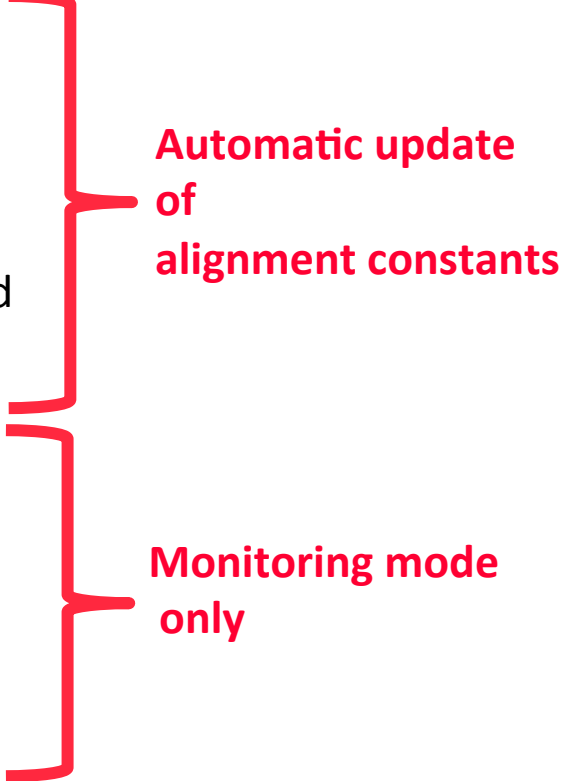


Update on Alignment and Calibration

07/03/2016 Claire Prouve - University of Bristol
on behalf of the Alignment & Calibration group

Overview alignments

Alignments

- 1. VELO alignment:** Alignment of both halves for translations and rotations in x, y and z.
 - 2. Tracker alignment:** Alignment of TT, IT and OT for translations in x, rotations and translations in z (online) and translations and rotations in y (offline).
 - 3. RICH mirror alignment:** Alignment of all individual mirrors for rotations around x and y.
 - 4. Muon alignment:** Alignment of both halves of each station for translations in x and y.
- 
- **Run on the HLT-farm at the beginning of every fill in the same order as above.**

Overview calibrations

Calibrations

- **OT calibration:** Global time alignment for all modules, extract the global time delay t_0 caused by a difference in collision time and the phase of the LHC clock received at LHCb.
- **RICH calibration:**
 - **Refractive index calibration:** correct the refractive index calculated from hardware sensors.
 - **HPD Image calibration:** calibration of the image for each anode element.
- **Calorimeter calibration:** Occupancy method and LED monitoring system, adjust the high voltage to compensate for the aging of the detector
- **Run on the monitoring histograms for ~every run (OT and RICH) or every fill (Calorimeter).**
- **π^0 calibration:** Calibrate the gain in each cell using the π^0 mass distribution with $\pi^0 \rightarrow \gamma\gamma$
Run on the alignment farm during TS.

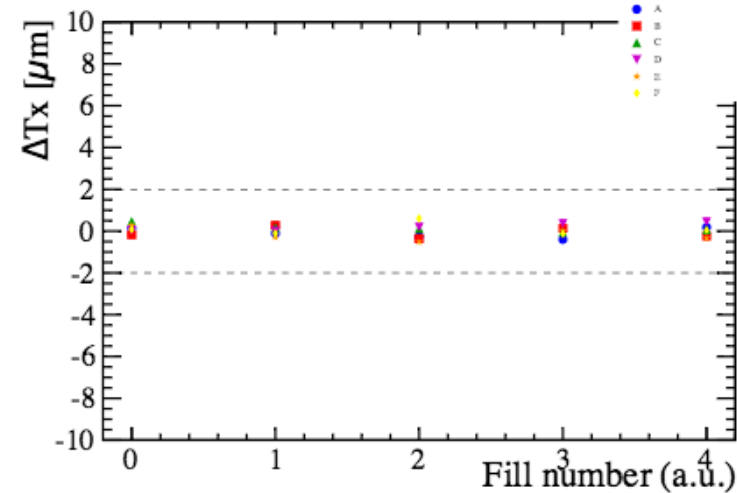
VELO alignment (1/2)

Giulio,
Silvia

Work during WS [Giulio's talk](#)

Threshold for automatic update of alignment constants:

- accuracy and precision used in 2015 taken from 2012 MC and 2012 data
 - If too small: sensitive to statistical fluctuations
If too big: unexpected behaviour
 - new stability study with data taken in 2015: several alignments made on different events from same fill
- ➔ **New thresholds determined.**



dof	2015		for 2016	
	Min variation	Max variation	Min variation	Max variation
$T_x T_y$ [μm]	2	10	1.5	10
T_z [μm]	4	10	5	10
R_x, R_y [μrad]	3.5	25	4	25
R_z [μrad]	15	100	30	100

VELO alignment (2/2)

Giulio,
Rosen

Dependence on initial alignment: [Giulio's talk](#)

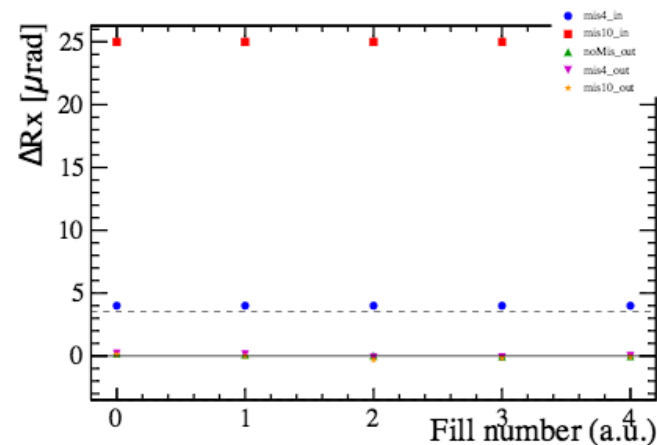
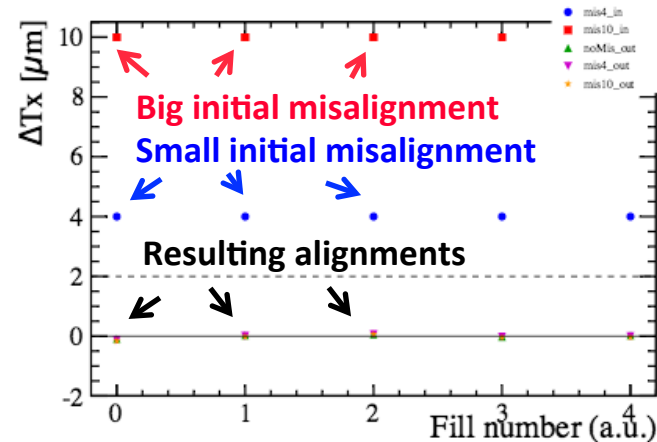
- stability study with data taken in 2015: several alignments made on same events starting from different alignments (optimal, small misalignment, big misalignment)
- ➔ **New alignment does not significantly depend on the initial alignment.**

To be done:

- optimization of the rate between collision and beam gas events in the HLT1 line (same HLT1 line as for the luminosity studies) to get more beam gas events

Plans for 2016 data-taking

- Apply the new thresholds for automatic update of alignment constants
- Adjust the rate of beam-gas events to collision events
- Continue running automatically as during the end of 2015



