



CIS 522: Lecture 2

Multilayer Perceptrons



Penn
Engineering

Today

- (1) Some admin
- (2) Review second set of notebooks
- (3) Questions and Answers

*Please start asking on chat now so we can
prioritize/ order*

- (4) DL as a field, and its history

PR our tutorials

Find ways of improving our tutorials

Put them in as a PR on github

Extra points!

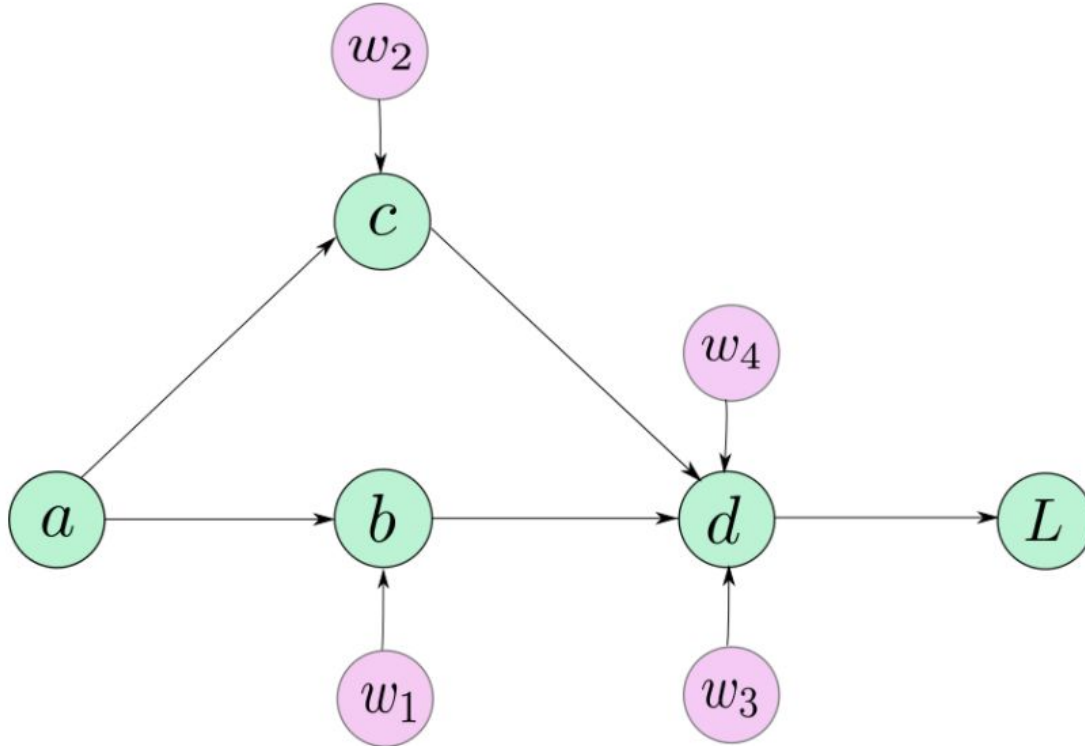
Permits

Everyone should have theirs by now for real. Contact Anka via email tomorrow (akreuel@seas.upenn.edu) if something is missing.

