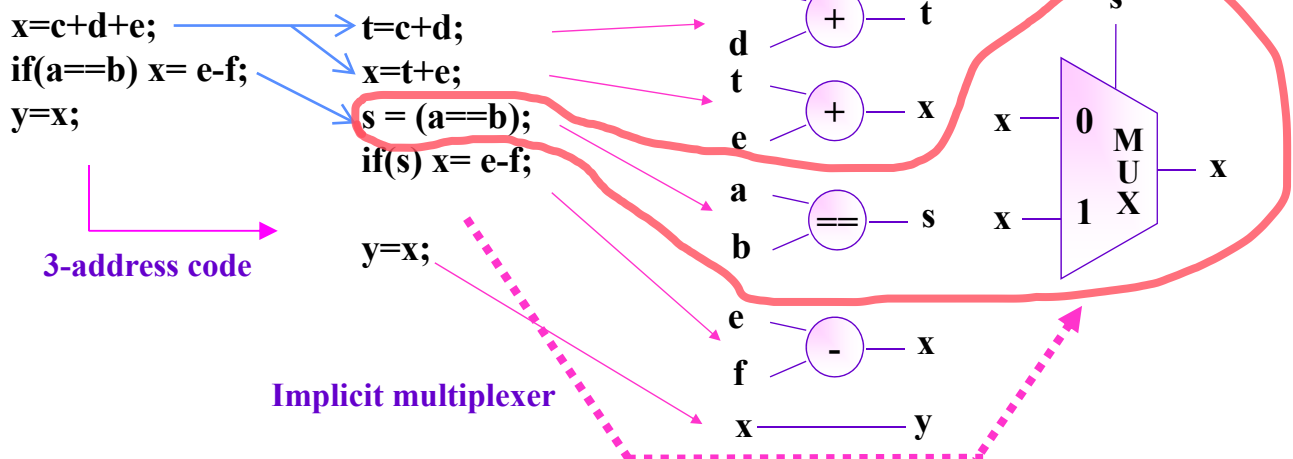
# Combinational Circuit Generation

- Functional unit allocation
  - Straightforward mapping with 3-address code
- Interconnection binding
  - Using control/data flow analysis

## Functional Unit Allocation

- 3-address code
  - $x = y \text{ op } z$  in general form
  - Function unit op with inputs y and z and output x

遇到連續運算的式子，將拆解為多個2-input的組合



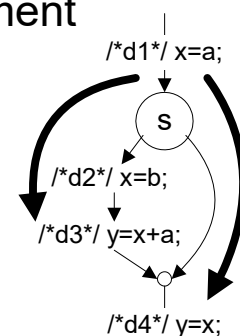
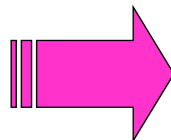
## Interconnection Binding

- Need the dependency information among functional units
  - Using **control/data flow analysis**
  - A traditional technique used in compiler design for a variety of code optimizations
  - Statically analyze and compute the set of assignments reaching a particular point in a program

## Control/Data Flow Analysis

- Terminology
  - A **definition** of a variable  $x$  definition中都會有一個賦值符號"="
  - An **assignment** assigns a value to the variable  $x$
  - $d1$  can reach  $d4$  but cannot reach  $d3$
  - $d1$  is killed by  $d2$  before reaching  $d3$  新的宣告會殺死(覆蓋)舊的宣告
- A definition can only be affected by those definitions being able to reach it
- Use a set of data flow equations to compute which assignments can reach a target assignment

```
/*d1*/ x = a;  
    if(s) begin  
/*d2*/   x = b;  
/*d3*/   y = x + a;  
    end  
/*d4*/ y = x;
```





## Combinational Circuit Generation: An Example

```
always @ ( x or a or b or c or d or s )
begin
/*d1*/  x = a + b;
/*d2*/  if ( s ) x = c - d;
/*d3*/  else x = x;
/*d4*/  y = x;
end
```

### Input HDL

```
always @ ( x or a or b or c or d or s )
begin
/*d1*/  x = a + b;
/*d2*/  if ( s ) x = c - d;
/*d3*/  else x = x;
/*d4*/  x = s mux x;
/*d5*/  y = x;
end
```

### Modified 3-address code

In[d1]={d4, d5} → computed by control/  
data flow analysis

a → d1 (+) → x  
b → d1 (+) → x

In[d2]={d1, d5}

c → d2 (-) → x  
d → d2 (-) → x

In[d3]={\*d1, d5}

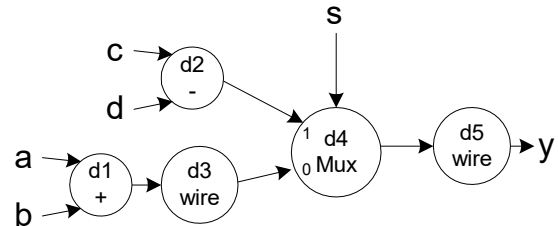
x → d3 (wire) → x

In[d4]={\*d2, \*d3, d5}

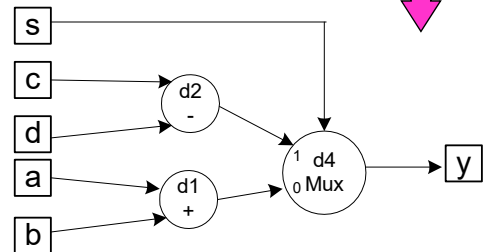
s → d4 (1 d4 0 Mux) → x  
x → d4 (1 d4 0 Mux) → x  
x → d4 (1 d4 0 Mux) → x

In[d5]={\*d4, d5}

x → d5 (wire) → y



### Interconnection binding



### Final result

### Functional unit allocation



## Outline

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- RTL synthesis
  - Combinational circuit generation
  - **Special element inferences**
- Two-level logic optimization
- Multi-level logic optimization
- Technology mapping
- Timing analysis
- Timing optimization
- Synthesis for low power



## Special Element Inferences

- Given a HDL code at RTL, three special elements need to be inferred to keep the special semantics
  - Latch (D-type) inference
  - Flip-Flop (D-type) inference
  - Tri-state buffer inference
- Some simple rules are used in typical approaches

```
reg Q;  
always@(D or en)  
  if(en) Q = D;
```

**Latch inferred!!**

```
reg Q;  
always@(posedge clk)  
  Q = D;
```

**Flip-flop inferred!!**

```
reg Q;  
always@(D or en)  
  if(en) Q = D;  
  else  Q = 1'bz;
```

**Tri-state buffer  
inferred!!**



## Preliminaries

- Sequential section
  - Edge triggered always statement
- Combinational section
  - All signals whose values are used in the always statement are included in the sensitivity list

```
reg Q;  
always@(posedge clk)  
  Q = D;
```

**Sequential section**  
**Conduct flip-flop inference**

```
reg Q;  
always@(in or en)  
  if(en) Q=in;
```

**Combinational section**  
**Conduct latch inference**



## Typical Latch Inference

- Conditional assignments are not completely specified
  - Check if the *else-clause* exists
  - Check if all case items exist
- Outputs conditionally assigned in an if-statement are not assigned before entering or after leaving the if-statement

```
always@(D or S)
if(S) Q = D;
```

└─→ Infer latch  
for Q

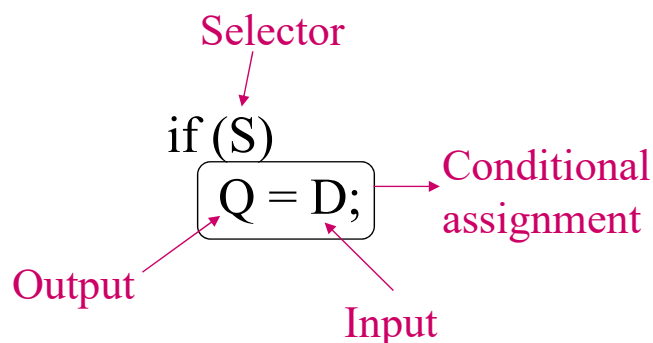
```
always@(S or A or B)
begin
Q = A;
if(S) Q = B;
end
```

→ Do not infer  
latch for Q



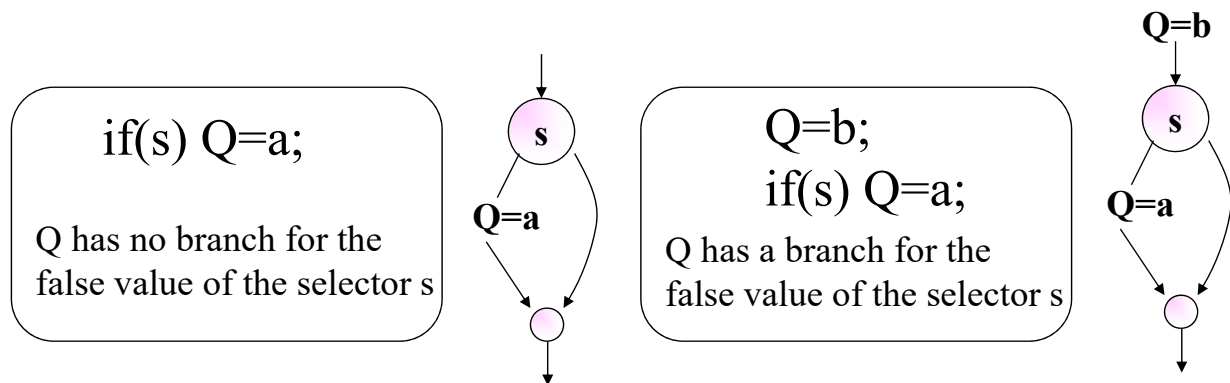
## Terminology (1/2)

