Lab 5: RV64 缺页异常处理

3210105488 刘扬

1 实验过程

1.1 准备工作

从repo同步框架,不赘述。

在 trap handler 中传入新的参数 stval 供本次实验使用:

```
void trap_handler(unsigned long scause, unsigned long sepc, unsigned long stval, struct
pt_regs *regs);
```

1.2 实现VMA

1.2.1 修改 proc.h

结构体定义如下:

```
0x0000000000000008
#define VM X MASK
#define VM_W_MASK
                      0x0000000000000004
#define VM R MASK
                      0x00000000000000002
                      0x0000000000000001
#define VM ANONYM
struct vm area struct {
                        /* VMA 对应的用户态虚拟地址的开始 */
   uint64 vm_start;
                        /* VMA 对应的用户态虚拟地址的结束 */
   uint64 vm_end;
   uint64 vm flags;
                        /* VMA 对应的 flags */
   /* uint64 t file offset on disk */ /* 原本需要记录对应的文件在磁盘上的位置,
                           但是我们只有一个文件 uapp,所以暂时不需要记录 */
   uint64 vm_content_offset_in_file;
                                             /* 如果对应了一个文件,
                    那么这块 VMA 起始地址对应的文件内容相对文件起始位置的偏移量,
                                    也就是 ELF 中各段的 p_offset 值 */
                                           /* 对应的文件内容的长度。
   uint64 vm_content_size_in_file;
                                              思考为什么还需要这个域?
                                              和 (vm end-vm start)
                                              一比,不是冗余了吗? */
};
/* 线程数据结构 */
struct task_struct {
   struct thread info thread info;
   uint64 state; // 线程状态
   uint64 counter; // 运行剩余时间
```

```
uint64 priority; // 运行优先级 1最低 10最高
uint64 pid; // 线程id

struct thread_struct thread;
uint64 satp;
pagetable_t pgd;
uint64 vma_cnt; /* 下面这个数组里的元素的数量 */
struct vm_area_struct vmas[0]; /* 为什么可以开大小为 0 的数组?
这个定义可以和前面的 vma_cnt 换个位置吗? */
};
```

添加 do mmap 和 vm area struct 声明:

```
void do_mmap(struct task_struct *task, uint64_t addr, uint64_t length, uint64_t flags,
     uint64_t vm_content_offset_in_file, uint64_t vm_content_size_in_file);
struct vm_area_struct *find_vma(struct task_struct *task, uint64_t addr);
```

1.2.2 修改 task init

修改 task_init 函数代码, 更改为 Demand Paging:

- 取消之前实验中对 U-MODE 代码以及栈进行的映射
- 调用 do_mmap 函数,建立用户 task 的虚拟地址空间信息。

在下述代码中, load program 调用了 do mmap 建立用户 task 的虚拟地址空间信息。

```
void task_init() {
    test_init(NR_TASKS);
    ...
    for (int i = 1;i < NR_TASKS;i++ ) {
        task[i] = (struct task_struct*)kalloc();
        task[i]->state = TASK_RUNNING;
    ...
        load_program(task[i], pgtbl); // 在load_program中调用do_mmap
        uint64 satp = (uint64)0x8 << 60;
        satp |= ((uint64)(pgtbl) - PA2VA_OFFSET) >> 12;
        task[i]->satp = satp;
    }
    printk("...proc_init_done!\n");
}
```

