



UNIVERSITY OF
TORONTO



Neural Progressive Meshes

Yun-Chun Chen^{1,2}

Vladimir G. Kim²

Noam Aigerman²

Alec Jacobson^{1,2}

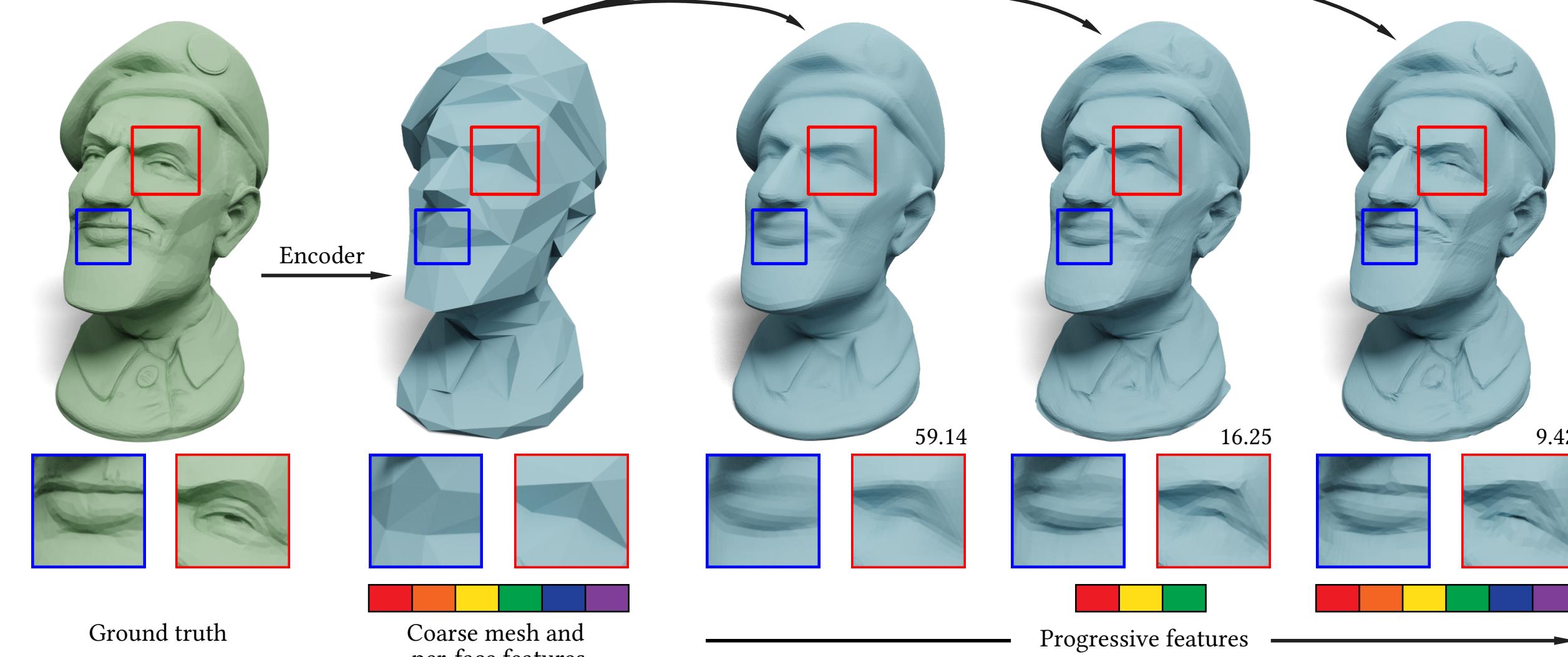
¹University of Toronto

²Adobe Research



Mesh Compression and Transmission

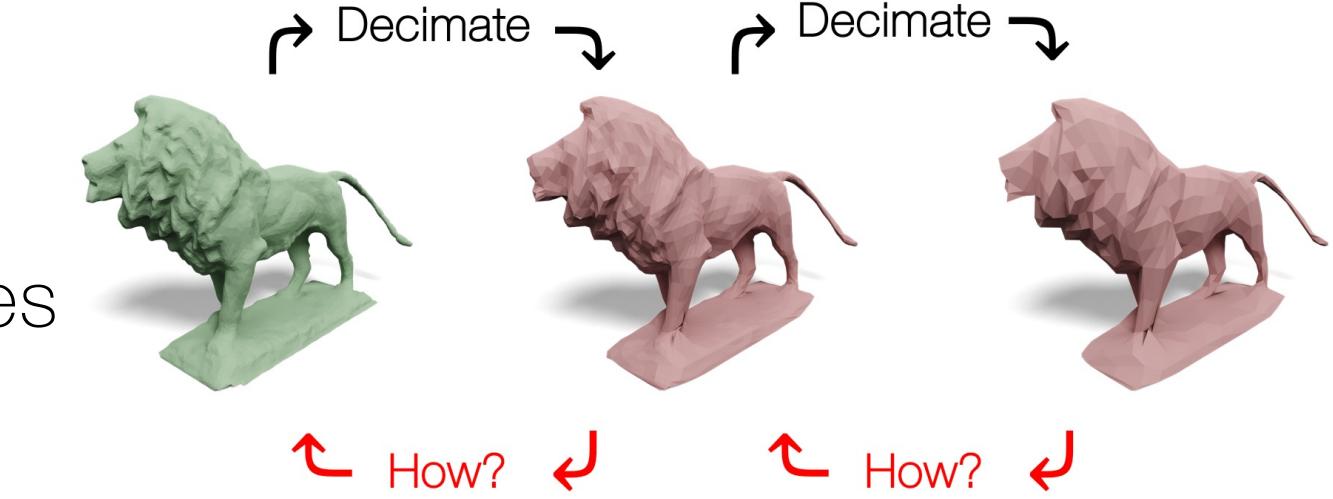
- Input: A triangle mesh
