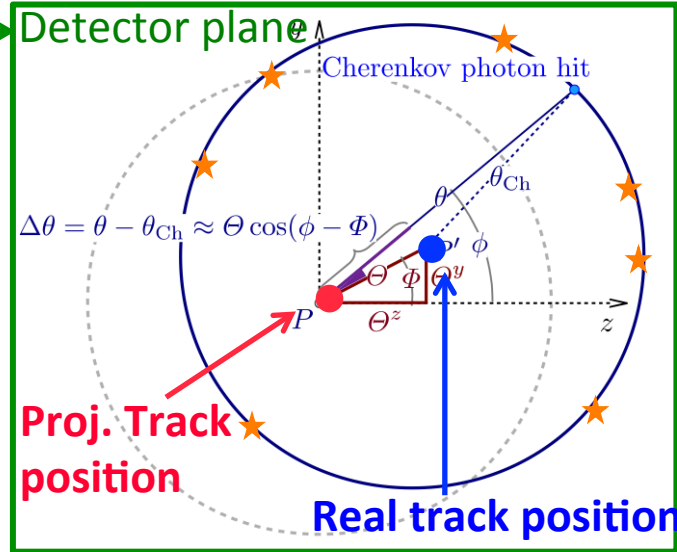
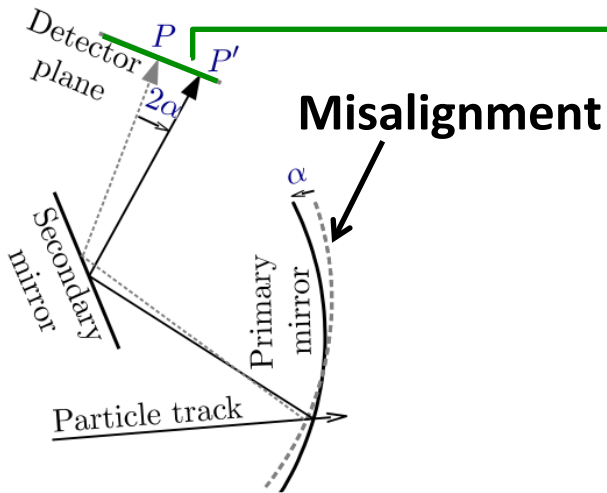


RICH Mirror Alignment

20/06/2016

Paras Naik, **Claire Prouve**, Anatoly Solomin + more

Misalignment

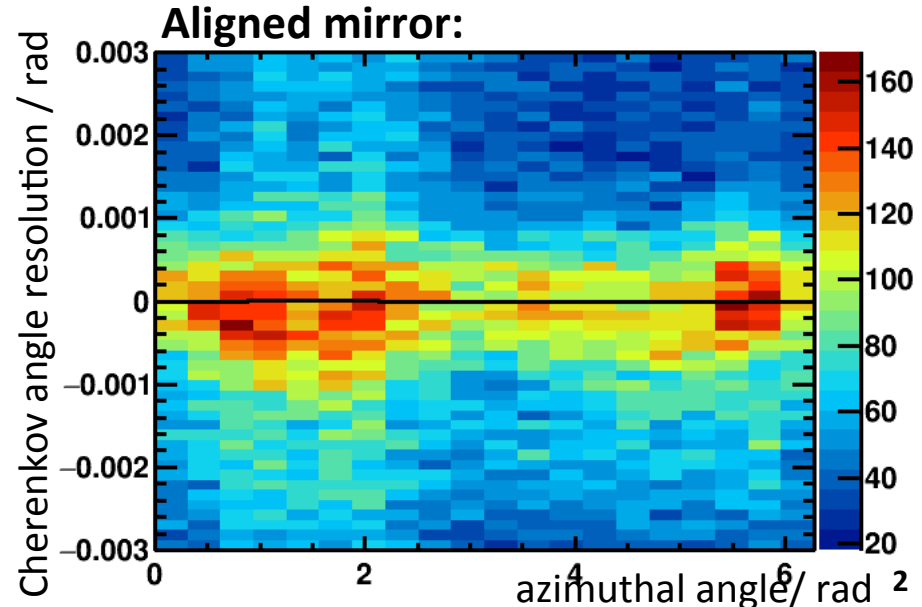
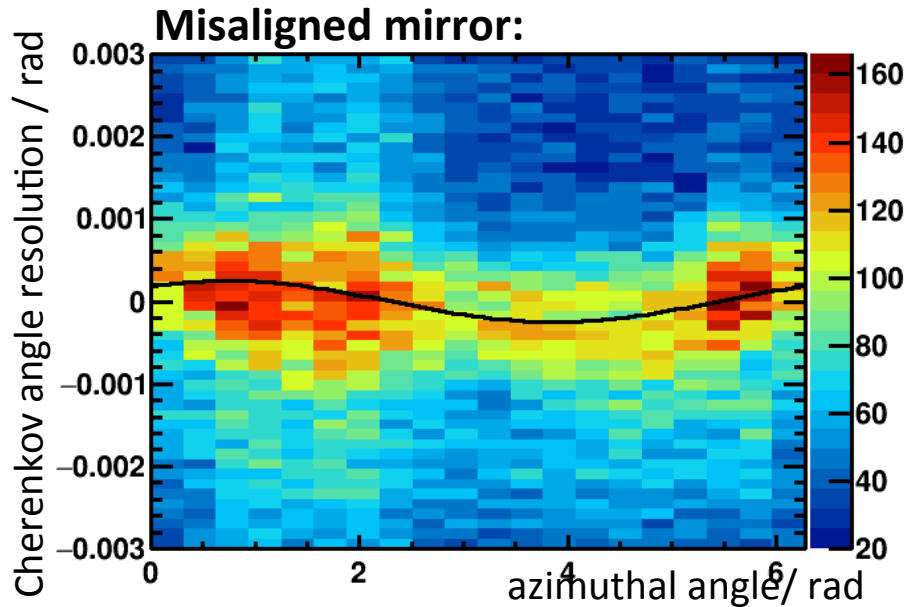


Identify misalignment:

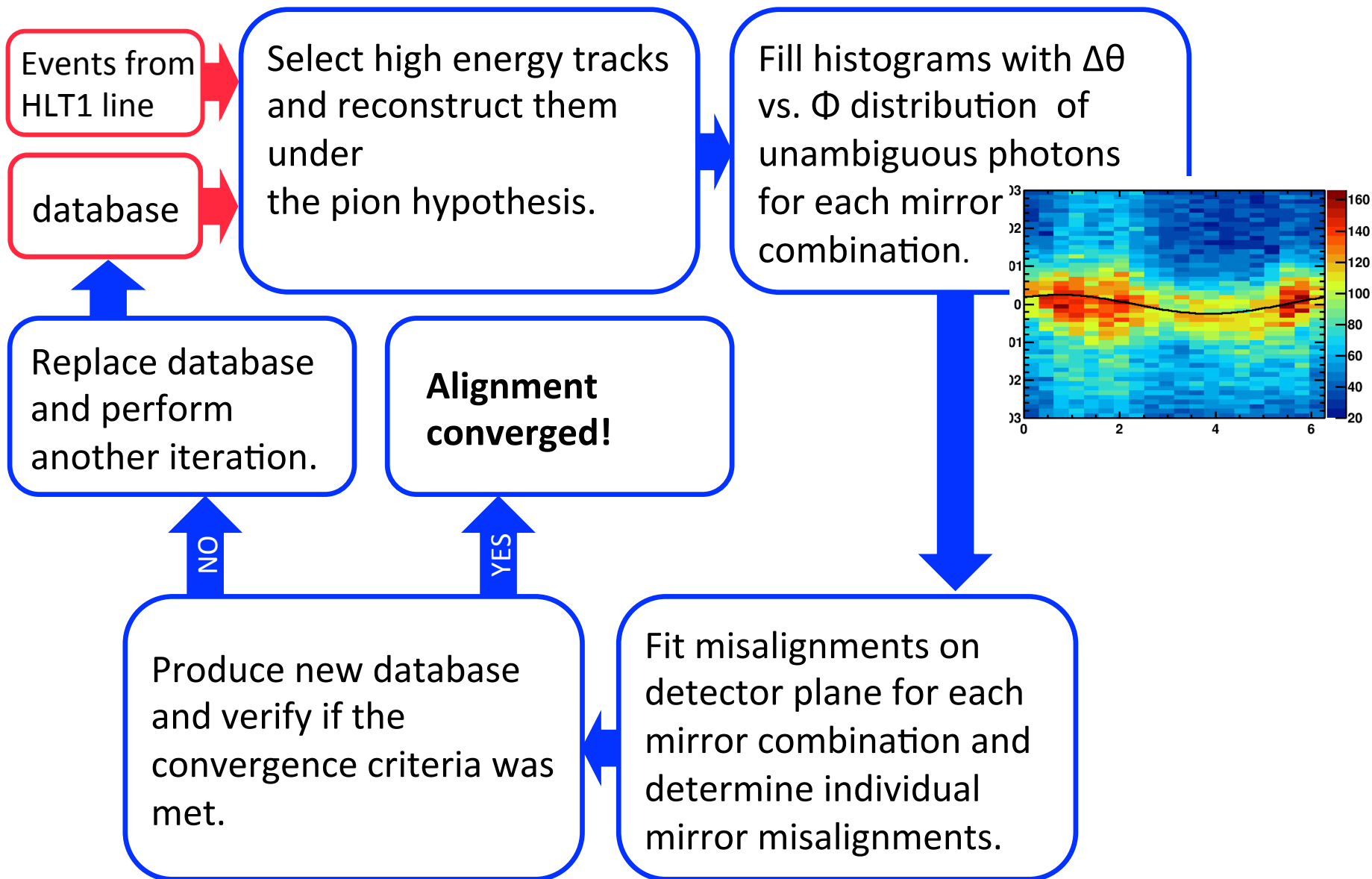
$$\Delta\theta_c(\Phi) = \theta_{\text{meas.}} - \theta_{\text{exp.}}$$

$$\Delta \theta_c^v(\Phi) = \Theta_{p,s}^y \cos(\Phi) + \Theta_{p,s}^z \sin(\Phi)$$

Misalignments on detector plane



Overview of the procedure



Run I vs. Run II

Run I:

- Offline, after data taking
- with Ganga for the Brunel reconstruction
- Alignment applied at the end-of-year reprocessing

Run II:

- **Online:** after HLT1 and before HLT2
- **HLT farm** (~1700 nodes)
- Alignment runs automatically **for each Fill** in monitoring mode since end of May
- **HLT1 lines** for each RICH detector
 - ➔ triggers on tracks that populate the outer mirrors

What's new in 2016?

Disentangling mirror-pairs

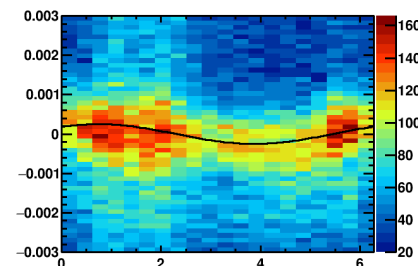
Each pair of **primary mirror** p and **secondary mirror** s has 2 equations:

$$\begin{aligned} & \boxed{A_{p,s}^y} \boxed{\alpha_p^y} + \boxed{B_{p,s}^y} \boxed{\beta_s^y} + \boxed{a_{p,s}^y} \boxed{\alpha_p^z} + \boxed{b_{p,s}^y} \boxed{\beta_s^z} = \boxed{\Theta_{p,s}^y} \\ & \boxed{A_{p,s}^z} \boxed{\alpha_p^z} + \boxed{B_{p,s}^z} \boxed{\beta_s^z} + \boxed{a_{p,s}^z} \boxed{\alpha_p^y} + \boxed{b_{p,s}^z} \boxed{\beta_s^y} = \boxed{\Theta_{p,s}^z} \end{aligned}$$

Magnification factors

individual mirror tilts

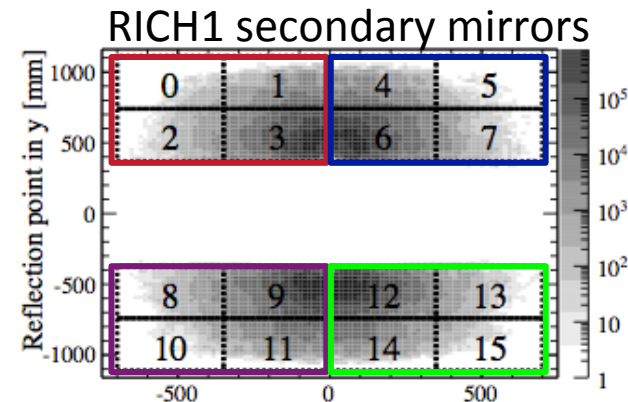
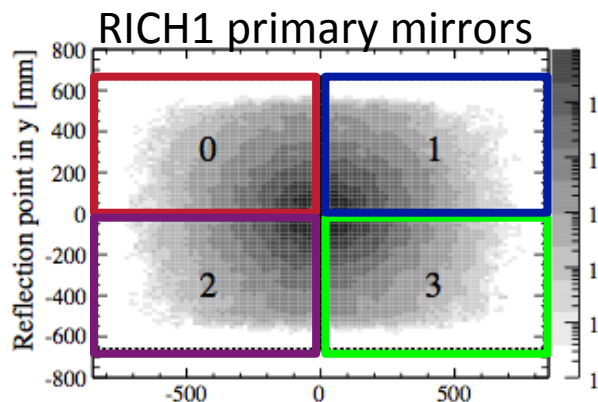
$$\Delta\theta_c(\Phi) = \Theta_{p,s}^y \cos(\Phi) + \Theta_{p,s}^z \sin(\Phi)$$



Challenge: not enough information to fully constrain the solution

RICH1: 8 equations for 10 unknowns

Rotation of primary mirrors followed by according rotation of secondary mirrors yields same results

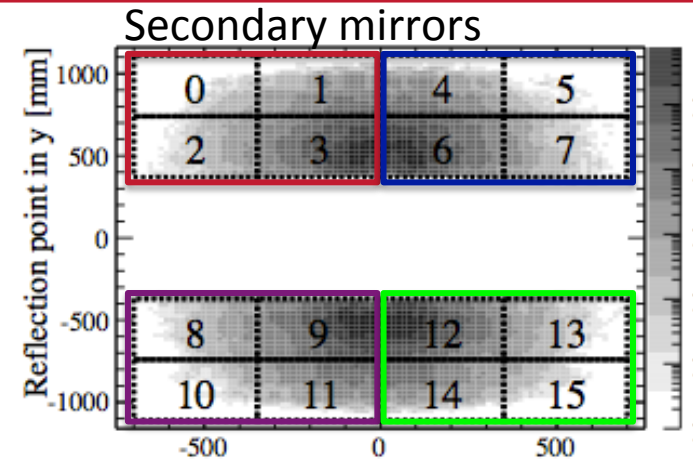
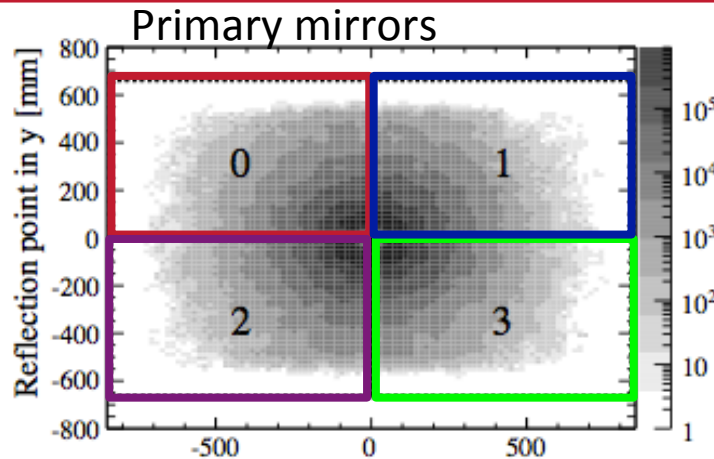


