GR notes

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Conventions

- 1. Greek index (e.g. α, β, μ, ν) take value from $\{0, 1, 2, 3\}$.
- 2. $(x^0, x^1, x^2, x^3) \equiv (t, x, y, z) \equiv x^{\alpha}$.
- 3. Latin index (e.g.i, j, k) take value from $\{1, 2, 3\}$.
- 4. Natural units (c = 1).
- 5. Einstein summation convention $ds^2 = g_{\mu\nu}x^{\mu}x^{\nu} = \sum_{\mu=0}^{3} \sum_{\nu=0}^{3} g_{\mu\nu}x^{\mu}x^{\nu}$.
- 6. Metric sign (-, +, +, +).

1 Differential Geometry

1.1 Manifolds

Mathematically, specetime is a **manifold**.

Definition 1.1. An n-dimensional manifold is a set that can be parameterized continuously by n independent real coordinates for each point. If a manifold is differentiable at each point, it is a **differentiable manifold**.

Definition 1.2. A coordinate system (also called chart) is n labels uniquely with each point of an n-dimensional manifold through a one-to-one mapping from \mathbb{R}^n to M. Generally, more than one charts are required to cover entire manifold, which called **atlas**.

Definition 1.3. Cartesian product $X \times Y$ is set of all possible ordered pairs of element which one from X and one from Y.

Subset of points within a manifold form curves and surfaces. Our spacetime is a 4-dimensianl **pseudo-Riemannian manifold** which is a differentiable manifold with some additional structures.

Remark. Manifolds also have a important property which a n-dimensional manifold locally **homeomorphism** to \mathbb{R}^n . See the discussion of topology for definition of homeomorphism. Basically this mean a small enough region on manifold is looks same as flat space. For example, surface of the Earth is a 2-sphere S^2 , but look at the ground around you, it seems flat.

1.1.1 Maps Between Manifolds

pullback pushforward

1.2 Tensor

Tensor is a quantity that have same form in all coordinate system. Tensor does not have components naturally, but when we choose specific coordinate system, we can write down its components. Tensor have **Covariance**, which mean it follow a specific transformation law.

1.2.1 Tensor Notation

1.3 Connection

Connection is an additional structure inposed into manifold. There is no naturally defined connection between tangent space at each point on a manifold, so we can define this additional structure. The manifold equip with a flat, torsion-free connection is called **affine manifold**.

Proof. Here is a proof shows that connection not a tensor by show connection does not obey tensor transformation law.

$$\begin{split} \nabla_{\beta'} e_{\alpha'} &= \Gamma_{\alpha'\beta'}^{\gamma'} e_{\gamma'} \\ &= \frac{\partial x^{\beta}}{\partial x^{\beta'}} \nabla_{\beta} (\frac{\partial x^{\alpha}}{\partial x^{\alpha'}} e_{\alpha}) \\ &= \frac{\partial x^{\beta}}{\partial x^{\beta'}} (\frac{\partial}{\partial x^{\beta}} \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} e_{\alpha} + \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} \Gamma_{\alpha\beta}^{\gamma} e_{\gamma}) \\ &= \frac{\partial x^{\beta}}{\partial x^{\beta'}} \frac{\partial}{\partial x^{\beta}} \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} e_{\alpha} + \frac{\partial x^{\beta}}{\partial x^{\beta'}} \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} \Gamma_{\alpha\beta}^{\gamma} e_{\gamma} \\ &= \frac{\partial x^{\beta}}{\partial x^{\beta'}} \frac{\partial}{\partial x^{\beta}} \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} \frac{\partial x^{\gamma'}}{\partial x^{\alpha'}} e_{\gamma'} + \frac{\partial x^{\beta}}{\partial x^{\beta'}} \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} \frac{\partial x^{\gamma'}}{\partial x^{\gamma'}} \Gamma_{\alpha\beta}^{\gamma} e_{\gamma'} \end{split}$$

which yield

$$\Gamma^{\gamma'}_{\alpha'\beta'} = \frac{\partial x^{\beta}}{\partial x^{\beta'}} \frac{\partial}{\partial x^{\beta}} \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} \frac{\partial x^{\gamma'}}{\partial x^{\alpha}} + \frac{\partial x^{\beta}}{\partial x^{\beta'}} \frac{\partial x^{\alpha}}{\partial x^{\alpha'}} \frac{\partial x^{\gamma'}}{\partial x^{\gamma}} \Gamma^{\gamma}_{\alpha\beta}$$
There is an extra term in transformation of connection, so connection is not a tensor.