load_program 如下:

```
static uint64 load_program(struct task_struct* task, pagetable_t pgtbl) {
    Elf64_Ehdr* ehdr = (Elf64_Ehdr*)_sramdisk;

    uint64 phdr_start = (uint64)ehdr + ehdr->e_phoff;
    int phdr_cnt = ehdr->e_phnum;
```

```
Elf64 Phdr* phdr;
   for (int i = 0; i < phdr cnt; i++) {
        phdr = (Elf64 Phdr*)(phdr start + sizeof(Elf64 Phdr) * i);
        if (phdr->p_type == PT_LOAD) {
            uint64 offset = (uint64)(phdr->p_vaddr) % PGSIZE;
            uint64 num_pages = (phdr->p_memsz + offset) / PGSIZE;
            if (num_pages * PGSIZE < (phdr->p_memsz + offset)){
                num_pages++;
            uint64 length = num_pages * PGSIZE;
            do mmap(task, phdr->p vaddr, length, phdr->p flags, phdr->p offset, phdr-
>p filesz);
   do_mmap(task, USER_END-PGSIZE, PGSIZE, VM_R_MASK | VM_W_MASK | VM_ANONYM, 0, 0);
   task->thread.sepc = ehdr->e entry;
   unsigned long sstatus = csr read(sstatus);
   sstatus &= ~(1 << 8); // sstatus[SPP] = 0
   sstatus |= 1 << 5; // sstatus[SPIE] = 1</pre>
   sstatus |= 1 << 18; // sstatus[SUM] = 1
   task->thread.sstatus = sstatus;
   task->thread.sscratch = USER END;
}
```

在 load_program 中**只建立用户 task 的虚拟地址空间信息**,并不进行读取,当真正访问该页时,才读取对应的页。

1.2.3 do_mmap 实现

简单地将传入的参数进行存储即可。注意flags的对应关系。

```
void do_mmap(struct task_struct *task, uint64 addr, uint64 length, uint64 flags,
    uint64 vm_content_offset_in_file, uint64 vm_content_size_in_file) {

    struct vm_area_struct* vma = &(task->vmas[task->vma_cnt]);
    task->vma_cnt++;
    vma->vm_start = addr;
    vma->vm_end = addr + length;
    vma->vm_flags = 0;
    if(flags & 1) {
        vma->vm_flags += (1 << 3);
    }
    if(flags & 2) {
        vma->vm_flags += (1 << 2);
    }
    if(flags & 4) {
        vma->vm_flags += (1 << 1);
    }
    vma->vm_content_offset_in_file = vm_content_offset_in_file;
    vma->vm_content_size_in_file = vm_content_size_in_file;
```

}

在实现完上述步骤后, trap handler 会检测到page fault, 但还不能对page fault进行处理。

1.2.4 实现 Page Fault 的检测与处理

在 trap_handler 中检测page fault

```
void trap_handler(unsigned long scause, unsigned long sepc, unsigned long stval, struct
pt_regs *regs) {
    if (scause == 0x80000000000000000) {
        ...
    }
    else if (scause == 8) {
        ...
    }
    else if(scause == (uint64)0xc || scause == (uint64)0xd || scause == (uint64)0xf) {
        printk("[S] Supervisor Page Fault, scause: %lx, stval: %lx, sepc: %lx\n", scause,
    stval, sepc);
        do_page_fault(regs, stval);
    }
    else {
        ...
    }
}
```

调用 do page fault 处理page fault:

• 需要先找到错误地址(stval)的vma, 调用了 find vma

```
struct vm_area_struct *find_vma(struct task_struct *task, uint64_t addr){
  for(int i = 0; i < task->vma_cnt; i++){
    if(addr >= task->vmas[i].vm_start && addr < task->vmas[i].vm_end){
      return &(task->vmas[i]);
    }
}
return NULL;
}
```

• 调用 create_mapping 进行页表映射

```
create_mapping(current->pgd, PGROUNDDOWN(stval), (uint64)new_page-PA2VA_OFFSET,
PGSIZE, (vma->vm_flags | 0x11))
```