➔ Need additional constraint

Disentangling – until 2016

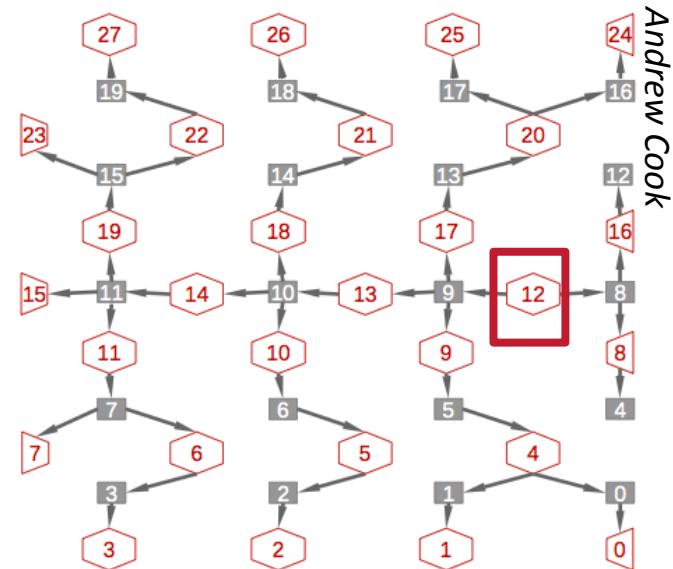
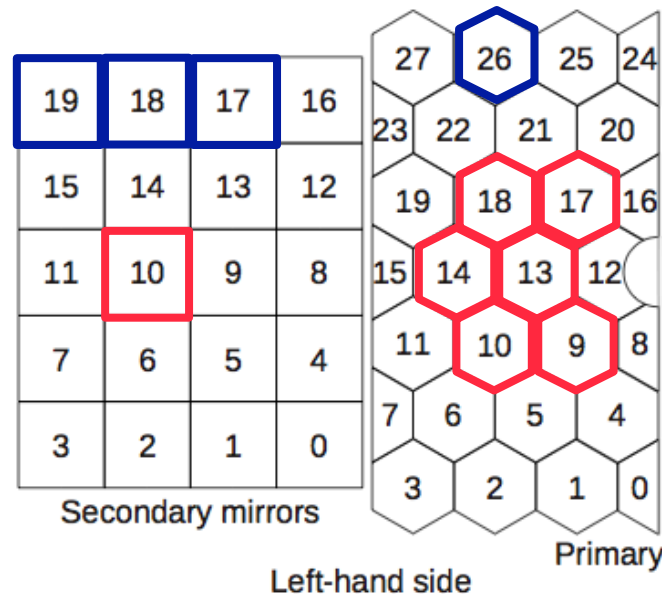
RICH1:

- fix primary mirrors, align secondary mirrors



RICH2:

- Left half: system of equations linking all mirrors starting from primary mirror 12.



Andrew Cook

Disentangling – from 2016

L2 regularization (ridge regression):

- rewrite problem as $\boxed{A}\boxed{x}=\boxed{b}$
Matrix of magnification factors Vector of individual mirror tilts Vector of results of fit to histograms
- Minimize: $\underbrace{\|Ax - b\|^2}_{\text{least square method}} + \underbrace{\|\Gamma x\|^2}_{\text{L2 regularization term}}$

Advantages:

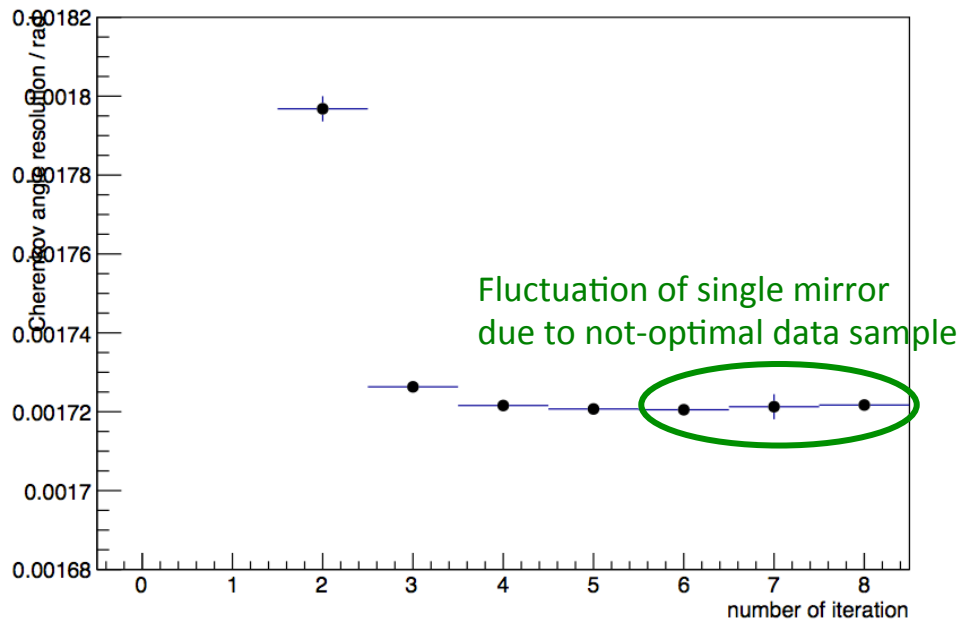
- more stable than the previous method
 - Stable w.r.t. small statistical fluctuations (unlike L1 regularization)
- ➔ Fewer iterations needed to converge