- Conditional assignment
- Selector: S
- Input: D
- Output: Q



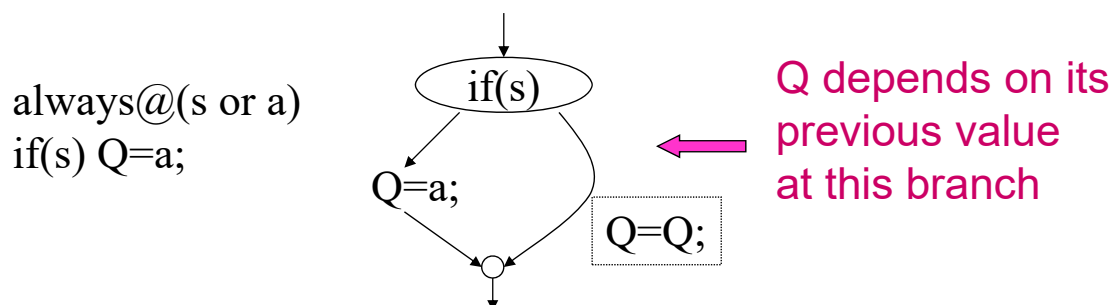
## Terminology (2/2)

- A variable  $Q$  has a *branch* for a value of selector  $s$ 
  - The variable  $Q$  is assigned a value in a path going through the branch



## Rules of Latch Inference (1/2)

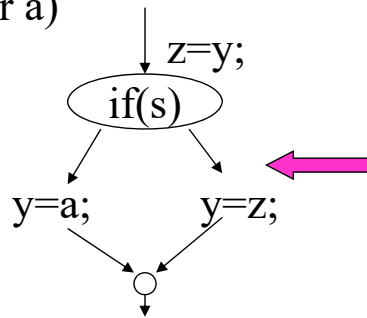
- Condition 1: There is no branch associated with the output of a conditional assignment for a value of the selector
  - Output depends on its previous value implicitly



## Rules of Latch Inference (2/2)

- Condition 2: The output value of a conditional assignment depends on its previous value explicitly

```
always@(s or z or y or a)
begin
  z = y;
  if(s) y=a;
  else y=z;
end
```



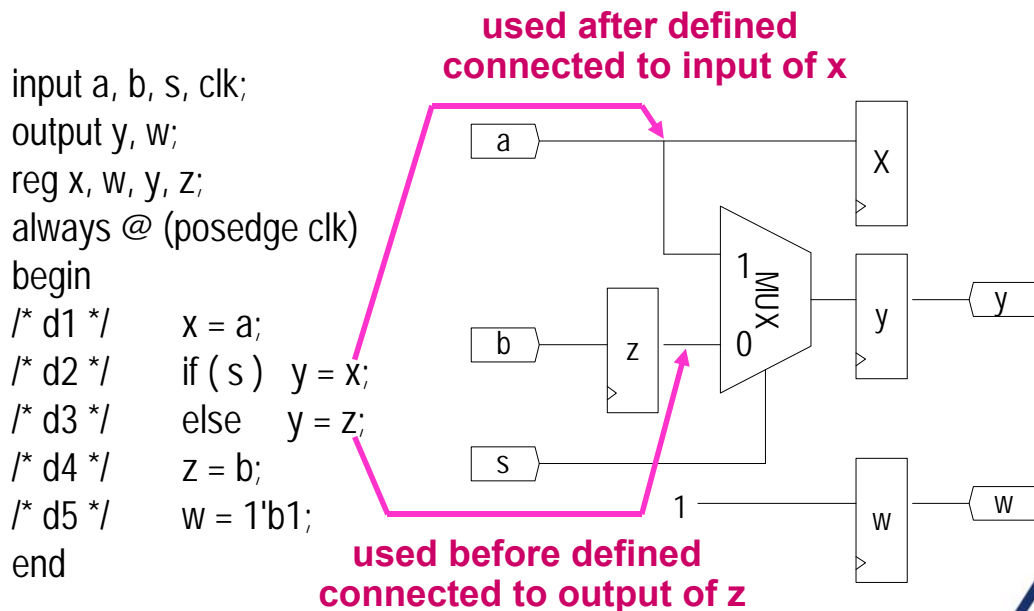
y depends on its previous value at this branch via the assignment z=y;

## Terminology

- Clocked statement: edge-triggered always statement
  - Simple clocked statement  
e.g., **always @ (posedge clock)**
  - Complex clocked statement  
e.g., **always @ (posedge clock or posedge reset)**
- Flip-flop inference must be conducted only when synthesizing the **clocked statements**

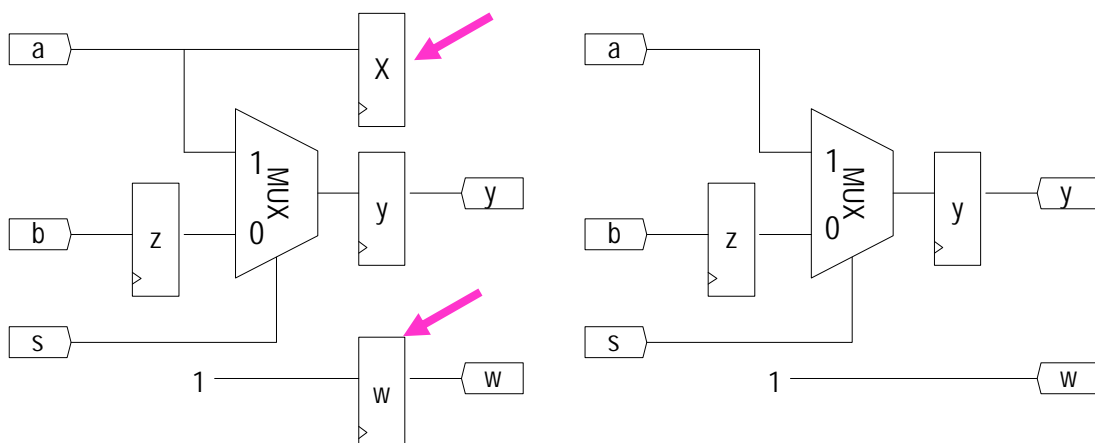
## Infer FF for Simple Clocked Statements (1/2)

- Infer a flip-flop for **each variable** being assigned in the simple clocked statement



## Infer FF for Simple Clocked Statements (2/2)

- Two post-processes
  - Propagating constants
  - Removing the flip-flops without fanouts



## Infer FF for Complex Clocked Statements

- The edge-triggered signal not used in the following operations is chosen as the clock signal
- The usage of asynchronous control pins requires the following syntactic template
  - An if-statement immediately follows the always statement
  - Each variable in the event list except the *clock signal* must be a selective signal of the if-statements
  - Assignments in the blocks B1 and B2 must be constant assignments (e.g., x=1, etc.)

**always @ (posedge clock or posedge reset or negedge set)**

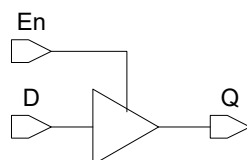
if(reset) begin **B1** end  
else if ( !set) begin **B2** end  
else begin **B3** end



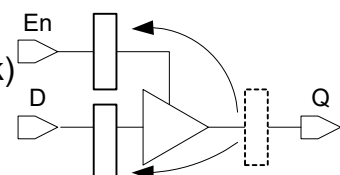
## Typical Tri-State Buffer Inference (1/2)

- If a data object Q is assigned a high impedance value 'Z' in a multi-way branch statement (if, case, ?:)
  - Associated Q with a tri-state buffer
- If Q associated with a tri-state buffer has also a memory attribute (latch, flip-flop)
  - Have the **Hi-Z propagation problem**
    - Real hardware cannot propagate Hi-Z value
  - Require two memory elements for the control and the data inputs of tri-state buffer

```
reg Q;  
always @ (En or D)  
if(En) Q = D;  
else Q = 1'bz;
```



```
reg Q;  
always @ (posedge clk)  
if(En) Q = D;  
else Q = 1'bz;
```

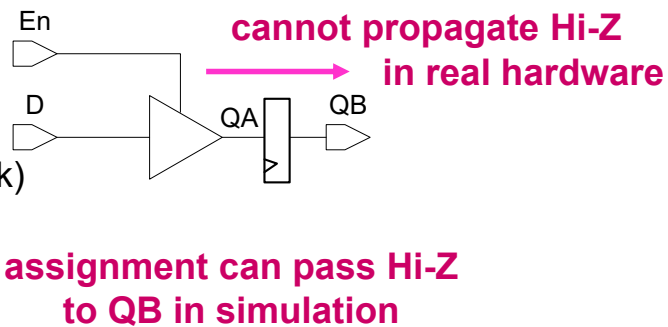


## Typical Tri-State Buffer Inference (2/2)

- It may suffer from mismatches between synthesis and simulation
  - Process by process
  - May incur the Hi-Z propagation problem

```
reg QA, QB;  
always @ (En or D)  
if(En) QA = D;  
else QA = 1'bz;
```

```
always @ (posedge clk)  
QB = QA;
```



## Outline

- Synthesis overview
- RTL synthesis
- Two-level logic optimization
  - Basic logic operations
  - Exact minimization
  - Heuristic methods
- Multi-level logic optimization
- Technology mapping
- Timing analysis
- Timing optimization
- Synthesis for low power



## Two-Level Logic Optimization

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- Two-level logic optimization
  - Key technique in logic optimization
  - Many efficient algorithms to find a near minimal representation in a practical amount of time
  - In commercial use for several years
  - Minimization criteria: **number of product terms**
- Example:  $F = XYZ + X\bar{Y}\bar{Z} + X\bar{Y}Z + \bar{X}YZ + XY\bar{Y}Z$



$$F = X\bar{Y} + YZ$$



## Optimization Approach

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- Exact Methods:
  - Compute minimum cover
  - Often impossible for large functions
  - Ex: Karnaugh maps, Quine-McCluskey
- Heuristic Methods:
  - Compute minimal covers (possibly minimum) in reasonable time
  - Large variety of methods and programs
  - Ex: MINI, PRESTO, ESPRESSO

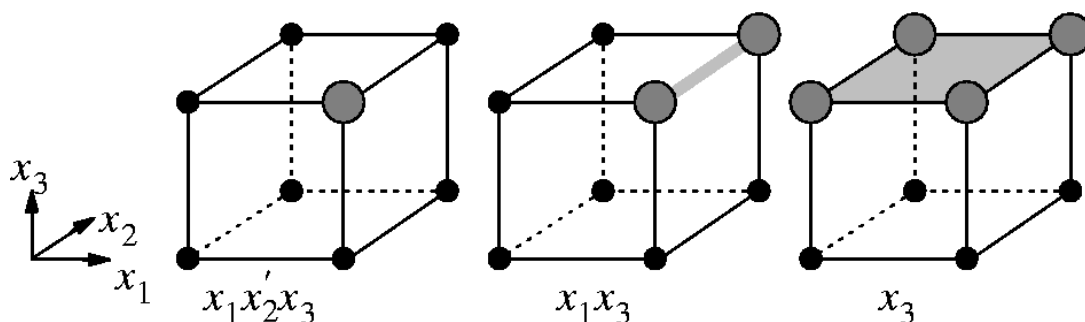


## Boolean Functions

- $B = \{0, 1\}$ ,  $Y = \{0, 1, D\}$
- A Boolean function  $f: B^m \rightarrow Y^n$ 
  - $f = \bar{x}_1 \bar{x}_2 + \bar{x}_1 \bar{x}_3 + \bar{x}_2 x_3 + x_1 x_2 + x_2 \bar{x}_3 + x_1 x_3$
- Input variables:  $x_1, x_2, \dots$
- The value of the output partitions  $B^m$  into three sets
  - the on-set
  - the off-set
  - the dc-set (don't-care set)

## Minterms and Cubes

- A **minterm** is a product of **all** input variables or their negations.
  - A minterm corresponds to a single point in  $B^n$ .
- A **cube** is a product of the input variables or their negations.
  - The fewer the number of variables in the product, the bigger the space covered by the cube.

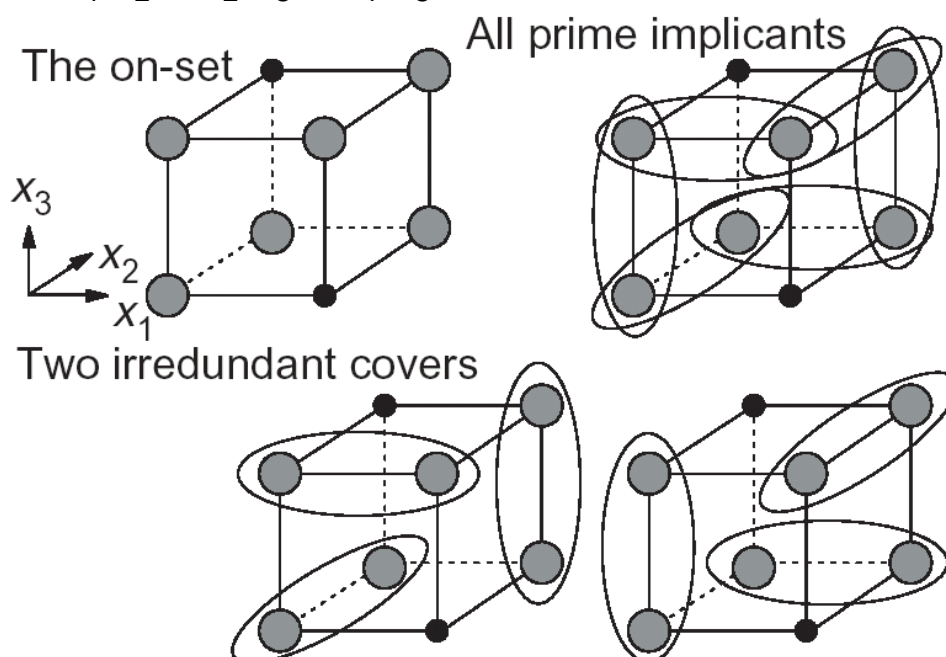


## Implicant and Cover

- An **implicant** is a cube whose points are either in the on-set or the dc-set.
- A **prime implicant** is an implicant that is not included in any other implicant.
- A set of prime implicants that together cover all points in the on-set (and some or all points of the dc-set) is called a prime cover.
- A prime cover is **irredundant** when none of its prime implicants can be removed from the cover.
- An irredundant prime cover is **minimal** when the cover has the minimal number of prime implicants.

## Cover Examples

- $f = \bar{x}_1 \bar{x}_3 + \bar{x}_2 x_3 + x_1 x_2$
- $f = \bar{x}_1 \bar{x}_2 + x_2 \bar{x}_3 + x_1 x_3$

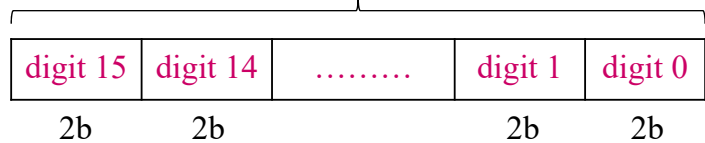


## The Positional-Cube Notation

- Encode each symbol by 2-bit fields as follows:

$\phi$  00  
 0 10  
 1 01  
 \* 11

One 32-bit integer  $\rightarrow$  16 binary digits



- Example:  $f = a'd' + a'b + ab' + ac'd$

10 11 11 10 ( $a' - - d'$ )  
 10 01 11 11 ( $a' b - -$ )  
 01 10 11 11 ( $a b' - -$ )  
 01 11 10 01 ( $a - c' d$ )

- Example:  $f_1 = a'b' + ab$ ;  $f_2 = ab$ ;  $f_3 = ab' + a'b$

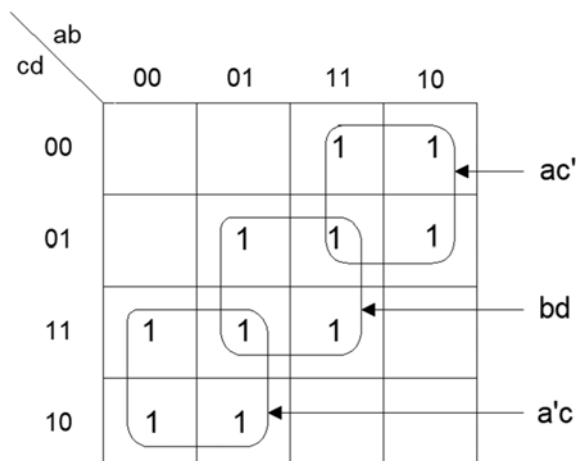
10 10 1 0 0 ( $a'b'$ )  
 10 01 0 0 1 ( $a'b$ )  
 01 10 0 0 1 ( $ab'$ )  
 01 01 1 1 0 ( $ab$ )

$f_1 \rightarrow$   
 $f_2 \uparrow$   
 $f_3 \leftarrow$



## AND Operation

Can be finished with a bit-wise AND instruction !!



10 11 01 11  $a'c$   
 $\cap$  11 01 11 01  $bd$   
 -----  
 10 01 01 01  $a'bcd$

10 11 01 11  $a'c$   
 $\cap$  01 11 10 11  $ac'$   
 -----  
 00 11 00 11  $\phi$

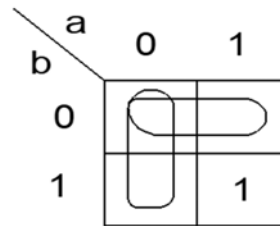


## Sharp Operation

$$\alpha \# \beta = \begin{array}{ccccc} a_1 b_1' & a_2 & \dots & a_{n-1} & a_n \\ a_1 & a_2 b_2' & \dots & a_{n-1} & a_n \\ \dots & \dots & \dots & \dots & \dots \\ a_1 & \dots & \dots & a_{n-1} b_{n-1}' & a_n \\ a_1 & \dots & \dots & a_{n-1} & a_n b_n' \end{array}$$

• Example

$$11 \ 11 \# 01 \ 01 = \begin{array}{cc} 10 & 11 \\ 11 & 10 \end{array}$$

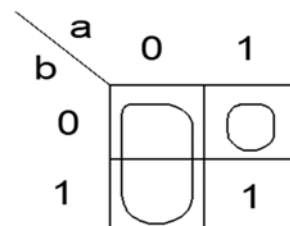


## Disjoint Sharp Operation

$$\alpha \textcircled{\#} \beta = \begin{array}{ccccc} a_1 b_1' & a_2 & \dots & a_{n-1} & a_n \\ a_1 b_1 & a_2 b_2' & \dots & a_{n-1} & a_n \\ \dots & \dots & \dots & \dots & \dots \\ a_1 b_1 & a_2 b_2 & \dots & a_{n-1} b_{n-1}' & a_n \\ a_1 b_1 & a_2 b_2 & \dots & a_{n-1} b_{n-1} & a_n b_n' \end{array}$$

• Example

$$11 \ 11 \textcircled{\#} 01 \ 01 = \begin{array}{cc} 10 & 11 \\ 01 & 10 \end{array}$$



## Effects of Basic Logic Operations

- Consider each implicant as a set
- **Intersection** is the largest cube contained in both implicants and is computed by **AND operation**
- The **distance** between two implicants is the **number of empty fields in their intersection**
  - If there is any empty field, the two implicants are disjoint
- The **supercube** of two sets (the sum of two functions) can be obtained by union the sets (**bit-wise OR**)
  - The smallest cube containing both implicants
- The **(disjoint) sharp operation** can be used to compute the **complementation**

$$R = U \# (F^{ON} \cup F^{DC})$$



## Cofactor (Restriction)

- Cofactor of  $f$  with respect to  $x_i = 0$ 
  - $f_{x_i'} = f_{x_i=0} = f(x_1, x_2, \dots, x_i=0, \dots, x_n)$
- Cofactor of  $f$  with respect to  $x_i = 1$ 
  - $f_{x_i} = f_{x_i=1} = f(x_1, x_2, \dots, x_i=1, \dots, x_n)$
  - Example:
$$f(x, y, z) = xy + yz' + x'z'$$
$$\rightarrow f_{x=0} = yz' + z' \quad f_{x=1} = y + yz'$$
- Cofactor with respect to any cube
  - Example:
$$f(x, y, z, w) = xy + zw' + w'x'$$
$$f_{x'y'} = f_{x=0, y=0} = zw' + w'$$
$$f_{xy'} = f_{x=1, y=0} = zw'$$