• 如果是非匿名的page,则需要将 uapp 对应地址的内容拷贝进来。注意要做对齐,如果是vm_start的所在的第一页,做拷贝时需要把vm_start的页偏移量考虑上,如果是后面的页,则拷贝一整页。

```
if(!(vma->vm_flags & VM_ANONYM)) {
    char *src_addr = (char*)(_sramdisk + vma->vm_content_offset_in_file);
    if(stval - PGROUNDDOWN(vma->vm_start) < PGSIZE) {</pre>
```

```
uint64 offset = stval % PGSIZE;
for(int j = 0;j < PGSIZE - offset;j++){
    new_page[j + offset] = src_addr[j];
}

else{
    uint64 pg_offset = (stval - PGROUNDDOWN(vma->vm_start)) / PGSIZE;
    uint64 offset = stval % PGSIZE;
    for(int j = 0;j < PGSIZE;j++){
        new_page[j] = src_addr[j + PGSIZE * pg_offset - offset];
    }
}</pre>
```

do_page_fault 完整代码如下:

```
void do page fault(struct pt regs *regs, unsigned long stval) {
    struct vm area struct *vma = find vma(current, stval);
    char *new page = alloc page();
    create mapping(current->pgd, PGROUNDDOWN(stval), (uint64)new page-PA2VA OFFSET,
PGSIZE, (vma->vm flags | 0x11));
    if(!(vma->vm_flags & VM_ANONYM)){
        char *src_addr = (char*)(_sramdisk + vma->vm_content_offset_in_file);
        if(stval - PGROUNDDOWN(vma->vm_start) < PGSIZE){</pre>
            uint64 offset = stval % PGSIZE;
            for(int j = 0; j < PGSIZE - offset; j++){</pre>
                new_page[j + offset] = src_addr[j];
        }
        else{
            uint64 pg offset = (stval - PGROUNDDOWN(vma->vm start)) / PGSIZE;
            uint64 offset = stval % PGSIZE;
            for(int j = 0; j < PGSIZE; j++){
                new_page[j] = src_addr[j + PGSIZE * pg_offset - offset];
            }
        }
    }
}
```

