

Yug Ajmera

Robotician

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YugAjmera • in yug-ajmera

yugajmera.github.io • yainnoware.blogspot.in (Blog)



Education

BITS Pilani Hyderabad Campus

B.E.(Hons.) Mechanical Engineering, Minor in Data Science,
CGPA : 8.57/10.0

Hyderabad, India

2017 - 2021

Zydus School For Excellence

ISC (Class XII), 94.6%

Ahmedabad, India

2017

Received 7 scholar trophies for academic excellence.

Skills

- **Experienced:** ROS, Gazebo, RVIZ, Python programming, Arduino and Raspberry Pi Interfacing, Soldering skills, HTML, CSS, Javascript.
- **Intermediate:** MoveIt, Java programming, C programming, Git, Linux, SolidWorks, Creo, IoT, OpenCV, AutoCAD, L^AT_EX, 3D printing, MATLAB.
- **Familiar:** V-REP, Android Studio, Processing 3, C++ programming.

Internships

APTRI Labs

Summer Intern,

Developed ALFA - An open-source floor-assistant robot, that can be controlled over the internet. Assembled electronics, wrote shell scripts and employed the Lighttpd webserver.

Ahmedabad, India

May 2019-July 2019

Vinnan Labs

Research Intern,

Worked on "Autonomous UV Sterilization Robot" based on ROS which was funded under BIRAC Innovation Challenge, SoCH. Wrote scripts to perform trajectory record and playback and implemented 3D mapping in ROS using Octomap.

Hyderabad, India

October 2018 - February 2019

Publications

- Ruchik Mishra, **Yug Ajmera**, Nikhil Mishra, Arshad Javed, Ego-centric Framework for a three-wheel omni-drive telepresence robot, 15th IEEE International Conference on Advanced Robotics and Its Social Impacts (ARSO 2019) (Accepted).
- **Yug Ajmera**, Robot User Interface : Web applications for control, mapping and navigation of mobile robots, Journal of Automation, Mobile Robotics and Intelligent Systems (Under Review).

Projects

Aerial Robotics.....

Autonomous control of Drone using on-board micro-controller

CS Department

Development of ROS packages for autonomous control

Ongoing

Currently working under Dr.Paresh Saxena to build a drone based on Raspberry Pi. The autonomous behavior will be implemented onboard using the ROS framework.

Mobile Robotics.....

navros_pkg **Personal**
ROS package for autonomous navigation of differential drive robots. February 2019

Implemented ROS Navigation stack on a Gazebo simulation of a custom differential driven car. SLAM algorithm is used for mapping and creating local and global cost maps. Used Dijkstra's algorithm for path planning and the robot localization is carried out using Adaptive Monte Carlo localization algorithm.

teleop_keyboard_omni3 **Personal**
Generic keyboard teleop for three-wheeled omnidirectional robots. March 2019

Performed motion analysis of three-wheeled robots and extended the results to develop the control algorithm. This package has been added to ROS package index. The code was initially tested on a Gazebo simulation and then extended to an actual robot.

line_maze_ros **Personal**
ROS package for solving line mazes using OpenCV August 2019

Implemented multiple centroid tracking algorithm to follow lines and used the left-hand rule to solve the maze. The results of the algorithm were verified using Gazebo simulations.

Medical Robotics.....

Smart Spoon **Mechanical Department**
Fabrication of Low-cost spoon for people with hand tremors Ongoing

This project is being done under Dr.Sujith R. and Dr.Amrita Priyadarshini. The PID control algorithm will be used to keep the spoon stable and the body will be 3D printed.

Arduino Projects.....

- o **Humanoid Robot** - Designed the robot on Solidworks and wrote the walking algorithm.
- o **Voice Controlled Car** - Most viewed project with 25K+ views on arduino.cc.

Positions of Responsibility

Hyperloop India
Software Lead Ongoing

Currently leading the software team of Hyperloop India for the Hyperloop Pod competition organized by SpaceX.

Student Mentorship Program
Mentor 2018-2019

Conducted classes for freshmen and sophomores on the basics of ROS.

Automation and Robotics Club (ARC)
Treasurer 2018-2019

Conducted, taught, and mentored numerous workshops related to robotics for freshers and sophomores. Executed and managed the activities of the club.

References

Prof. Paresh Saxena
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