

Tissue Transplantation Experiments: Inference and other Problems

Yue Wang

Department of Computational Medicine,
University of California, Los Angeles

Experiments

- Tissue transplantation experiments.
- Take one piece of one tissue, and graft it to another tissue.
- Observe how the grafted tissue behaves.

- To simplify the problem, we consider a rough classification of results:
- The grafted tissue develops normally.
- The grafted tissue develops abnormally.

Experiments

- Species: *Xenopus laevis* (African clawed frog).
- Donor: Upper lateral lip (development stage 11).
- Host: Lower lip (development stage 11).
- Result: Normal. The transplanted tissue will develop normally as if it was the host tissue.

Experiments

How to infer the unknown experimental results?

		Donor						
		AM19	PM19	PM15	UL11	LL11	LL15	LL19
Host	AM19	?	N	A	A	A	A	N
	PM19	?	N	?	N	N	?	?
	PM15	?	?	?	?	?	?	?
	UL11	?	N	?	N	N	?	?
	LL11	?	N	?	N	N	?	?
	LL15	?	?	?	?	?	?	?
		LL19	?	?	?	?	?	?

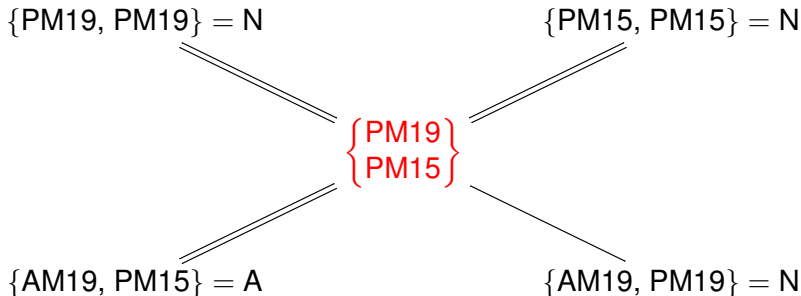
Table: Results reported by Krneta-Stankic et al. 2010

N=normal; A=abnormal. AM=anterior paraxial mesoderm;
PM=presomitic mesoderm; UL=upper lateral lip; LL=lower lip;
Number=developmental stage.

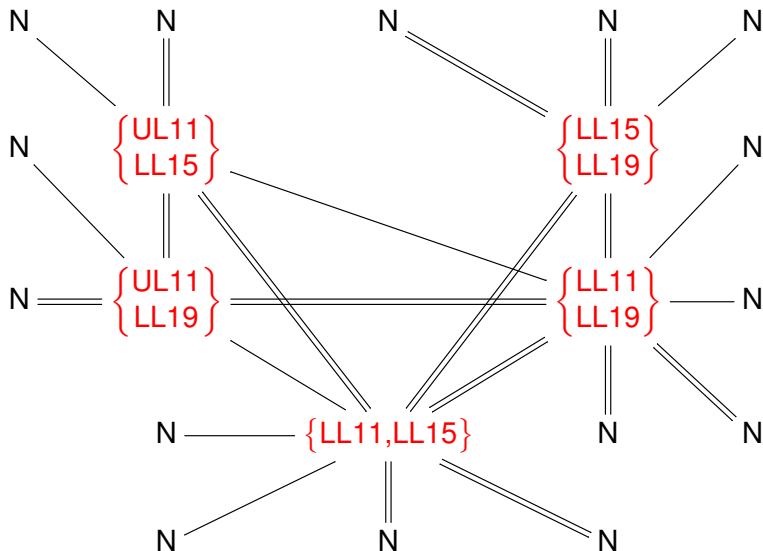
- Core idea: similar experiments should have similar results.
- Similar experiments: similar donors and similar hosts.
- With this idea, we can use known results to infer unknown results.
- Assume we have known the similarities between experiments.

