

# DD2437 – Artificial Neural Networks and Deep Architectures (annda)

Lecture 5: Radial basis function NN and introduction to competitive learning

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KTH Pawel Herman DD2437 annda

- Interpolation problem and RBFs
- RBF networks hybrid learning
- · Weight interpretation in the input space
- · Competitive mechanisms for unsupervised learning

#### Lecture overview

- Interpolation problem and radial-basis functions (RBFs)
- RBF networks hybrid learning
- Weight interpretation
- Competitive mechanisms for unsupervised learning

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#### The separability of patterns

#### Cover's theorem

"A complex pattern classification problem, projected nonlinearly to a high-dimensional space, is more likely to be linearly separable than in low dimensional space, especially if it is not populated too densely."

Cover, 1965

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#### The separability of patterns

#### Cover's theorem

"A complex pattern classification problem, projected nonlinearly to a high-dimensional space, is more likely to be linearly separable than in low dimensional space, especially if it is not populated too densely."

Cover, 1965

#### So, we need to have:

- 1) Many nonlinear mappings  $\varphi_i(\mathbf{x} \in \mathbf{R}^M)$ :  $\mathbf{R}^M \to \mathbf{R}^1$ , where i = 1,..., N (large)
- 2) Linear function for separability in high N-dimensional space

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### The radial-basis-function (RBF) technique

Nonlinear mapping with the use of radial-basis-functions (RBFs):

$$\varphi_i(\|\mathbf{x}-\mathbf{x}_i\|)$$

 $\mathbf{x}_i$  – RBF centre

 $\|\cdot\|$  – vector norm, often Euclidean

 $\varphi_i(r)$  – kernel function, often Gaussian

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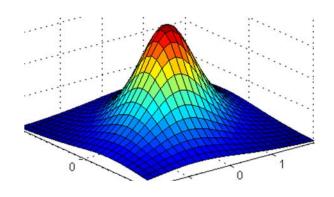
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$$\varphi_i(r = \|\mathbf{x} - \mathbf{x}_i\|) = \exp\left(-\frac{r^2}{2\sigma^2}\right)$$



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# The radial-basis-function (RBF) technique

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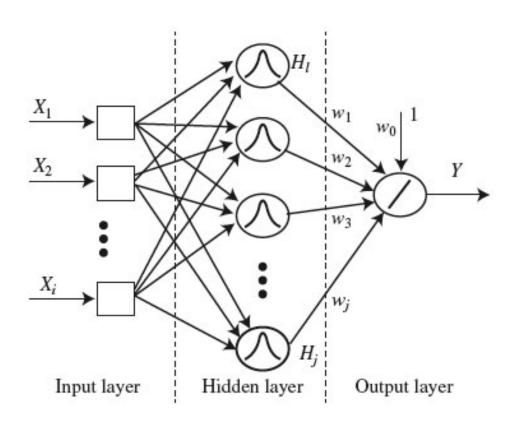
 $\mathbf{x}_i$  – RBF centre  $\|\cdot\|$  – vector norm, often Euclidean  $\varphi_i(r)$  – kernel function, often Gaussian

Linear operation in N-dimensional space:

$$F(\mathbf{x}) = \sum_{i=1}^{N} w_i \varphi_i \left( \left\| \mathbf{x} - \mathbf{x}_i \right\| \right)$$

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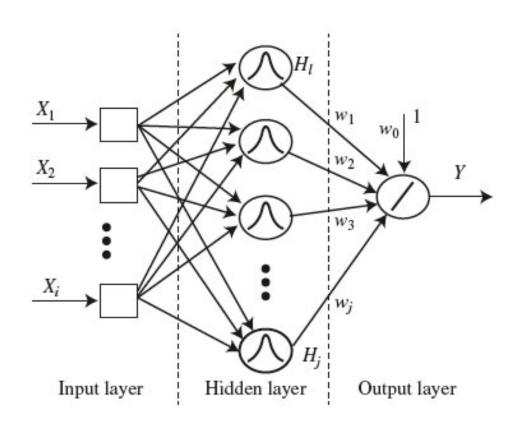
#### The RBF neural network concept



In the *exact interpolation*, the size of the hidden layer, N, is equal to the number of samples n

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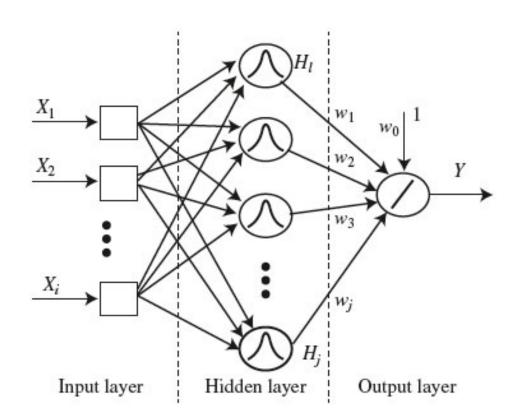


In the *exact interpolation*, the size of the hidden layer, N, is equal to the number of samples n

**BUT** this is not robust especially if a lot of samples are corrupted with noise!

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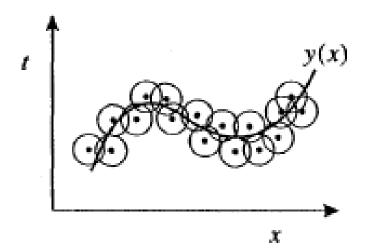
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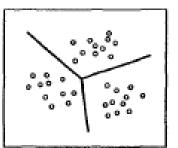
We need modifications:

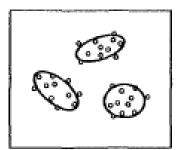
- 1) N < n
- 2) centres  $\mathbf{x}_i$  different from samples
- 3) widths,  $\sigma$ , also differ across RBF nodes
- 4) it is possible to include biases

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# Examples



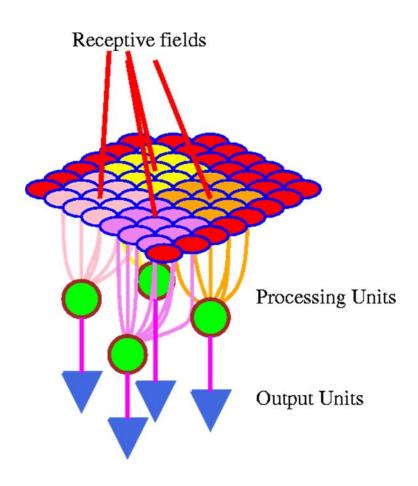




See *Bishop (1995)* for Bayesian interpretation of classification with RBF networks

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### Analogy with receptive fields

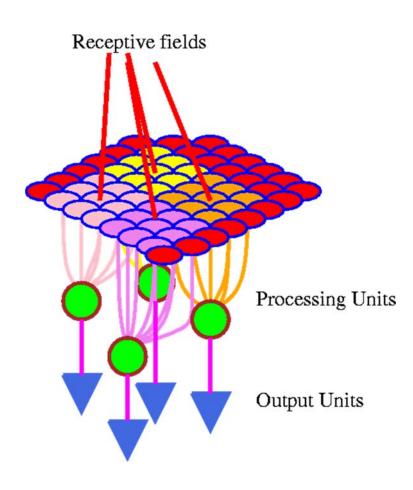


The **receptive field** of a unit is the region of the input space from which a stimulus pattern evokes a response.

Haykin, 2009

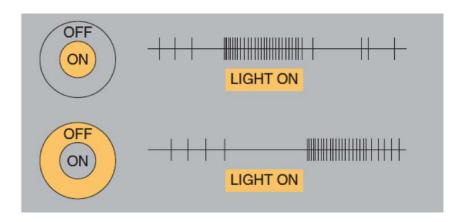
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### Analogy with receptive fields

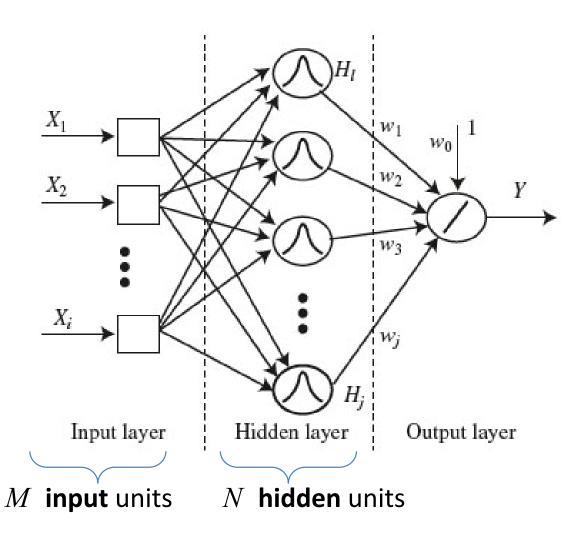


#### Example:

Retinal ON-centre and OFF-centre cells



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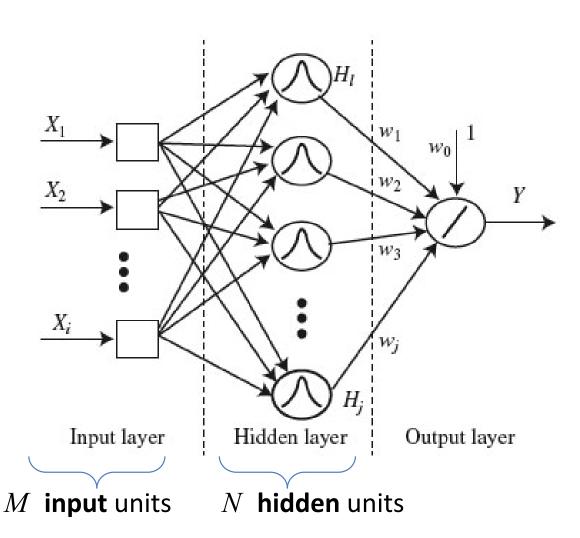


*n* training samples

KTH

mapping:  $\mathbb{R}^M \to \mathbb{R}^N \to \mathbb{R}^1$ 

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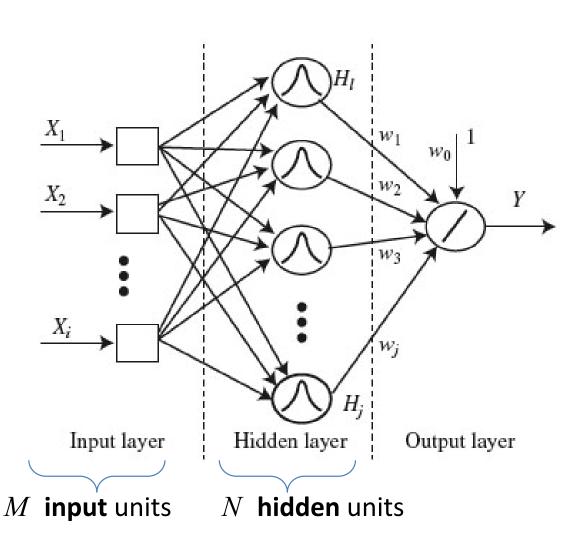


Size of the **input layer** determined by the dimensionality of the input.

