

輸入執行指令

接下來是輸入各項指令，千萬注意輸入內容和輸入環境

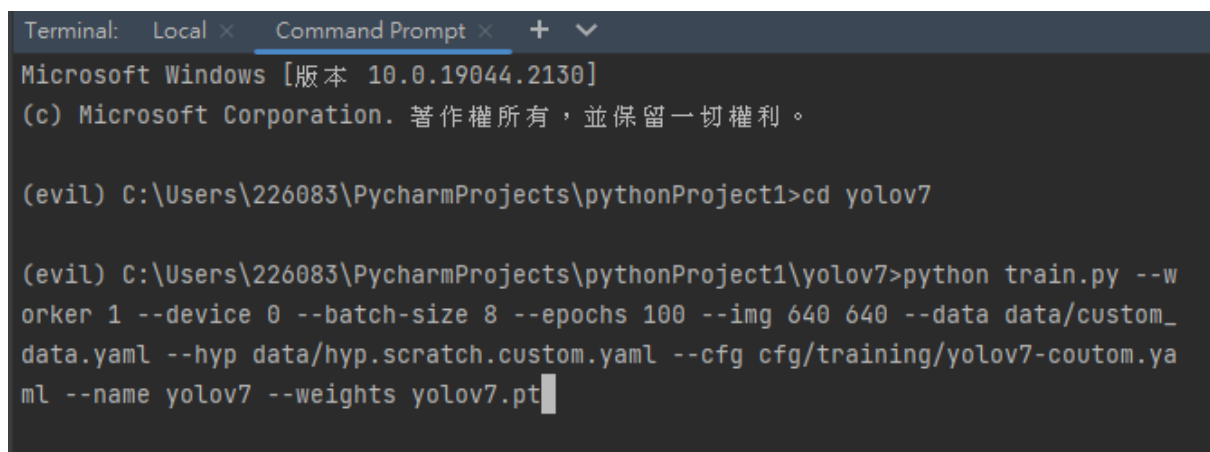
內容錯誤例如：

worker 1，中間有空格

batch-siza，明顯錯誤，改成size

環境錯誤：

套件都在yolov7這個資料夾環境下，所以當然是在這邊執行



```
Terminal: Local x Command Prompt x + v
Microsoft Windows [版本 10.0.19044.2130]
(c) Microsoft Corporation. 著作權所有，並保留一切權利。

(evil) C:\Users\226083\PycharmProjects\pythonProject1>cd yolov7

(evil) C:\Users\226083\PycharmProjects\pythonProject1\yolov7>python train.py --w
orker 1 --device 0 --batch-size 8 --epochs 100 --img 640 640 --data data/custom_
data.yaml --hyp data/hyp.scratch.custom.yaml --cfg cfg/training/yolov7-coutom.ya
ml --name yolov7 --weights yolov7.pt
```

指令如下：

```
python train.py --worker 1 --device 0 --batch-size 8 --epochs 100 --img 640 640 --
data data/custom_data.yaml --hyp data/hyp.scratch.custom.yaml --cfg
cfg/training/yolov7-custom.yaml --name yolov7 --weights yolov7.pt
```

python train.py：訓練過程執行train.py這個檔案，不是detect.py

data data/custom_data.yaml：決定訓練圖片的路徑和標籤數目、種類

hyp data/hyp.scratch.custom.yaml：各項參數，直接用就好，暫時別去改動

cfg cfg/training/yolov7-coutom.yaml：演算法相關，前面針對這檔案作出標籤數量的改動(80 → 2)

name yolov7：你的環境資料夾名稱

weights yolov7.pt：使用的模型種類，選用yolov7.pt，之後可以考慮換成其他模型

```
hyp.scratch.custom.yaml x
1  lr0: 0.01 # initial learning rate (SGD=1E-2, Adam=1E-3)
2  lrf: 0.1 # final OneCycleLR learning rate (lr0 * lrf)
3  momentum: 0.937 # SGD momentum/Adam beta1
4  weight_decay: 0.0005 # optimizer weight decay 5e-4
5  warmup_epochs: 3.0 # warmup epochs (fractions ok)
6  warmup_momentum: 0.8 # warmup initial momentum
7  warmup_bias_lr: 0.1 # warmup initial bias lr
8  box: 0.05 # box loss gain
9  cls: 0.3 # cls loss gain
10 cls_pw: 1.0 # cls BCELoss positive_weight
11 obj: 0.7 # obj loss gain (scale with pixels)
12 obj_pw: 1.0 # obj BCELoss positive_weight
13 iou_t: 0.20 # IoU training threshold
14 anchor_t: 4.0 # anchor-multiple threshold
15 # anchors: 3 # anchors per output layer (0 to ignore)
16 fl_gamma: 0.0 # focal loss gamma (efficientDet default gamma=1.5)
17 hsv_h: 0.015 # image HSV-Hue augmentation (fraction)
18 hsv_s: 0.7 # image HSV-Saturation augmentation (fraction)
19 hsv_v: 0.4 # image HSV-Value augmentation (fraction)
20 degrees: 0.0 # image rotation (+/- deg)
21 translate: 0.2 # image translation (+/- fraction)
22 scale: 0.5 # image scale (+/- gain)
23 shear: 0.0 # image shear (+/- deg)
24 perspective: 0.0 # image perspective (+/- fraction), range 0-0.001
25 flipud: 0.0 # image flip up-down (probability)
26 fliplr: 0.5 # image flip left-right (probability)
27 mosaic: 1.0 # image mosaic (probability)
28 mixup: 0.0 # image mixup (probability)
29 copy_paste: 0.0 # image copy paste (probability)
30 paste_in: 0.0 # image copy paste (probability), use 0 for faster training
31 loss_ota: 1 # use ComputeLossOTA, use 0 for faster training
```

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確認輸入內容正確後，開始執行，等她跑完