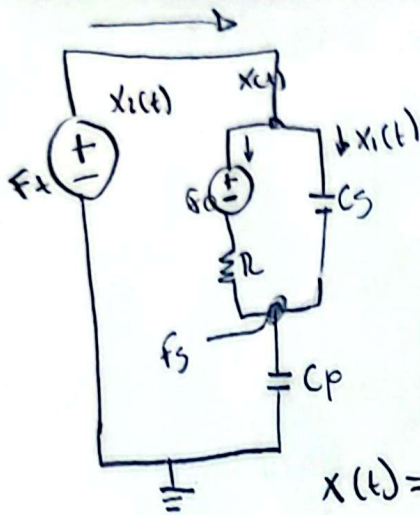


Circuito eléctrico



$$X(t) = X_1(t) + X_2(t)$$

Modelado

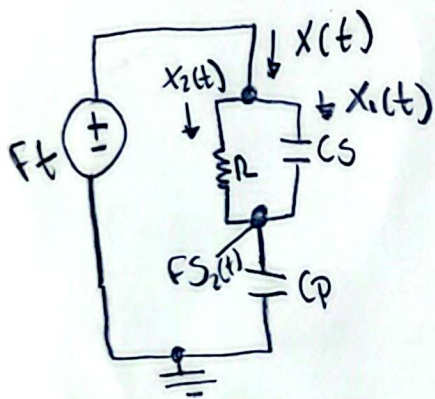
mallos:

$C \rightarrow \text{Integral}$

Nodos:

$C \rightarrow \text{derivada}$

Análisis apagado F_0 (por nodos)



$$X(t) = X_1(t) + X_2(t)$$

$$X(t) = C_p \frac{d[f_s(t)]}{dt}$$

$$X_1(t) = C_s \frac{d[F(t) - f_s(t)]}{dt}$$

$$X_2(t) = \frac{F(t) - f_s(t)}{R}$$

$$C_p \frac{d f_s(t)}{dt} = C_s \frac{d [F(t) - f_s(t)]}{dt} + \frac{F(t) - f_s(t)}{R}$$

Transformada de Laplace:

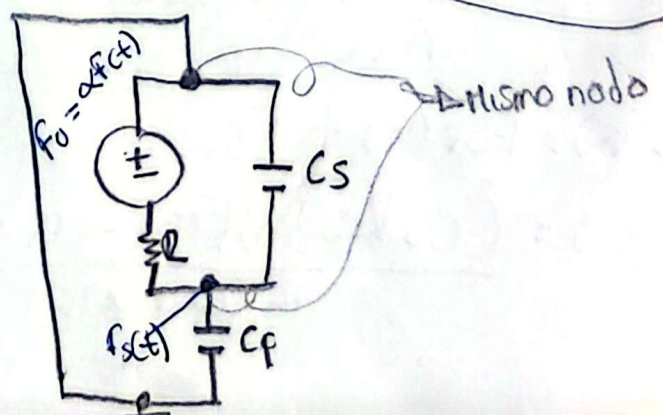
$$C_p s F_s(s) = C_s s [F(s) - f_s(s)] + \frac{F(s) - f_s(s)}{R}$$

Agrupar:

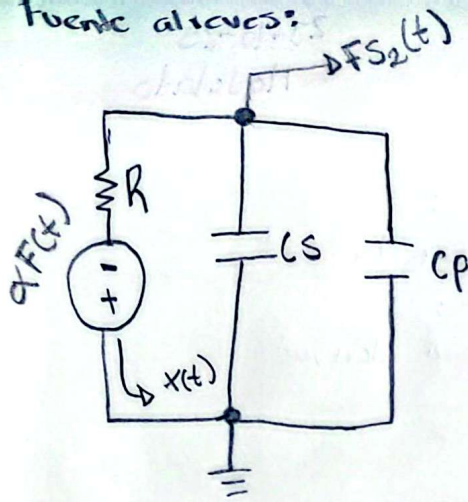
$$(C_p s + C_s s + \frac{1}{R}) F_s(s) = (C_s s + \frac{1}{R}) F(s)$$

$$\frac{F_s(s)}{F(s)} = \frac{(C_s s + \frac{1}{R})}{C_p s + C_s s + \frac{1}{R}} = \frac{C_s R + 1}{C_p R s + C_s R s + 1} \rightarrow \frac{F_s(s)}{F(s)} = \frac{C_s R + 1}{C_p R s + C_s R s + 1}$$

$$F_{s1}(s) = \frac{(C_s R + 1) F(s)}{R(C_s + C_p) s + 1}$$



Fuente alveces:



Ec. Principales:

$$-\alpha F(t) = R x(t) + \frac{1}{Cs + Cp} \int x(t) dt$$

$$F_s(t) = \frac{1}{Cs + Cp} \int x(t) dt$$

Transformada de Laplace:

$$-\alpha F(s) = R X(s) + \frac{X(s)}{(Cs + Cp)s}$$

$$F_o(s) = \frac{X(s)}{(Cs + Cp)s}$$

$$F(s) = - \frac{R(Cs + Cp)s + 1}{\alpha(Cs + Cp)s} X(s)$$

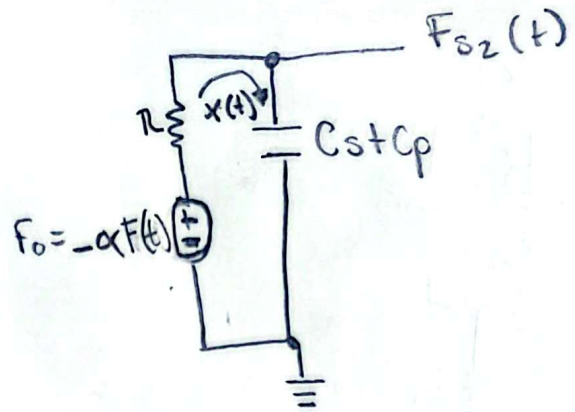
$$\frac{F_s(s)}{F(s)} = \frac{\frac{X(s)}{(Cs + Cp)s}}{\frac{R(Cs + Cp)s + 1}{\alpha(Cs + Cp)s}} \quad X(s)$$

$$F_{s2}(s) = - \frac{\alpha F(s)}{R(Cs + Cp)s + 1}$$

$$F_s(s) = F_{s1}(s) + F_{s2}(s)$$

$$F_s(s) = \frac{(CsRs + 1)F(s) - \alpha F(s)}{R(Cs + Cp)s + 1}$$

Da la vuelta a la fuente:



$$\frac{F_s(s)}{F(s)} = \frac{CsRs + 1 - \alpha}{R(Cs + Cp)s + 1}$$

$$= - \frac{\alpha}{R(Cs + Cp)s + 1}$$

● Estabilidad del sistema en lazo abierto:

Modelado Pract#3

$$[RC_p + RC_s]s + 1 = 0$$

▲ como es de 1er orden solo desprecio "s":

$$s = - \frac{1}{RC_p + RC_s}$$

▷ Cálculo de los polos:

A) Control

$$s = - \frac{1}{(100)(100 \times 10^{-6}) + (100)(10 \times 10^{-6})}$$

$$s_1 = -90.909$$

B) Caso

$$s = - \frac{1}{(10000)(100 \times 10^{-6}) + (10000)(10 \times 10^{-6})}$$

$$s_2 = -0.909$$

El sistema tendría una respuesta estable.

● Error en estado estacionario

$$e(t) = \lim_{s \rightarrow 0} R(s) \left[1 - \frac{F(s)}{F(s)} \right]$$

$$e(t) = \lim_{s \rightarrow 0} \frac{1}{s} \left[1 - \frac{RC_s s + 1 - \alpha}{R[RC_p + RC_s]s + 1} \right]$$

$$e(t) = \lim_{s \rightarrow 0} 1 \left[1 - \frac{1 - 0.25}{1} \right] =$$

$$e(t) = \lim_{s \rightarrow 0} 1 [1 - 0.75] = \frac{0.25}{1} = \alpha$$

Error

Parámetro	Control	Caso
$F(t)$	1V	1V
α	0.25	0.25
C_s	10nF	10nF
C_p	100nF	100nF
R	100Ω	10kΩ
$\frac{F(s)}{F(s)} = \frac{RC_s s + 1 - \alpha}{[RC_p + RC_s]s + 1}$		