## Cofactor of Implicants

- The cofactor of an implicant  $\alpha$  w.r.t an implicant  $\beta$  is:

- $\alpha_\beta = \phi$  when  $\alpha$  does not intersect  $\beta$

Otherwise,  $\alpha_\beta = a_1 + b_1' \quad a_2 + b_2' \quad \dots \quad a_n + b_n'$

- Example: Given  $f = a'b' + ab$ , calculate  $f_a$

$$f = \begin{matrix} 10 & 10 \\ 01 & 01 \end{matrix} \quad \begin{matrix} c(a) = 01 & 11 \\ c(a') = 10 & 00 \end{matrix} \quad (\text{cube representation})$$

The cofactor of the first implicant is void

—  $a'b'$  intersect with  $a$  is empty

The cofactor of the second implicant is  $11 \ 01$

—  $(01 \ 01) + (10 \ 00) = (11 \ 01)$

$\rightarrow f_a = b$



## Shannon Expansion

$$\begin{aligned} f &= x' \cdot f_{x=0} + x \cdot f_{x=1} \\ &= x_i' \cdot y_j' \cdot f_{x_i' y_j'} + x_i \cdot y_j' \cdot f_{x_i y_j'} + x_i' \cdot y_j \cdot f_{x_i' y_j} + x_i \cdot y_j \cdot f_{x_i y_j} \end{aligned}$$

- Example:

$$f_x = y + zw'$$

$$f_{x'} = zw' + w'$$

$$f = x(y + zw') + x'(zw' + w')$$

- Decompose a function into two components, one for the subspace  $x = 0$ , the other for the subspace  $x = 1$

$$f = x'f_{x'} + xf_x$$

- Allow a divide and conquer strategy on several problems
  - $f_{x'}$  and  $f_x$  do not depend on  $x$  and thus have one less variable



## Consensus Operator

- Definition:  $\forall x(f) = f_x \cdot f_{x'}$
- $\forall x(f)$  evaluate  $f$  to be true for  $x = 1$  and  $x = 0$
- Represent the component that is independent of that variable

- Example:

$$f(x,y,z,w) = xy + zw' + w'x'$$

$$f_x \cdot f_{x'} = zw' + w'y$$

## Smoothing Operations

- Definition:  $\exists x(f) = f_x + f_{x'}$
- $\exists x(f)$  evaluate  $f$  to be true when  $x = 1$  or  $x = 0$
- Example:

$$f(x,y,z,w) = xy + zw' + w'x'$$

$$\exists x(f) = f_x + f_{x'} = (zw' + w') + (zw' + y)$$



## Boolean Difference

- $\frac{\partial f}{\partial x}$  is called Boolean difference of  $f$  with respect to  $x$
- Definition:  $\frac{\partial f}{\partial x} = f_x \oplus f_x^-$
- $f$  is sensitive to the value of  $x$  when  $\frac{\partial f}{\partial x} = 1$
- Example:  $f(x,y,z,w) = xy + zw' + w'x'$   
 $f_{x'} = f(x=0,y,z,w) = zw' + w'$   
 $f_x = f(x=1,y,z,w) = y + zw'$   
 $f_{x'} \oplus f_x = (zw' + w') \oplus (y + zw')$

## Outline

- Synthesis overview
- RTL synthesis
- Two-level logic optimization
  - Basic logic operations
  - Exact minimization
  - Heuristic methods
- Multi-level logic optimization
- Technology mapping
- Timing analysis
- Timing optimization
- Synthesis for low power

# The Quine-McCluskey Algorithm

- Theorem:[Quine,McCluskey] There exists a minimum cover for  $F$  that is prime
  - Need to look just at primes (reduces the search space)
- Classical methods: two-step process
  1. Generation of all prime implicants (of the union of the on-set and dc-set)
  2. Extraction of a minimum cover (covering problem)
- Exponential-time exact algorithm, huge amounts of memory!
- Other methods do not first enumerate all prime implicants; they use an implicit representation by means of ROBDDs.



## Primary Implicant Generation (1/5)

ab		a			
		00	01	11	10
cd	00	X	1	0	1
	01	0	1	1	1
	11	0	X	X	0
	10	0	1	0	1

Diagram illustrating the Karnaugh map for Primary Implicant Generation (1/5). The map is a 4x4 grid with rows labeled 'cd' and columns labeled 'ab'. The cells contain values: X, 1, 0, 1, 0, 1, 1, 1, 0, X, X, 0, 0, 1, 0, 1. Brackets indicate groupings: 'a' groups columns 11 and 10; 'b' groups columns 01 and 11; 'c' groups rows 11 and 10; 'd' groups rows 01 and 11.



## Primary Implicant Generation (2/5)

Implication Table		
	Column I	
zero "1"	0000	
one "1"	0100	
	1000	
	0101	
two "1"	0110	
	1001	
	1010	
	0111	
three "1"	1101	
	1111	
four "1"	1111	



## Primary Implicant Generation (3/5)

Implication Table		
	Column I	Column II
	0000	0-00
		-000
	0100	
	1000	010-
		01-0
	0101	100-
	0110	10-0
	1001	
	1010	01-1
		-101
	0111	011-
	1101	1-01
	1111	-111
		11-1

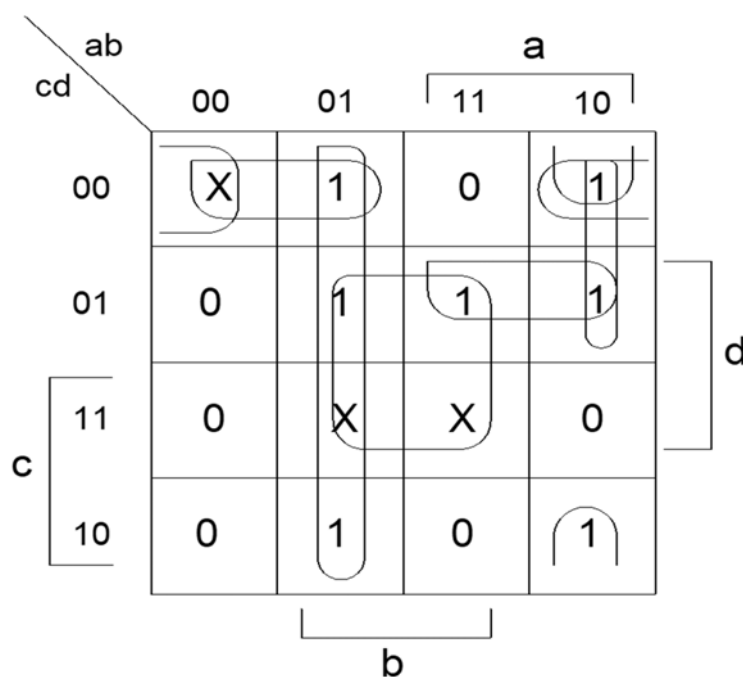


## Primary Implicant Generation (4/5)

Implication Table		
Column I	Column II	Column III
0000	0-00 *	01-- *
	-000 *	
0100		-1-1 *
1000	010-	
	01-0	
0101	100- *	
0110	10-0 *	
1001		
1010	01-1	
	-101	
0111	011-	
1101	1-01 *	
1111	-111	
	11-1	



## Primary Implicant Generation (5/5)



Prime Implicants:

$$0-00 = a'c'd'$$

$$100- = ab'c'$$

$$1-01 = ac'd$$

$$-1-1 = bd$$

$$-000 = b'c'd'$$

$$10-0 = ab'd'$$

$$01-- = a'b$$



## Column Covering (1/4)

	4	5	6	8	9	10	13
0,4 (0-00)	×						
0,8 (-000)				×			
8,9 (100-)				×	×		
8,10 (10-0)				×		×	
9,13 (1-01)					×		×
4,5,6,7 (01- -)	×	×	×				
5,7,13,15 (-1-1)		×					×

rows = prime implicants

columns = ON-set elements

place an "X" if ON-set element  
is covered by the prime implicant



## Column Covering (2/4)

	4	5	6	8	9	10	13
0,4 (0-00)	×						
0,8 (-000)				×			
8,9 (100-)				×	×		
8,10 (10-0)				×		×	
9,13 (1-01)					×		×
4,5,6,7 (01- -)	×	×	×				
5,7,13,15 (-1-1)		×					×

If column has a single X, then the  
implicant associated with the row  
is essential. It must appear in  
minimum cover



## Column Covering (3/4)

	4	5	6	8	9	10	13
0,4 (0-00)	×						
0,8 (-000)				×			
8,9 (100-)				×	×		
8,10 (10-0)				×		×	
9,13 (1-01)					×		×
4,5,6,7 (01- -)	×	×	×				
5,7,13,15 (-1-1)		×					×

Eliminate all columns covered by essential primes



## Column Covering (4/4)

	4	5	6	8	9	10	13
0,4 (0-00)	×						
0,8 (-000)				×			
8,9 (100-)				×	×		
8,10 (10-0)				×		×	
9,13 (1-01)					×		×
4,5,6,7 (01- -)	×	×	×				
5,7,13,15 (-1-1)		×					×

Find minimum set of rows that cover the remaining columns

$$f = ab'd' + ac'd + a'b$$



## Petrick's Method

- Solve the **satisfiability** problem of the following function

$$P = (P1+P6)(P6+P7)P6(P2+P3+P4)(P3+P5)P4(P5+P7)=1$$

		4	5	6	8	9	10	13
P1	0,4 (0-00)	×						
P2	0,8 (-000)				×			
P3	8,9 (100-)				×	×		
P4	8,10 (10-0)				×		×	
P5	9,13 (1-01)					×		×
P6	4,5,6,7 (01- -)	×	×	×				
P7	5,7,13,15 (-1-1)		×					×

- Each term represents a corresponding column
- Each column must be chosen at least once
- All columns must be covered



## ROBDDs and Satisfiability

- A Boolean function is **satisfiable** if an assignment to its variables exists for which the function becomes '1'
- Any Boolean function whose ROBDD is unequal to '0' is satisfiable.
- Suppose that choosing a Boolean variable  $x_i$  to be '1' costs  $c_i$ . Then, the **minimum-cost satisfiability** problem asks to minimize: 
$$\sum_{i=1}^n c_i \mu(x_i)$$

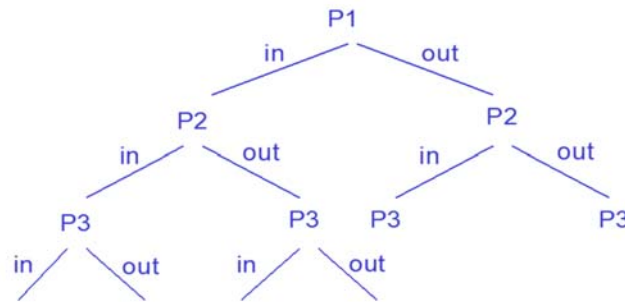
where  $\mu(x_i) = 1$  when  $x_i = '1'$  and  $\mu(x_i) = 0$  when  $x_i = '0'$ .

- Solving minimum-cost satisfiability amounts to computing the shortest path in an ROBDD, which can be solved in linear time.
  - Weights:  $w(v, \eta(v)) = c_i$ ,  $w(v, \lambda(v)) = 0$ , variable  $x_i = \phi(v)$ .



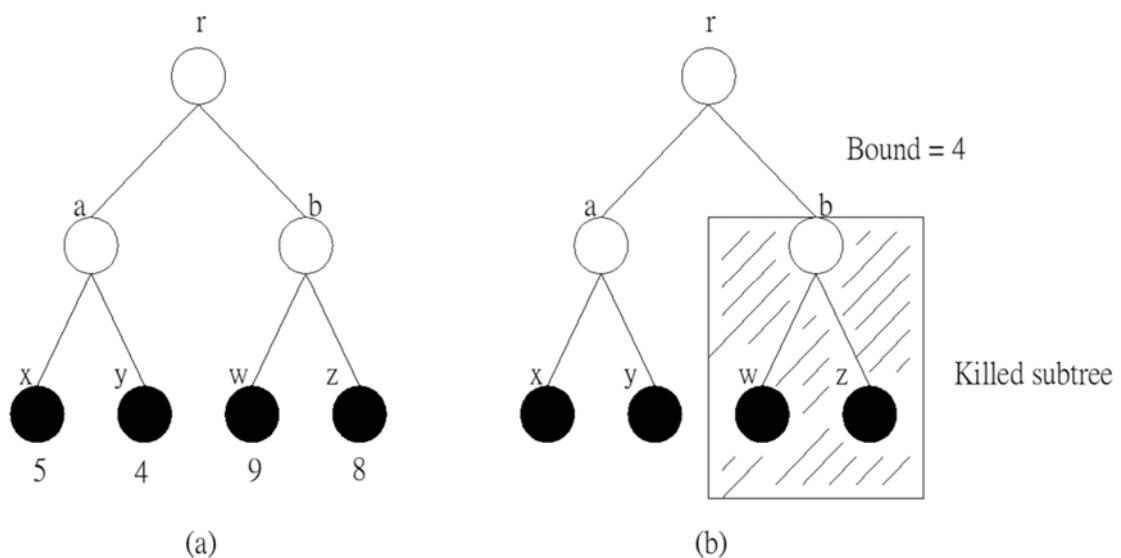
## Brute Force Technique

- Brute force technique: Consider all possible elements



- Complete branching tree has  $2^{|P|}$  leaves!!
  - Need to prune it
- Complexity reduction
  - Essential primes can be included right away
    - If there is a row with a singleton “1” for the column
  - Keep track of best solution seen so far
    - Classic **branch and bound**

## Branch and Bound Algorithm





## Outline

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  - **Heuristic methods**
- Multi-level logic optimization
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## Why Heuristic Optimization ?

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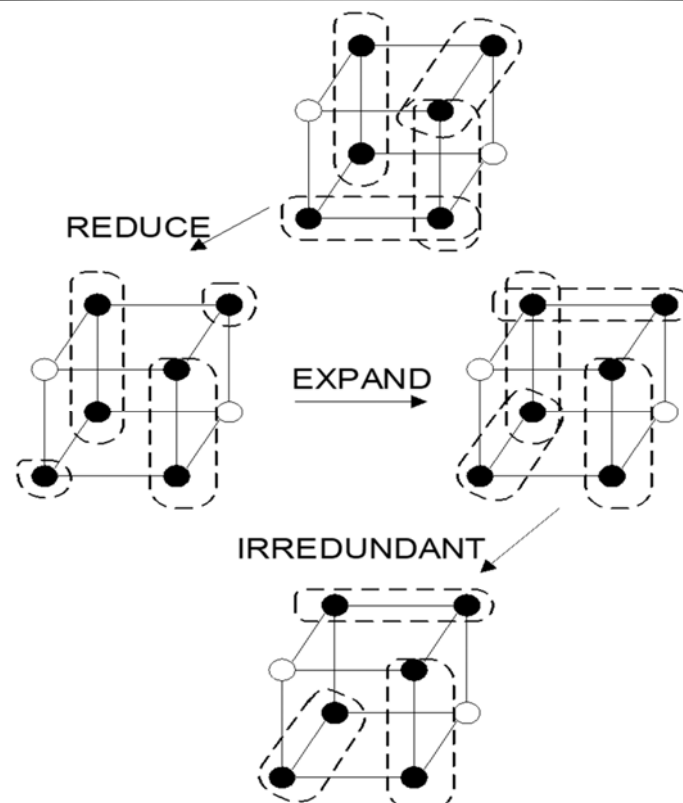
- Generation of **all** prime implicants is impractical
  - The number of prime implicants for functions with  $n$  variables is in the order of  $3^n/n$
- Finding an *exact* minimum cover is NP-hard
  - Cannot be finished in polynomial time
- Heuristic method: provide irredundant covers with reasonably small cardinality
  - Fast and applicable to most functions
- Key idea: avoid generation of all prime implicants
  - Given initial cover
  - Make it prime
  - Make it irredundant
- Iterative improvement by modifying the implicants



# Logic Minimizer -- ESPRESSO

- “ESPRESSO” developed by UC Berkeley
  - The kernel of existing synthesis tools
- EXPAND:
  - A minterm of  $ON(f)$  is selected, and expanded until it becomes a prime implicant
  - Make implicants prime
- IRREDUNDANT COVER:
  - The prime implicant is put in the final cover, and all minterms covered by this prime implicant are removed
  - Make cover irredundant
- REDUCE:
  - Reduce size of each implicant while preserving cover
- Iteratively find alternative covers
  - Repeat the 3 steps to find the solutions with lower costs

## ESPRESSO - Illustrated



## Pseudo Code of ESPRESSO

```
espresso (F, D)    /* F = ON_SET , D = DC_SET */
{
  R = complement (F + D);    /* R = OFF_SET */
  F = expand (F, R);          /* initial expansion */
  F = irredundant_cover (F, D); /* initial irredundant cover */
  E = essential_primes (F, D); /* extract essential primes */
  C = F - E;
  D = D + E;
  repeat {
    C = reduce (C, D);
    C = expand (C, R);
    C = irredundant_cover (C, D);
  } until (C unchanged);
  return C + E ;
}
```



## Expand (1/3)

- Increase the size of each implicant
  - Implicants of smaller size can be covered and deleted
  - Maximally expanded implicants are primes
  - Raising one ( or more ) of its 0s to 1
- Validity checking
  - Checking for an intersection of the expanded implicant with  $F^{OFF}$
- Two factors affect the quality and the efficiency of the algorithm
  - The order in which the implicants are selected
  - The order in which the 0 entries are raised to 1



## Expand (2/3)

- Heuristic on the order of implicants
  - Compute column count vector (number of '1' in each column)
  - The weight of each cube is the inner product of itself and the column count vector
  - Sort implicants in **ascending** order of weight
    - Low weight correlates to having few 1s in the columns
    - **Expand first those cubes that are unlikely to be covered**
- Ex:  $f = a'b'c' + ab'c' + a'bc' + a'b'c$ ; don't care :  $abc'$

choose lowest weight →

**F<sub>ON</sub>:**

10	10	10
01	10	10
10	01	10
10	10	01

column count →

31	31	31
----	----	----

**F<sub>DC</sub>:**

01	01	10
01	11	01
11	01	01

**F<sub>OFF</sub>:**

Column count vector =  $[313131]^T$

Weight of the implicants =  $(9,7,7,7)$

Ex: 2<sup>nd</sup> implicant of F<sub>ON</sub>

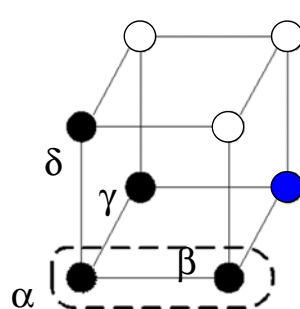
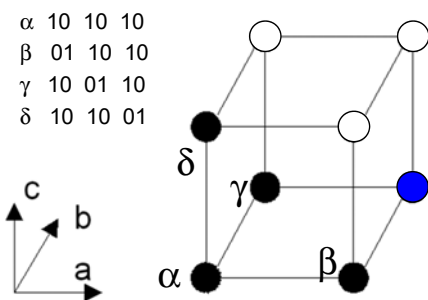
01	10	10
x) 31	31	31
01	30	30