*n* training samples

mapping:  $\mathbb{R}^M \to \mathbb{R}^N \to \mathbb{R}^1$ 

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Size of the **input layer** determined by the dimensionality of the input.

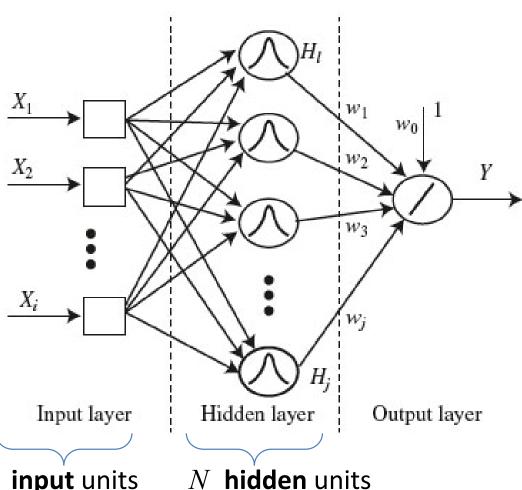
#### Hidden layer

- N has to be decided
- centres and widths of hidden units have to be identified

*n* training samples

mapping:  $\mathbb{R}^M \to \mathbb{R}^N \to \mathbb{R}^1$ 

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*M* input units

*n* training samples, mapping:  $\mathbb{R}^M \to \mathbb{R}^N \to \mathbb{R}^1$ 

Size of the **input layer** determined by the dimensionality of the input.

#### Hidden layer

- N has to be decided
- centres and widths of hidden units have to be identified

Output layer performs a linear mapping – e.g., training with least square methods

$$\begin{bmatrix} \varphi_{11} & \varphi_{12} & \dots & \varphi_{1N} \\ \varphi_{21} & \varphi_{22} & \dots & \varphi_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \varphi_{n1} & \varphi_{n2} & \dots & \varphi_{nN} \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_N \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \end{bmatrix}$$

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#### Hybrid learning – RBF layer

- Clustering algorithms
  - k-means clustering
  - clustering with Kohonen feature maps (SOMs), vector quantization (VQ)
  - estimate of the cluster width (variance problem)
- Gaussian mixture models: expectation-maximization (EM) alg.

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- Gaussian mixture models: expectation-maximization (EM) alg.
- Supervised tuning of the RBF parameters with gradient descent

$$\frac{\partial E}{\partial \mu_{ji}} = \sum_{n} \sum_{k} \left\{ y_k(\mathbf{x}^n) - t_k^n \right\} w_{kj} \exp\left(-\frac{\|\mathbf{x}^n - \mu_j\|^2}{2\sigma_j^2}\right) \frac{(x_i^n - \mu_{ji})}{\sigma_j^2}$$

$$\frac{\partial E}{\partial \sigma_j} = \sum_{n} \sum_{k} \left\{ y_k(\mathbf{x}^n) - t_k^n \right\} w_{kj} \exp\left(-\frac{\|\mathbf{x}^n - \mu_j\|^2}{2\sigma_j^2}\right) \frac{\|\mathbf{x}^n - \mu_j\|^2}{\sigma_j^3}$$
Bishop, 1995

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Subset selection with orthogonal least squares

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### Hybrid learning – output layer

Least-squares fitting – batch approach

$$\begin{bmatrix} \varphi_{11} & \varphi_{12} & \dots & \varphi_{1N} \\ \varphi_{21} & \varphi_{22} & \dots & \varphi_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \varphi_{n1} & \varphi_{n2} & \dots & \varphi_{nN} \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_N \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \end{bmatrix}$$

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Recursive least-squares estimation (see Haykin, RLS algorithm)

delta rule:

$$\begin{aligned} \mathbf{\Delta}\mathbf{w} &= -\eta \nabla_{\mathbf{w}} \hat{\xi} \\ &= -\eta \frac{1}{2} \nabla_{\mathbf{w}} (f(x_k) - \mathbf{\Phi}(x_k)^{\top} \mathbf{w})^2 \\ &= \eta (f(x_k) - \mathbf{\Phi}(x_k)^{\top} \mathbf{w}) \mathbf{\Phi}(x_k) \\ &= \eta e \mathbf{\Phi}(x_k) \end{aligned} \qquad \mathbf{\Phi}(x_k) = \begin{pmatrix} \phi_1(x_k) \\ \phi_2(x_k) \\ \vdots \\ \phi_n(x_k) \end{pmatrix}$$

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- Hidden units in MLP rely on weighted linear summations of inputs
   (a matter of interpretation: it could be seen as the correlation or scalar prod)
  - RBFs rely on distance to prototype vectors

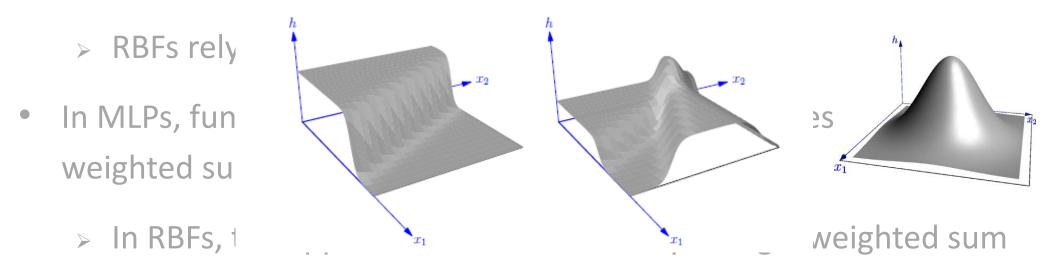
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- Hidden units in MLP rely on weighted linear summations of inputs
  - > RBFs rely on distance to prototype vectors
- In MLPs, function approximation is defined as by a nested sum of weighted summations
  - > In RBFs, the approximation is defined by a single weighted sum