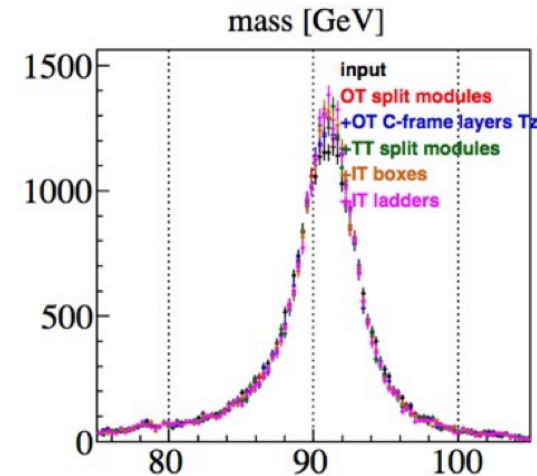
Tracker alignment

Wouter, Maurizio,
Francesca, Lucia

Work during WS

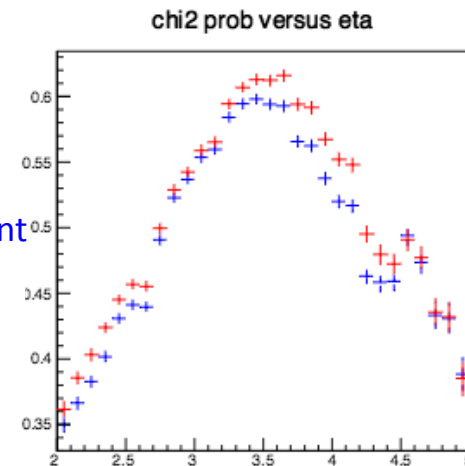
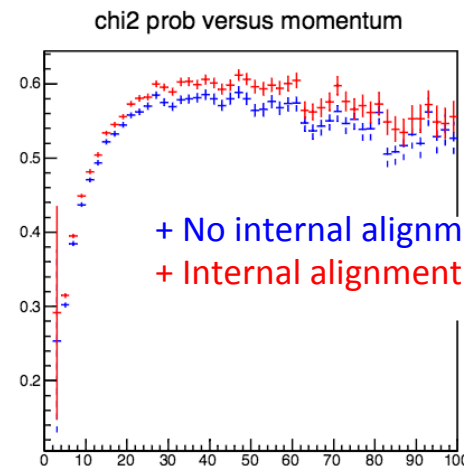
Z $\rightarrow\mu\mu$ decays + additional degrees of freedom: [Wouter's talk](#)

- Z $\rightarrow\mu\mu$ decays collected in 2015
- OT modules split above/below the beam pipe, OT C-frames in z, split TT modules, IT boxes, IT layers and ladders
- ➔ Z peak ~15% narrower, and improved track χ^2 after alignment
- ➔ Improved internal IT alignment



D⁰ decays + additional degrees of freedom: [Maurizio's talk](#)

- Default D⁰ decays
- Same configuration as for Z alignment for OT and IT
- ➔ Same improvements in track χ^2 and overlap-residuals as on Z sample
- ➔ No improvement in D⁰ mass resolution



Tracker alignment

Wouter, Maurizio,
Francesca, Lucia

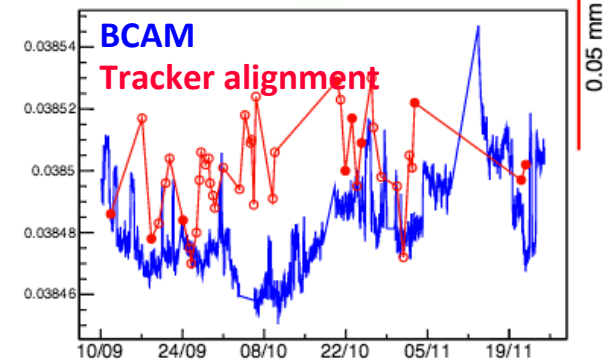
To be done:

- Evaluation of alignment with high momentum tracks and tracks from J/ψ events
- Study different alignment configurations
- Stability study for IT: correlation between movement seen by BCAM ([Pavol's talk](#)) and tracker alignment under study
- Stability study for OT and TT: stability of alignment constants of the different elements

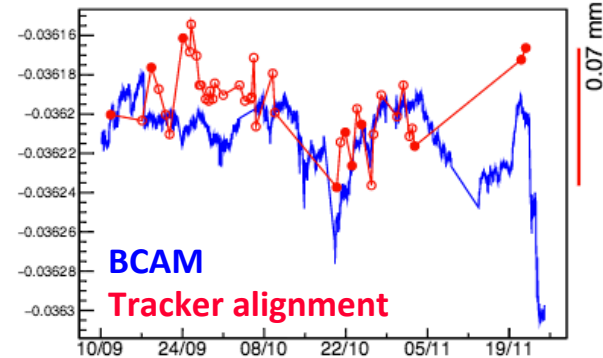
Plans for 2016 data-taking

- 1st alignment with big data-sample and all degrees of freedom at the beginning of data-taking
- Alignment in y with magnet-off data
- Use D^0 events plus high-momentum tracks (and possibly J/ψ events)
- Detector was opened and IT box was moved
→ expect significant misalignment at the start