- **Geodesics**
- 1.5 Riemann Tensor

Gravitation

- 2.1 Equivalence Principle
- 2.2 General Covariance Principle
- 2.3 Einstein's Equation

Black Holes 3

- 3.1 Schwarzschild
- 3.2 Kerr

Gravitational Radiation

Linearized Gravity

When the gravitational field are weak, the metric take following form:

$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$$

which we treat the gravitational field as a perturbation of flat spacetime metric.

Effect of GW on matter

5 Cosmology

A Special Relativity

A.1 Spacetime

Definition A.1. Inertial coordinate

The coordinate system must satisfy three property to be consider inertial coordinat:

- 1. The distance between two points are independent of time.
- 2. The clocks at every points ticking off time coordinate t at same rate.
- 3. The geometry of space is always flat.

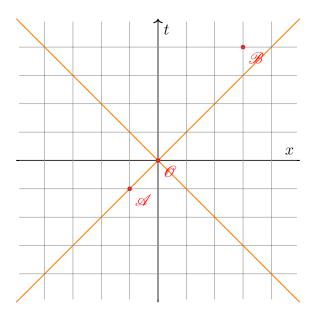


Figure 1: two events with coordinate (-1, -1, 0, 0) and (4, 3, 0, 0). Orange line is light's worldline.

The event in 4-D spacetime is defined by a set of coordinate (t, x, y, z). For simplicity, we assume those events have y = 0, z = 0 so that we can draw a 2D graph to represent them.

Analog to Euclidean geometry, just like the euclidean distance $\Delta l^2 = \Delta x^2 + \Delta y^2 + \Delta z^2$, we define the spacetime interval $\Delta s^2 = -\Delta t^2 + \Delta x^2 + \Delta y^2 + \Delta z^2$.

Remark. There are a lot different conventions to define the sign of interval, here we just use the popular one (-,+,+,+).

Example.

Interval for the two events in Figure 1 is $\Delta s^2 = -\Delta t^2 + \Delta x^2 + \Delta y^2 + \Delta z^2 = -9$.

The universality speed of light means that $\frac{\Delta r}{\Delta t} = \frac{\sqrt{\Delta x^2 + \Delta y^2 + \Delta z^2}}{\Delta t} = 1$ are always hold, then we can then write the interval $\Delta s^2 = -\Delta t^2 + \Delta x^2 + \Delta y^2 + \Delta z^2 = 0$. This experimental fact yield all laws of special relativity.

When the interval Δs^2 is less than 0, we call the separation bewteen events is **timelike**; When the interval Δs^2 is equal to 0, we call it **lightlike** or null; When the interval Δs^2 is greater than 0, we call it **spacelike**.

- A.2 Energy and Momentum
- A.3 Fluid

B Topological Space

C Property for some tensors

$$F_{\mu\nu} = -F_{\nu\mu}$$

$$T_{ij} = T_{ji}$$

$$g_{\mu\nu} = g_{\nu\mu}$$

$$\Gamma^{\lambda}_{\mu\nu} = \Gamma^{\lambda}_{\nu\mu} \text{ (Torsion free)}$$

$$R_{\alpha\beta\mu\nu} = -R_{\beta\alpha\mu\nu}$$

$$R_{\alpha\beta\mu\nu} = -R_{\alpha\beta\nu\mu}$$

$$R_{\alpha\beta\mu\nu} = R_{\mu\nu\alpha\beta}$$

$$R_{\alpha\beta\mu\nu} + R_{\alpha\nu\beta\mu} + R_{\alpha\mu\nu\beta} = 0$$

$$R_{\alpha\beta} = R_{\beta\alpha}$$