2<sup>nd</sup> weight =  $0+1+3+0+3+0 = 7$



## Expand (3/3)

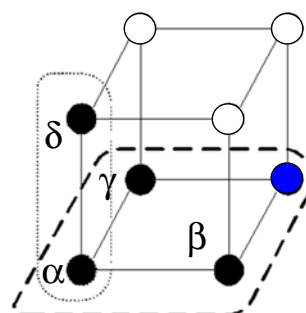
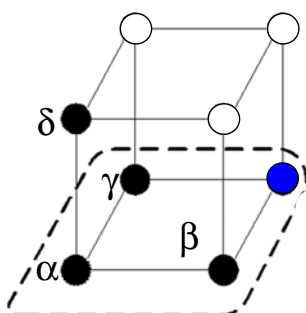
α 10 10 10  
β 01 10 10  
γ 10 01 10  
δ 10 10 01



01 10 10 → 11 10 10 **OK**  
11 10 10 → 11 11 10 **OK**  
11 11 10 → 11 11 11 **X**

F updated to :

11	11	10
10	10	01



10 10 01 → 11 10 01 **X**  
10 10 01 → 10 11 01 **X**  
10 10 01 → 10 10 11 **OK**

Expanded cover :

11	11	10
10	10	11



## Reduce (1/2)

- Decrease the size of each implicant of a given cover F  
→ successive expansion may lead to smaller cover
  - A reduced implicant is valid when, along with the remaining implicants, it still covers the function
  - The reduced cover has the same cardinality as the original one
- Let  $\alpha \in F$  be an implicant and  $Q = F \cup F^{DC} - \{\alpha\}$ 
  - The maximally reduced cube is  
 $\alpha'' = \alpha \cap \text{supercube}(Q_{\alpha}') \quad // \text{ the part not covered by other implicants}$
- $\alpha \# Q = \alpha \cap Q'$  can yield a set of cubes  
 $\alpha'' = \alpha \cap \text{supercube}(Q')$   
 $= \alpha \cap \text{supercube}((\alpha \cap Q_{\alpha}') \cup (\alpha' \cap Q_{\alpha}'))$   
 $= \alpha \cap \text{supercube}(Q_{\alpha}')$



## Reduce (2/2)

- Sorting the implicants
  - Weight the implicants as for the Expand operator
  - Sort implicants in **descending** order of weight
    - First process those that overlap many other implicants
    - Lower as many \* as possible to 1 or 0
- Replacing each implicant by the maximally reduced one

F:  $\alpha$  11 11 10

$\beta$  10 10 11

column count vector = [212121]<sup>T</sup>

weight vector = [8,7]

Reduce  $\alpha$  first → fail

Reduce  $\beta$ :

$$Q = F \cup F^{DC} - \{\beta\} = \{\alpha, \beta\} - \{\beta\}$$

$$= 11 \ 11 \ 10 \quad // \text{ only } \alpha \text{ is left}$$

$$Q' = 11 \ 11 \ 01, \quad Q_{\beta}' = Q'$$

$$\text{supercube}(Q_{\beta}') = Q' \quad // \text{ not in } Q$$

$$\beta'' = \beta \cap Q' = 10 \ 10 \ 01$$

Reduced cover is

11 11 10

10 10 **01**

$\beta'' \rightarrow$  In  $\beta$  but not in Q



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- Synthesis overview
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## Multi-Level Logic Optimization

- Level: maximum number of gates cascaded in series between the inputs and outputs of a network
  - Can be considered as an indication for worst-case delay
  - Assume all variables and their complements are available
- Two-level networks have the least depth, not least area
  - It's possible to further reduce the number of gates by increasing the logic levels and reusing existing logic gates
    - Common factors or kernel extraction
    - Common expression resubstitution

- Example:

$$\begin{aligned} f1 &= abcd + abce + \bar{a}\bar{b}cd + \bar{a}\bar{b}cd + \bar{a}c + cdf + \bar{a}\bar{b}cde + \bar{a}\bar{b}cdf \\ f2 &= bdg + \bar{b}dfg + \bar{b}dg + \bar{b}deg \end{aligned}$$



$$f1 = c(\bar{a} + x) + \bar{a}\bar{c}\bar{x}$$

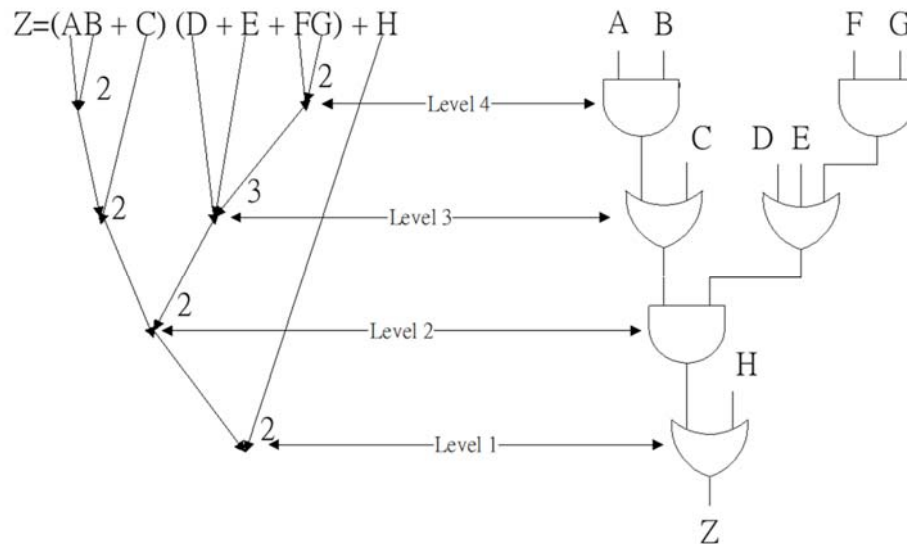
$$f2 = gx$$

$$x = d(b + f) + \bar{d}(\bar{b} + e)$$



## Multi-Level Logic

- Multi-level logic:
  - A set of logic equations with no cyclic dependencies
- Example:  $Z = (AB + C)(D + E + FG) + H$ 
  - 4-level, 6 gates, 13 gate inputs



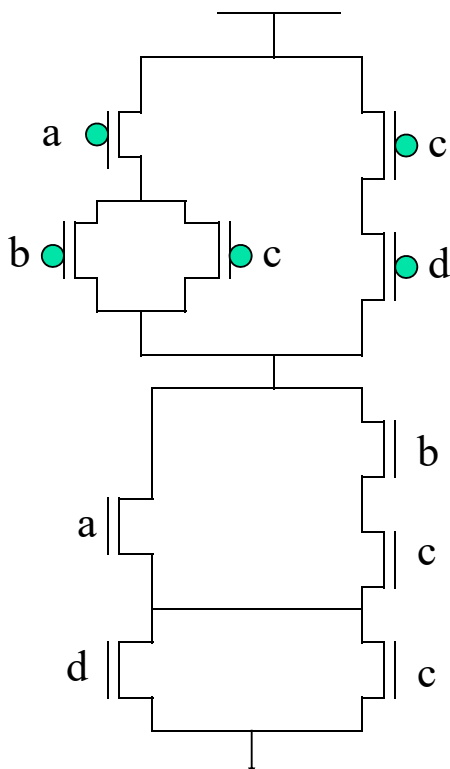
## Multi-Level v.s. Two-Level

- |  |  |
|--|--|
| <ul style="list-style-type: none"> <li>• Two-level:           <ul style="list-style-type: none"> <li>– Often used in control logic design</li> <li>– <math>f_1 = x_1x_2 + x_1x_3 + x_1x_4</math></li> <li>– <math>f_2 = x_1'x_2 + x_1'x_3 + x_1x_4</math></li> <li>– Only <math>x_1x_4</math> shared</li> <li>– Sharing restricted to common cube</li> </ul> </li> </ul> | <ul style="list-style-type: none"> <li>• Multi-level:           <ul style="list-style-type: none"> <li>– Datapath or control logic design</li> <li>– Can share <math>x_2 + x_3</math> between the two expressions</li> <li>– Can use complex gates</li> <li>– <math>g_1 = x_2 + x_3</math></li> <li>– <math>g_2 = x_1x_4</math></li> <li>– <math>f_1 = x_1y_1 + y_2</math></li> <li>– <math>f_2 = x_1'y_1 + y_2</math></li> <li>– (<math>y_i</math> is the output of gate <math>g_i</math>)</li> </ul> </li> </ul> |
|--|--|

## Factored Forms (1/2)

- A *factored form* is defined recursively by the following rules:
  - A literal is a factored form
  - A sum of two factored form is a factored form
  - A product of two factored forms is a factor form
- A factored form describes an implementation of the function as a complex gate
  - Any depth of sum-of-product
- Ex: a  
a'  
ab'c  
ab + c'd  
(a + b)(c + a' + de) + f

## Factored Forms (2/2)



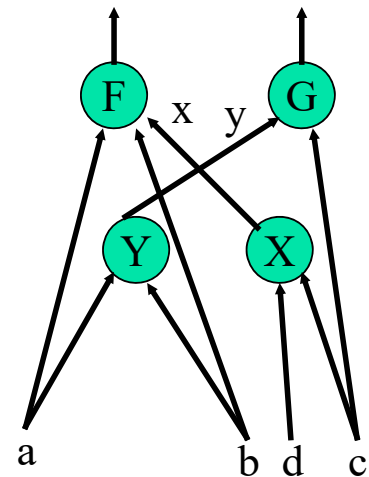
- A CMOS complex gate implementing  $f = ((a + bc)(c + d))'$   
 $2 \times \text{literal count} = \# \text{ transistors}$
- Adv:
  - Nature multi-level representation
  - Good estimate of the complexity of function
  - Represent both the function and its complement
- Disadv:
  - More difficult to manipulate than two-level form
  - Lack of the notion of optimality