IT1 A side X-coordinate



IT1 C side X-coordinate



Muon alignment

Silvia,
Stefania

Work during WS

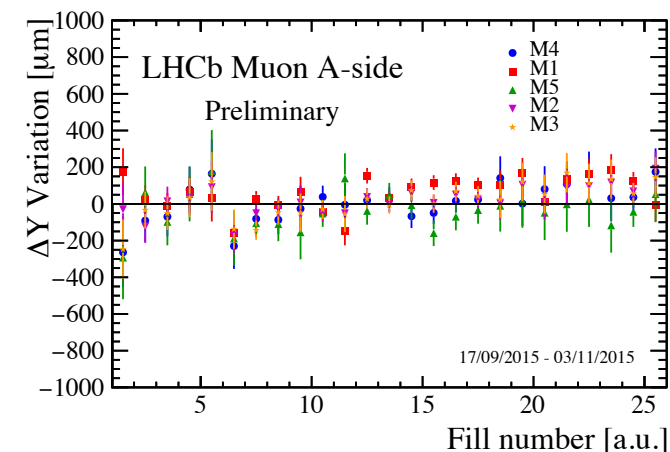
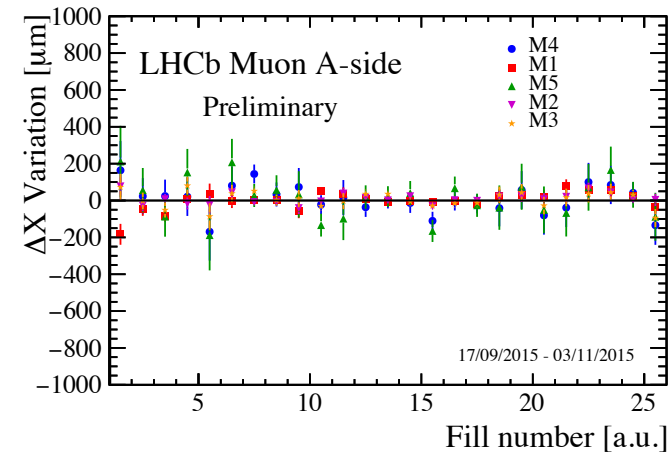
No work necessary, alignment was already stable in 2015.

Plans for 2016 data-taking

- Muon system was opened during WS
- misalignment in muon system can create asymmetry in L0Muon

➔ initial alignment needed

1. software alignment
 2. if misalignment is big move the chambers mechanically and perform new alignment
 3. produce new LUT for L0Muon
- Run in monitoring mode



RICH Mirror Alignment (1/3)

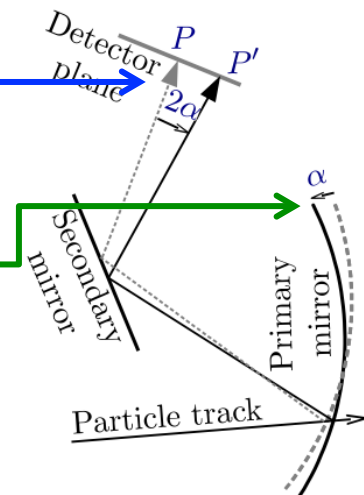
Anatoly,
Claire,
Paras

Work during WS

Studies on increase of speed

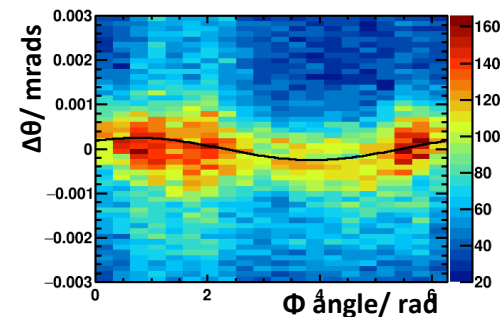
1. Magnification coefficients:

- translate the misalignment-on-the-detector-plane into actual mirror tilts
- Previously calculated for every alignment for each iteration on data
- Tested using the same set for all alignments and all iterations
- ➔ No significant difference in resulting mirror tilts and **procedure 9 times faster!!!**



2. New method for fitting histograms:

- use same Gaussian width for each slice in phi
- ➔ Same resulting mirror-tilts and **3 times faster**



3. New method for determining individual mirror misalignments:

- No more fixed mirrors + align all mirrors at the same time
- ➔ **Less iterations needed** obtaining the same Cherenkov angle resolution.

RICH Mirror Alignment (2/2)

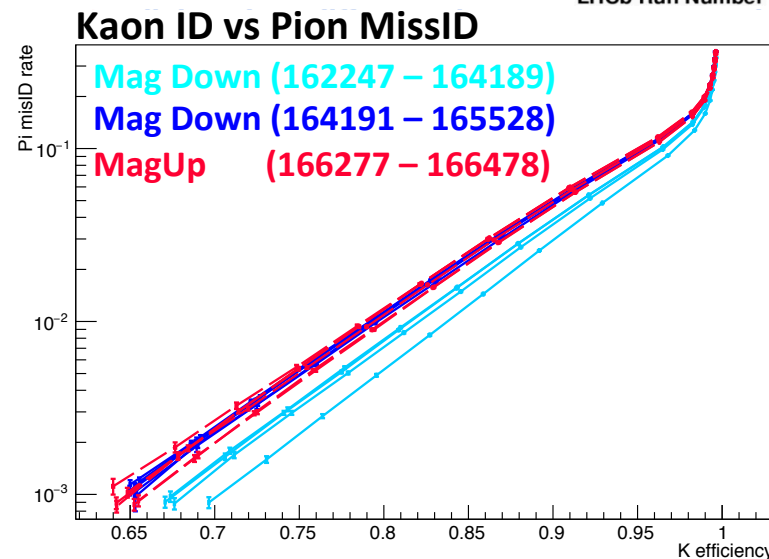
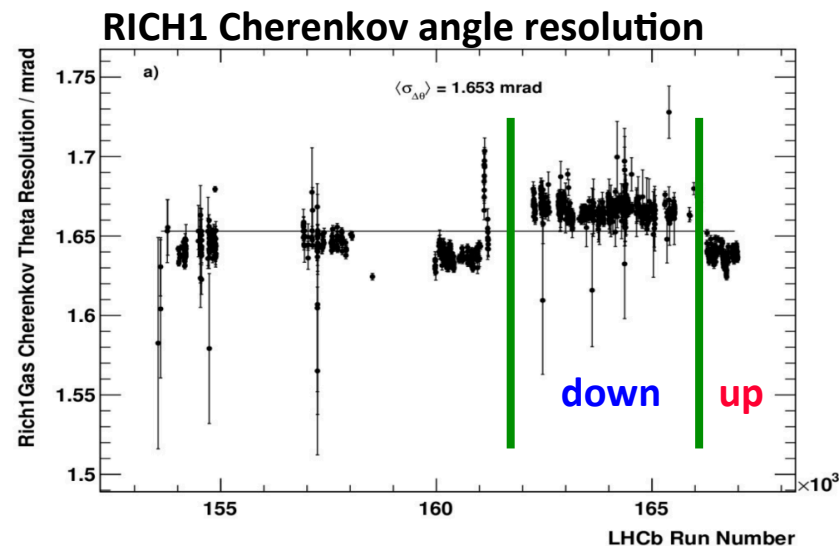
Anatoly,
Claire,
Paras

Number of events needed for stable alignment:

- several alignments made on different runs from same time-period
- ➔ 1M events for RICH1, 2M events for RICH2

Magnet polarity:

- Different Cherenkov angle resolution for different magnet polarities in RICH1
- Increase in energy required to pass L0 between **Mag Down** and **Mag Down**
- **No evidence that the PID suffers if we use the same alignment for both polarities**
- More studies ongoing



RICH Mirror Alignment (3/3)

Anatoly,
Claire,
Paras

Plans for 2016 data-taking

- Adjust HLT1 prescale for RICH1 to get desired number of events for both RICHs in same amount of time
- Run every fill if possible to have more stability studies
 - Stability of alignment constants
 - Stability of Cherenkov angle resolution
- Revisit in September if we can run less often

