Topic 10: STATISTICAL LEARNING THEORY

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Back to Supervised Learning

- Training set: $S = \{(x_1, y_1), (x_2, y_2), \dots, (x_m, y_m)\}$ with $x_i \in \mathcal{X}$ and $y_i \in \mathcal{Y}$
- Assumption: each (x,y) is chosen IID from some distribution p on $\mathcal{X} \times \mathcal{V}$
- Hypothesis: a mapping $f: x \mapsto y$ chosen from some hypothesis space \mathcal{F}
- Loss function: $\ell_{\text{true}}(\widehat{y}, y) = \mathbb{I}(\widehat{y} \neq y)$ (0/1 loss)
- Goal: find an $\widehat{f} \in \mathcal{F}$ with low true error

$$\mathcal{E}_{\text{true}}[\widehat{f}] = \mathbb{E}_{(x,y)\sim p} \, \ell(\widehat{f}(x),y).$$

Frequentist (discriminative) approach: just focus on finding a good \widehat{f} . Don't worry about learning p .

Regularized Risk Minimization (RRM)

Finds $\widehat{f} \in \mathcal{F}$, which minimizes the regularized risk

$$\mathcal{E}_{S}^{\text{reg}}[f] = \underbrace{\frac{1}{m} \sum_{i=1}^{m} \ell(f(x_i), y_i)}_{\text{training error}} + \underbrace{\lambda \Omega[f]}_{\text{regularizer}}$$

But how well will \widehat{f} do on future examples? What is its true error???

ightarrow Statistical Learning Theory

Empirical error vs. true error

 What we can measure (and what we optimize for) is the empirical error on the training set

$$\mathcal{E}_{\mathcal{S}}[f] = \frac{1}{m} \sum_{i=1}^{m} \mathbb{I}(f(x_i) \neq y_i).$$

What we want to bound is the true error.

$$\mathcal{E}_{\text{true}}[\widehat{f}] = \mathbb{E}_{(x,y)\sim p} \ell(\widehat{f}(x), y).$$

Question: Does a low \mathcal{E}_S imply a low \mathcal{E}_{true} ? Yes, provided we are not overfitting.

Probably Approximately Correct bounds

Can we show (without knowing p) that for some small ϵ

$$\mathcal{E}_{\text{true}}(\hat{f}) \le \mathcal{E}_{\mathcal{S}}(\hat{f}) + \epsilon? \tag{1}$$

No, because a really misleading training set can always mess us up.

Let's say that a training set S is **evil** if for the \widehat{f} that our algorithm returns, (1) is violated. PAC style bounds show that $\mathbb{P}[S \text{ is evil}] < \delta$, i.e.,

$$\mathbb{P}ig[\mathcal{E}_{\mathsf{true}}(\widehat{f}) > \mathcal{E}_{S}(\widehat{f}) + \epsilon ig] < \delta$$

for some small probability δ (over draws of S).

[Valiant, 1984]



"This is science at its best." -New York Times

PROBABLY APPROXIMATELY CORRECT

Nature's Algorithms for Learning and Prospering in a Complex World

53589083

LESLIE VALIANT

Hoeffding bound

For any given f with $\mathcal{E}_{\text{true}}[f] = \pi$, whether or not f makes a mistake on a random $(x,y) \sim p$ is just a $\text{Bernoulli}(\pi)$ random variable.

Hoeffding bound: If $X_1, X_2, \ldots, X_m \sim^{\text{IID}} \text{Bernoulli}(\pi)$, then

$$\mathbb{P}\left[\,\frac{1}{m}\sum_{i=1}^{m}X_{i}<\pi-\epsilon\,\right]\leq e^{-2m\epsilon^{2}}.$$

Therefore, with probability $1-\delta$ we can guarantee that the difference in error is less than

$$\epsilon = \sqrt{\frac{\log(1/\delta)}{2m}}.$$

This is how hold-out sets work.

A false argument

Since $X_i = \mathbb{I}(\widehat{f}(x_i) \neq y_i)$ are IID Bernoulli $(\mathcal{E}_{true}(\widehat{f}))$ random variables,

$$\mathbb{P}[S \text{ is evil}] = \mathbb{P}\big[\,\mathcal{E}_S(\widehat{f}) < \mathcal{E}_{\text{true}}(\widehat{f}) - \epsilon\,\big] \leq e^{-2m\epsilon^2}.$$

Question: What is the problem here?

The hypothesis \widehat{f} also depends on S, so given \widehat{f} , the random variables X_1, X_2, \ldots, X_m are not distributed according to the same distribution as a general $X = \mathbb{I}(\widehat{f}(x) \neq y)$, and give an overoptimistic estimate of $\mathcal{E}_{\text{true}}[\widehat{f}]$.

In fact, the \widehat{f} chosen by ERM/RRM tends to be one for which $\mathcal{E}_{\text{true}} - \mathcal{E}_{\mathcal{S}}$ is particularly high. \to This is not just a theoretical difficulty.

