

Low-Latency Privacy-Aware Robot Behavior guided by Automatically Generated Text Datasets

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Abstract

Objective : Realize humanoid robot exhibiting privacy-aware behavior.

Summary : Without collecting ethically sensitive images, distill knowledge from an LLM and achieve text-based image privacy recognition.

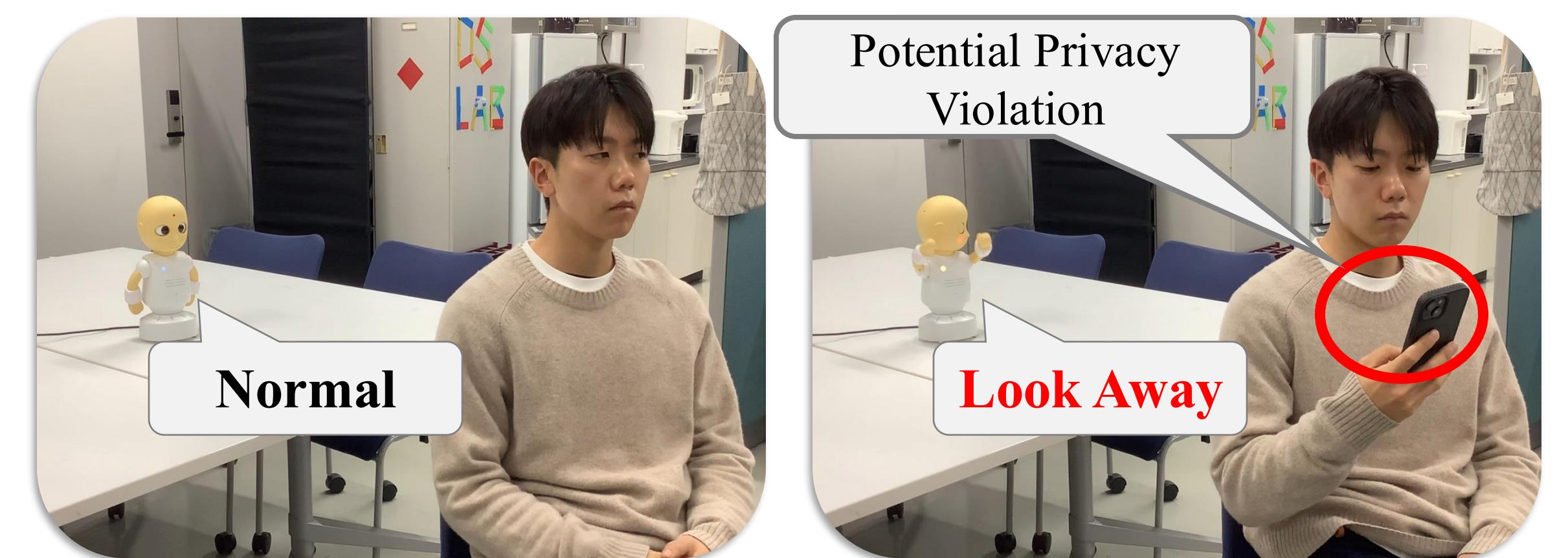
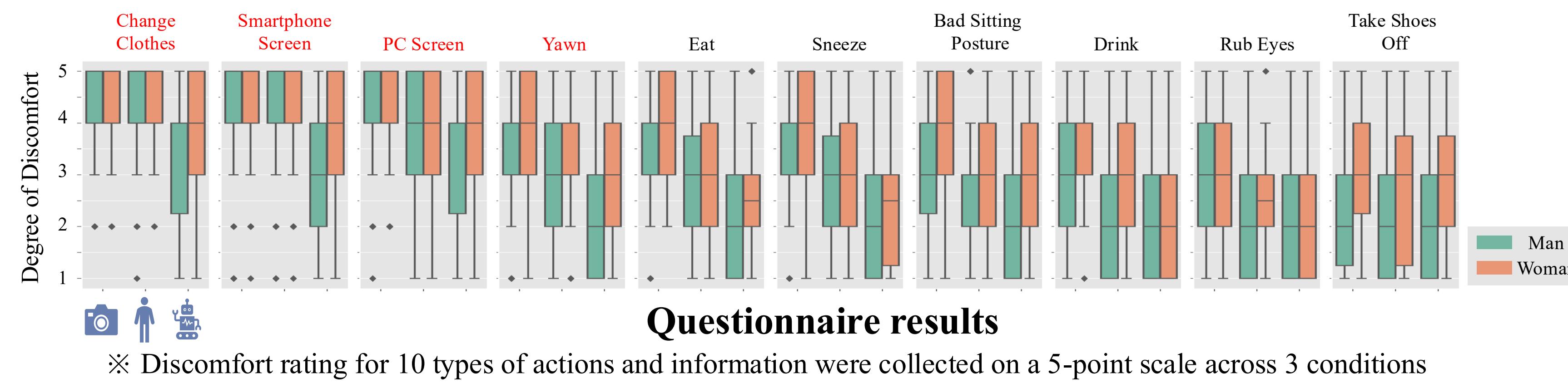
Background