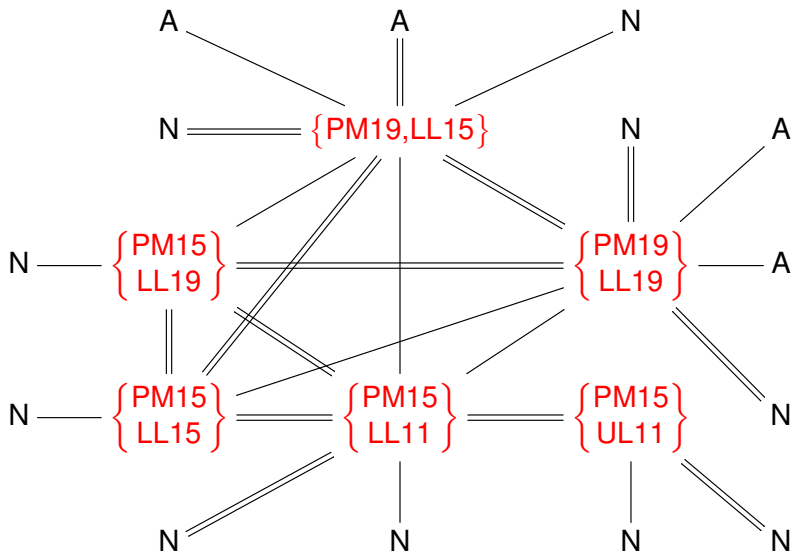
Experiment similarity chart:

Black/red terms are experiments with known/unknown results.



Double/single/no line: high/medium/low similarity.

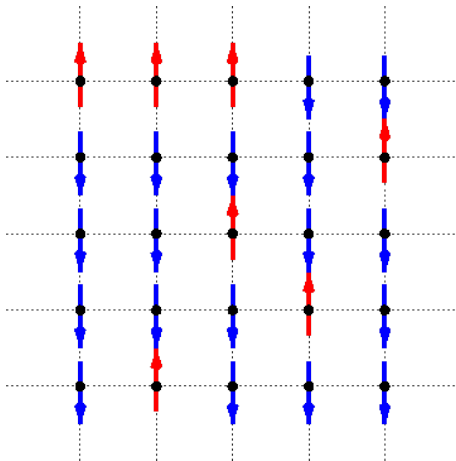




- We design a penalty function that evaluates guesses of unknown experimental results.
- There is a penalty if two similar experiments have different results.
- For the concrete form of this function, we can get inspirations from the Ising model.

Ising model

The Ising model describes ferromagnetism in statistical mechanics. Consider a set of lattice sites, where each site k has a variable σ_k that takes $+1$ or -1 .



- For a configuration σ , its energy function is

$$H(\sigma) = - \sum_{i \sim j} J_{ij} \sigma_i \sigma_j,$$

where $i \sim j$ means site i and site j are neighboring, and J_{ij} is the interaction coefficient (no external field).

- The probability of a configuration σ is

$$P_{\beta}(\sigma) = e^{-\beta H(\sigma)} / Z_{\beta},$$

where $\beta = (k_B T)^{-1}$, Z_{β} is the normalization constant.

- Configuration with high energy (high penalty) has small probability. Neighboring sites tend to have the same value.

Analogies between tissue transplantation experiments and the Ising model:

Tissue transplantation	Ising model
Experiment similarity chart	Lattice
Experiment	Site
Result: normal/abnormal	Value: +1/-1
Similar experiments	Neighboring sites
Penalty: similar experiments have different results	Penalty: neighboring sites have different values
Penalty function?	Energy function

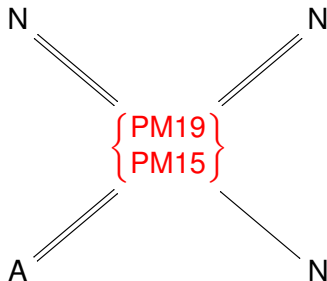
Pure analogy, not physical correspondence.

- Regard N as +1, and A as -1.
- If two experiments $\sigma_\gamma, \sigma_\delta$ are similar, set $J_{\gamma\delta} = 2J_0$ or J_0 . Otherwise, set $J_{\gamma\delta} = 0$.
- The penalty function is

$$H(\sigma) = - \sum_{\gamma, \delta} J_{\gamma\delta} \sigma_\gamma \sigma_\delta.$$

- The probability of a configuration σ is

$$P_\beta(\sigma) = e^{-\beta H(\sigma)} / Z_\beta.$$



- $\{PM19, PM15\} = N: H = -3, P = 0.65.$
- $\{PM19, PM15\} = A: H = 3, P = 0.35.$
- Result=N is the most probable guess. $P(N) = 0.65.$

