

SET UP SPI

Set up the spi to mode 0

Mode	Full-Duplex Master
Hardware NSS Signal	Disable
Hardware RDY Signal	Disable

Configuration

Reset Configuration

✓ Parameter Settings

✓ User Constants

✓ NVIC Settings

✓ DMA Settings

✓ GPIO Settings

Configure the below parameters :

Basic Parameters

Frame FormatMotorola

Data Size8 Bits

First BitMSB First

Clock Parameters

Prescaler (for Baud Rate)32

Baud Rate4.0 MBits/s

Clock Polarity (CPOL)Low

Clock Phase (CPHA)1 Edge

Autonomous Mode

StateDisable

CRC Parameters

CRC CalculationDisabled

Advanced Parameters

NSSP ModeEnabled

NSS Signal TypeSoftware

Fifo ThresholdFifo Threshold 01 Data

Nss PolarityNss Polarity Low

Master Ss Idleness00 Cycle

Master Inter Data Idleness00 Cycle

Master Receiver Auto SuspDisable

Master Keep Io StateMaster Keep Io State Disable

IO SwapDisabled

Ready Master ManagementInternal

Ready Signal PolarityHigh

Make sure that the SPI pins MATCHES THE IIS3DWB datasheet

Pin Name	Signal on Pin	Pin Context Assign...	Pin Privilege access	GPIO output level	GPIO mode	GPIO Pull-up/Pull-d...	Maximum output sp...	Fast Mode	User Label	Modified
PD3	SPI2_MISO	n/a	n/a	n/a	Alternate Function ...	No pull-up and no p...	Low	n/a		<input type="checkbox"/>
PI1	SPI2_SCK	n/a	n/a	n/a	Alternate Function ...	No pull-up and no p...	Low	n/a		<input type="checkbox"/>
PI3	SPI2_MOSI	n/a	n/a	n/a	Alternate Function ...	No pull-up and no p...	Low	n/a		<input type="checkbox"/>

Then set up the GPIO

Pin Name	Signal on Pin	Pin Context Assign...	Pin Privilege access	GPIO output level	GPIO mode	GPIO Pull-up/Pull-d...	Maximum output sp...	Fast Mode	User Label	Modified
PF12	n/a	n/a	n/a	Low	Output Push Pull	Pull-up	Medium	n/a	CS_DWB[IIS3DWB]	<input checked="" type="checkbox"/>
PF15	n/a	n/a	Non-privileged access	n/a	External Interrupt M...	No pull-up and no p...	n/a	n/a	INT1[IIS3DWB]	<input checked="" type="checkbox"/>
PH10	n/a	n/a	n/a	Low	Output Push Pull	No pull-up and no p...	Medium	n/a	LED2[ORANGE]	<input checked="" type="checkbox"/>
PH12	n/a	n/a	n/a	Low	Output Push Pull	No pull-up and no p...	Medium	n/a	LED1[GREEN]	<input checked="" type="checkbox"/>

And interrupt

NVIC Interrupt Table	Enabled	Preemption Priority	Sub Priority
EXTI Line15 interrupt	<input checked="" type="checkbox"/>	0	0

PLEASE MAKE SURE IT MATCHES THE ISS3DWB PINS IN DATASHEET

SETUP IIS3DWB

Download the middleware X-CUBE-MEMS1

▼ STMicroelectronics.X-CUBE-MEMS1	✓	11.2.0	▼
> <i>Exposed APIs</i>			
▼ <i>Device</i> MEMS1_Applications		11.2.0	
Application			Not selected ▼
> <i>Board Part</i> AccGyr		5.6.0	
> <i>Board Part</i> AccMag		5.7.0	
▼ <i>Board Part</i> Acc	✓	1.5.0	
LIS2DW12			Not selected ▼
LIS2DH12			Not selected ▼
IIS2DLPC			Not selected ▼
AIS2DW12			Not selected ▼
AIS328DQ			Not selected ▼
AIS3624DQ			Not selected ▼
H3LIS331DL			Not selected ▼
IIS2ICLX			Not selected ▼
AIS2IH			Not selected ▼
LIS2DU12			Not selected ▼
IIS3DWB	✓	1.3.0	SPI ▼
LIS2DUX12			Not selected ▼
ST1VAFE3BX			Not selected ▼

Go to the middleware and set up this

☒ Board Part Acc

Configuration

Reset Configuration

☒ Parameter Settings ☒ Platform Settings

Platform proposal

BSP

Name	IPs or Components	Found Solutions	BSP API
IIS3DWB_CS	GPIO:Output	PF12 [CS_DWB[IIS3DWB]]	Unknown
IIS3DWB BUS IO driver	SPI:Full-Duplex Master	SPI2	BSP_BUS_DRIVER

CHECK WHO_AM_I REGISTER TO SEE IF SENSOR ON

In a new file **vib_io.c**

Add the includes needed

```
#include "vib_io.h"
#include "iis3dwb_reg.h"
#include "steval_stwinbx1_bus.h"
#include "main.h" // for CS_DWB_GPIO_Port, CS_DWB_Pin

extern SPI_HandleTypeDef hspi2;
static stmdev_ctx_t dev_ctx;
```