In practice, can always use a holdout set. \to Honest answer, but doesn't tell us anything about why ERM actualy works.



The union bound

Idea of Uniform convergence: put a bound on

$$\mathbb{P}\left[\exists f \in \mathcal{F} \quad \mathcal{E}_{S}(f) < \mathcal{E}_{true}(f) - \epsilon\right] \geq \mathbb{P}[S \text{ is evil}]$$

The event on the left does not depend on \hat{f} , so now the (x_i, y_i) 's really are IID.

If $\mathcal F$ is a finite set of cardinality $\mathcal C$, we have the **union bound**:

$$\mathbb{P}\left[\exists f \in \mathcal{F} \quad \mathcal{E}_{S}(f) < \mathcal{E}_{\text{true}}(f) - \epsilon\right] \leq C e^{-2m\epsilon^{2}},$$

giving

$$\epsilon = \sqrt{\frac{\log |\mathcal{F}| + \log(1/\delta)}{2m}}.$$

This is a huge overkill and only works for finite hypothesis spaces. (There are lots of $f \in \mathcal{F}$, but they are not all that different in behavior.)



Vapnik–Chervonenkis theory How do we quantify just how prone \mathcal{F} is to overfitting?

Key idea

Take an independent **ghost sample** S' of size m from p (bit like a virtual hold-out set) and prove

$$\mathcal{E}_{S}[\widehat{f}] \text{ is low } \implies \mathcal{E}_{S'}[\widehat{f}] \text{ is low } \implies \mathcal{E}_{\text{true}}[\widehat{f}] \text{ is low.}$$

This reduces to computing the union bound wrt $\mathcal{F}\downarrow_{S\cup S'}$.

For simplicity, in the following slides assume the simplest case of $\mathcal{E}_S[\widehat{f}] = 0$

Idea 1: Symmetrization

Any $f \in \mathcal{F}$ splits $\overline{S} = S \cup S'$ into two sets:

- 1. the mistake points $E_f = \{ (x, y) \in \overline{S} \mid f(x) \neq y \}$
- 2. the correct points $E'_f = \{ (x, y) \in \overline{S} \mid f(x) = y \}$.

We say that f is **bad** if $|E_f| \geq k := \lfloor m\epsilon/2 \rfloor$, but all the mistakes are in S'.

• Given x_1, \ldots, x_{2m} and an f with $|E_f| \ge k$, what is the probability that it is **bad**?

$$p \le {m \choose k} / {2m \choose k} = \frac{m(m-1)\dots(m-k+1)}{2m(2m-1)\dots(2m-k+1)} \le 2^{-k}.$$

• Now what is the probability that there is some $f \in \mathcal{F}$ that is bad? By the union bound:

$$p \leq 2^{-k} |\mathcal{F}\downarrow_{\overline{S}}|,$$

where $|\mathcal{F}\downarrow_{\overline{S}}|$ is the number of ways that \mathcal{F} can carve up \overline{S} into $E_f\cup E_f'$.

Idea 2: Vapnik-Chervonenkis dim

Definition

We say that a set $V \subseteq \mathcal{X}$ is shattered by \mathcal{F} if $|\mathcal{F}\downarrow_V| = 2^{|V|}$. The VC-dimension d of \mathcal{F} is the cardinality of the largest $V \subseteq \mathcal{X}$ that is shattered by \mathcal{F} .

Examples:

For linear classifiers in \mathbb{R}^n , d = n + 1.

For axis-aligned rectangles in \mathbb{R}^n , d = 2n.

Lemma (Sauer-Shelah)

If the VC–dimension of $\mathcal F$ is d , then for any $V\subseteq\mathcal X$ of cardinality m

$$|\mathcal{F}\downarrow_V| \leq \left(\frac{em}{d}\right)^d$$

Idea 3: Chernoff bound

Theorem

If X_1, X_2, \ldots, X_m are independently distributed binary random variables with $\mathbb{P}(X_i=1)=\theta$ and $\mathbb{P}(X_i=0)=1-\theta$, then

$$\mathbb{P}\left[\frac{1}{m}\sum_{i=1}^{m}X_{i}<\left(1-\gamma\right)\theta\right]< e^{-m\theta\gamma^{2}/2}.$$

