

Topic 7: KERNEL METHODS

CMSC 35400/STAT 37710 Machine Learning
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General form of kernel methods

$k: \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is a PSD kernel and \mathcal{H}_k is the associated RKHS. Kernel methods (aka. Hilbert space learning algorithms) solve the RRM problem

$$\hat{f} = \operatorname{argmin}_{f \in \mathcal{H}_k} \left[\underbrace{\frac{1}{m} \sum_{i=1}^m \ell(f(x_i), y_i)}_{\text{training error}} + \underbrace{\Omega(\|f\|_{\mathcal{H}_k})}_{\text{regularizer}} \right].$$

- Ω can be any increasing function $\mathbb{R}^+ \rightarrow \mathbb{R}^+$.
- The final hypothesis is $\hat{h}(x) = \sigma(\hat{f}(x))$. For example, in the SVM, simply $\hat{h}(x) = \operatorname{sgn}(\hat{f}(x))$.
- ℓ is the **surrogate loss**. For example, in classification, the hinge loss is a surrogate for the zero-one loss.

Instead of actually having to search over a function space, all such problems reduce to m dimensional optimization thanks to the reproducing property $f(x) = \langle f, k_x \rangle$ and the Representer Theorem.

The modularity of kernel methods

Regularized risk minimization in RKHSs is a powerful paradigm because it has distinct moving parts:

- **The loss**

- Reflects the nature of the problem (classification/regression/ranking/...).
- Determines exactly what type of optimization problem we end up with.

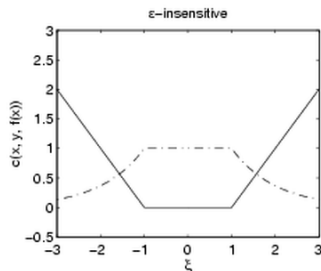
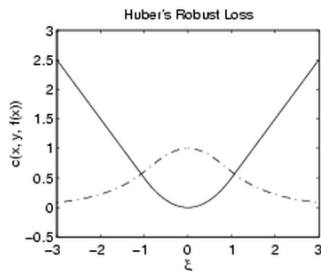
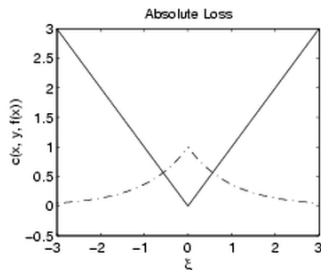
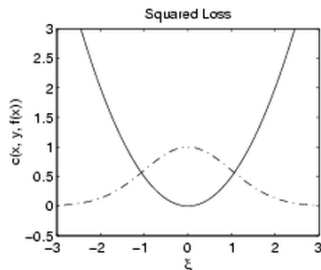
- **The kernel**

- Regulates overfitting by determining the regularization term.
- Reflects our prior knowledge about the problem.

Can dream up virtually any kernel machine and solve it efficiently as long as

1. The loss only involves function evaluations $f(x) = \langle f, k_x \rangle$ at data points;
2. The regularizer is an increasing function of $\|f\|_{\mathcal{F}}$.

Loss functions for regression



1. The kernel perceptron

The vanilla perceptron

```
w ← 0 ;  
t ← 1 ;  
while(true){  
    if w · xt ≥ 0 predict ŷt = 1 ; else predict ŷt = -1 ;  
    if ((ŷt = -1) and (yt = 1)) let w ← w + xt ;  
    if ((ŷt = 1) and (yt = -1)) let w ← w - xt ;  
    t ← t + 1 ;  
}
```

At any t , the weight vector is of the form

$$\mathbf{w} = \sum_{i=1}^{t-1} c_i \mathbf{x}_i \quad \text{where} \quad c_i \in \{-1, 0, +1\} .$$

The kernel perceptron

```
t ← 1 ;  
while(1){  
  if  $\sum_{i=1}^{t-1} c_i k(\mathbf{x}_i, \mathbf{x}_t) \geq 0$  predict  $\hat{y}_t = 1$  ; else  $\hat{y}_t = -1$  ;  
   $c_t \leftarrow 0$  ;  
  if  $((\hat{y}_t = -1) \text{ and } (y_t = 1))$  let  $c_t = 1$  ;  
  if  $((\hat{y}_t = 1) \text{ and } (y_t = -1))$  let  $c_t = -1$  ;  
   $t \leftarrow t + 1$  ;  
}
```

2. Kernel PCA

PCA in feature space

Recall that in \mathbb{R}^D (after centering), the first principal component is given by

$$\mathbf{v}_1 = \arg \max_{\|\mathbf{v}\|=1} \frac{1}{m} \sum_{i=1}^m (\mathbf{x}_i \cdot \mathbf{v})^2.$$

Clearly, \mathbf{v}_1 lies in the span, i.e., $\mathbf{v}_1 = \sum_{i=1}^m \alpha_i \mathbf{x}_i$.

Kernel analog:

$$f_1 = \operatorname{argmax}_{f \in \mathcal{F} \mid \|f\|=1} \sum_{i=1}^m \langle f, \phi(x_i) \rangle^2.$$

Once again, $f = \sum_{i=1}^m \alpha_i \phi(x_i)$ for some $\alpha_1, \dots, \alpha_m \in \mathbb{R}$.