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Hidden units in MLP rely on weighted linear summations of inputs

Weighted sum of Base Functions



- MLPs form distributed activations (many hidden units contribute to the output for a given input, which partly leads to local minima etc.)
  - In RBFs, very few local basis functions (wrt. input) are activated for a given input

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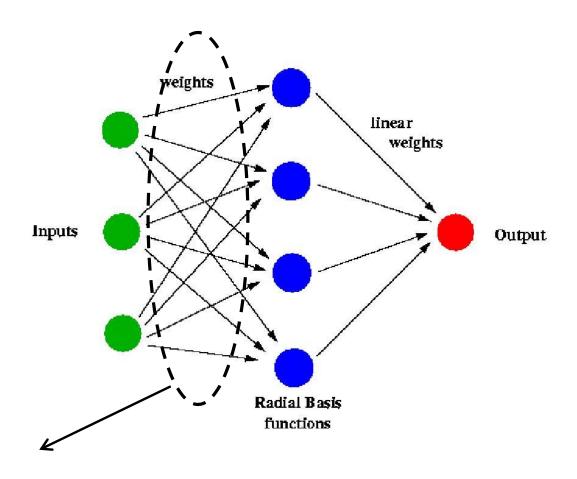
- In MLPs, usually all parameters/weights are trained at the same time
  - > In RBFs, hybrid two-stage training is used

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- In MLPs, usually all parameters/weights are trained at the same time
  - > In RBFs, hybrid two-stage training is used
- MLPs rely on complex multi-layer architecture
  - > RBF NNs have simple one-hidden-layer architecture

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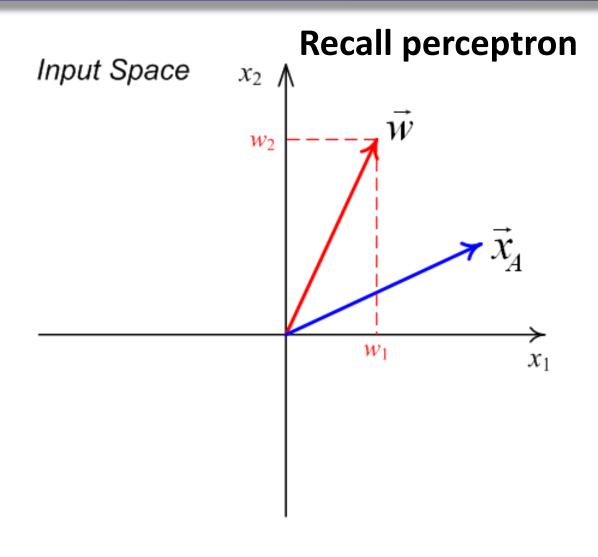
#### Interpretation of the weights to hidden layer

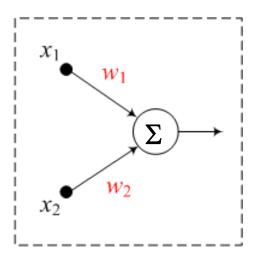


Do these connections have weights?

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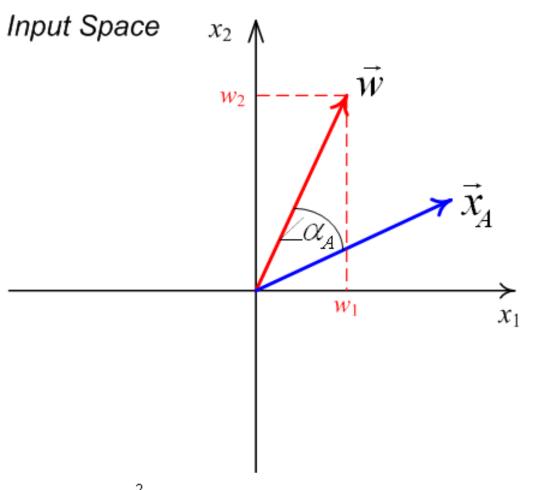
#### Weights in the input space

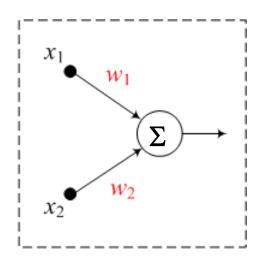




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#### Weights in the input space – scalar product

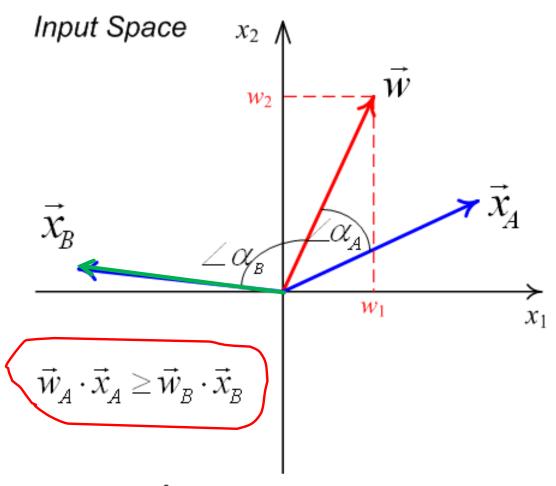


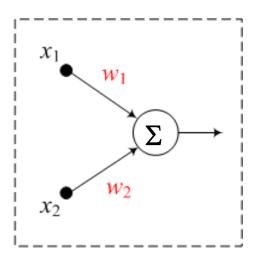


$$\vec{w} \cdot \vec{x} = \sum_{i=1}^{2} w_{i} x_{i} = w_{1} x_{1} + w_{2} x_{2} = ||\vec{w}|| ||\vec{x}|| \cos(\angle \alpha)$$

