COMP0037 ASSIGNMENT 2

Group: `Group L`

1 Introduction [dai ding]

2 Effect of Vehicle Drive Speed [Yusi]

3 Reactive Planner [Yun]

4 Frontier-Based Exploration System [Yun]

5 Integration of the Planner and the Exploration System [Yun]

6 Information-Theoretic Path Planning [Yusi]

7 Conclusion [dai ding]

References