Syrure Linear Systems

Goal: solve n hneur exis in n unknowns.

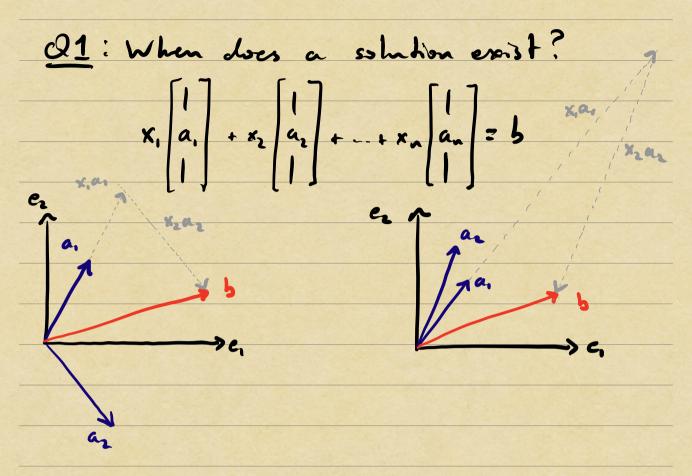
anix, + une xe + ... + ann xn = bn

equations
$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{nn} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

unkuruns

Computational task: "solve" Ax= b

In high-herel lunguages like Julia/Madas



If columns of A are linearly independent, A is invertible and unique sola is $x = A^{-1}b$.

See Trefethen Lecture 1 Thm 1,3 for list of equivalent conelitions.

Q2: When is Ax= 5 well-conditioned?
(Solution sensitive to perturbations)

Sousihily to perharbutions in b (not A)

 $X = A^{-1}b$ $A^{-1} + A^{-1} + A^{-1$

We can bound Kpr (b) independent of b

A-1 showk b?

b = AA-16 => 11611 5 11A11 11A-611

=> 11511 < 11A11

(b) < ||A'|||A|| = k(A)

"Conclition **

of A"

Condition & of A is also condition #

of x=A'b w.r.t. perharbadions in A.

The Singular Value Decomposition

A powerful way to understand how A shrinks: Stretches different vectors is through the singular value decomposition (SVD).

Lett singular vector singular value right singular vectors

$$A = \begin{bmatrix} 1 & 1 \\ u_1 & u_n \end{bmatrix} \begin{bmatrix} G_1 & V_1 & -1 \\ -V_1 & -1 \end{bmatrix}$$

$$U \quad \Sigma \quad V^*$$
unitary diagonal unitary
$$G_1, G_2, \dots, G_n$$

The SVD is one of many LA factorizations
that decomposes a matrix into a product
of highly structured matrices, whose
individual action is easier to understand.

Cz rotation
ez scaling ez reflection

Vz

Vz

Cz rotation

Cz ro

Unitary Orthogonal matrices

(complex) (real)

$$Q = \begin{bmatrix} 1 & 1 \\ q & q_m \end{bmatrix}$$
 (writery

 $Q = \begin{bmatrix} 1 & 1 \\ q & q_m \end{bmatrix}$ (=) $q_i q_j = \begin{bmatrix} 1 & i = i \\ 0 & i \neq j \end{bmatrix}$

equivalently

 $Q = Q = I$ ($Q^{-1} = Q^{-1}$)

Multiplying by a preserves beneth

110x11, = 11x11,

ble $\|Q_x\|_2^2 = (Q_x)^4 (Q_x) = x^4 Q^4 Q_x = x^4 x = \|x\|_2^2$

Key Iden: Express K(A) using singular vals of A.

(1)
$$||A||_2 = \sup_{x \in \mathbb{R}^n} \frac{||U \in V^* x||_2}{||x||_2} = \sup_{x \in \mathbb{R}^n} \frac{||\mathcal{E}V^* x||_2}{||x||_2}$$

$$= \sup_{x \in \mathbb{R}^n} \frac{||\mathcal{E}y||_2}{||V_y||_2} = \sup_{x \in \mathbb{R}^n} \frac{||\mathcal{E}y||_2}{||y||_2}$$

$$y = V^* x$$

6, - amplifying action
6n - Shrinking action