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#### Weights in the input space – scalar product

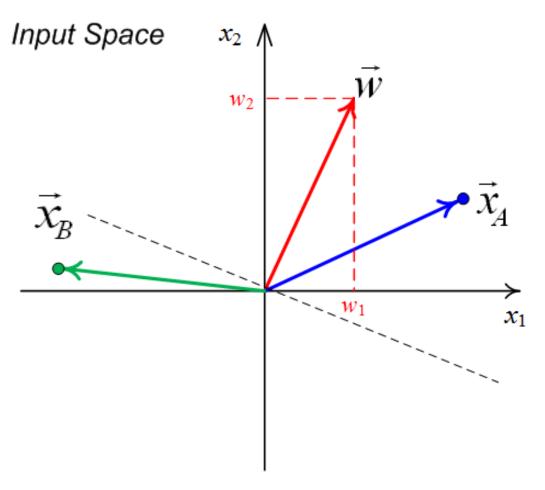


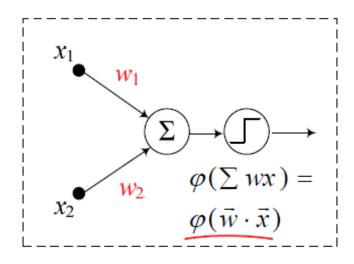


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#### Weights in the input space – perceptron classifier

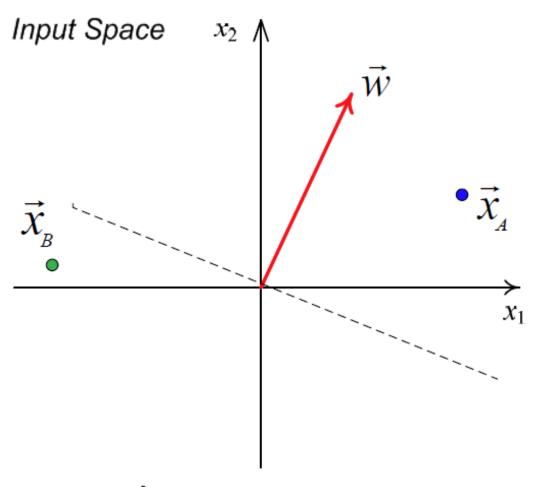


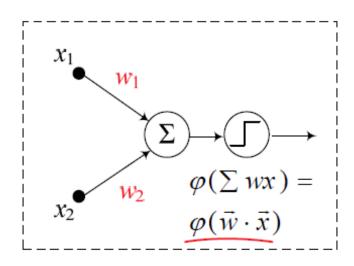


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### Weights in the input space – perceptron classifier



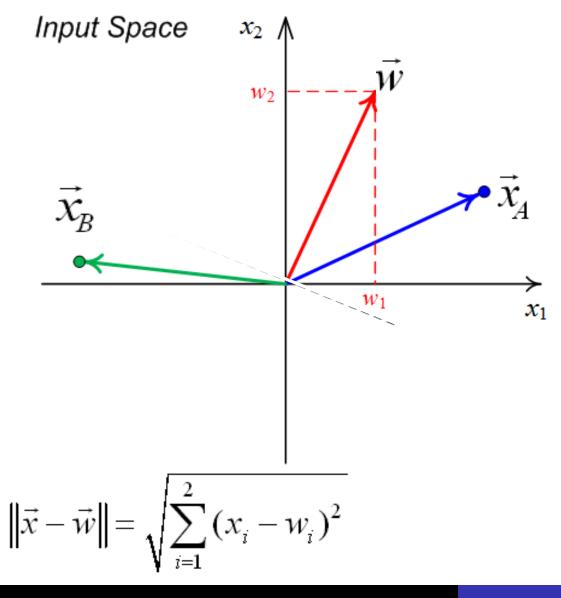


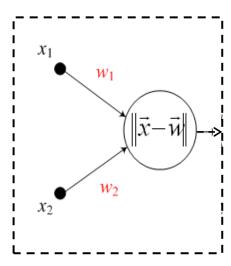
based on scalar product

$$\vec{w} \cdot \vec{x} = \sum_{i=1}^{2} w_{i} x_{i} = w_{1} x_{1} + w_{2} x_{2} = ||\vec{w}|| ||\vec{x}|| \cos(\angle \alpha)$$

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#### Weights in the input space – Euclidean distance

