Digital Image Processing

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Problem 9 Requirement

9. Image segmentation (Test image: fig3.tif)

- (a). Develop a program to implement the Roberts, Prewitt, Sobel, the Marr-Hildreth and the Canny edge detectors. Use the image 'building.tif' to test your detectors. (For technique details of Marr-Hildreth and Canny, please refer to pp.736-747 (3rd edition, Gonzalez DIP) or MH-Canny.pdf at the same address of the slides.)
- (b). Develop a program to implement the Otsu's method of thresholding segementation, and compare the results with the global thresholding method using test image 'polymersomes.tif. (For technique details, please refer to pp.763-770 (3rd edition, Gonzalez DIP), or Otsu.pdf at the same ftp address of slides.)

Problem 9 solution

edge_detection.m

```
MATLAB
img = imread('building.tif');
gray_img = mat2gray(img);
thresh = 0.33;
ave_filter_img = imfilter(gray_img,ones(5,5)/25);
robert_img = edge(ave_filter_img,'Roberts');
prewitt_img = edge(ave_filter_img, 'Prewitt');
sobel_img = edge(ave_filter_img,'Sobel');
marr_img = edge(ave_filter_img,'log',0.0008,4);
canny_img = edge(ave_filter_img, 'Canny', [0.04 0.1], 4);
% imshow(canny_img);title('robert');
subplot(2,3,1),imshow(img);title('original');
subplot(2,3,2),imshow(robert_img);title('robert');
subplot(2,3,3),imshow(prewitt_img);title('prewitt');
subplot(2,3,4),imshow(sobel_img);title('sobel');
subplot(2,3,5),imshow(marr_img);title('marr');
subplot(2,3,6),imshow(canny_img);title('canny');
```

Original



Roberts



Prewitt



Sobel



Marr-Hildren



Canny



thresh_seg.m

```
MATLAB
function T=gbt(x)
[M,N]=size(x);
T=x(randi(M-1),randi(N-1));
T0=0;
mean1=sum(sum(x(x<=T)))/sum(sum(x<=T));
mean2=sum(sum(x(x>T)))/sum(sum(x>T));
while abs(T-T0)>10^-8
    T0=T;
    T=(mean1+mean2)/2;
    mean1=sum(sum(x(x<=T)))/sum(sum(x<=T));
    mean2=sum(sum(x(x>T)))/sum(sum(x>T));
img = mat2gray(imread('polymersomes.tif'));
gbt_img = im2bw(img,gbt(img));
otsu_thresh = graythresh(img);
otsu_img = im2bw(img,otsu_thresh);
imshowpait(gbt_img,otsu_img,'montage');
```