- Goal: Develop a framework that learns a progressive compressed representation of meshes for transmission purposes



Decimation and Level-of-Detail Methods

Mesh decimation methods

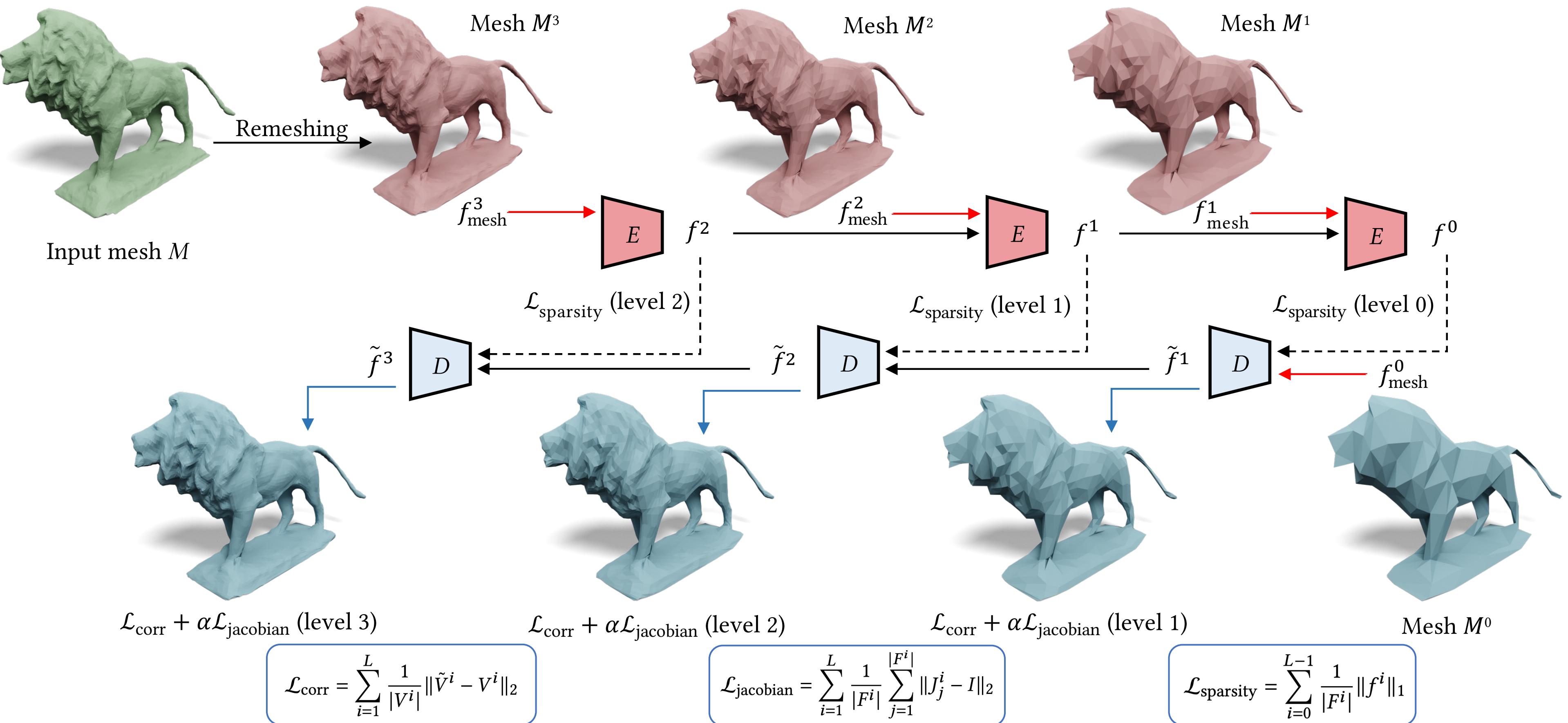
- E.g., QSLIM [Garland et al. 1997]
- Provide a way to compress meshes
- Lose original geometric details
- Do not provide a way to progressively improve the quality of meshes