Kernel PCA

As in \mathbb{R}^D , f will be the highest e-value e-vector of the sample covariance operator

$$\Sigma(f) = \frac{1}{m} \sum_{i=1}^m \phi(x_i) \langle f, \phi(x_i) \rangle.$$

Plugging in $f = \sum_{\ell=1}^m \alpha_{\ell} \phi(x_{\ell})$ and multiplying from the right by any $\phi(x_j)$:

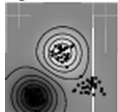
$$\frac{1}{m} \sum_{i=1}^m \sum_{\ell=1}^m \langle \phi(x_j), \phi(x_i) \rangle \langle \phi(x_i), \phi(x_{\ell}) \rangle \alpha_{\ell} = \lambda \sum_{\ell=1}^m \langle \phi(x_j), \phi(x_{\ell}) \rangle \alpha_{\ell}.$$

Using $\langle \phi(x_j), \phi(x_i) \rangle = k(x_i, x_j)$ and letting K be the Gram matrix,

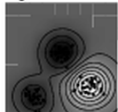
$$K^2 \alpha = m \lambda K \alpha \quad \implies \quad K \alpha = m \lambda \alpha,$$

so kernel PCA reduces to just finding the first eigenvector of the Gram matrix!

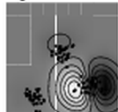
Eigenvalue=0.251



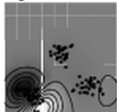
Eigenvalue=0.233



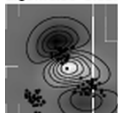
Eigenvalue=0.052



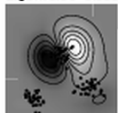
Eigenvalue=0.044



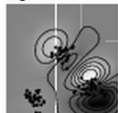
Eigenvalue=0.037



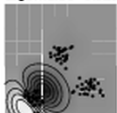
Eigenvalue=0.033



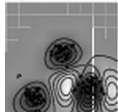
Eigenvalue=0.031



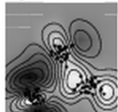
Eigenvalue=0.025



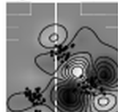
Eigenvalue=0.014



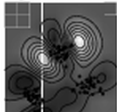
Eigenvalue=0.008



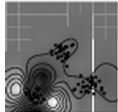
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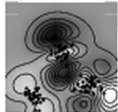
Eigenvalue=0.006



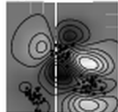
Eigenvalue=0.005



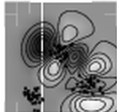
Eigenvalue=0.004



Eigenvalue=0.003



Eigenvalue=0.002



3. Ridge Regression

Ridge Regression

Using squared error loss and setting $\lambda = m/2C$,

$$\hat{f} = \operatorname{argmin}_{f \in \mathcal{H}_k} \underbrace{\left[\sum_{i=1}^m (f(x_i) - y_i)^2 + \lambda \|f\|_{\mathcal{H}_k}^2 \right]}_{\mathcal{R}[f]}.$$

By the Representer Theorem, $f(x) = \sum_{i=1}^m \alpha_i k(x_i, x)$, so

$$\mathcal{R}[f] = \sum_{i=1}^m \left(\sum_{j=1}^m \alpha_j k(x_i, x_j) - y_i \right)^2 + \lambda \sum_{i=1}^m \sum_{j=1}^m \alpha_i \alpha_j k(x_i, x_j).$$

Ridge Regression

Letting $\mathbf{y} = (y_1, \dots, y_m)$, $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_m)^\top$ and $K_{i,j} = k(x_i, x_j)$,

$$\mathcal{R}(\boldsymbol{\alpha}) = \|\mathbf{K}\boldsymbol{\alpha} - \mathbf{y}\|^2 + \lambda \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha}.$$

At the optimum,

$$\frac{\partial \mathcal{R}(\boldsymbol{\alpha})}{\partial \alpha_i} = [\mathbf{K}(\mathbf{K}\boldsymbol{\alpha} - \mathbf{y})]_i + \lambda [\mathbf{K}\boldsymbol{\alpha}]_i = 0,$$

so

$$\mathbf{K}(\mathbf{K}\boldsymbol{\alpha} - \mathbf{y}) + \lambda \mathbf{K}\boldsymbol{\alpha} = 0 \quad \implies \quad \boldsymbol{\alpha} = (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{y}.$$

Ridge Regression

Defining $\mathbf{k}_x = k(x_i, x)$, the final solution is

$$\hat{f}(x) = \mathbf{k}_x^\top (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{y}.$$

- In this case RRM reduced to just inverting a matrix.
- In fact, this is just **ridge regression**, which is a classical method in statistics, and the simplest non-linear regression/interpolation method possible.
- Ridge regression is the same as the MAP of a Gaussian Process with mean zero and covariance function k .