Configuration					Penalty Probability	
-1	-1	-1	-1	-1	14	0.0019
1	-1	-1	-1	-1	10	0.0029
-1	1	-1	-1	-1	14	0.0019
1	1	-1	-1	-1	2	0.0064
-1	-1	1	-1	-1	14	0.0019
1	-1	1	-1	-1	2	0.0064
-1	1	1	-1	-1	6	0.0043
1	1	1	-1	-1	-14	0.0319
-1	-1	-1	1	-1	16	0.0016
1	-1	-1	1	-1	12	0.0024
-1	1	-1	1	-1	8	0.0035
1	1	-1	1	-1	-4	0.0117
-1	-1	1	1	-1	12	0.0024
1	-1	1	1	-1	0	0.0079
-1	1	1	1	-1	-4	0.0117
1	1	1	1	-1	-24	0.0868

For each configuration of the unknown results (guesses), we can calculate its probability. We can determine the most probable guesses:

		Donor						
		AM19	PM19	PM15	UL11	LL11	LL15	LL19
Host	AM19	<i>N</i>	<i>N</i>	<i>A</i>	<i>A</i>	<i>A</i>	<i>A</i>	<i>N</i>
	PM19	<i>N</i>	<i>N</i>	<u><i>N</i></u>	<i>N</i>	<i>N</i>	<u><i>N</i></u>	<u><i>N</i></u>
	PM15	<i>A</i>	<u><i>N</i></u>	<i>N</i>	<u><i>N</i></u>	<u><i>N</i></u>	<u><i>N</i></u>	<u><i>N</i></u>
	UL11	<i>A</i>	<i>N</i>	<u><i>N</i></u>	<i>N</i>	<i>N</i>	<u><i>N</i></u>	<u><i>N</i></u>
	LL11	<i>A</i>	<i>N</i>	<u><i>N</i></u>	<i>N</i>	<i>N</i>	<u><i>N</i></u>	<u><i>N</i></u>
	LL15	<i>A</i>	<u><i>N</i></u>	<u><i>N</i></u>	<u><i>N</i></u>	<u><i>N</i></u>	<i>N</i>	<u><i>N</i></u>
	LL19	<i>N</i>	<u><i>N</i></u>	<u><i>N</i></u>	<u><i>N</i></u>	<u><i>N</i></u>	<u><i>N</i></u>	<i>N</i>

We can also calculate the expectation of all guesses, i.e., the probability for each experimental result to be “N”:

		Donor						
		AM19	PM19	PM15	UL11	LL11	LL15	LL19
Host	AM19	100%	100%	0%	0%	0%	0%	100%
	PM19	100%	100%	<u>65%</u>	100%	100%	<u>49%</u>	<u>56%</u>
	PM15	0%	<u>65%</u>	100%	<u>62%</u>	<u>62%</u>	<u>53%</u>	<u>54%</u>
	UL11	0%	100%	<u>62%</u>	100%	100%	<u>81%</u>	<u>81%</u>
	LL11	0%	100%	<u>62%</u>	100%	100%	<u>90%</u>	<u>90%</u>
	LL15	0%	<u>49%</u>	<u>53%</u>	<u>81%</u>	<u>90%</u>	100%	<u>86%</u>
	LL19	100%	<u>56%</u>	<u>54%</u>	<u>81%</u>	<u>90%</u>	<u>86%</u>	100%

Another situation

What if the known experimental results are not deterministic, but stochastic?

Another situation

		Donor				
		PLE11	PLE12	PLE14	PLE16	PLE19
Host	LFR\PLE14	61%	58%	82%	?	?
	LFR\PLE16	?	?	?	?	?
	LFR\PLE19	4%	24%	83%	?	100%

Table: Results reported by Henry et al. 1987

- Percentage is lens formation (normal growth) rate.
- PLE11: presumptive lens ectoderm, stage 11.
- LFR\PLE14: lens-forming region without presumptive lens ectoderm, stage 14.

Another situation

Decompose the stochastic results into several deterministic results with different probabilities:

$$[61\%N \ 58\%N] : P([N \ N]) = 61\% \times 58\% = 31\%.$$

$$P([N \ A]) = 61\% \times (100\% - 58\%) = 26\%.$$

$$P([A \ N]) = (100\% - 61\%) \times 58\% = 23\%.$$

$$P([A \ A]) = (100\% - 61\%) \times (100\% - 58\%) = 16\%.$$

$$[61\%N \ 58\%N] = 35\%[N \ N] + 26\%[N \ A] + 23\%[A \ N] + 16\%[A \ A].$$

For each deterministic configuration, apply our method to obtain the expectation of guesses. Then average over these deterministic configurations.