Level-of-detail methods

- E.g., Progressive Meshes [Hoppe 1996]
- Provide a way to transmit incremental data for mesh quality improvement
- Lose details as polygon count reduces

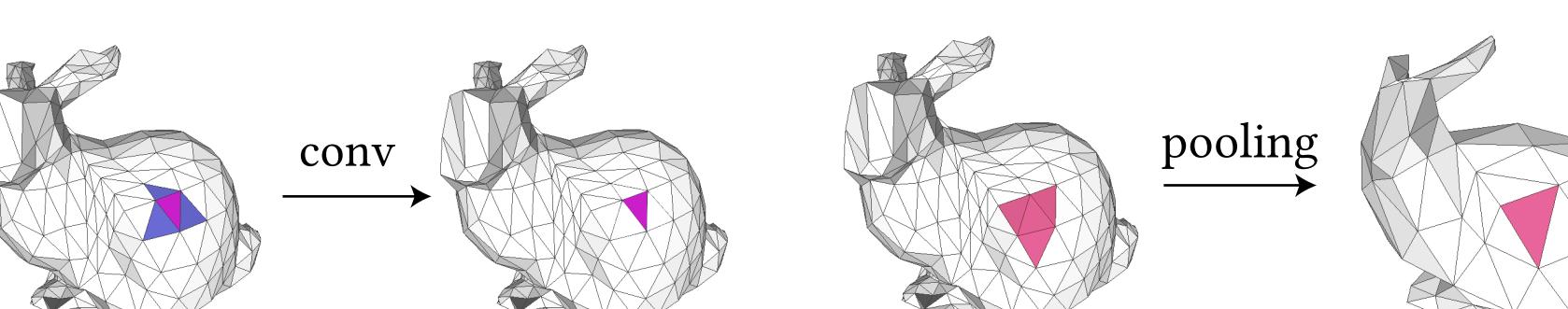
Method: Neural Progressive Meshes



Encoder and Decoder

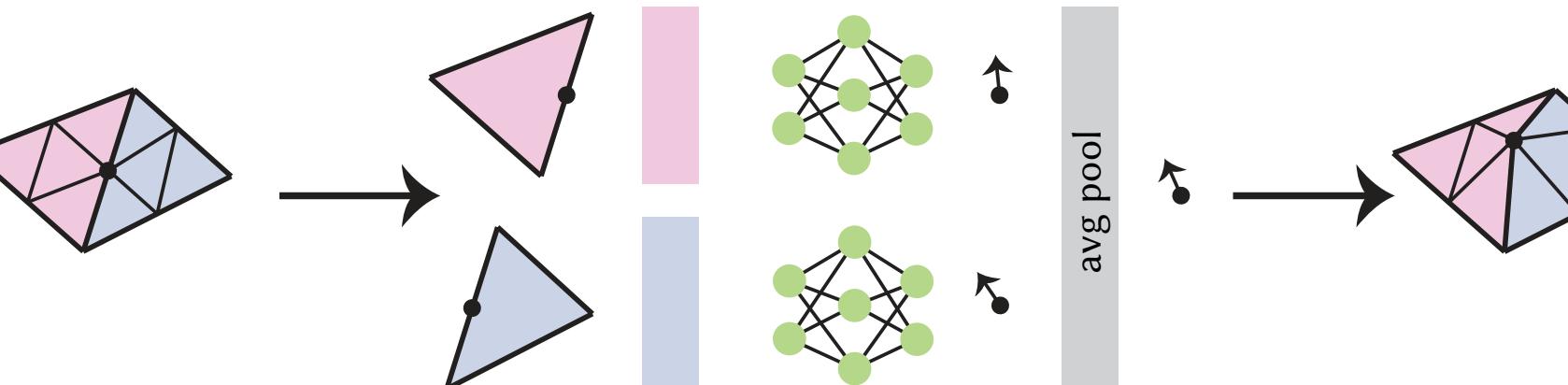
Encoder