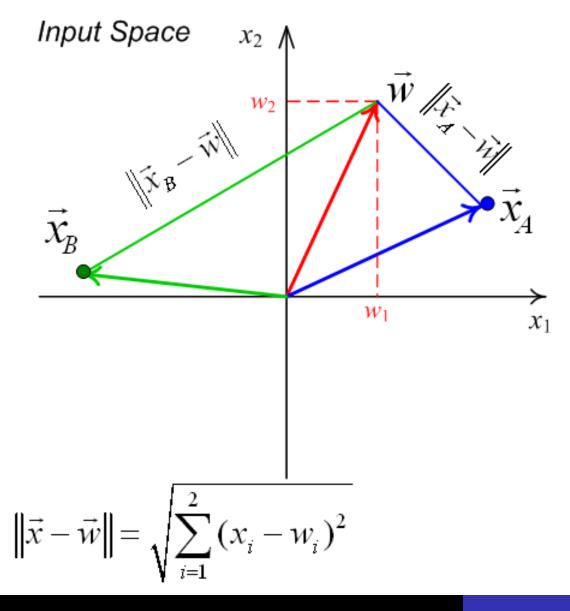


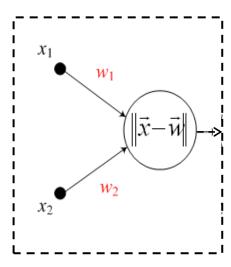


Euclidean distance measure:  $\|\vec{x} - \vec{w}\|$ 

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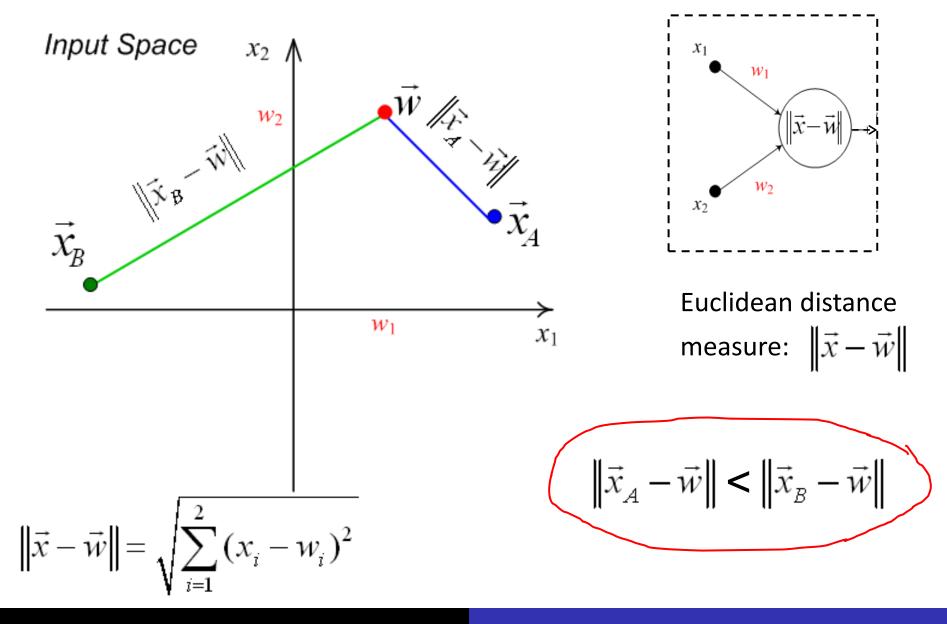




Euclidean distance measure:  $\|\vec{x} - \vec{w}\|$ 

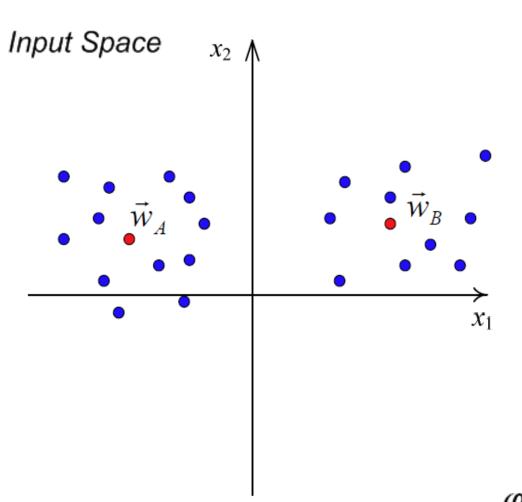
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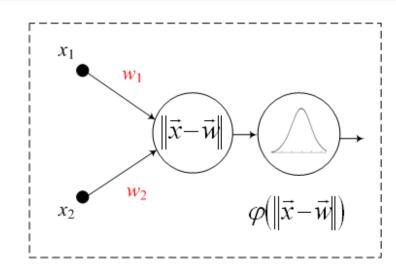
#### Weights in the input space – Euclidean distance



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# Weights in the input space – proximity measure



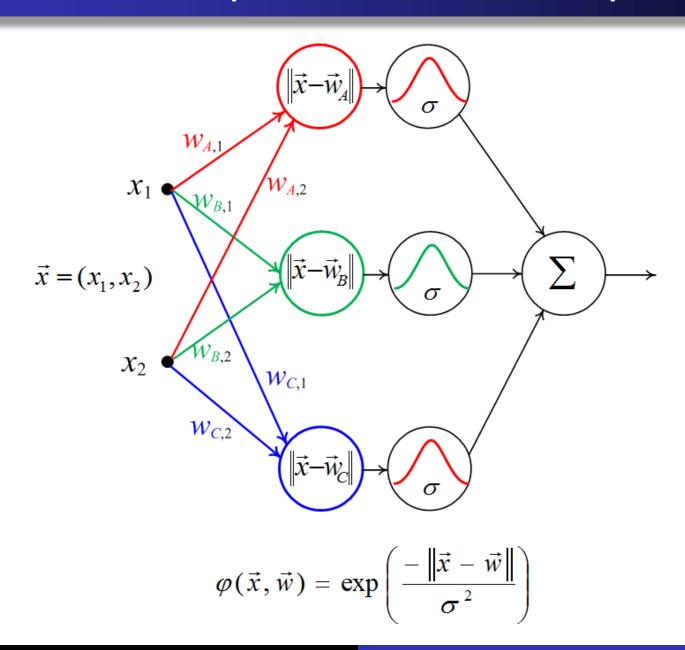


based on Euclidean distance

$$\varphi(\|\vec{x} - \vec{w}\|) = \exp\left(-\frac{\|\vec{x} - \vec{w}\|}{\sigma^2}\right)$$