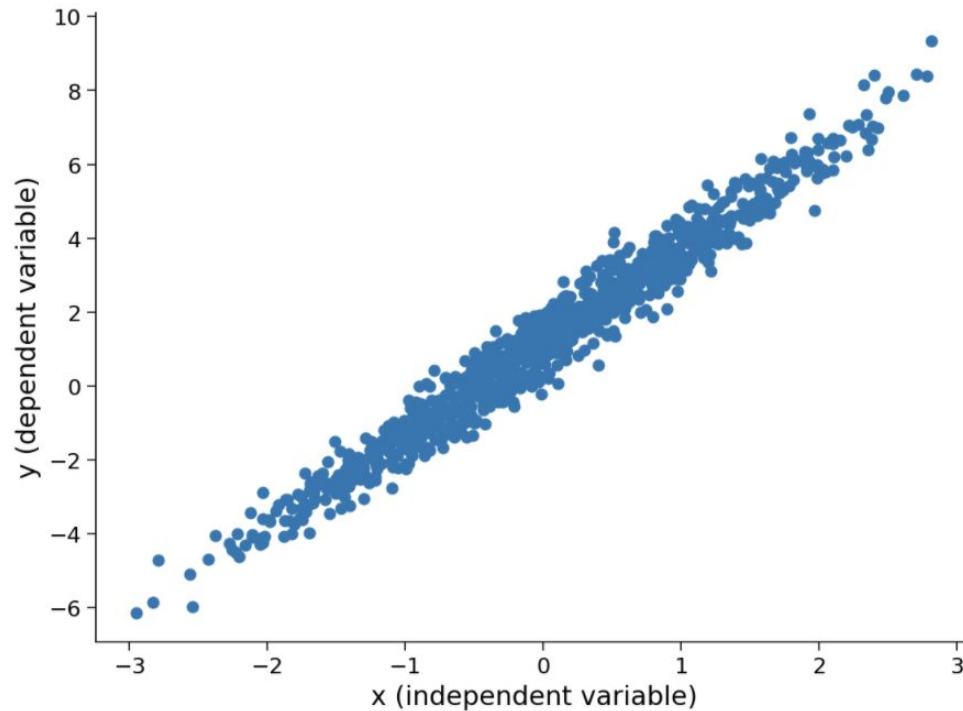
Ed discussion

Invites coming

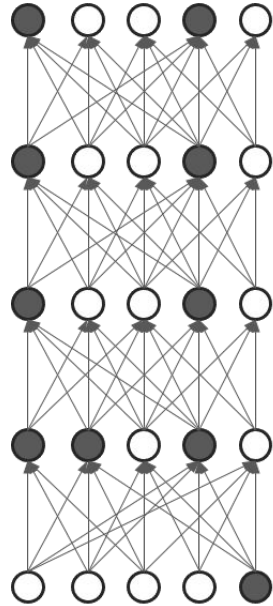
(2) Let us talk about this week's notebooks