- Loop maintains a 4-to-1 face mapping



Decoder

- Adjacent face features for vertex displacement prediction



Data Generation

- Successive self-parameterization in [Liu et al. 2020]

- Maintain a bijective map for each edge collapse

- Stochastic QSLIM for data augmentation

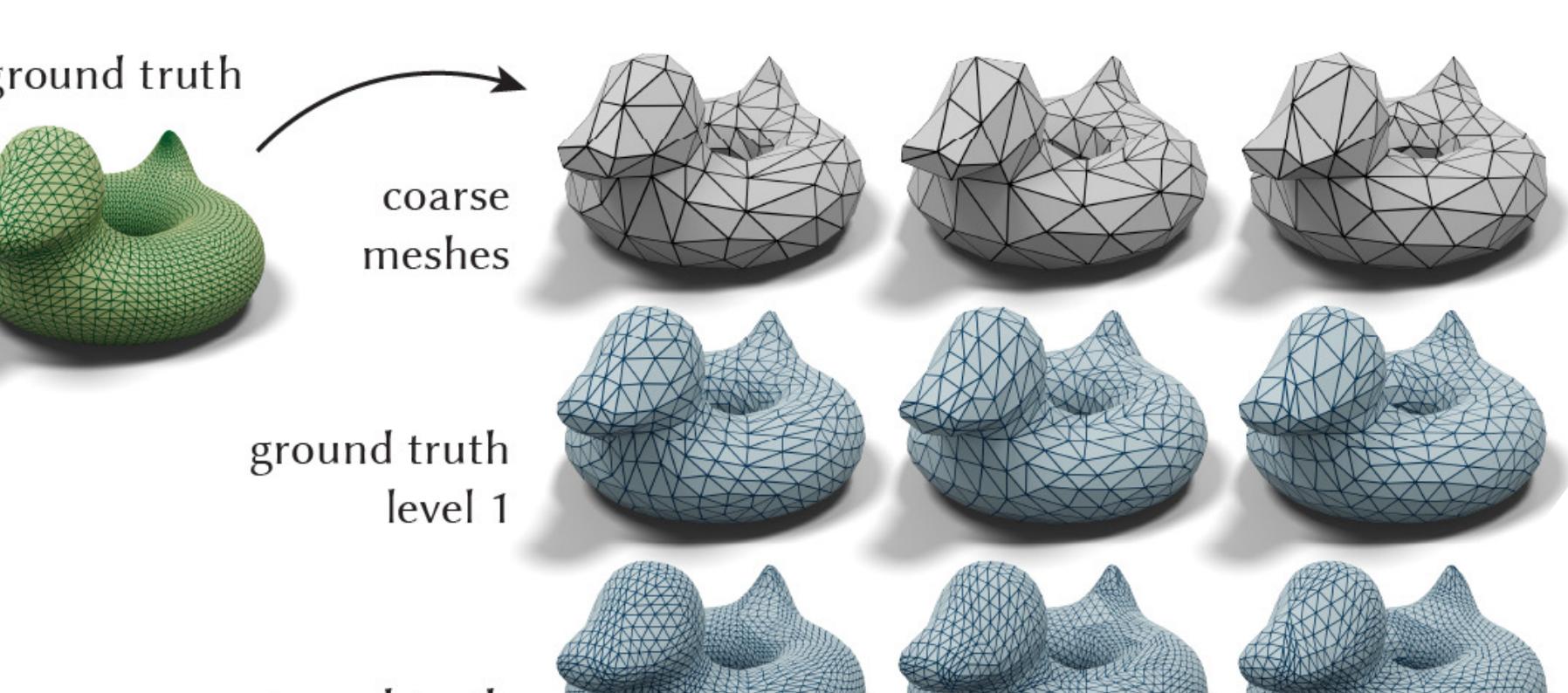
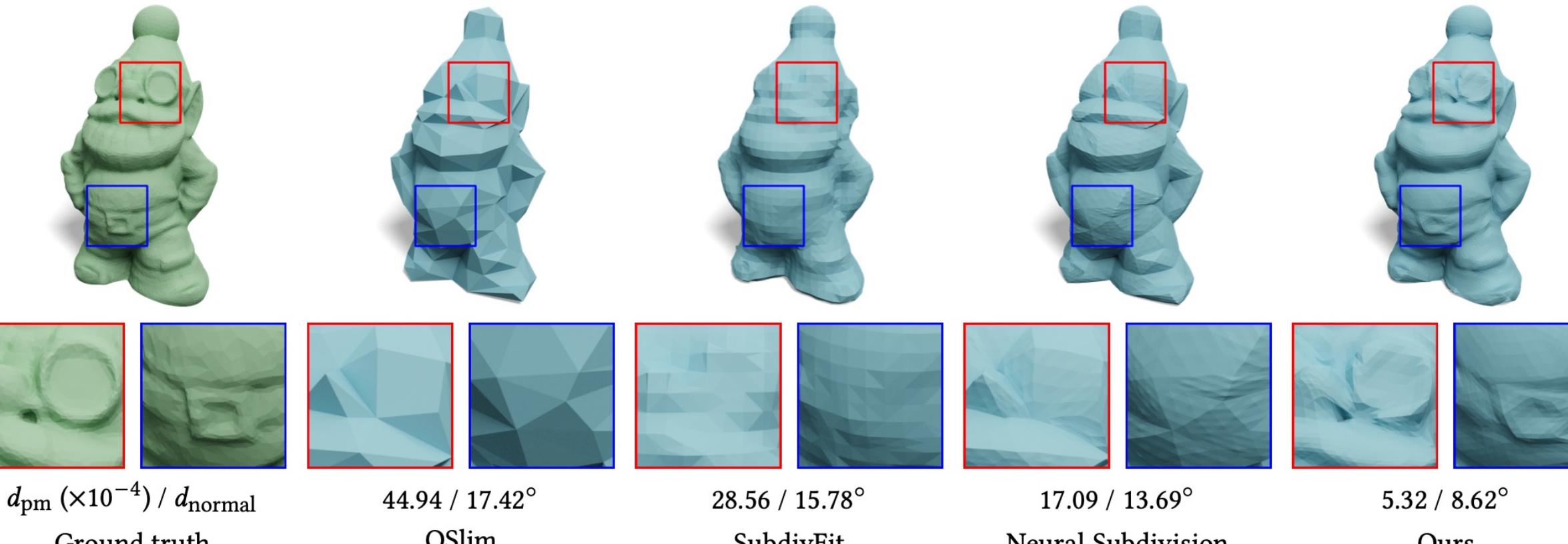