Recent results

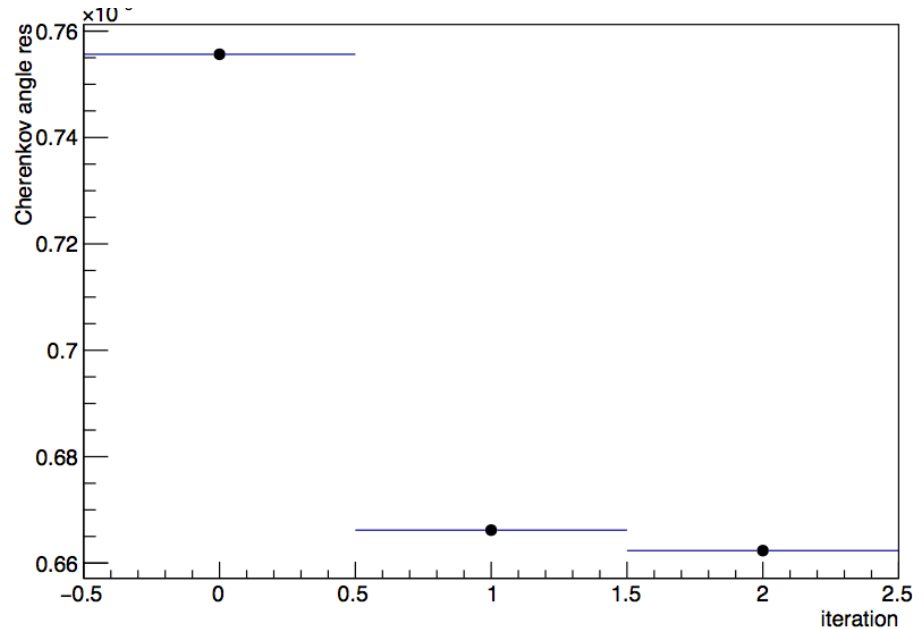
First alignment 2016

- In the global tag cond-20160517
- Started from completely unaligned mirrors

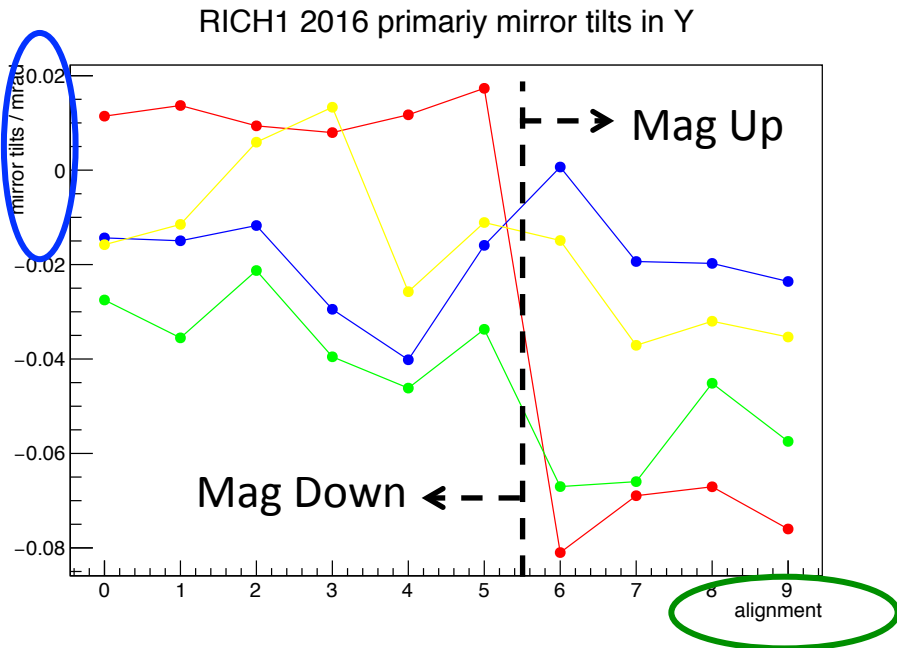
RICH1 Cherenkov angle resolution per iteration of first alignment 2016



