### Lab Practice

#### 1. Harris corner detector

Harris operator is a simple point feature extraction operator. The matrix M, inspired by autocorrelation function in signal processing, associated with autocorrelation function which is given. The eigenvalue of the M-matrix is the first-order curvature of the autocorrelation function. If both curvature values are high, the point is considered to be the eigenpoint. In order to eliminate the influence of noise on corner detection, a Gaussian filter can be used to smooth the image.

## Create a new Harris. Py file

(1) Used to calculate the response function of the corner detector:

```
from scipy.ndimage import filters
from numpy import *
from pylab import *
def compute_harris_response(im,sigma=3):

#计算导数
imx=zeros(im.shape)
filters.gaussian_filter(im,(sigma,sigma),(0,1),imx)
imy=zeros(im.shape)
filters.gaussian_filter(im,(sigma,sigma),(1,0),imy)
Wxx=filters.gaussian_filter(imx*imx,sigma)

#计算harris矩阵分里
Wxy=filters.gaussian_filter(imx*imy,sigma)
Wyy=filters.gaussian_filter(imy*imy,sigma)
#计算矩阵的特征值和迹
Wdet=Wxx*Wyy-Wxy**2
Wtr=Wxx+Wyy
return Wdet/Wtr
```

(2) To obtain the descending order of the response values of all candidate pixel points and corner points (min\_dist=6,threshold=0.1):

(3) Display the corner points in the image:

```
def plot_harris_points(image,filtered_coords):
    """绘制图像中检测到的角点"""

figure()
    gray()
    imshow(image)
    plot([p[1] for p in filtered_coords],[p[0]for p in filtered_coords],'+')
    axis('off')
    show()
```

# In the same directory as Harris.py, create a new practice.py file

(4) Call the established function and run the following command:

```
from PIL import Image
from numpy import *
import harris
from pylab import *
from scipy.ndimage import filters

im=array(Image.open('a.jpg').convert('L'))
harrisim=harris.compute_harris_response(im)
filtered_coords=harris.get_harris_points(harrisim)
harris.plot_harris_points(im,filtered_coords)
```

(5) Examples are shown below:



## 2. Call Harris corner detector in the PCV module

(1) Steps to install the PCV module library:

https://blog.csdn.net/weixin 42578378/article/details/88617207

(2) Use the Harris corner detector to detect corners (min dist=6,threshold=[0.01,0.5,0.1]):

```
from pylab import *
from PTL import Image
from PCV.localdescriptors import harris

# 读入图像
im = array(Image.open('a.jpg').convert('L'))

# 检测harris角点
harrisim = harris.compute_harris_response(im)

# Harris响应函数
harrisim1 = 255 - harrisim

figure()
gray()

# 圖出Harris响应图

subplot(221)
imshow(harrisim1)
print (harrisim1.shape)
axis('off')
axis('equal')

threshold = [0.01, 0.05, 0.1]
for i, thres in enumerate(threshold):
    filtered_coords = harris.get_harris_points(harrisim, 6, thres)
    subplot(2, 2, i + 2)
    imshow(im)
    print( im.shape)
    plot([p[1] for p in filtered_coords], [p[0] for p in filtered_coords], '*')
    axis('off')

show()
```

(3) Examples are shown below:

