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- Cover page: with title and names (1 page)
- table of contents (1 page)
- Introduction/problem statement
 - The project (problem and explanation):Yulin
Minimally invasive surgery/Surgical robotics (1 page)-Leen
 - Engineering (1 page) - Jie Li
 - Why we need it?(Pose estimation)
 - Why use marker-less?
 - Clinical aspect(problem and proposed ideas) -Leen
- Related work (1 page) - Yanrui Liu
 - Different types of networks
- proposed methodology
 - Research Methods: Outline the approach, including qualitative and quantitative methods, data collection techniques, and analysis plans.
 - Framework: Present the theoretical or conceptual framework guiding the project.
- goals for the project / specifications -Jinling Qiu
 - Tools & Techniques: Python, PyTorch, OpenCV.
 - Objective 1, 2, 3...
- risk assessment-Yulin
- timeline / roles of team members(Leen) (1 page)-Yulin
 - Leen : look into clinical related motivations, roles of team members and non-academic responsibilities
 - Yanrui Liu: Related work
 - Jinling Qiu: goals for the project / specifications
 - Yulin Huang: Build the Latex Frame work(Including cover, table of content, references...), problem statement, risk assessment, timeline
 - Jie Li: Engineering considerations in introduction
- non-academic responsibilities (Leen)
- References (2 pages)