RICH2 Cherenkov angle resolution per iteration of first alignment 2016



Stability of tilts – RICH1

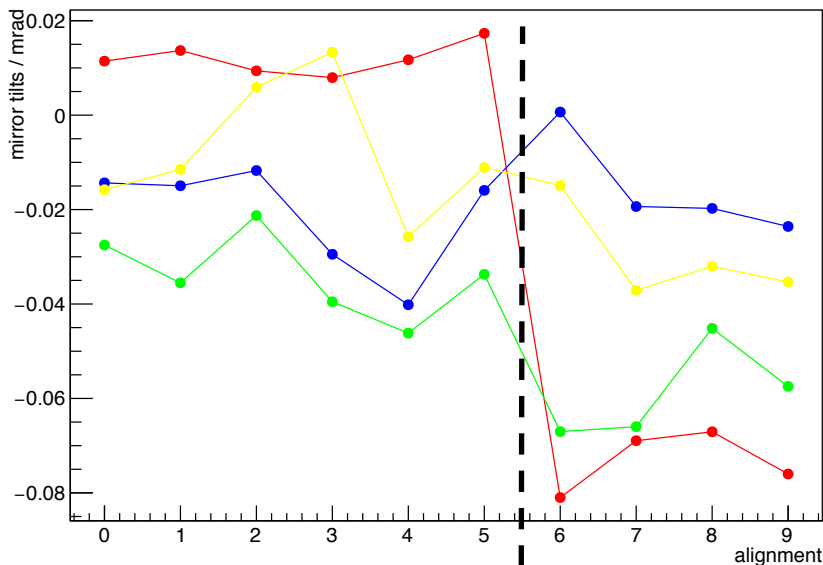


Changes of mirror tilts
wrt current DB

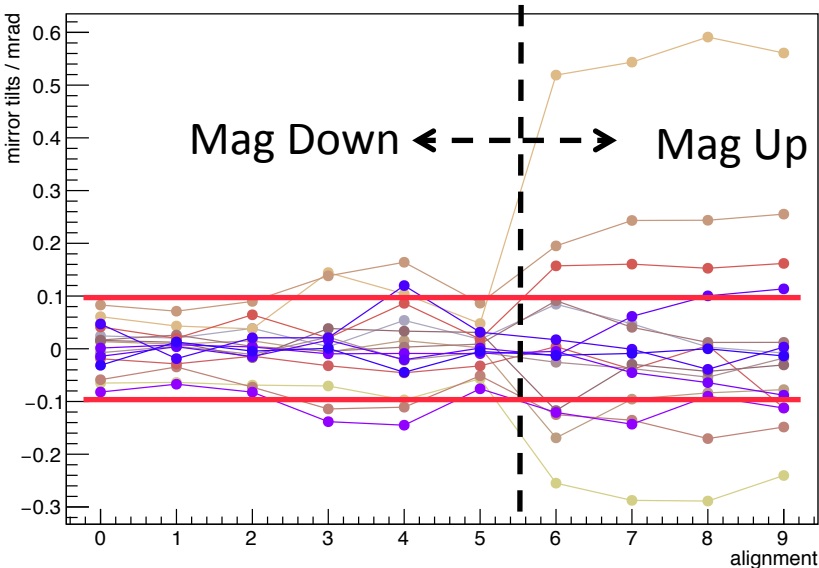
of alignment run
between 24/05 - 19/06

Stability of tilts – RICH1

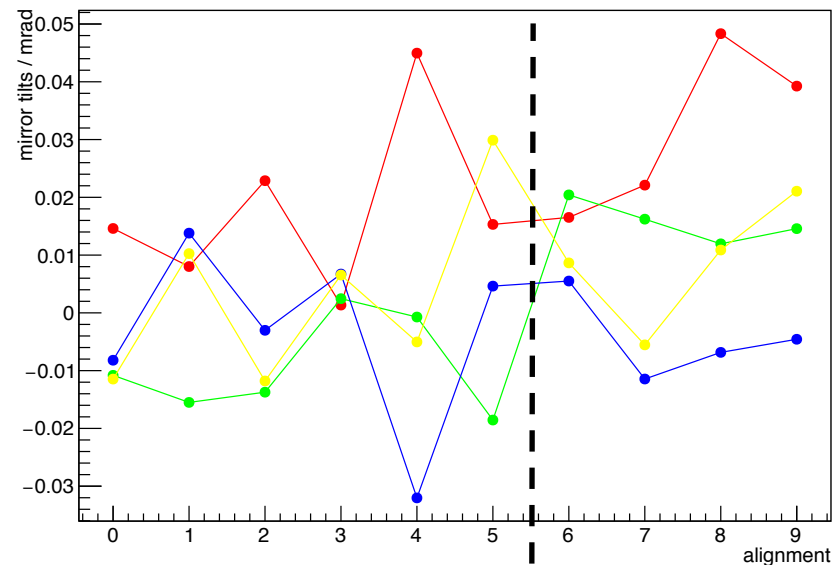
RICH1 2016 primary mirror tilts in Y



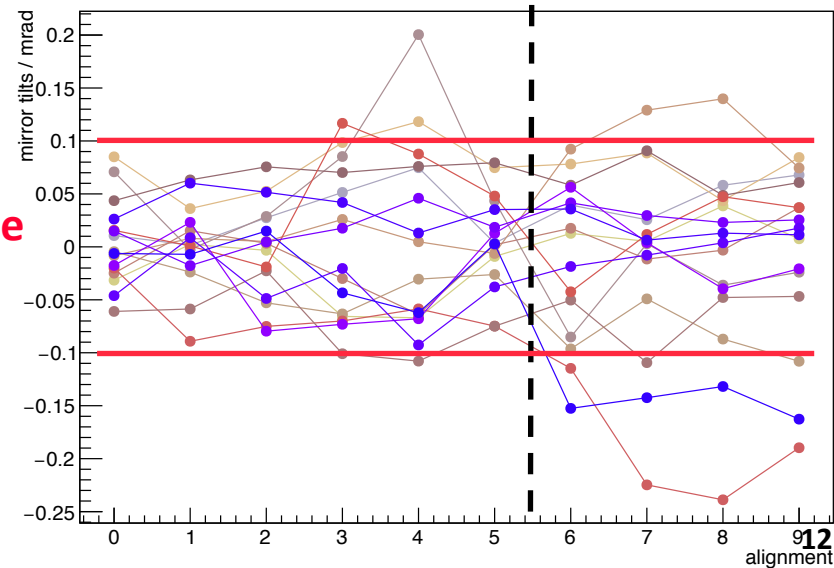
RICH1 2016 secondary mirror tilts in Y



RICH1 2016 primary mirror tilts in Z



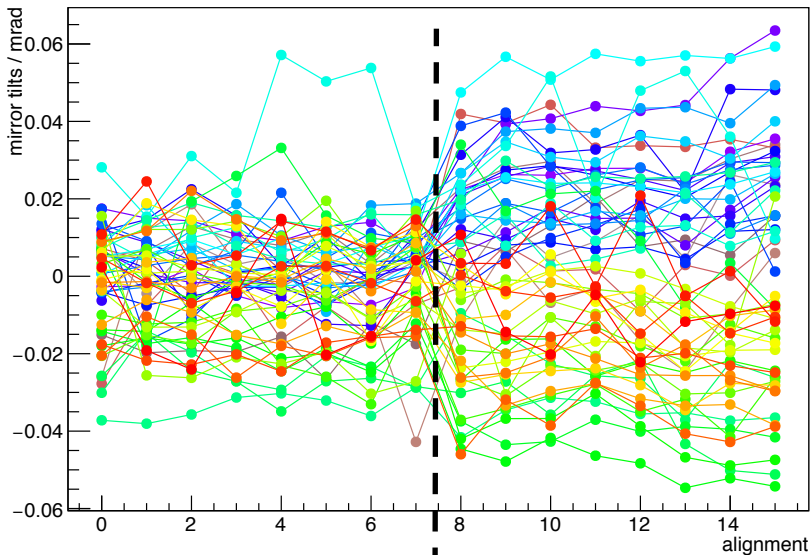
RICH1 2016 secondary mirror tilts in Z



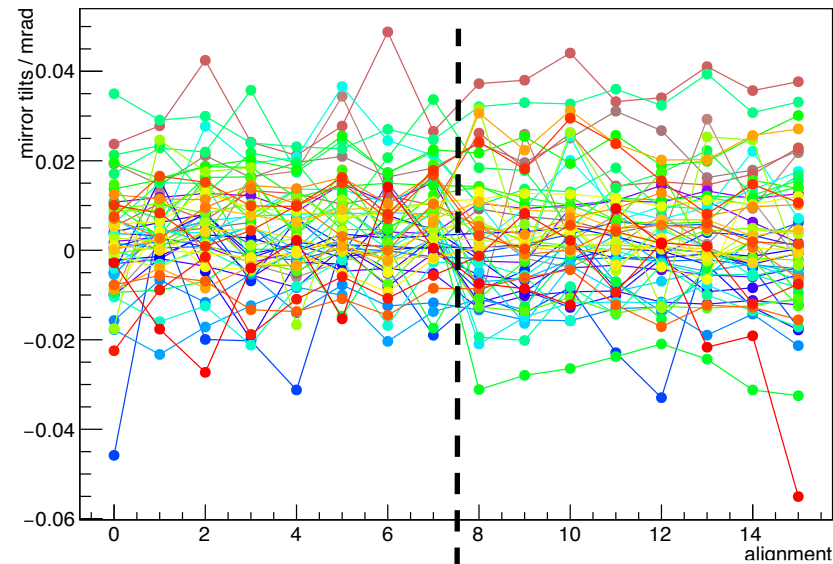
**Convergence
criteria
0.1 mrad**

Stability of tilts – RICH2

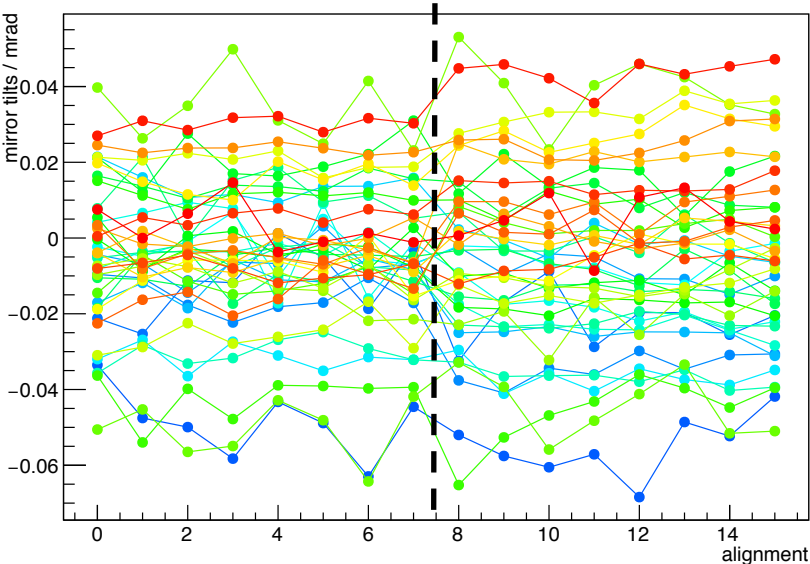
RICH2 2016 primary mirror tilts in Y



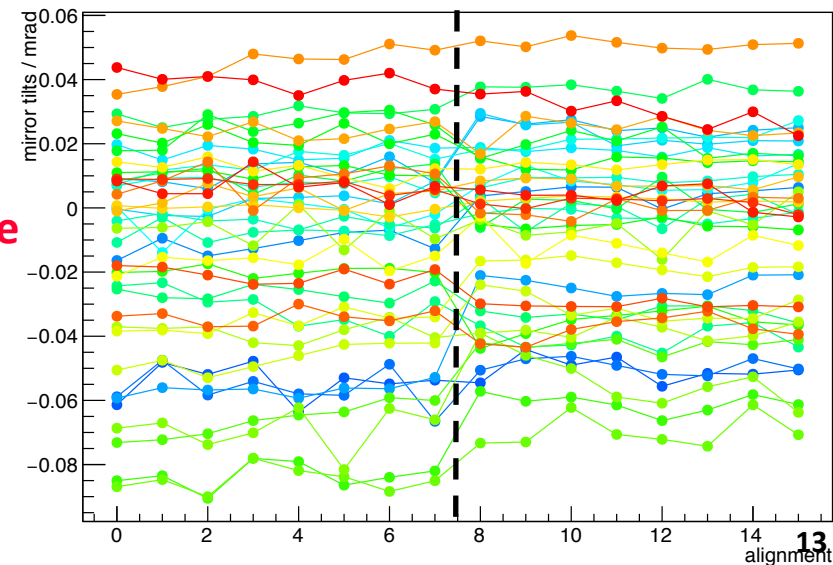
RICH2 2016 primary mirror tilts in Z