Another situation

		Donor				
		PLE11	PLE12	PLE14	PLE16	PLE19
Host	LFR\PLE14	61%	58%	82%	<u>93%</u>	<u>94%</u>
	LFR\PLE16	<u>39%</u>	<u>53%</u>	<u>88%</u>	<u>97%</u>	<u>97%</u>
	LFR\PLE19	4%	24%	83%	<u>96%</u>	100%

Experimental design

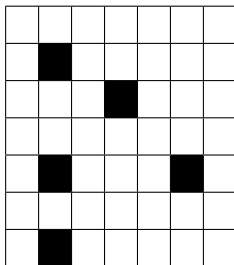
- There are many tissue transplantation experiments, and we want to know all the results.
- We can choose some experiments to conduct, and use the known results to infer other experiments.
- How to choose experiments to conduct?
- We need enough data to conduct the inference. We should minimize the experimental cost.

Experimental design

- The results of non-conducted experiments are inferred by similar conducted experiments.
- To guarantee the inference quality, one non-conducted experiment should be similar to at least k conducted experiments (e.g., $k = 2$ or $k = 1$).
- The most efficient design: no conducted experiments are similar, and each non-conducted experiment is similar to exactly k conducted experiments.

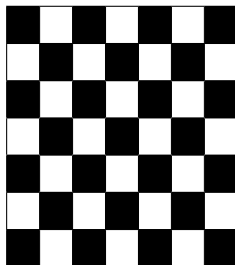
Experimental design

- Consider the figure that each unit is an experiment, and neighboring units are similar experiments.
- Black units are conducted experiments, and white units are non-conducted experiments.
- How to color the figure, so that two black units are not neighboring, and each white unit is neighboring to k black units?



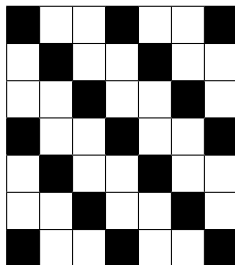
Experimental design

No neighboring black units, and each white unit is neighboring to $k = 4$ black units (ignore the boundary cases).



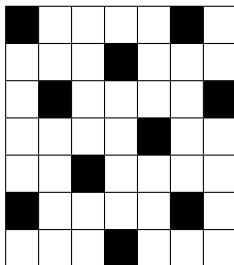
Experimental design

No neighboring black units, and each white unit is neighboring to $k = 2$ black units (ignore the boundary cases).



Experimental design

No neighboring black units, and each white unit is neighboring to $k = 1$ black units (ignore the boundary cases).



Experimental design

- For $k = 4$, we need to conduct $1/2$ experiments.
- For $k = 2$, we need to conduct $1/3$ experiments.
- For $k = 1$, we need to conduct $1/5$ experiments.

Experimental design

- In practice, the experiment similarity chart is not 2-dimensional, but 4-dimensional.
- Similar coloring problems for such 4-dimensional figures.
- We need some abstract methods.

Experimental design

- For $k = 8$, color a unit (x, y, z, w) if

$$x + y + z + w \equiv 0 \pmod{2}.$$

We need to conduct $1/2$ experiments.

- For $k = 4$, color a unit (x, y, z, w) if

$$x + y + z + w \equiv 0 \pmod{3}.$$

We need to conduct $1/3$ experiments.

Experimental design

- For $k = 2$, color a unit (x, y, z, w) if

$$x + 2y + z + 2w \equiv 0 \pmod{5}.$$

We need to conduct $1/5$ experiments.

- For $k = 1$, color a unit (x, y, z, w) if

$$x + 2y + 3z + 4w \equiv 0 \pmod{9}.$$

We need to conduct $1/9$ experiments.

Experimental design

- In practice, $k = 2$ or $k = 1$ is enough to conduct satisfactory inference. Therefore we only need to conduct $1/5 - 1/3$ experiments (two-dimensional) or $1/9 - 1/5$ experiments (four-dimensional).
- The more experiment similarities we have, the fewer experiments we need to conduct.

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