Humanoid robots with human-like appearance should behave naturally and consider privacy

⇒ User study with 200 participants

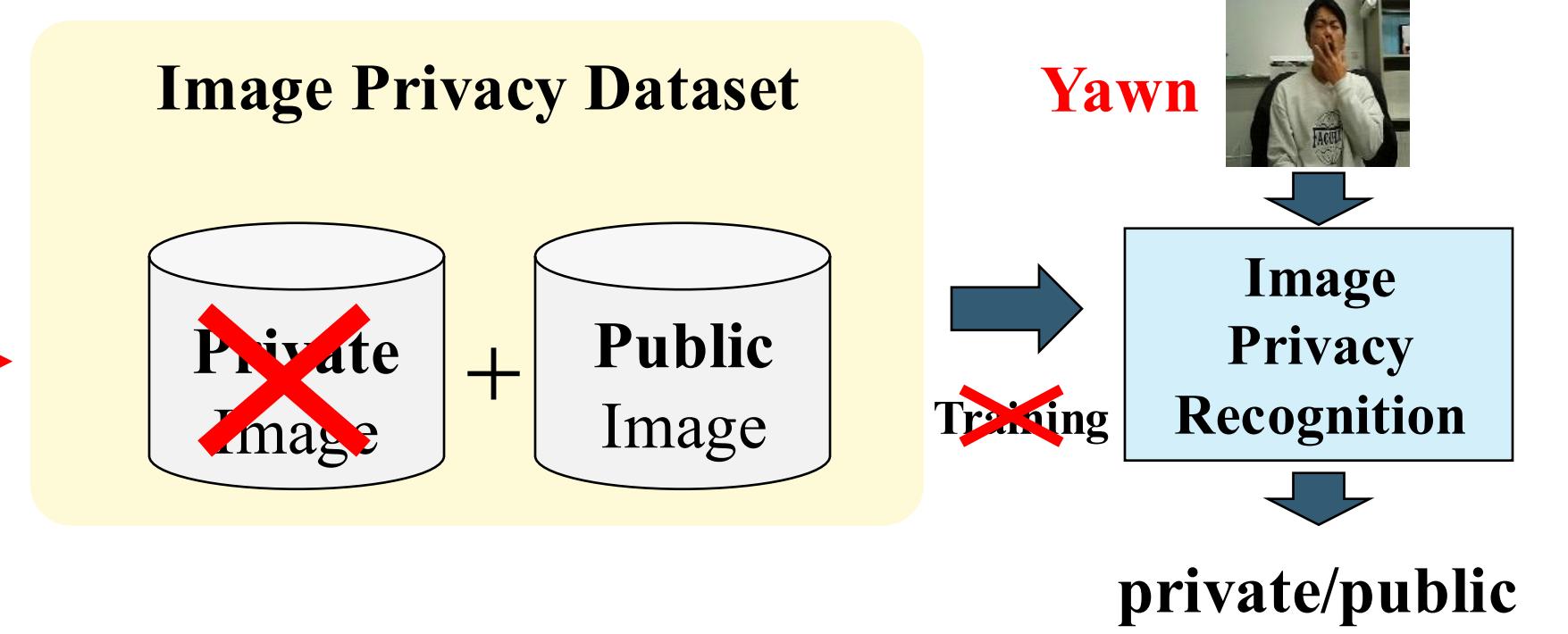
◆ Discomfort arises when a robot observes private scenes
(e.g., changing clothes, smartphone/PC screen).

◆ Robot observation causes less discomfort than cameras or humans.
However, discomfort remains in private contexts.