RICH2 2016 secondary mirror tilts in Y



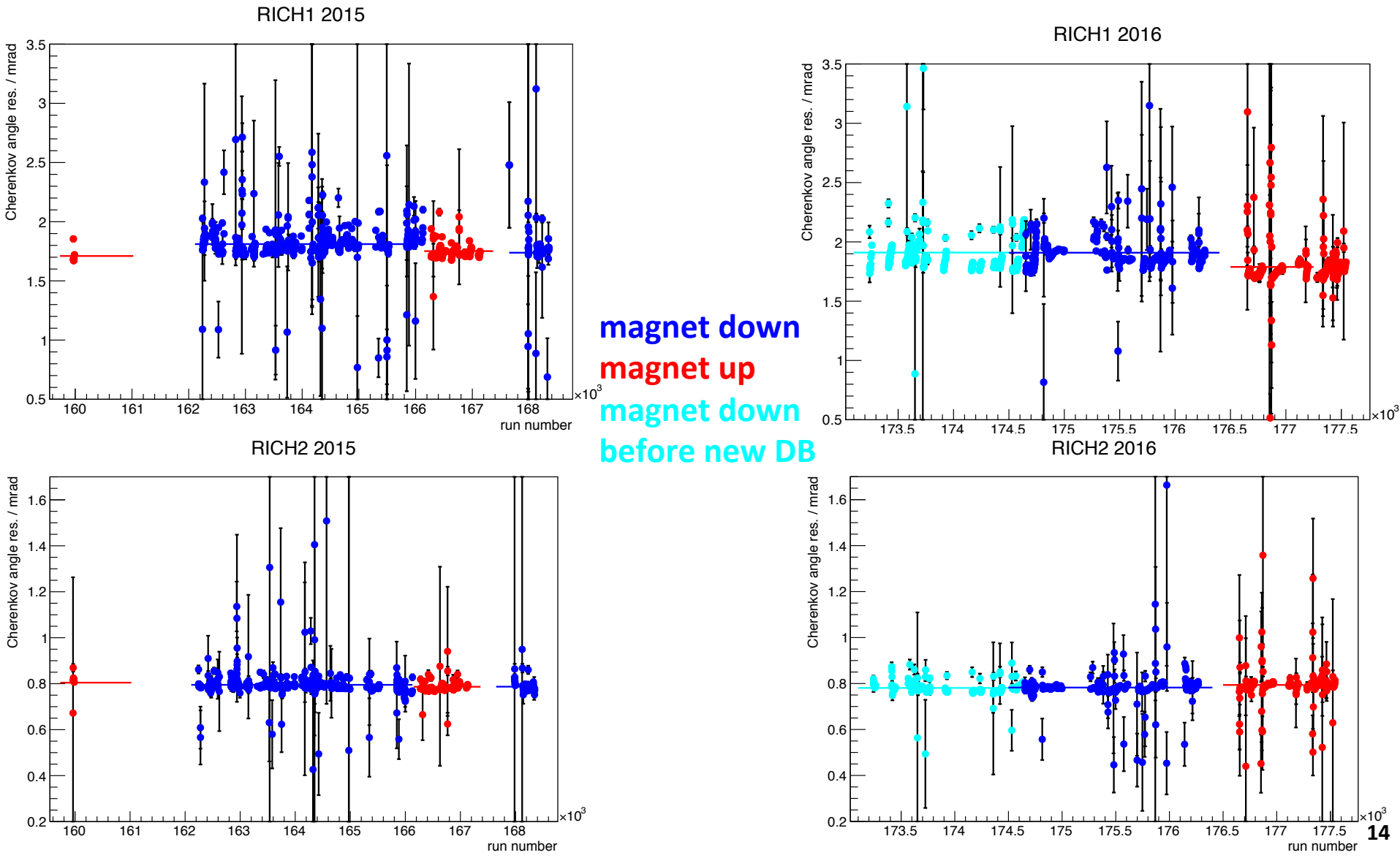
RICH2 2016 secondary mirror tilts in Z



Convergence
criteria
0.1 mrad

Stability of Resolution

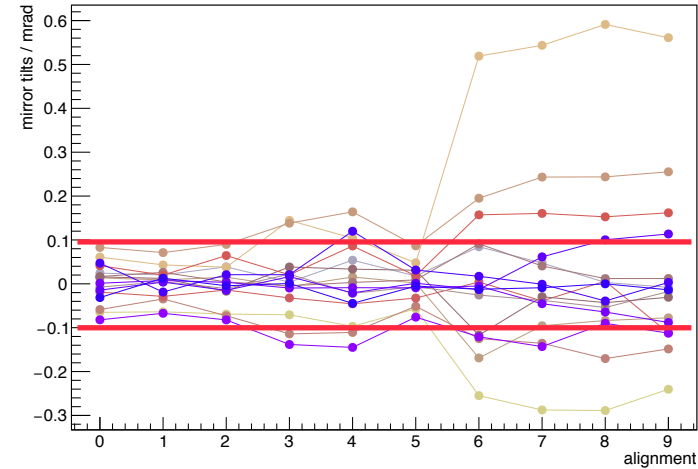
Resolutions from refractive index calibration (without HPD image correction).



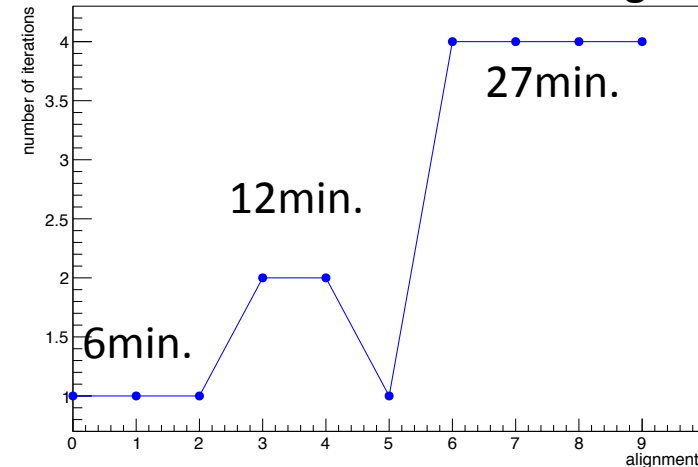
More very new features

- **Different convergence criteria** for primary and secondary mirrors in y and z respectively
- Possibility to automatically **compare output of alignment** with another given alignment
 - ➔ during MagUP start from MagUP alignment (which is not in the database currently)
 - ➔ converge within few iterations
 - ➔ calculate the difference to alignment in the current Conditions Database

RICH1 2016 secondary mirror tilts in Y



Iterations needed to converge



Current 'monitoring'