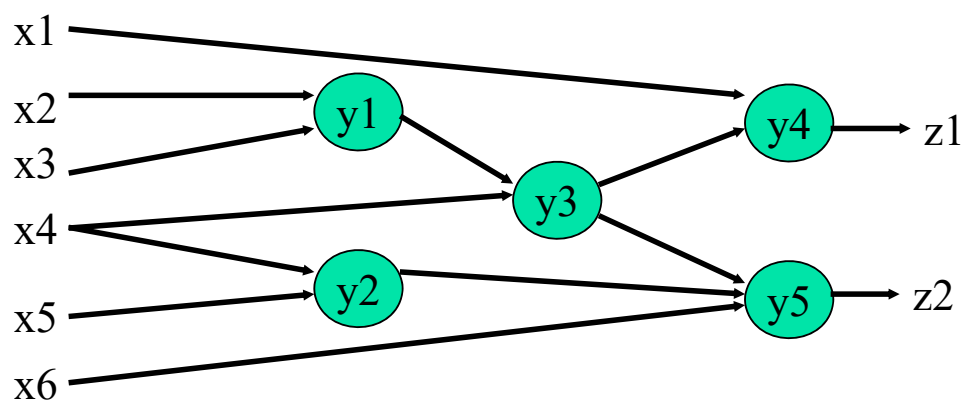
## Boolean Network

- Directed acyclic graph (DAG)
- Each source node is a primary input
- Each sink node is a primary output
- Each internal node represents an equation
- Arcs represent variable dependencies

fanin of y : a, b  
fanout of x : F



## Boolean Network : An Example



$$y1 = f_1(x2, x3) = x2' + x3'$$

$$y2 = f_2(x4, x5) = x4' + x5'$$

$$y3 = f_3(x4, y1) = x4'y1'$$

$$y4 = f_4(x1, y3) = x1 + y3'$$

$$y5 = f_5(x6, y2, y3) = x6y2 + x6'y3'$$



## Multi-Level Logic Optimization

- Technology independent
- Decomposition/Restructuring
  - Algebraic
  - Functional
- Node optimization
  - Two-level logic optimization techniques are used



## Decomposition / Restructuring

- Goal : given initial network, find best network
- Two problems:
  - Find good **common subfunctions**
  - How to perform **division**
- Example:

$$f_1 = abcd + abce + ab'cd' + ab'c'd' + a'c + cdf + abc'd'e' + ab'c'df'$$

$$f_2 = bdg + b'dfg + b'd'g + bd'eg$$

**minimize** (in sum-of-products form):

$$f_1 = bcd + bce + b'd' + b'f + a'c + abc'd'e' + ab'c'df'$$

$$f_2 = bdg + dfg + b'd'g + d'eg$$

**decompose:**

$$f_1 = c(a' + x) + ac'x' \quad x = d(b + d) + d'(b' + e)$$

$$f_2 = gx$$

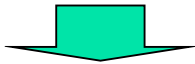


## Basic Operations (1/2)

### 1. decomposition

(single function)

$$f = abc + abd + a'c'd' + b'c'd'$$



$$f = xy + x'y'$$

$$x = ab$$

$$y = c + d$$

### 2. extraction

(multiple functions)

$$f = (az + bz')cd + e$$

$$g = (az + bz')e'$$

$$h = cde$$



$$f = xy + e$$

$$g = xe'$$

$$h = ye$$

$$x = az + bz'$$

$$y = cd$$

## Basic Operations (2/2)

### 3. factoring

(series-parallel decomposition)

$$f = ac + ad + bc + bd + e$$



$$f = (a + b)(c + d) + e$$

### 4. substitution

(with complement)

$$g = a + b$$

$$f = a + bc + b'c'$$



$$f = g(a + c) + g'c'$$

### 5. elimination

$$f = ga + g'b$$

$$g = c + d$$



$$f = ac + ad + bc'd'$$

$$g = c + d$$

**“Division” plays  
a key role !!**

## Division

- Division:  $p$  is a Boolean divisor of  $f$  if  $q \neq \phi$  and  $r$  exist such that  $f = pq + r$ 
  - $p$  is said to be a factor of  $f$  if in addition  $r = \phi$ :
$$f = pq$$
  - $q$  is called the **quotient**
  - $r$  is called the **remainder**
  - $q$  and  $r$  are **not unique**
- **Weak division**: the unique algebraic division such that  $r$  has as few cubes as possible
  - The quotient  $q$  resulting from weak division is denoted by  $f / p$  (it is **unique**)

## Weak Division Algorithm (1/2)

Weak\_div( $f, p$ ):

$U =$  Set  $\{u_j\}$  of cubes in  $f$  with literals not in  $p$  deleted

$V =$  Set  $\{v_j\}$  of cubes in  $f$  with literals in  $p$  deleted

/\* note that  $u_j.v_j$  is the  $j$ -th cube of  $f$  \*/

$V^i = \{v_j \in V : u_j = p_i\}$

$q = \cap V^i$

$r = f - pq$

return( $q, r$ )

## Weak Division Algorithm (2/2)

- Example

common expressions

$$f = acg + adg + ae + bc + bd + be + a'b$$

$$p = ag + b$$

$$U = ag + ag + a + b + b + b + b$$

$$V = c + d + e + c + d + e + a'$$

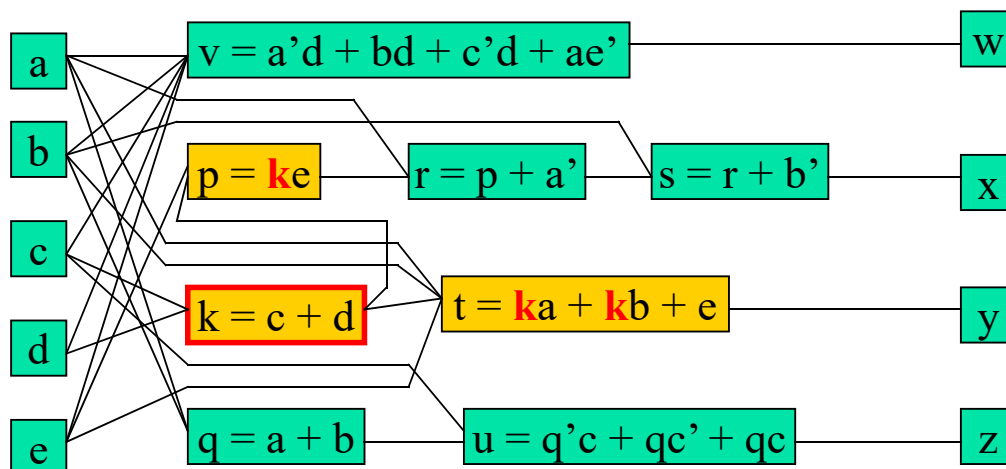
$$V^{ag} = c + d$$

$$V^b = c + d + e + a'$$

$$q = c + d = f/p$$

## Algebraic Substitution (1/3)

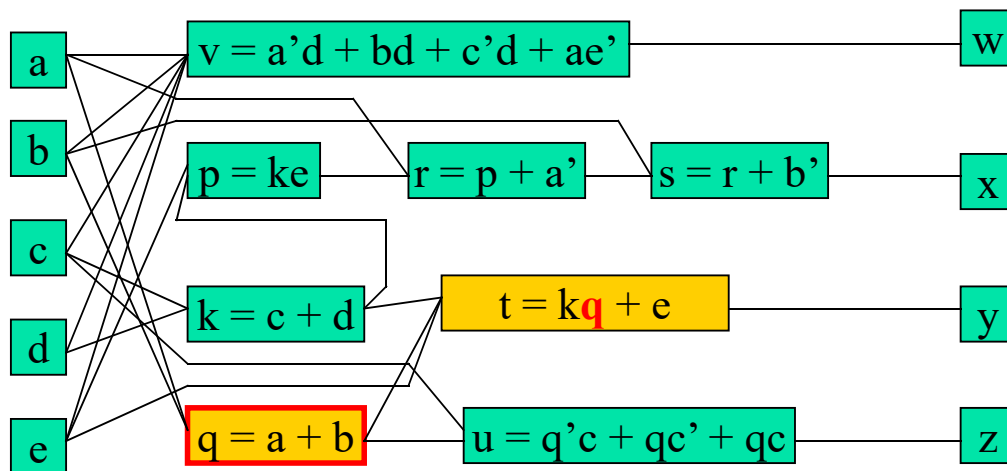
- Idea: An existing node in a network may be a useful divisor in another node.



$$f_t = ka + kb + e$$

$$f_q = a + b$$

## Algebraic Substitution (2/3)



$$f_t = kq + e$$

## Algebraic Substitution (3/3)

- Consist of the process of dividing the function  $f_i$  at node  $i$  in the network by the function  $f_j$  (or by  $f_j'$ ) pairwise
- During substitution,  $f_i$  is transformed into
 
$$f_i = (f_i/f_j)y_j + (f_i/f_j')y_j' + r$$
 if  $f_i/f_j$  and/or  $f_i/f_j'$  are not null
- No need to try all pairs. The cases where  $f_j$  is not an algebraic divisor of  $f_i$  can be excluded
  - $f_j$  contains a literal not in  $f_i$
  - $f_j$  contains more terms than  $f_i$
  - for any literal, the count in  $f_j$  exceeds that in  $f_i$
  - $f_i$  is  $f_j$ 's transitive fanin (cycle)

## Algebraic Divisor

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- Example:

$$X = (a + b + c)de + f$$

$$Y = (b + c + d)g + aef$$

$$Z = aeg + bc$$

- Single-cube divisor:  $ae$
- Multiple-cube divisor:  $b + c$
- Extraction of **common sub-expression** is a global area optimization effort



## Kernels and Kernel Intersections

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- An expression is **cube-free** if no cube divides the expression evenly
  - e.g.,  $ab + c$  is cube-free;  $ab + ac$  and  $abc$  are not cube-free
  - A cube-free expression must have more than one cube
- The **primary divisors** of an expression  $f$  are the set of expressions

$$D(f) = \{f/c \mid c \text{ is a cube}\}$$

- The **kernels** of an expression  $f$  are the set of expressions
$$K(f) = \{g \mid g \in D(f) \text{ and } g \text{ is cube free}\}$$