Problems of existing methods

■ Specialized model (Image Privacy Recognition Model) : usually requires an image privacy dataset

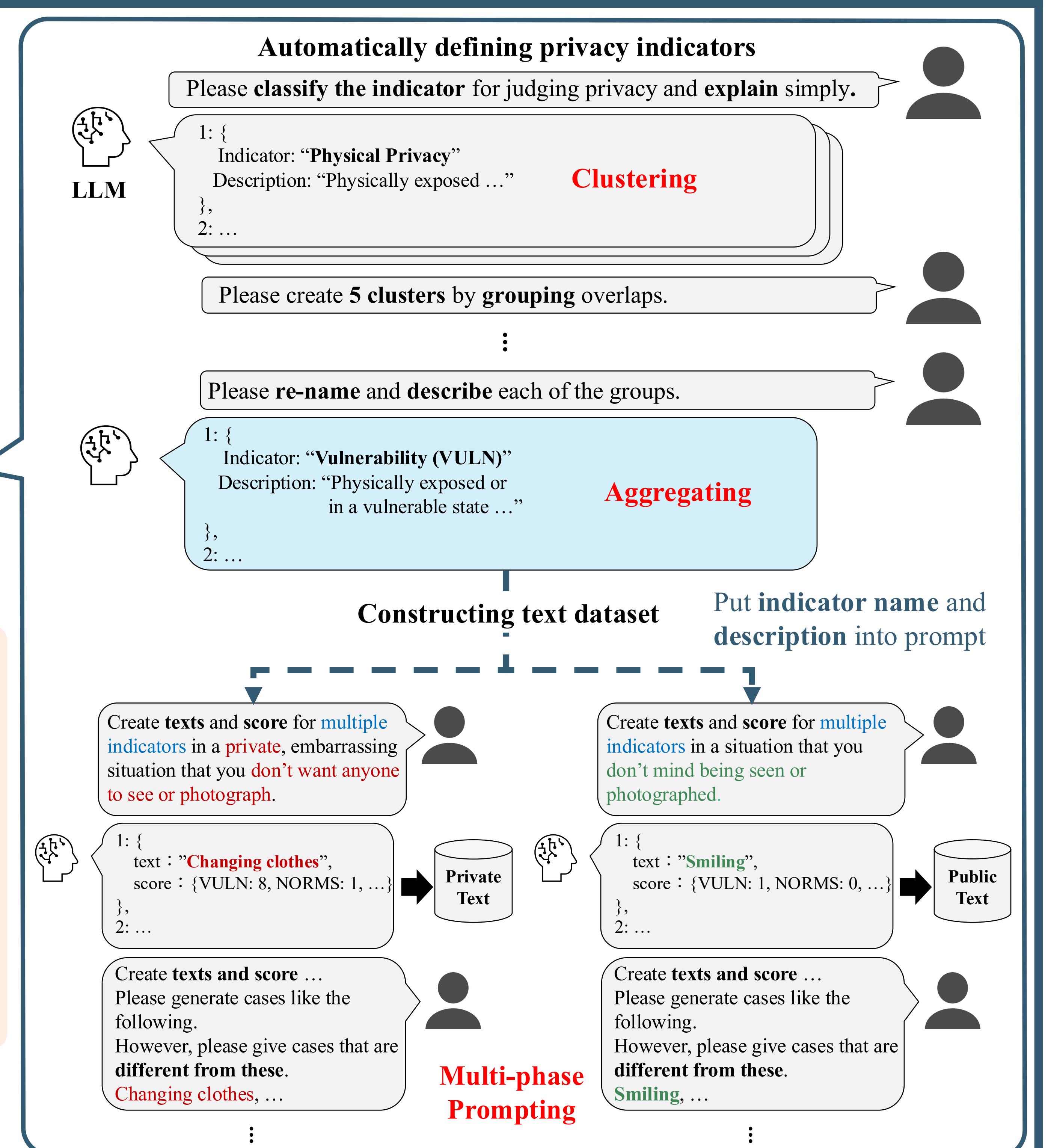
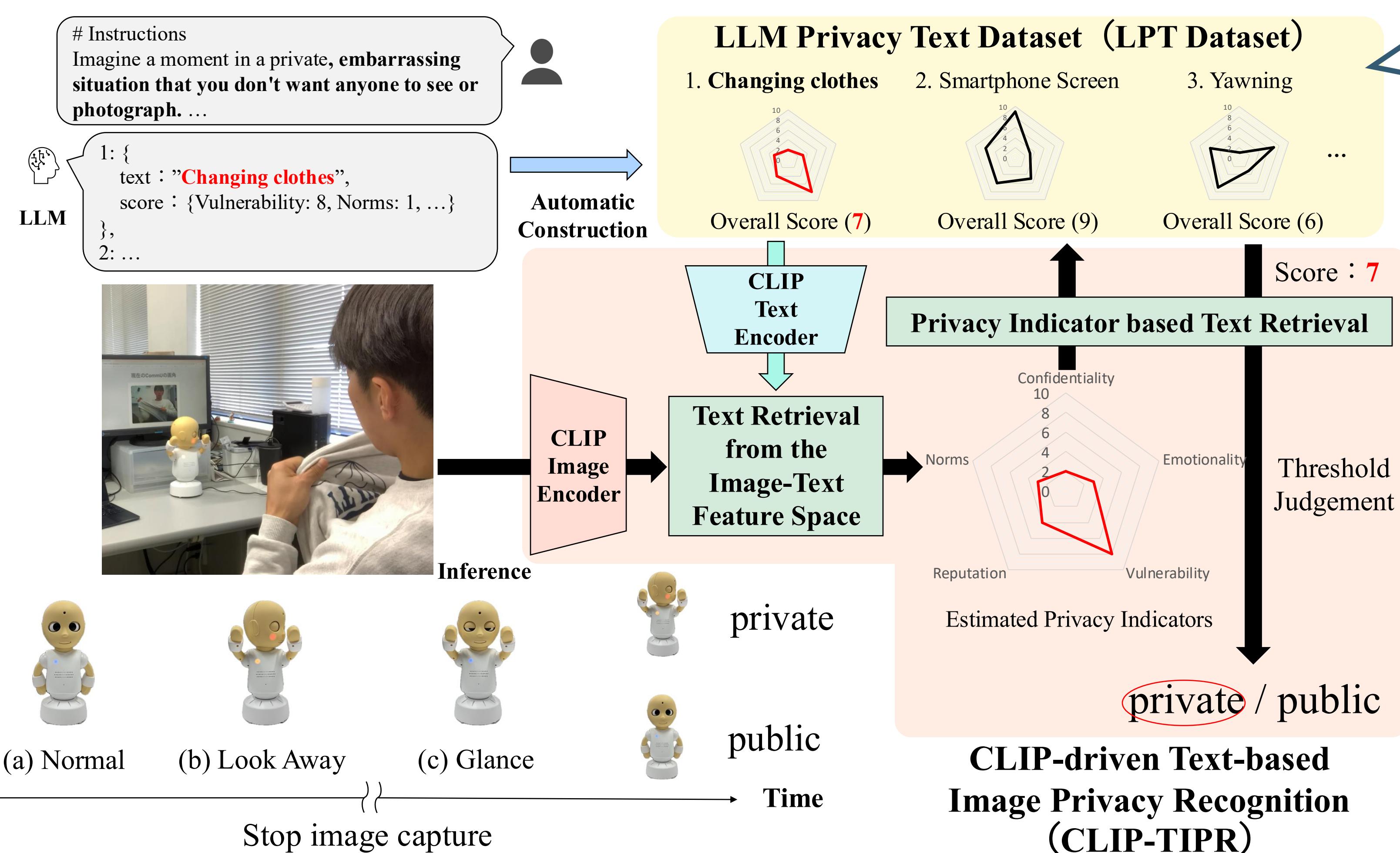