One-class SVM and Multiclass SVM

The one-class SVM (outlier detection)

RKHS primal form

$$\hat{f} = \operatorname{argmin}_{f \in \mathcal{H}_k} \left[\frac{1}{m} \sum_{i=1}^m (1 - f(x_i))_{\geq 0} + \frac{1}{2C} \|f\|_{\mathcal{H}_k}^2 \right].$$

Tries to peg $f(x_i) \geq 0$ for all points x_1, \dots, x_m in the training set
→ outlier detector.

Dual form

$$\begin{aligned} \text{maximize}_{\alpha_1, \dots, \alpha_m} L(\boldsymbol{\alpha}) &= \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j k(x_i, x_j) \\ \text{subject to} \quad &0 \leq \alpha_i \leq \frac{C}{m} \quad \forall i \end{aligned}$$

The Multiclass SVM

- Defining $f_z(x) = zf(x)/2$ for $z = \pm 1$,

$$\ell_{\text{hinge}}(f(x), y) = (1 - yf(x))_{\geq 0} = (1 - (f_y(x) - f_{-y}(x)))_{\geq 0},$$

i.e., the correct answer is supposed to beat the incorrect answer by at least a margin of 1.

- This inspires the **multiclass hinge loss**

$$\ell(f_1(x), \dots, f_k(x), y) = \sum_{y' \in \{1, 2, \dots, k\} \setminus \{y\}} (1 - (f_y(x) - f_{y'}(x)))_{\geq 0},$$

which is the basis of the k -class SVM ($f_j(x)$ is a bit like a “score”). This is essentially the same notion of multiclass margin as in the k -class perceptron. Predict $\hat{y} = \operatorname{argmax}_{j \in \mathcal{Y}} f_j(x, j)$.

RKHS form of Multiclass SVM

The loss now depends on not just $f_y(x)$, but also $f_{y'}(x)$ for all $y' \neq y$, so the RKHS form also needs to be generalized slightly:

$$\hat{f} = \operatorname{argmin}_{f \in \mathcal{H}_k} \left[\underbrace{\frac{1}{m} \sum_{i=1}^m \ell(f_1(x_i), f_2(x_i), \dots, f_k(x_i), y_i)}_{\text{training error}} + \underbrace{\Omega(\|f\|_{\mathcal{H}})}_{\text{regularizer}} \right].$$

The corresponding generalized Representer Theorem will say that

$$f_j(x) = \sum_{i=1}^m \alpha_{i,j} k(x_i, x)$$

for all $j \in \{1, \dots, k\}$, so now we have many more coefficients to optimize.

Structured prediction

Multiclass to Structured Prediction

What if we combine $f_1, \dots, f_k: \mathcal{X} \rightarrow \mathbb{R}$ in the k -class SVM into a single function $f: \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$ where $\mathcal{Y} = \{1, \dots, k\}$? The loss becomes

$$\ell(f, x, y) = \sum_{y' \in \mathcal{Y} \setminus \{y\}} (1 - (f(x, y) - f(x, y')))_\geq 0.$$

IDEA: Use this to search for f in a **joint RKHS** of functions $f: \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$:

- Kernel becomes $k((x, y), (x', y'))$.
- We can now put structure on \mathcal{Y} as well as \mathcal{X} .
- We are now learning a single mapping $f: \mathcal{X} \rightarrow \mathcal{Y}$ directly.
- At the extreme, the distinction between \mathcal{X} and \mathcal{Y} is blurred.

→ **structured prediction**

RRM form of Structured Prediction

Let k be a psd kernel $k: (\mathcal{X} \times \mathcal{Y}) \times (\mathcal{X} \times \mathcal{Y}) \rightarrow \mathbb{R}$, let \mathcal{H}_k be the corresponding RKHS, and Ω a monotonically increasing function. Solve

$$\hat{f} = \arg \min_{f \in \mathcal{H}_k} \left[\underbrace{\frac{1}{m} \sum_{i=1}^m \ell((f(x_i, y))_{y \in \mathcal{Y}}, y_i)}_{\text{training error}} + \underbrace{\Omega \|f\|_{\mathcal{F}}}_{\text{regularizer}} \right],$$

and predict $\hat{y} = \operatorname{argmax}_{y \in \mathcal{Y}} \hat{f}(x, y)$.

The loss (in principle) now depends on $f(x_i, y)$ for all possible y . Therefore, the Representer Theorem says that f is of the form

$$f(x, y) = \sum_{i=1}^m \sum_{y^* \in \mathcal{Y}} \alpha_{i, y^*} k((x_i, y^*), (x, y)).$$

In practice, this is usually unfeasible, so only add α_{i, y^*} coefficients to the optimization on the fly “as needed”.

Kernels for Structured Learning

The simplest way to get a kernel $k: (\mathcal{X} \times \mathcal{Y}) \times (\mathcal{X} \times \mathcal{Y}) \rightarrow \mathbb{R}$:

- Get a kernel $k_{\mathcal{X}}$ that quantifies similarity between the x 's.
- Get a kernel $k_{\mathcal{Y}}$ that quantifies similarity between the y 's.
- Define

$$k((x, y), (x', y')) = k_{\mathcal{X}}(x, x') \cdot k_{\mathcal{Y}}(y, y').$$

Question: Is this a valid kernel? What is its RKHS?