

Summary of Multiple Integration

$$\iiint_R f \, dV$$

- Rect: $dV = dzdxdy$
- Cylinder: $dV = dz \cdot r dr d\theta$
- Spherical: $dV = \rho^2 \sin \varphi \, d\rho \, d\varphi \, d\theta$

Applications

- Mass
- Avg value of f
- Moment of inertia
- Gravitational attraction on mass at O

$$\iint_S \vec{F} \cdot \hat{n} \, dS \quad \text{or} \quad \iint_S \vec{F} \, d\vec{S}$$

Calculate formulas for $\hat{n} dS$

Ex: $\hat{n} dS = \dots dxdy$

Becomes $\iint \dots dxdy$

+ general cases:

- $z = z(x, y)$

$$\hat{n} dS = \langle -z_x, -z_y, 1 \rangle dxdy$$

- \vec{N} given normal vector

$$\hat{n} dS = \pm \frac{\vec{N}}{\vec{N} \cdot \hat{k}} dxdy$$

$$\int_C \vec{F} \cdot d\vec{r}$$

$$= \int_C P dx + Q dy + R dz$$

With $\vec{F} = \langle P, Q, R \rangle$

Typical S

- ◆ Horizontal plane: yz-plane

$$dS = dydz$$

$$\hat{n} = \pm \hat{i}$$

- ◆ Sphere, centered at O

$$\hat{n} = \pm \frac{\langle x, y, z \rangle}{a}, \quad a \text{ is radius}$$

$$dS = a^2 \sin \varphi \, d\varphi \, d\theta$$

- ◆ Cylinder, centered at O

$$\hat{n} = \pm \frac{\langle x, y, 0 \rangle}{a}, \quad a \text{ is radius}$$

$$dS = a \, dz d\theta$$

Parameterize C

-> express in terms of a single variable

$$\iiint_R f \, dV \xleftrightarrow{\text{div thm}} \iint_S \vec{F} \cdot \hat{n} \, dS \xleftrightarrow{\text{Stokes thm}} \int_C \vec{F} \cdot d\vec{r}$$

Divergence Theorem

$$\iint_S \vec{F} \cdot \hat{n} dS = \iiint_D (\nabla \cdot \vec{F}) dV$$

Stokes Theorem

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \hat{n} dS$$

Fundamental Theorem for Line Integrals

$$f(P_1) - f(P_0) = \int_C (\nabla f) \cdot d\vec{r}$$

Also: given \vec{F} with $\text{curl} = 0$, find potential