RICH alignment summaries

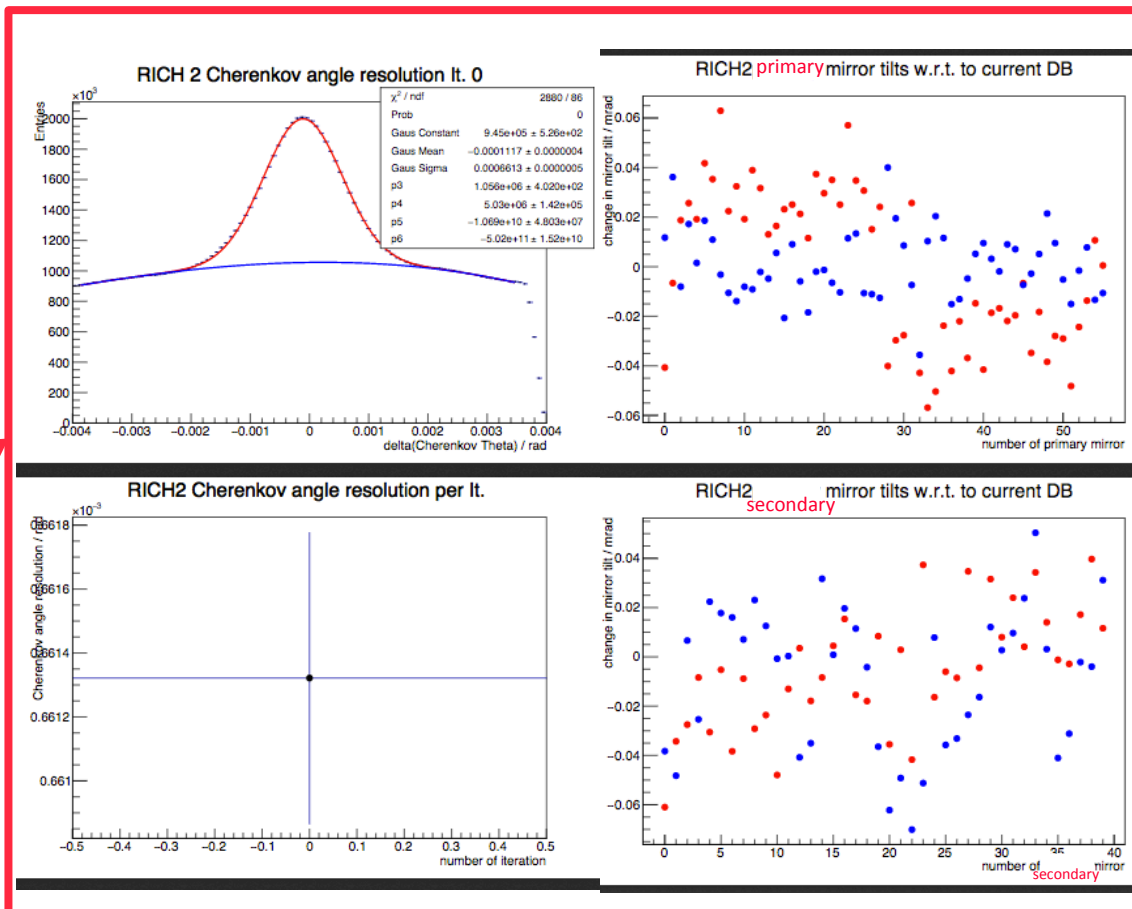
<https://lbggroups.cern.ch/rich/alignmentview.php>

Date:

End date: ☒ Use end date?

- Tilts in y
- Tilts in z

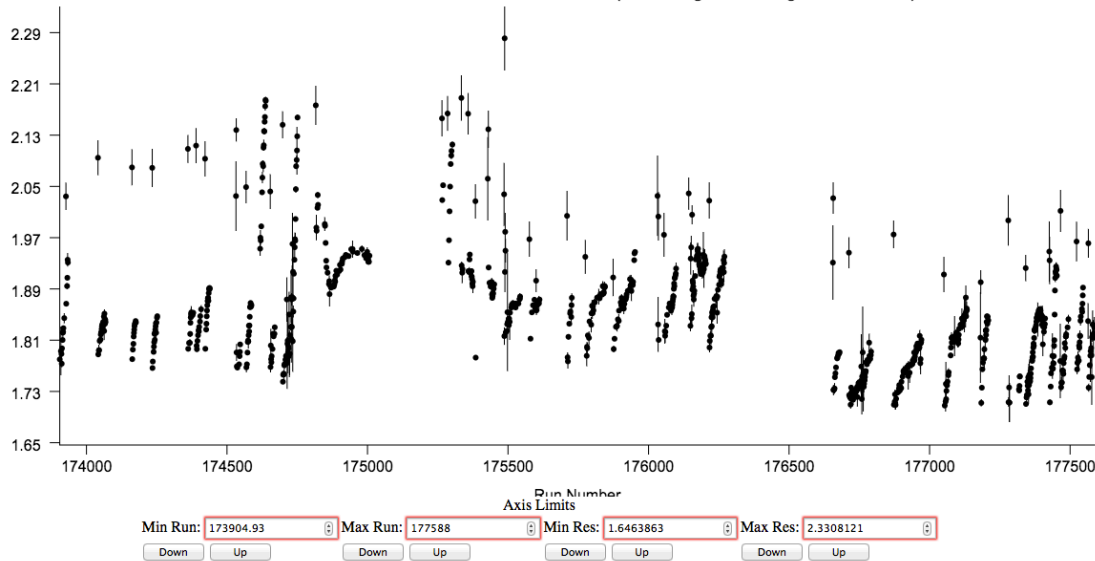
RICH 1 alignments	RICH 2 alignments
20160616_170644	
20160616_174432	
20160616_180427	
20160616_182620	
20160616_185541	
20160616_191413	
20160616_192744	
20160616_195828	
20160616_203146	
20160616_205455	
20160617_162358	
	20160617_163833
20160618_202237	
	20160618_203859
	20160619_103743
20160619_155907	
	20160619_161042
20160619_183331	
	20160619_185109



Backup

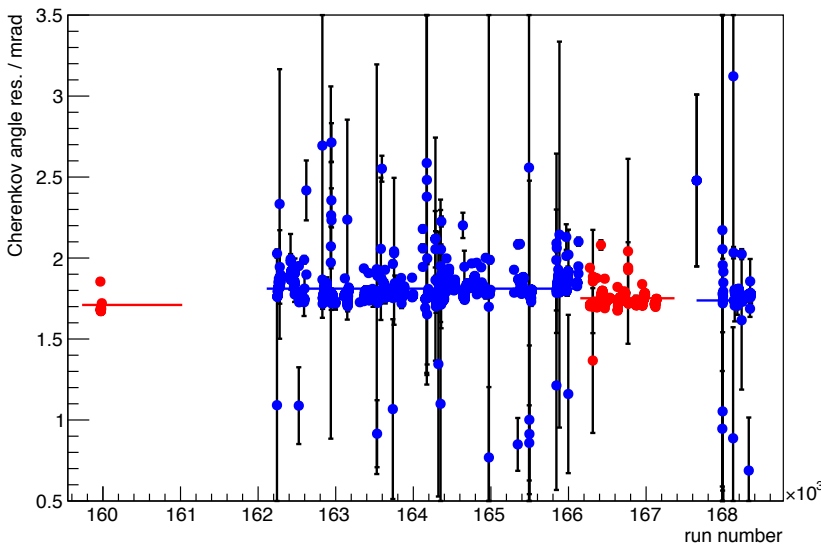
Resolution

RICH1 Online Brunel Cherenkov Resolution (Excluding HPD Image Corrections)

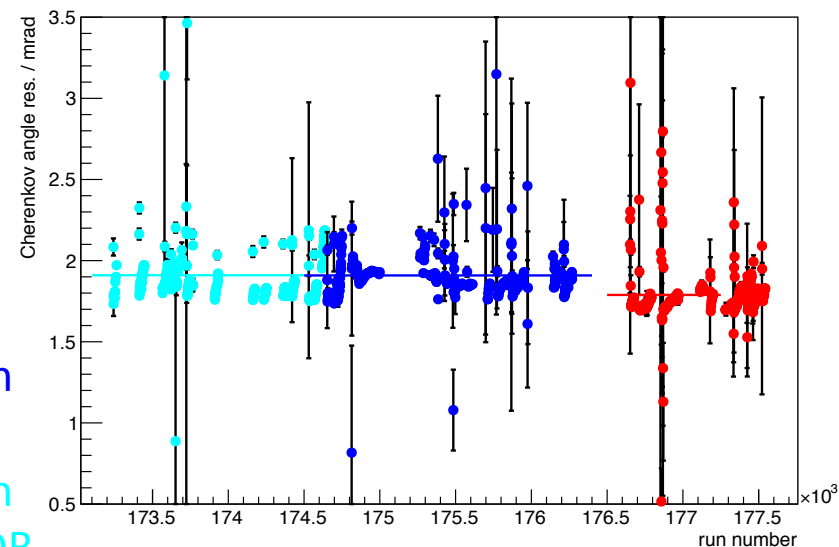


Without HPD image
correction:
Degradation of resolution
over fill.
➔ Longer fills in 2016