OT global t_0 calibration

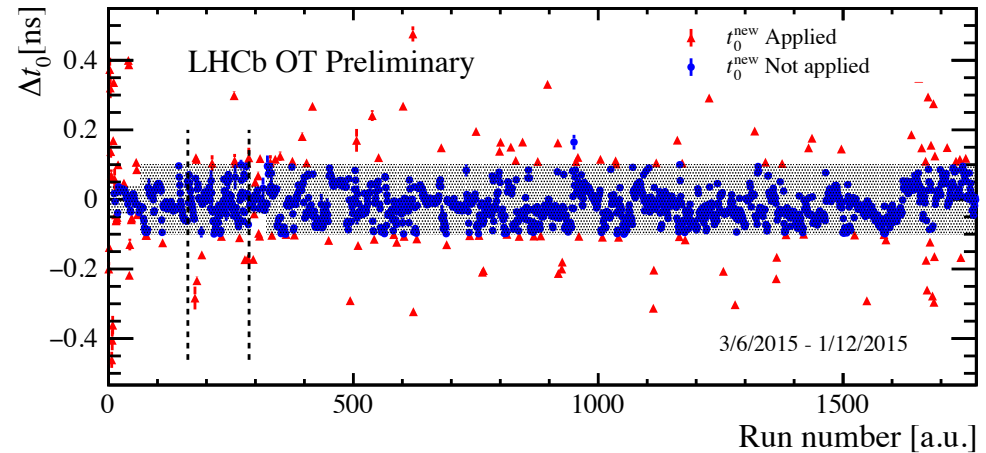
Philippe,
Lucia

Work during WS

- No conceptual work necessary, calibration already worked well in 2015.
- Some work on the monitoring.

Plans for 2016 data-taking

Continue running automatically on ~every run as during 2015.



RICH calibration

Chris,
Jibo

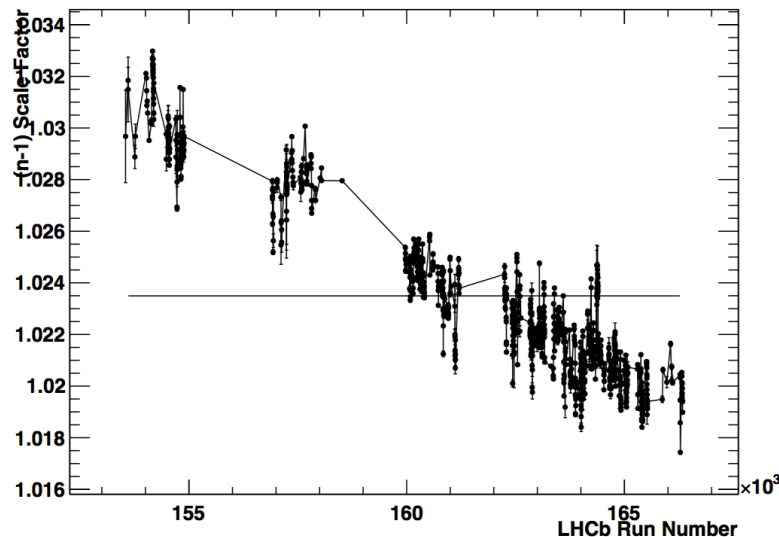
Work during WS

- No work conceptual necessary, calibration already worked well in 2015.

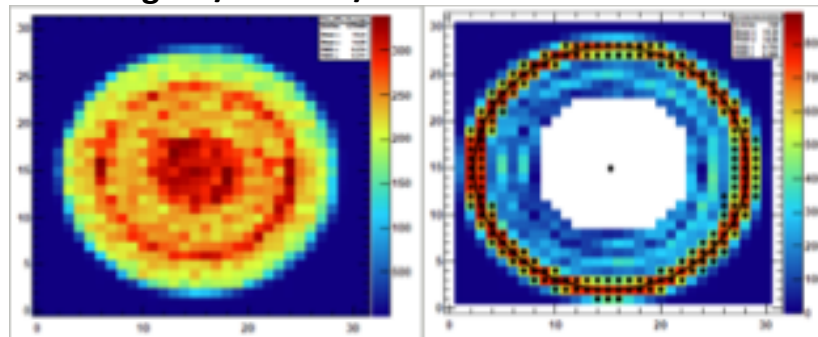
Plans for 2016 data-taking

Continue running automatically on ~every run as during 2015.

Rich1Gas (n-1) corrections by Run



HPD image w/o and w/ Sobel filter



CALO calibration

Marie-Noelle,
Jean Francois

Work during WS

LED method:

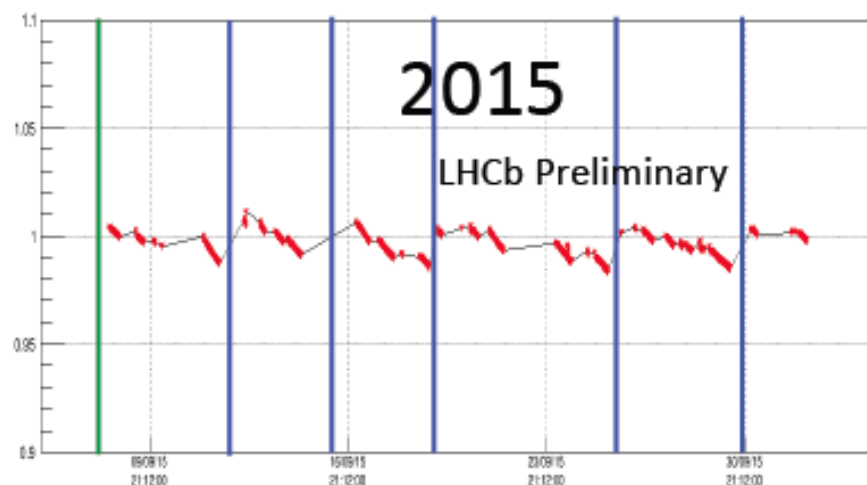
- Worked well in 2015
- Failing LED were replaced

Occupancy method:

- Noticed dependency on the beam conditions
- Study still ongoing

Over-calibration of cells in inner region of ECAL:

- Compared occupancy in cells in MC and data
- Cells were identified, HV was reduced



Plans for 2016 data-taking

- Run LED method for both ECAL and HCAL automatically at the start of each fill
- Run occupancy method for each fill (without applying the results) to study the dependency on the beam conditions

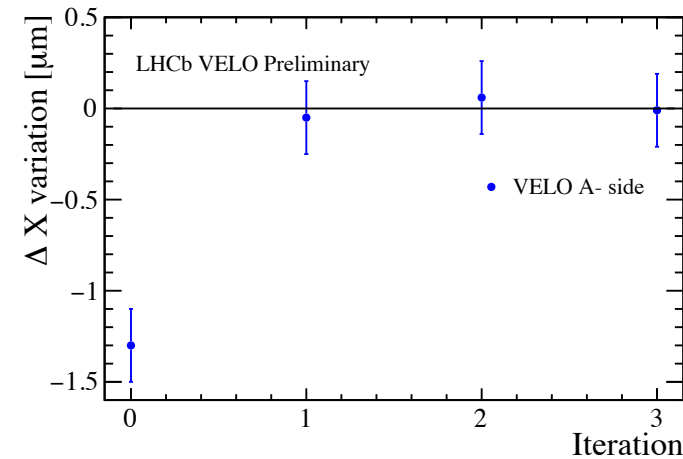
Pi0 calibration

????

Monitoring and Alarms

Work in progress:

- Show development of alignment constants during the alignment procedure in presenter
- Show the stability of the alignment constants over time in presenter
- Alarm if something goes *wrong*: change in constants too large, no convergence was reached...
- Developing procedure for case of alarms