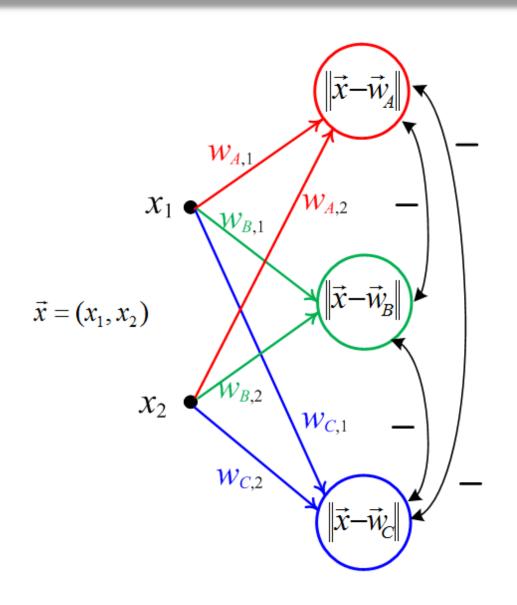
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#### RBF network – interpretation of the input weights



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#### Competition and winner-take-all mechanism



Competition

between nodes

- Winner

Takes All

(WTA)

$$\vec{w}_A = (w_{A,1}, w_{A,2})$$

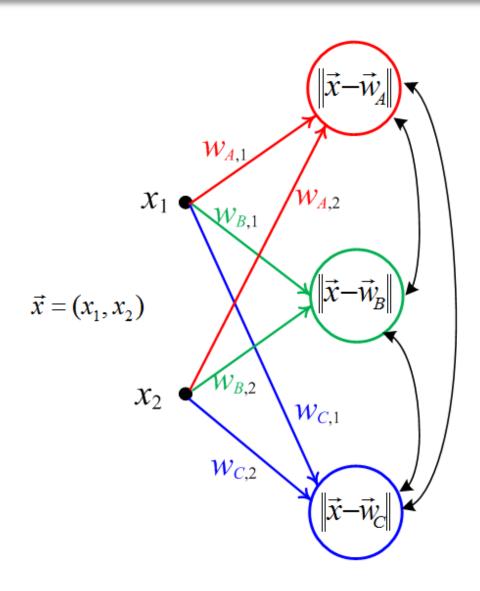
$$\vec{w}_A = (w_{A,1}, w_{A,2})$$

$$\vec{w}_B = (w_{B,1}, w_{B,2})$$

$$\vec{w}_C = (w_{C,1}, w_{C,2})$$

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#### Competitive mechanisms



If the **red** node  $w_A$  wins, then:

$$\Delta \vec{w}_{A} = \eta \vec{x}$$

OR

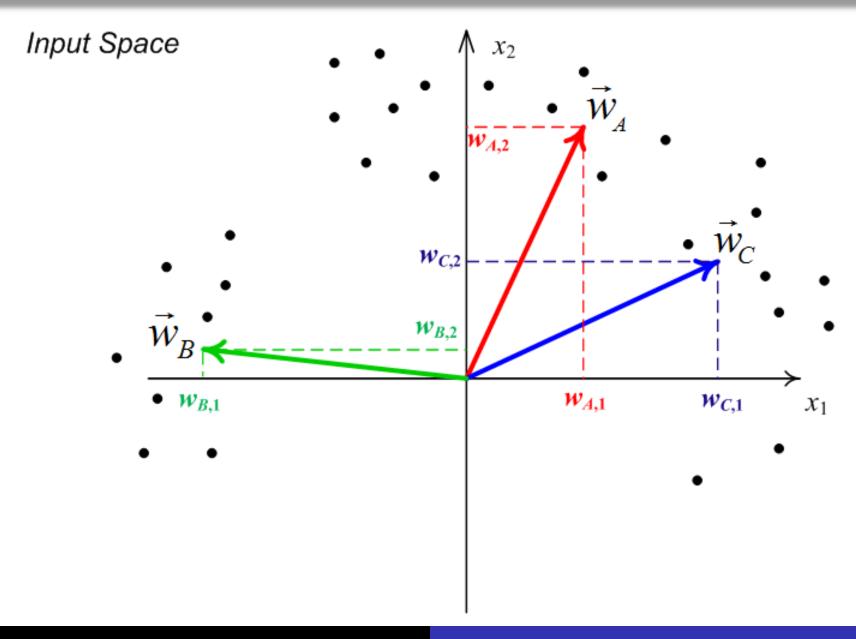
$$\Delta \vec{w}_{A} = \eta(\vec{x} - \vec{w}_{A})$$