RICH1 2015



RICH1 2016



New HLT Lines

- Trigger on tracks that will populate the hardest-to-populate mirror-pairs
- ➔ usually the very outer mirrors
- Other tracks in the events will populate the rest

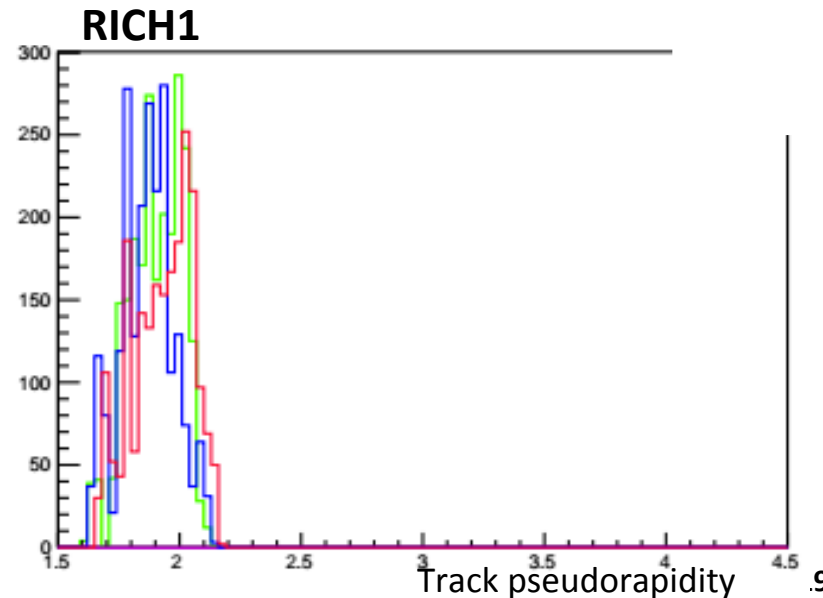
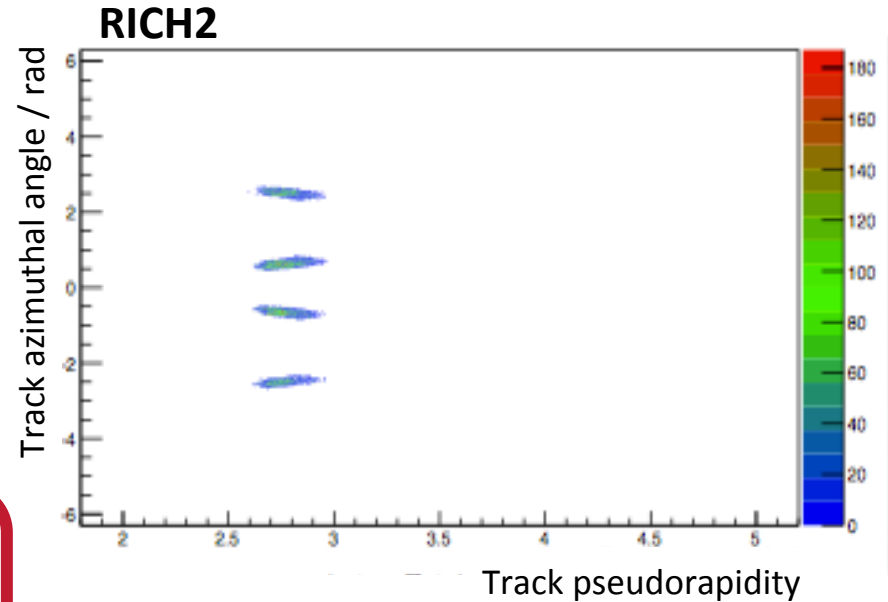
RICH2 line:

$p > 40 \text{ GeV}$ && $\chi^2 < 2$ && $2.65 < \eta < 2.80$
 $(-2.59 < \Phi < -2.49)$ || $(-0.65 < \Phi < -0.55)$ ||
 $(0.45 < \Phi < 0.65)$ || $(2.49 < \Phi < 2.59)$

RICH1 line:

$p > 10 \text{ GeV}$ && $\chi^2 < 2$ && $1.6 < \eta < 2.04$
 $(-2.65 < \Phi < -2.3)$ || $(-0.8 < \Phi < -0.5)$ ||
 $(0.5 < \Phi < 0.8)$ || $(2.3 < \Phi < 2.65)$

Need to reconstruct ~10 times less events!



Magnification coefficients

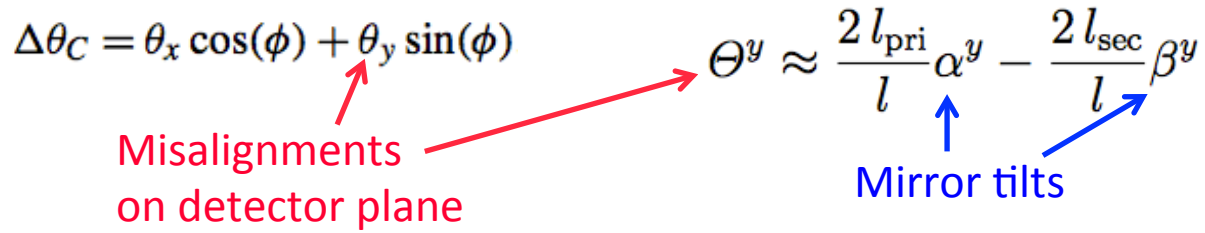
Magnification coefficients: Translate the tilt on the detector plane into actual mirror tilts

$$\Delta\theta_C = \theta_x \cos(\phi) + \theta_y \sin(\phi)$$

Misalignments
on detector plane

$$\Theta^y \approx \frac{2l_{\text{pri}}}{l} \alpha^y - \frac{2l_{\text{sec}}}{l} \beta^y$$

Mirror tilts



Magnification coefficients are calculated new for each iteration:

- Introduce 8 rotations: primary and secondary mirrors rotated around $\pm y$ and $\pm z$ axis respectively
- Rotate about 0.3 mrad (half the resolution of RICH2)
- Reconstruct events for each rotation and evaluate the tilts on the detector plane

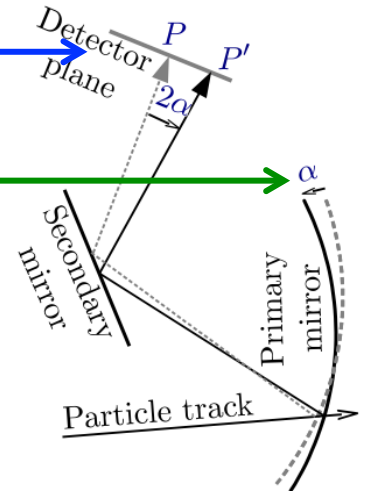
Need to reconstruct all events 9 times!

$$\Theta^y \approx 2.0 \alpha^y - 0.9 \beta^y \quad \text{and} \quad \Theta^z \approx 1.8 \alpha^z + 0.6 \beta^z.$$

Further improvements

Magnification coefficients:

- translate the misalignment-on-the-detector-plane into actual mirror tilts
 - Previously calculated for every alignment for each iteration on data
 - Tested using the same set for all alignments and all iterations
- ➔ No significant difference in resulting mirror tilts and **procedure 9 times faster!!!**



Improved method for fitting histograms:

- use same Gaussian width for each slice in ϕ
- ➔ Same resulting mirror-tilts and **3 times faster**