Alarm Screen

Mode: ☒ Current Alarms ☐ Historical Alarms

Quick Filters: None available

Dir	Description	Alarm text	Dir	Value	Ack	Time
E	TTDCS SafeHLog	TT_REDA_BOT_LV22V too many consecutive bad readings SPEC	CAME	TRUE		20160107 13:49:24
E	TTDAQCS TT_C86_C8H5_HUM dewPoint	Dewpoint NEAR temperature safety margin	CAME	17.531431629		20160107 13:49:38
W	TTDAQCS TT_C86_C8H5_HUM BOX_RH	Humidity HIGH in Detector Box	CAME	191.04086343		20160107 13:49:38
W	TTDAQCS TT_C86_C8H5_HUM dewPoint	Dewpoint BELOW temperature safety margin	CAME	17.531431629		20160107 13:49:38
E	TTDAQCS TT_C86_C8H5_HUM BOX_RH	Humidity Very HIGH in Detector Box	CAME	191.04086343		20160107 13:49:38
W	TTDAQCS TT_C86_A13A17A21C8H5_HUM	Dewpoint NEAR temperature safety margin	CAME	14.34720467		20160107 13:49:38
W	TTDAQCS TT_C86_A13A17A21C8H5_HUM	Humidity HIGH in Detector Box	CAME	200.6336670		20160107 13:49:38
E	TTDAQCS TT_C86_A13A17A21C8H5_HUM	Dewpoint BELOW temperature safety margin	CAME	14.34720467		20160107 13:49:38
E	TTDAQCS TT_C86_A13A17A21C8H5_HUM	Humidity Very HIGH in Detector Box	CAME	200.6336670		20160107 13:49:38
W	TTDAQCS TT_AT6_A23G3H3_HUM BOX	Humidity below 0% FAIL	CAME	187.0301966		20160107 13:49:41
E	TTDAQCS TT_AT6_A23G3H3_HUM BOX	Humidity below 0% FAIL	CAME	187.0301966		20160107 13:49:41
W	TTDAQCS TT_AT6_C1H1_HUM dewPoint	Dewpoint NEAR temperature safety margin	CAME	241.2781334		20160107 13:49:48
W	TTDAQCS TT_AT6_C1H1_HUM BOX_RH	Humidity HIGH in Detector Box	CAME	191.37676022		20160107 13:49:48
E	TTDAQCS TT_AT6_C1H1_HUM dewPoint	Dewpoint BELOW temperature safety margin	CAME	241.2781334		20160107 13:49:48
E	TTDAQCS TT_AT6_C1H1_HUM BOX_RH	Humidity Very HIGH in Detector Box	CAME	191.37676022		20160107 13:49:48
W	TTDAQCS TT_AT6_A11A15A19C3H2_HUM	Humidity HIGH in Detector Box	CAME	244.0158613		20160107 13:49:48
W	TTDAQCS TT_AT6_A11A15A19C3H2_HUM	Humidity Very HIGH in Detector Box	CAME	199.0909167		20160107 13:49:48
E	TTDAQCS TT_AT6_A11A15A19C3H2_HUM	Dewpoint BELOW temperature safety margin	CAME	244.0158613		20160107 13:49:48
E	TTDAQCS TT_AT6_A11A15A19C3H2_HUM	Humidity Very HIGH in Detector Box	CAME	199.0909167		20160107 13:49:48
W	TTDAQCS TT_C76_A24C7H7_HUM dewP	Dewpoint NEAR temperature safety margin	CAME	11.19742635		20160107 13:50:05
W	TTDAQCS TT_C76_A24C7H7_HUM BOX	Humidity HIGH in Detector Box	CAME	176.70274946		20160107 13:50:05
E	TTDAQCS TT_C76_A24C7H7_HUM dewP	Dewpoint BELOW temperature safety margin	CAME	11.19742635		20160107 13:50:05
E	TTDAQCS TT_C76_A24C7H7_HUM BOX	Humidity Very HIGH in Detector Box	CAME	176.70274946		20160107 13:50:05
W	TTDAQCS TT_C76_A14A16A22C8H5_HUM	Dewpoint NEAR temperature safety margin	CAME	13.89247946		20160107 13:50:05
W	TTDAQCS TT_C76_A14A16A22C8H5_HUM	Humidity HIGH in Detector Box	CAME	193.9776674		20160107 13:50:05
E	TTDAQCS TT_C76_A14A16A22C8H5_HUM	Dewpoint BELOW temperature safety margin	CAME	13.89247946		20160107 13:50:05
E	TTDAQCS TT_C76_A14A16A22C8H5_HUM	Humidity Very HIGH in Detector Box	CAME	193.9776674		20160107 13:50:05
E	IsCooling TTCoolingPlant CBP14 avOutput	CBP14 Temperature TOO HIGH	CAME	16.850799942		20160107 13:53:09
W	Water Inlet	VELO Cooling Water Inlet temperature is high	CAME	7.4 °C		20160107 14:19:15
E	IsCooling TTCoolingPlant CBP14 avOutput	CBP14 return temperature TOO HIGH	CAME	18.34795942		20160107 14:53:19
E	CO2RefillLevel	No Calibration Firm available	CAME	TRUE		20160107 16:12:37
E	Q3MMR31	This DU has lost the link with its ODE board	CAME	TRUE		20160107 16:29:32
E	Water Inlet	VELO Cooling Water Inlet temperature is high	CAME	7.4 °C		20160108 01:17:50
E	VELOOnlineAlignment	ERROR: Velo Alignment converged but constants changes is unreac	CAME	TRUE		20160108 09:12:38

Alarms Displayed: 1924 Unacknowledged: 8 All displayed systems are connected Deselect Rows Close

Conclusion

- Many studies done during WS
- Improvements in performance
- Improvements in speed
- Some small improvements/studies still to be made
- Further work on the monitoring required
- Getting ready for data-taking!