## Co-Kernels

- A cube  $c$  used to obtain the kernel  $k = f/c$  is called a **co-kernel** of  $k$ 
  - $C(f)$  is used to denote the set of co-kernels of  $f$
- Example

$$x = adf + aef + bdf + bef + cdf + cef + g$$

$$= (a + b + c)(d + e)f + g$$

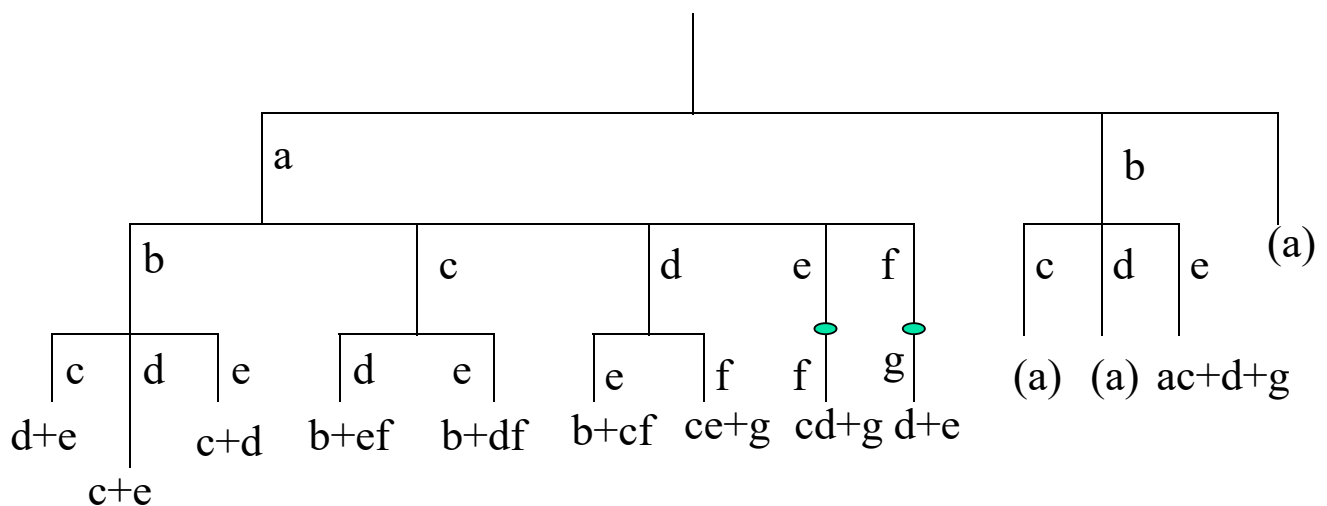
Kernel	Co-kernel
$a + b + c$	$df, ef$
$d + e$	$af, bf, cf$
$(a + b + c)(d + e)f + g$	1

- Kernels and co-kernels can help to find common divisors between expressions



## Kerneling Illustrated

$$abcd + abce + adfg + aefg + adbe + acdef + beg$$





## Cube-Literal Matrix & Rectangles (1/2)

- Cube-literal matrix
  - Each matrix element indicates if this literal appears in the cube
- Ex:  $f = x_1x_2x_3x_4x_7 + x_1x_2x_3x_4x_8 + x_1x_2x_3x_5 + x_1x_2x_3x_6 + x_1x_2x_9$

	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	$x_8$	$x_9$
$x_1x_2x_3x_4x_7$	1	1	1	1	0	0	1	0	0
$x_1x_2x_3x_4x_8$	1	1	1	1	0	0	0	1	0
$x_1x_2x_3x_5$	1	1	1	0	1	0	0	0	0
$x_1x_2x_3x_6$	1	1	1	0	0	1	0	0	0
$x_1x_2x_9$	1	1	0	0	0	0	0	0	1



## Cube-Literal Matrix & Rectangles (2/2)

- A **rectangle** (R, C) of a matrix A is a subset of rows R and columns C such that

$$A_{ij} = 1 \forall i \in R, j \in C$$

- Rows and columns need not be continuous
- A **prime rectangle** is a rectangle not contained in any other rectangle
  - A prime rectangle indicates a co-kernel kernel pair

- Example:

$$R = \{\{1, 2, 3, 4\}, \{1, 2, 3\}\}$$

- co-kernel:  $x_1x_2x_3$
- kernel:  $x_4x_7 + x_4x_8 + x_5 + x_6$

	$x_1$	$x_2$	$x_3$	$x_4$
$x_1x_2x_3x_4x_7$	1	1	1	1
$x_1x_2x_3x_4x_8$	1	1	1	1
$x_1x_2x_3x_5$	1	1	1	0
$x_1x_2x_3x_6$	1	1	1	0
$x_1x_2x_9$	1	1	0	0



## Rectangles and Logic Synthesis

- Kernels  $\Leftrightarrow$  prime rectangles of the cube-literal matrix
- Optimum selection of kernels  $\Leftrightarrow$  **rectangle covering**
  - Kernel intersection  $\Leftrightarrow$  finding rectangles

- Ex: single cube extraction

$$F = abc + abd + eg$$

$$G = abfg$$

$$H = bd + ef$$

$$(\{1,2,4\},\{1,2\}) \Leftrightarrow ab$$

$$(\{2,5\},\{2,4\}) \Leftrightarrow bd$$

$$F = Xc + XY + eg, \quad X = ab$$

$$G = Xfg, \quad Y = bd$$

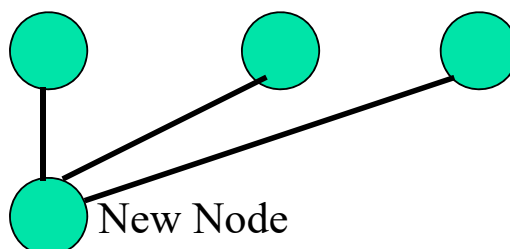
$$H = Y + ef$$

		<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
		1	2	3	4	5	6	7
<i>abc</i>	1	1	1	1	0	0	0	0
<i>abd</i>	2	1	1	0	1	0	0	0
<i>eg</i>	3	0	0	0	0	1	0	1
<i>abfg</i>	4	1	1	0	0	0	1	1
<i>bd</i>	5	0	1	0	1	0	0	0
<i>ef</i>	6	0	0	0	0	1	1	0



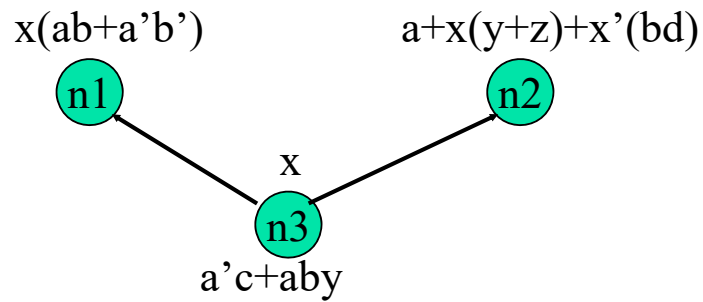
## Kernel Extraction (1/2)

- 1. Find all kernels of all functions
- 2. Choose one with best "value"
- 3. Create new node with this as function
- 4. Algebraically substitute new node everywhere
- Repeat 1,2,3,4 until best value  $\leq$  threshold

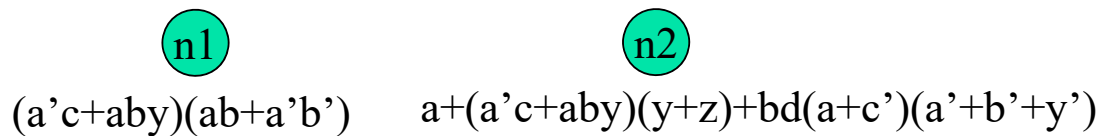


## Kernel Extraction (2/2)

- After



- Before



Literals after = 5+7+5=17      Literals before = 9+15 = 24  
 before – after = value = 7

## Example – Decomposition (1/2)

Original:  $f_1 = ab(c(d + e) + f + g) + h$  (literal = 8+8 = 16)  
 $f_2 = ai(c(d + e) + f + j) + k$

Kernel extraction: (literal = 2+7+7 = 16)

$$K^0(f_1) = K^0(f_2) = \{d + e\}$$

$$l = d + e$$



$$f_1 = ab(cl + f + g) + h$$

$$f_2 = ai(cl + f + j) + k$$

Kernel extraction: (literal = 2+3+5+5 = 15)

$$K^0(f_1) = \{cl + f + g\}$$

$$K^0(f_2) = \{cl + f + j\}$$

$$K^0(f_1) \cap K^0(f_2) = cl + f$$



$$m = cl + f$$

$$f_1 = ab(m + g) + h$$

$$f_2 = ai(m + j) + k$$

Cube extraction: (literal = 2+3+2+5+5 = 17)

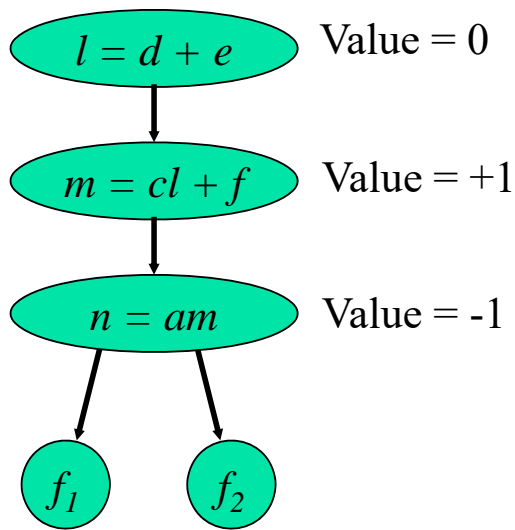
$$n = am$$



$$f_1 = b(n + ag) + h$$

$$f_2 = i(n + aj) + k$$

## Example – Decomposition (2/2)



- Eliminate -1

$$n = a(c(d + e) + f)$$

$$f_1 = b(n + ag) + h$$

$$f_2 = i(n + aj) + k$$

merge 3 levels  
together