SPI Write Wrapper

```
/* SPI write wrapper: assert CS, send reg & data, de-assert CS */
static int32_t drv_write(void *handle, uint8_t reg, uint8_t *bufp, uint16_t len) {
    HAL_GPIO_WritePin(CS_DWB_GPIO_Port, CS_DWB_Pin, GPIO_PIN_RESET);
    BSP_SPI2_Send(&reg, 1);
    BSP_SPI2_Send(bufp, len);
    HAL_GPIO_WritePin(CS_DWB_GPIO_Port, CS_DWB_Pin, GPIO_PIN_SET);
    return 0;
}
```

SPI Read Wrapper

```
/* SPI read wrapper: assert CS, send reg|0x80, read data, de-assert CS */
static int32_t drv_read(void *handle, uint8_t reg, uint8_t *bufp, uint16_t len) {
    reg |= 0x80;
    HAL_GPIO_WritePin(CS_DWB_GPIO_Port, CS_DWB_Pin, GPIO_PIN_RESET);
    BSP_SPI2_Send(&reg, 1);
    BSP_SPI2_Recv(bufp, len);
    HAL_GPIO_WritePin(CS_DWB_GPIO_Port, CS_DWB_Pin, GPIO_PIN_SET);
    return 0;
}
```

Initialize the IIS3DWB

```
/**
 * @brief Initialize the IIS3DWB vibration sensor and configure it for data acquisition.
 *
 * This function performs the following:
 * - Initializes the SPI interface for communication with the IIS3DWB sensor.
 * - Sets up the STM32 sensor driver context with board-specific read/write functions.
 * - Verifies the sensor is connected by reading the WHO_AM_I register.
 * - Resets the IIS3DWB sensor to default configuration.
 * - Configures the sensor for 3-axis measurement at 26.7 kHz, 2g full scale, with block data update.
 * - Sets the output data filter path to 6.3 kHz bandwidth.
 * - Enables the data-ready interrupt on INT1.
 *
 * @retval 0 Initialization and configuration successful.
 * @retval -1 SPI interface initialization failed.
 * @retval -2 IIS3DWB sensor not found (WHO_AM_I mismatch).
 */
```

```
int32_t vib_io_init(void)
{
    uint8_t whoamI, rst;

    /* 1) bring up the SPI bus */
    if (BSP_SPI2_Init() != BSP_ERROR_NONE) return -1;

    /* 2) hook our wrappers into the ST driver */
    dev_ctx.write_reg = drv_write;
    dev_ctx.read_reg = drv_read;
    dev_ctx.handle = &hspi2;
    dev_ctx.mdelay = HAL_Delay;

    /* 3) check device ID */
    iis3dwb_device_id_get(&dev_ctx, &whoamI);
}
```

```

if (whoamI != IIS3DWB_ID)                                return -2;          // WHO_AM_I_EXPECTED 0x7B

/* 4) reset sensor */
iis3dwb_reset_set(&dev_ctx, PROPERTY_ENABLE);
do {
    iis3dwb_reset_get(&dev_ctx, &rst);
} while (rst);

/* 5) basic configuration */
iis3dwb_block_data_update_set(&dev_ctx, PROPERTY_ENABLE);
iis3dwb_xl_data_rate_set (&dev_ctx, IIS3DWB_XL_ODR_26kHz);
iis3dwb_xl_full_scale_set(&dev_ctx, IIS3DWB_2g);
iis3dwb_xl_filt_path_on_out_set(&dev_ctx, IIS3DWB_LP_6kHz);

/* 6) enable data-ready interrupt on INT1 */
iis3dwb_int1_ctrl_t int1_ctrl;
iis3dwb_read_reg(&dev_ctx, IIS3DWB_INT1_CTRL, (uint8_t *)&int1_ctrl, 1);
int1_ctrl.int1_drdy_xl = 1;
iis3dwb_write_reg(&dev_ctx, IIS3DWB_INT1_CTRL, (uint8_t *)&int1_ctrl, 1);

return 0;
}

```

In a new file **vib_io.h**

Add the header

```

#ifndef VIB_IO_H
#define VIB_IO_H

#include <stdint.h>
#include "iis3dwb_reg.h"
#include "stm32u5xx_hal.h"

/* call once at startup. returns 0 on success */
int32_t vib_io_init(void);

#endif /* VIB_IO_H */

```

In **main.c**

Add check code in user code 2

```

/* USER CODE BEGIN 2 */
if(vib_io_init() != 0) HAL_GPIO_TogglePin(LED2_GPIO_Port, LED2_Pin); // LED2[ORANGE] ON
else                    HAL_GPIO_TogglePin(LED1_GPIO_Port, LED1_Pin); // LED1[GREEN] ON
/* USER CODE END 2 */

```