■ General-purpose model (LVLM): requires about 3 seconds for high-accuracy recognition, causing large delay

Proposed Framework

Contributions

- Enable humanoid robots to **recognize privacy-sensitive situations** and **respond appropriately**.
- Propose a **low-latency and robust** recognition method with **fewer ethical concerns** by utilizing a **text dataset automatically constructed by an LLM**.



Experiments

Details of LPT Dataset

- Model: GPT-4o
- Number of Indicators: 5
- Generated Texts: $1,000 \times 2$ (private/public)

Evaluation Metrics

macro F1-score

Comparison Methods

#	Methods	Text Dataset
I	ZSVCP	LPT Dataset (binary)
II	CLIP-TIPR (Text-based)	Single Abstract Indicator ※ Construct with only overall score
III	CLIP-TIPR (Indicator-based)	LPT Dataset
IV	LVLM-simple	-
V	LVLM-cot	-

Examples of LPT Dataset text and scores

	Text			CONF	EMO	VULN	REP	NORMS	OA
	Having your pants accidentally torn in a very public place.			0	6	8	7	9	10
	Having your phone sent a personal message to a group chat by mistake.			5	7	0	6	8	9
	Photographed yawning widely in a serious meeting.			0	2	1	3	6	6

Quantitative Evaluation Results

#	macro F1-score ↑			Processing Time (s) ↓
	CPI Dataset	PrivacyAlert	VISPR	
I	0.500	0.543	0.525	0.059
II	0.440	0.577	0.306	0.058
III	0.680	0.582	0.461	0.074
IV	0.417	0.249	0.437	2.040
V	0.644	0.706	0.415	3.198

CLIP-TIPR (III) achieved accurate and robust performance

User Feedback Results

Score

TP Rate TN Rate Harmonic Mean (TP/TN) Reaction Immediacy

II III V III + V

Proposed methods (III · III+V) achieved accurate and low-latency recognition

Future Work

- Improve recognition for fine-grained actions and objects.
- Address differences in privacy perceptions across cultures and individuals.