2 实验结果

我在实验中创建了4个user进程,每个进程发生3次page fault,依次分别是取指令错误,栈错误和访存错误,一共12次page fault。

```
switch to [PID = 1 PRIORITY = 37 COUNTER = 4]
[S] Supervisor Page Fault, scause: 000000000000000, stval: 0000000000100e8, sepc: 0
000000000100e8
[S] Supervisor Page Fault, scause: 00000000000000f, stval: 0000003fffffffff8, sepc: 0
000000000010124
[S] Supervisor Page Fault, scause: 00000000000000d, stval: 000000000011880, sepc: 0
00000000010140
[PID = 1] is running, variable: 0
[PID = 1] is running, variable: 1
[PID = 1] is running, variable: 2
[PID = 1] is running, variable: 3
switch to [PID = 4 PRIORITY = 66 COUNTER = 5]
[S] Supervisor Page Fault, scause: 000000000000000, stval: 0000000000100e8, sepc: 0
000000000100e8
[S] Supervisor Page Fault, scause: 00000000000000f, stval: 0000003fffffffff8, sepc: 0
000000000010124
[S] Supervisor Page Fault, scause: 00000000000000d, stval: 000000000011880, sepc: 0
000000000010140
[PID = 4] is running, variable: 0
[PID = 4] is running, variable: 1
[PID = 4] is running, variable: 2
[PID = 4] is running, variable: 3
[PID = 4] is running, variable: 4
[PID = 4] is running, variable: 5
switch to [PID = 3 PRIORITY = 52 COUNTER = 8]
[S] Supervisor Page Fault, scause: 000000000000000, stval: 0000000000100e8, sepc: 0
000000000100e8
[S] Supervisor Page Fault, scause: 00000000000000f, stval: 0000003fffffffff8, sepc: 0
000000000010124
[S] Supervisor Page Fault, scause: 00000000000000d, stval: 000000000011880, sepc: 0
000000000010140
[PID = 3] is running, variable: 0
[PID = 3] is running, variable: 1
[PID = 3] is running, variable: 2
[PID = 3] is running, variable: 3
[PID = 3] is running, variable: 4
[PID = 3] is running, variable: 5
[PID = 3] is running, variable: 6
[PID = 3] is running, variable: 7
[PID = 3] is running, variable: 8
switch to [PID = 2 PRIORITY = 88 COUNTER = 9]
[S] Supervisor Page Fault, scause: 000000000000000, stval: 0000000000100e8, sepc: 0
000000000100e8
[S] Supervisor Page Fault, scause: 00000000000000f, stval: 0000003fffffffff8, sepc: 0
000000000010124
[S] Supervisor Page Fault, scause: 00000000000000d, stval: 000000000011880, sepc: 0
00000000010140
[PID = 2] is running, variable: 0
[PID = 2] is running, variable: 1
[PID = 2] is running, variable: 2
[PID = 2] is running. variable: 3
```

```
[PID = 2] is running, variable: 4
[PID = 2] is running, variable: 5
[PID = 2] is running, variable: 6
[PID = 2] is running, variable: 7
[PID = 2] is running, variable: 8
[PID = 2] is running, variable: 9
SET [PID = 4 PRIORITY = 66 COUNTER = 1]
SET [PID = 3 PRIORITY = 52 COUNTER = 4]
SET [PID = 2 PRIORITY = 88 COUNTER = 10]
SET [PID = 1 PRIORITY = 37 COUNTER = 4]
switch to [PID = 4 PRIORITY = 66 COUNTER = 1]
[PID = 4] is running, variable: 6
switch to [PID = 1 PRIORITY = 37 COUNTER = 4]
[PID = 1] is running, variable: 4
[PID = 1] is running, variable: 5
[PID = 1] is running, variable: 6
[PID = 1] is running, variable: 7
[PID = 1] is running, variable: 8
switch to [PID = 3 PRIORITY = 52 COUNTER = 4]
[PID = 3] is running, variable: 9
switch to [PID = 1 PRIORITY = 37 COUNTER = 4]
[PID = 1] is running, variable: 4
[PID = 1] is running, variable: 5
[PID = 1] is running, variable: 6
[PID = 1] is running, variable: 7
[PID = 1] is running, variable: 8
switch to [PID = 3 PRIORITY = 52 COUNTER = 4]
[PID = 3] is running, variable: 9
[PID = 3] is running, variable: 10
[PID = 3] is running, variable: 11
[PID = 3] is running, variable: 12
switch to [PID = 2 PRIORITY = 88 COUNTER = 10]
[PID = 2] is running, variable: 10
[PID = 2] is running, variable: 11
[PID = 2] is running, variable: 12
[PID = 2] is running, variable: 13
[PID = 2] is running, variable: 14
[PID = 2] is running, variable: 15
QEMU: Terminated
parallels@ubuntu-linux-22-04-02-desktop:~/oslab/lab5$
```

3 思考题

1. uint64 t vm content size in file; 对应的文件内容的长度。为什么还需要这个域?

在 do_mapp 中, vm_content_size_in_file 映射的是 uapp 中的 phdr->p_filesz,而本段内容在内容镜像中的大小是大于 phdr->p_filesz 的。在上个lab的思考题中也提到过这二者的区别:段的文件映像是指存储在文件中的段的部分。段的内存映像是指在程序执行期间加载到内存中的段的部分。 p_memsz (即 length)大于 p_filesz (即 vm_content_size_in_file)的原因是,可加载段可能包含 .bss 节,该节包含未初始化的数据。将此数据存储在磁盘上会很浪费,因此,仅在ELF文件加载到内存后才占用空间。 struct

2. vm_area_struct vmas[0];为什么可以开大小为 0 的数组?这个定义可以和前面的 vma_cnt 换个位置吗?

参考: 你了解C语言的"柔性数组"吗? 看完你就知道了 - 知乎 (zhihu.com)

该数组是柔性数组。这个特性允许你在定义结构体的时候创建一个空数组,而这个数组的大小可以在程序运行的过程中根据你的需求进行更改。特别注意的一点是:这个空数组必须声明为结构体的最后一个成员,并且还要求这样的结构体至少包含一个其他类型的成员。

可以看到柔性数组必须在结构体的最后声明。在本实验中,如果和vma_cnt交换位置,在后续写入vmas数组时,会将vma_cnt的值覆盖掉,导致错误。