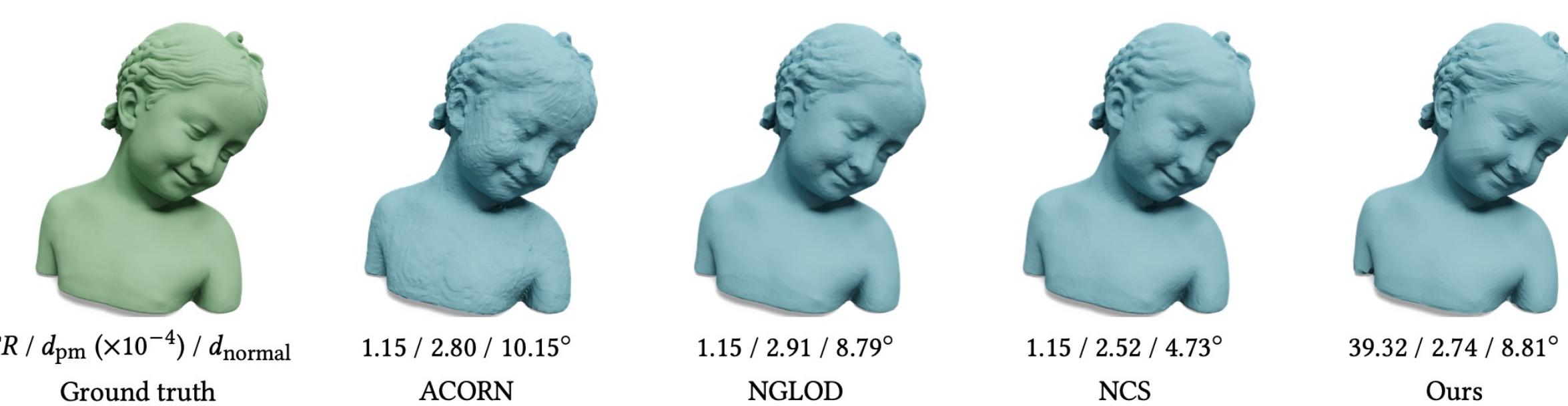
Image courtesy of [Liu et al. 2020]