Linear Regression



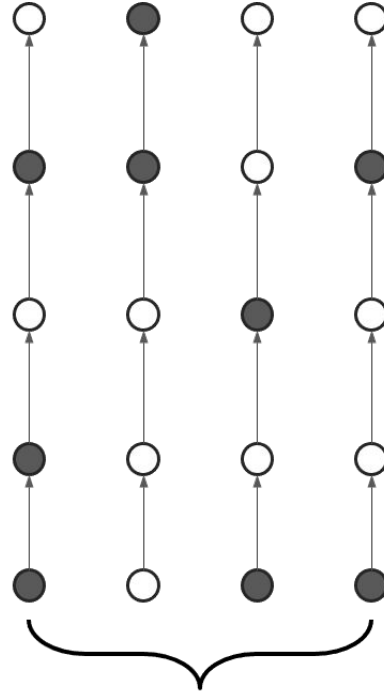
Shallow vs deep linear networks



SVD change
of vars

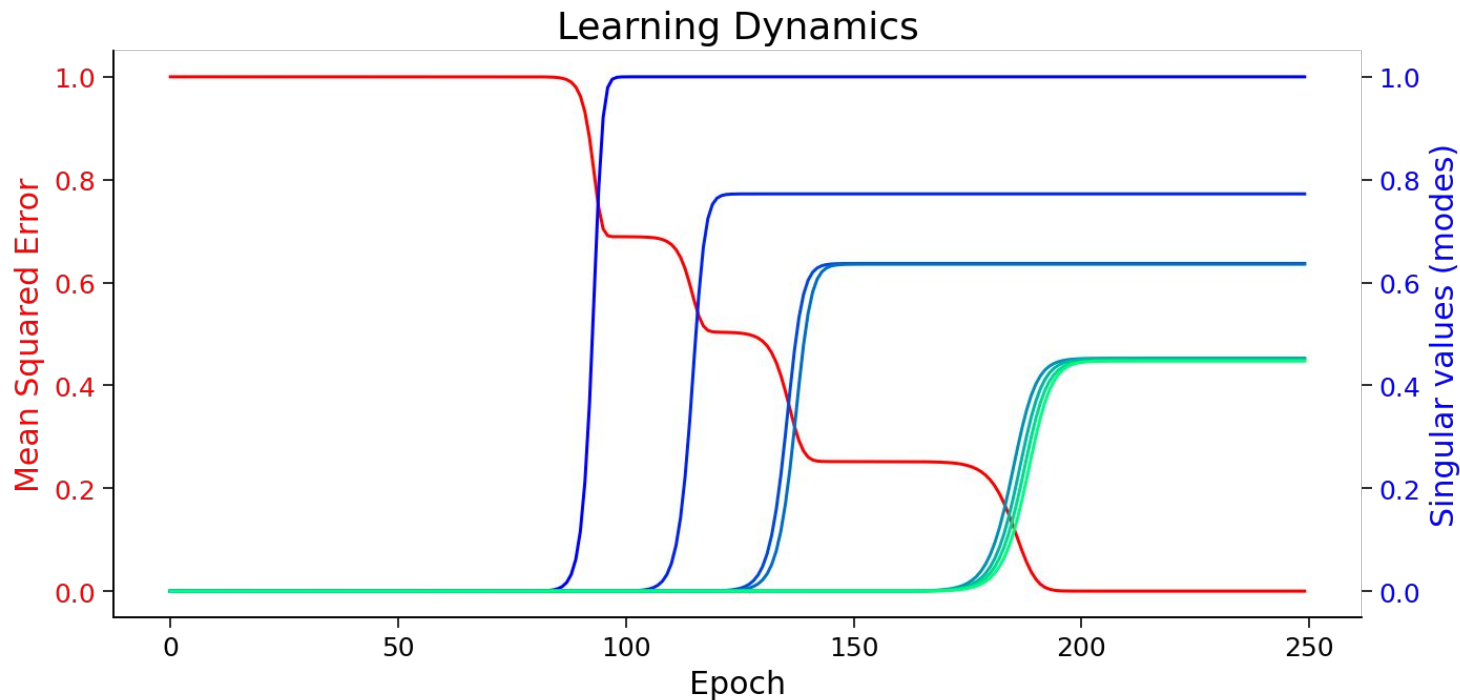


Decoupled
Initial conds



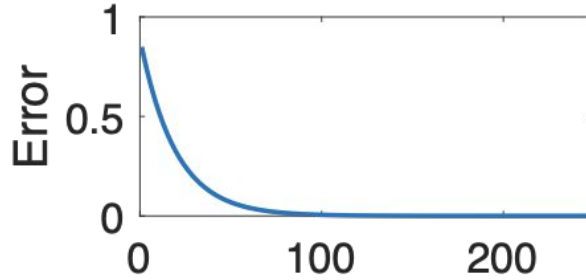
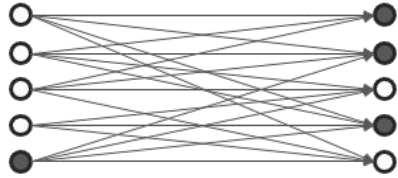
N independent, scalar modes

Spent some time on race models

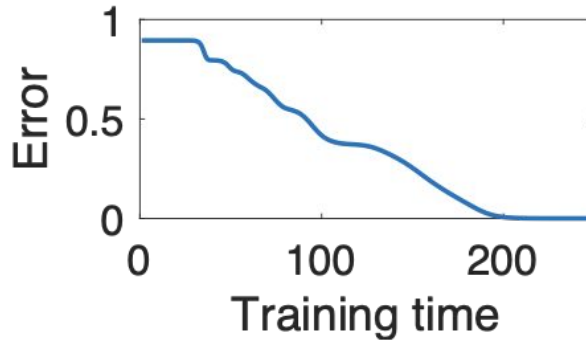
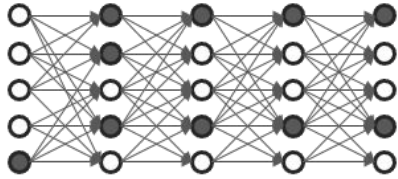


The effect of depth on training

Shallow



Deep



Some cost function engineering

MSE

Mean absolute error (MAE)

% correct guesses

Whatever the problem calls for

The intricacies of network initialization

Xavier

He

The principles

Some high dimensional intuitions

Draw from N -dimensional isotropic Gaussian, $N(0, \sigma^2)$ per dimension, where $N \gg 1$

Angle between two vectors?

Proportion of mass within fixed δ skin of sphere

Variance?

Best estimator for future points?

Questions and Answers

Let us spend some time talking about them

Looking towards to the week ahead

Optimization

We will learn about

SGD - noisy approximation, and cheap

Batch normalization

Momentum

Rate scheduling

Adaptive Learning rates

Various problems

Deeper insights

Optimization is not just about finding a minimum

It is about finding a minimum that generalizes well

Let us review what makes a minimum good

Shallow

Deep

Potential problems

- a) No gradients
- b) Infinite gradients
- c) All gradients in low dimensional space

Lets understand the field

<https://60years.vizhub.ai/>

Causality in atari games

RECURRENT INDEPENDENT MECHANISMS

**Anirudh Goyal¹, Alex Lamb¹, Jordan Hoffmann^{1, 2, *}, Shagun Sodhani^{1, *}, Sergey Levine⁴
Yoshua Bengio^{1, **}, Bernhard Schölkopf^{3, **}**

ABSTRACT

We explore the hypothesis that learning modular structures which reflect the dynamics of the environment can lead to better generalization and robustness to changes that only affect a few of the underlying causes. We propose Recurrent Independent Mechanisms (RIMs), a new recurrent architecture in which multiple groups of recurrent cells operate with nearly independent transition dynamics, communicate only sparingly through the bottleneck of attention, and compete with each other so they are updated only at time steps where they are most relevant. We show that this leads to specialization amongst the RIMs, which in turn allows for remarkably improved generalization on tasks where some factors of variation differ systematically between training and evaluation.

