

CS685 Homework 7

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1. The measurements has zero-mean Gaussian noise, and the range and the bearing measurements are independent of each other.

$$\begin{aligned} P(z|x, l) &= P(z_r|x, l)P(z_\theta|x, l) \\ &= \frac{1}{\sigma_r\sqrt{2\pi}}e^{-\frac{(z_r-||l-x||)^2}{2\sigma_r^2}} \cdot \frac{1}{\sigma_\theta\sqrt{2\pi}}e^{-\frac{(z_\theta-\theta)^2}{2\sigma_\theta^2}} \end{aligned}$$

where $||l - x||$ is the distance between x and l and θ is the angle between x and l .

2. (a) My friend is more likely to be on campus.

To calculate which place my friend is more like to be is to compare $P(p_0|d, x)$ and $P(p_1|d, x)$ which is larger. According to Baye's rule, we have

$$P(p|d, x) = \frac{P(d|p, x)P(p|x)}{P(d|x)}$$

where

$$\begin{aligned} P(d|p, x) &= P(d_0|p, x_1)P(d_1|p, x_0) \\ &= \frac{1}{\sigma_0\sqrt{2\pi}}e^{-\frac{(d_0-||p-x_0||)^2}{2\sigma_0^2}} \cdot \frac{1}{\sigma_1\sqrt{2\pi}}e^{-\frac{(d_1-||p-x_1||)^2}{2\sigma_1^2}} \\ &= \frac{1}{\sqrt{2\pi}}e^{-\frac{(3.9-||p-x_0||)^2}{2}} \cdot \frac{1}{\sqrt{3\pi}}e^{-\frac{(4.5-||p-x_1||)^2}{3}} \end{aligned}$$

because distance measurements are independent of each other, and disturbed by zero-mean Gaussian noise.

We have

$$\begin{aligned} ||p_0 - x_0|| &= \sqrt{(10 - 12)^2 + (8 - 4)^2} = \sqrt{20} \\ ||p_0 - x_1|| &= \sqrt{(10 - 5)^2 + (8 - 7)^2} = \sqrt{26} \\ ||p_1 - x_0|| &= \sqrt{(6 - 12)^2 + (3 - 4)^2} = \sqrt{37} \\ ||p_1 - x_1|| &= \sqrt{(6 - 5)^2 + (3 - 7)^2} = \sqrt{17} \end{aligned}$$

So,

$$P(d|p_0, x) = 0.0979$$

$$P(d|p_1, x) = 0.0114$$

Also, because we have no prior knowledge.

$$P(p_0|x) = P(p_1|x) = 0.5$$

Subsequently,

$$P(p_0|d, x) = \alpha P(d|p_0, x)P(p_0|x) = 0.0489\alpha$$

$$P(p_1|d, x) = \alpha P(d|p_1, x)P(p_1|x) = 0.0057\alpha$$

(b) If we have prior knowledge that

$$P(p_0|x) = 0.3$$

$$P(p_1|x) = 0.7$$

Then

$$P(p_0|d, x) = \alpha P(d|p_0, x)P(p_0|x) = 0.0294\alpha$$

$$P(p_1|d, x) = \alpha P(d|p_1, x)P(p_1|x) = 0.0080\alpha$$

My friend is still more likely to be on campus.

3. Shown in Fig. 1.

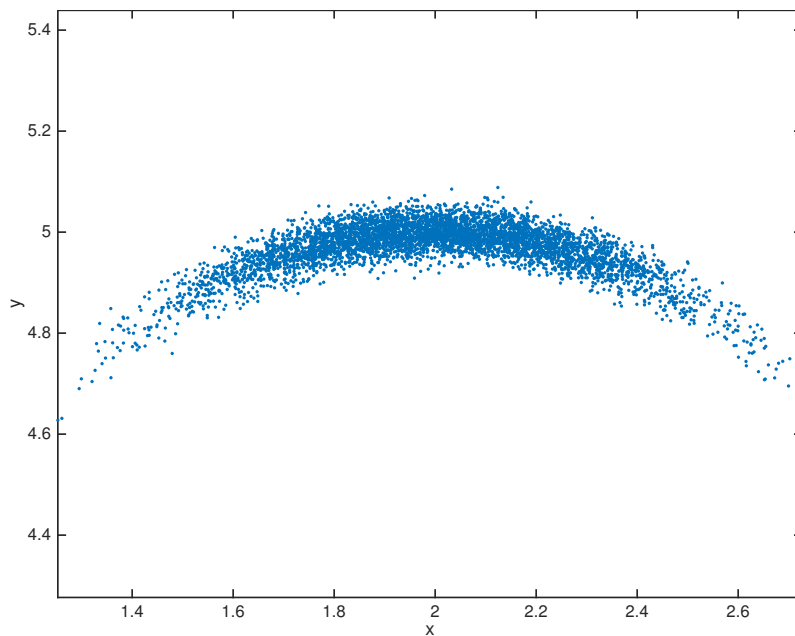


Figure 1: Motion model in 5000 runs.