Experimental Results

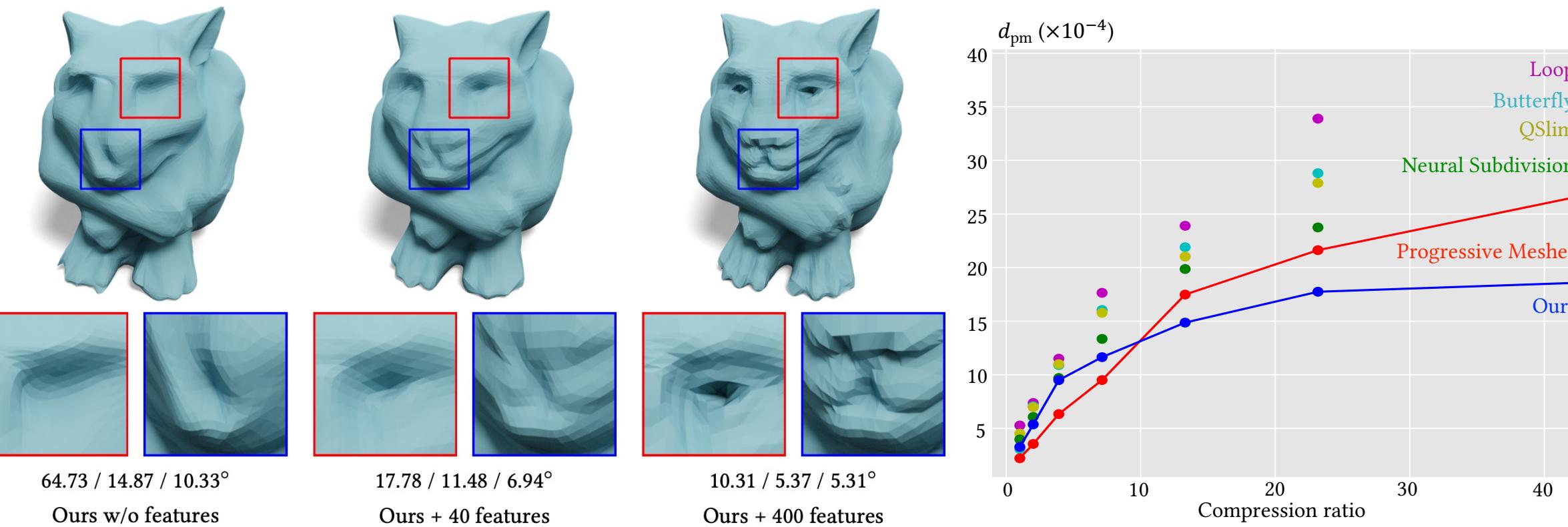
Comparison to decimation and subdivision methods



Comparison to neural overfitting methods



Progressive features



References

- Hoppe. 1996. *Progressive Meshes*.
- Hoppe et al. 1994. *Piecewise Smooth Surface Reconstruction*.
- Liu et al. 2020. *Neural Subdivision*.
- Garland et al. 1997. *Surface Simplification Using Quadric Error Metrics*.
- Hu et al. 2022. *Subdivision-based Mesh Convolution Networks*.
- Morreale et al. 2022. *Neural Convolutional Surfaces*.
- Martel et al. 2021. *ACORN: Adaptive Coordinate Networks for Neural Scene Representation*.
- Takikawa et al. 2021. *Neural Geometric Level of Detail: Real-time Rendering with Implicit 3D Shapes*.

$$CR = \frac{3|V|}{3|V^0| + \sum_{f \in \mathcal{T}} \dim(f)}$$