$$\vec{w}_A = (w_{A,1}, w_{A,2})$$
 $\vec{w}_B = (w_{B,1}, w_{B,2})$ 

$$\vec{w}_C = (w_{C,1}, w_{C,2})$$

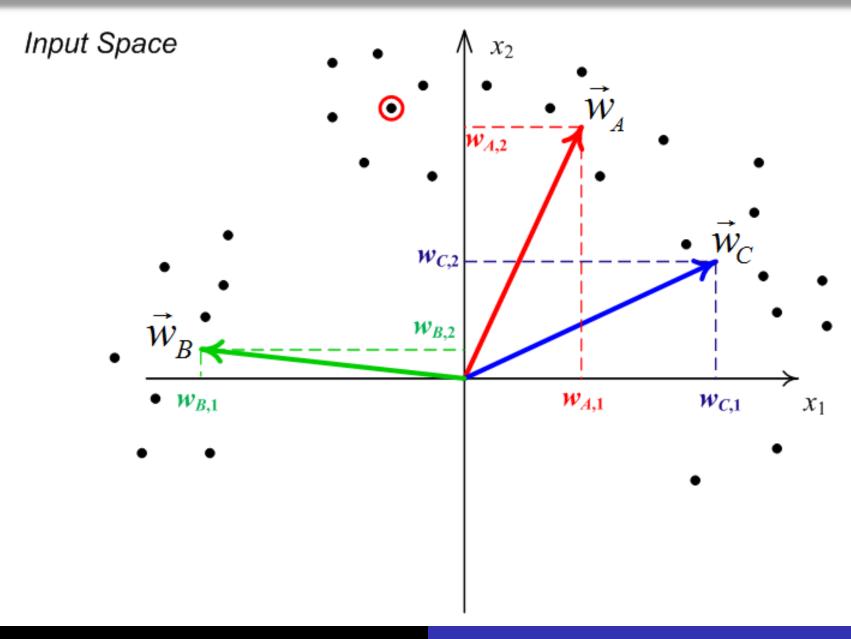
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# Competition – update of the input weights, example



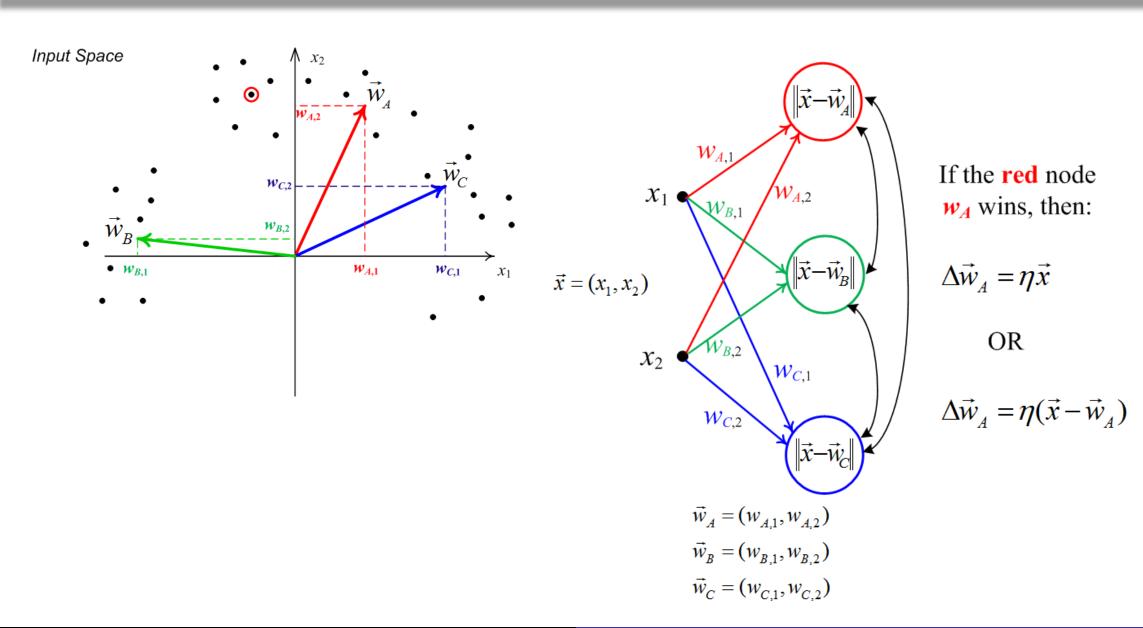
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# Competition – update of the input weights



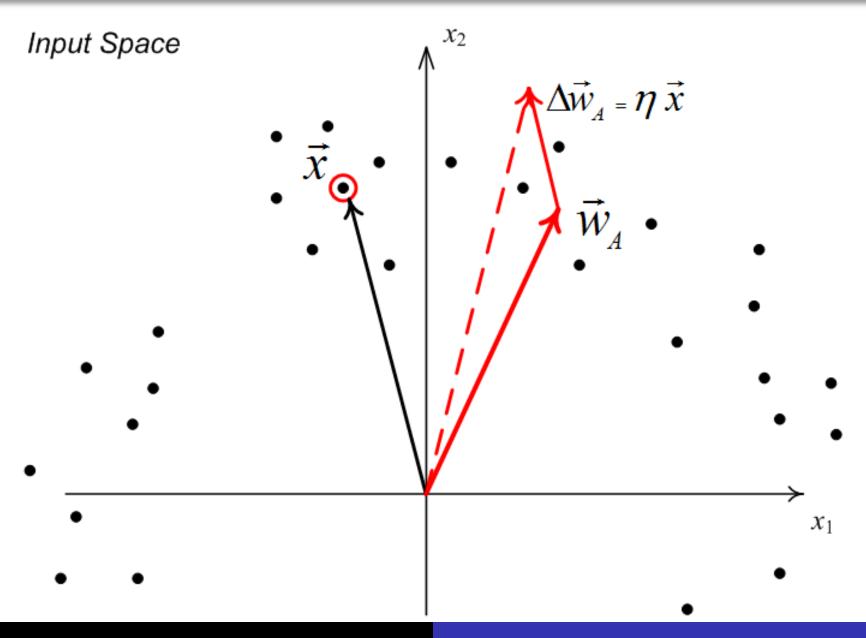
- Interpolation problem and RBFs
- RBF networks hybrid learning
- · Weight interpretation in the input space
- · Competitive mechanisms for unsupervised learning

#### Competition – update of the input weights



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#### Competition – update of the input weights, ver. 1



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#### Competition – update of the input weights, ver. 2