Corollary

For any f , and any IID sample S' of size $m \ge 8/\mathcal{E}_{\text{true}}(f)$,

$$\mathbb{P}[\mathcal{E}_{S'}(f) < \mathcal{E}_{\text{true}}(f)/2] < 0.5.$$

Putting it all together

$$\begin{split} &\mathbb{P}\big[\,\,\mathcal{E}_{\text{true}}(\widehat{f}) > \epsilon\,\,\big] \\ &\leq 2\,\mathbb{P}\,[\,\,\mathcal{E}_{S'}(f) > \epsilon/2\,\,] \qquad \text{(Chernoff)} \\ &\leq 2\cdot 2^{-\lfloor m\epsilon/2\rfloor}\,|\,\mathcal{F}\!\downarrow_{\overline{S}}\,| \qquad \text{(symmetrization and using }\,\,\mathcal{E}_S(\widehat{f}) = 0\,) \\ &\leq 2\cdot 2^{-\lfloor m\epsilon/2\rfloor}\,\big(\frac{2em}{d}\big)^d \qquad \text{(Sauer-Shelah)} \\ &< \delta \qquad \text{(this is what we require)} \end{split}$$

In the $\mathcal{E}_{S}(\widehat{f}) > 0$ case the analysis is only a shade more involved.

A general VC-bound

Theorem

If ${\mathcal F}$ is a hypothesis class over ${\mathcal X}$ of VC–dimension d, then

$$\mathbb{P}\left|\left|\mathcal{E}_{\text{true}}(\widehat{f}) > \mathcal{E}_{S}(\widehat{f}) + \sqrt{\frac{d(\log\frac{2m}{d}+1) + \log(4/\delta)}{m}}\right|\right| \leq \delta$$

Margin-based VC bound

If \mathcal{F}_{γ} is the space of hyperplanes with margin $\geq \gamma$ in \mathbb{R}^n and $\widehat{f} \in \mathcal{F}$, then

$$\mathbb{P}\left[\mathcal{E}_{\mathsf{true}}(\widehat{f}) > \mathcal{E}_{\mathcal{S}}(\widehat{f}) + \sqrt{\frac{\frac{1}{\gamma^2}(\log(2m\gamma^2) + 1) + \log(4/\delta)}{m}}\right] \leq \delta.$$

Rademacher averages

Effective hypothesis space

First, put (x, y) together into a single variable z, and for $f \in \mathcal{F}$ define

$$f'(z) = \begin{cases} 0 & \text{if } f(x) = y \\ 1 & \text{if } f(x) \neq y \end{cases}.$$

Notice that

$$\mathbb{P}[\mathcal{E}_{\text{true}}(\widehat{h}) > \mathcal{E}_{S}(\widehat{h}) + \epsilon] \leq \delta \quad \Longleftrightarrow \quad \mathbb{P}\big[\sup_{f' \in \mathcal{F}'} [\mathbb{E}f'(z) - \mathbb{E}_{S}f'(z)] > \epsilon\big] \leq \delta,$$

where $\mathcal{F}' = \{ f' \mid f \in \mathcal{F} \}$ is the effective hypothesis class. \rightarrow For simplicity, in the following work with \mathcal{F}' , but drop the dashes.

Rademacher average

The Rademacher average of ${\mathcal F}$ (w.r.t. the unknown distribution p) is

$$R_m(\mathcal{F}) = \mathbb{E}\left[\sup_{f \in \mathcal{F}} \frac{1}{m} \sum_{i=1}^m \sigma_i f(z_i)\right],$$

where $z_1, \ldots, z_m \sim p$ and $\sigma_1, \ldots, \sigma_m$ are independent Rademacher random variables (i.e., $\mathbb{P}(\sigma_i = +1) = \mathbb{P}(\sigma_i = -1) = 1/2$).

The empirical Rademacher average given $S = \{z_1, \ldots, z_m\}$ is

$$\widehat{R}_m(\mathcal{F}) = \mathbb{E}_{\sigma_1,\dots,\sigma_m} \left| \sup_{f \in \mathcal{F}} \frac{1}{m} \sum_{i=1}^m \sigma_i f(z_i) \right|.$$

SUMMARY

- Instead of trying to prove $\mathcal{E}_{ ext{true}}[\widehat{f}] \leq \epsilon$, prove $\mathbb{P}[\mathcal{E}_{ ext{true}}(\widehat{f}) > \epsilon] < \delta$.
- Given \widehat{f} , the training set is no longer IID from $p \rightarrow$ union bound.
- Instead of $|\mathcal{F}|$, characterize the complexity of \mathcal{F} by its behavior on a finite sample \to VC-dimension.
- $\mathcal{E}_{S'}[\widehat{f}]$ is concentrated around its mean \to Chernoff bound.
- The probability that all the errors in $S \cup \overline{S}$ will be in \overline{S} and none in S is small \to symmetrization.
- VC-bounds are outmoded. Nowadays people use Rademacher averages and stronger concentration results.
- For practical purposes the bounds are way too loose. Things can be bad, but they are usually not as bad as they could be.

FURTHER READING

- L Valiant: A Theory of the Learnable (1984)
- V. Vapnik: Statistical Learning Theory (1998)
- F. Cucker & S. Smale: On the mathematical foundations of learning (2001)
- O. Bousquet, S. Bucheron, G. Lugosi: Introduction to statistical learning theory