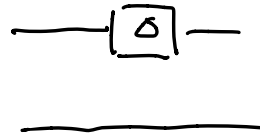


Quantum Teleportation

(a)

$$\begin{cases} \Delta \equiv (n - n_0)L/c_0 \\ p|0\rangle = |0\rangle \\ p|1\rangle = e^{i\Delta}|1\rangle \end{cases}$$



For a dual state

$$|\psi\rangle = C_0|01\rangle + C_1|10\rangle$$

After the "circuit"

$$|\psi_1\rangle = C_0|01\rangle + C_1 \cdot e^{i\Delta} \cdot |10\rangle$$

$$= \underline{e^{+i\frac{\Delta}{2}}} \cdot (e^{-i\frac{\Delta}{2}} \cdot C_0|01\rangle + C_1 \cdot e^{i\frac{\Delta}{2}} C_1|10\rangle)$$

global phase

By our definition of dual states.

$$|\psi\rangle = C_0|\hat{0}\rangle + C_1|\hat{1}\rangle$$

$$|\psi_1\rangle = e^{-i\frac{\Delta}{2}} C_0|\hat{0}\rangle + C_1 \cdot e^{i\frac{\Delta}{2}} |\hat{1}\rangle$$

The transformation is $\begin{bmatrix} e^{-i\frac{\Delta}{2}} & 0 \\ 0 & e^{i\frac{\Delta}{2}} \end{bmatrix}$

in the matrix form.

The matrix is nothing but $R_z(\Delta) = e^{-iZ\frac{\Delta}{2}}$

$$e^{-iZ\frac{\Delta}{2}} = \cos\frac{\Delta}{2} \cdot I - i \cdot \sin\frac{\Delta}{2} \cdot Z = \begin{bmatrix} e^{-i\frac{\Delta}{2}} & 0 \\ 0 & e^{i\frac{\Delta}{2}} \end{bmatrix}$$

$Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ pauli-Z matrix

$$e^{-iZ\frac{\Delta}{2}} = \sum_{n=0}^{\infty} \frac{(-iZ\frac{\Delta}{2})^n}{n!}$$

$$= \sum_{n=0}^{\infty} \frac{(-i)^n}{n!} \left(\frac{\Delta}{2}\right)^n \cdot Z^n$$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}^3 = Z$$

$$\Rightarrow e^{-iZ\frac{\Delta}{2}} = \sum_{\substack{n=0 \\ n, \text{ even}}}^{\infty} \frac{(-i)^n}{n!} \left(\frac{\Delta}{2}\right)^n \cdot I + \sum_{\substack{n=0 \\ n, \text{ odd}}}^{\infty} \frac{(-i)^n}{n!} \left(\frac{\Delta}{2}\right)^n \cdot Z$$

$$= I \cdot \sum_{n=0}^{\infty} \frac{(-i)^{2n}}{(2n)!} \left(\frac{\Delta}{2}\right)^{2n} + Z \sum_{n=0}^{\infty} \frac{(-i)^{2n+1}}{(2n+1)!} \left(\frac{\Delta}{2}\right)^{2n+1}$$

$$= I \cdot \cos\frac{\Delta}{2} + Z (-i) \cdot \sin\frac{\Delta}{2}$$

$$= \begin{bmatrix} \cos\frac{\Delta}{2} & 0 \\ 0 & \cos\frac{\Delta}{2} \end{bmatrix} + \begin{bmatrix} -i\sin\frac{\Delta}{2} & 0 \\ 0 & i\sin\frac{\Delta}{2} \end{bmatrix} = \begin{bmatrix} e^{-i\frac{\Delta}{2}} & 0 \\ 0 & e^{+i\frac{\Delta}{2}} \end{bmatrix}$$

$$(b) \quad H_{bs} = i\theta(ab^\dagger - a^\dagger b)$$

$$B = \exp[\theta(a^\dagger b - ab^\dagger)]$$

a & b commute
with each other

$$\Rightarrow B^\dagger = \exp[\theta(ab^\dagger - a^\dagger b)] \\ = \exp[-\theta(a^\dagger b - ab^\dagger)]$$

$$B a B^\dagger \neq a \cos \theta + b \sin \theta$$

$$e^{\lambda G} A e^{-\lambda G} = \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} C_n$$

$$C_0 = A, \quad C_1 = [G, C_0], \quad C_2 = [G, C_1]$$

$$\dots \quad C_n = [G, C_{n-1}]$$

In our case

$$A = a \quad C_1 = [a^\dagger b - ab^\dagger, a]_+ \\ = b[a^\dagger, a]_+ - \cancel{b^\dagger[a, a]_+} \\ = -b$$

$$C_2 = [a^\dagger b - ab^\dagger, -b]_+ \\ = - (a^\dagger [b, b]_+ - a[b^\dagger, b]_+) \\ = -a$$

$$C_3 = [(a^\dagger b - a b^\dagger), -a]_+$$

$$= (-1) \cdot (-b) = b$$

$$\Rightarrow B \cdot a \cdot B^\dagger$$

$$n = 0 \quad 1 \quad 2 \quad 3 \quad 4$$

$$C_n = a, -b, -a, b, a, \dots$$

$$= \sum_{n=0}^{\infty} \frac{\theta^n}{n!} C_n$$

$$= \sum_{n=0}^{\infty} \frac{(i\theta)^{2n}}{(2n)!} \cdot a + \sum_{n=0}^{\infty} \frac{i \cdot (i\theta)^{2n+1}}{(2n+1)!} \cdot b$$

$$= \sum_{n=0}^{\infty} \underbrace{(i^2)^n}_{=(-1)^n} \cdot \frac{\theta^{2n}}{(2n)!} a + \sum_{n=0}^{\infty} (i \cdot i) \underbrace{(i^2)^n}_{=(-1)^n} \cdot \frac{\theta^{2n+1}}{(2n+1)!} \cdot b$$

(using (29))

$$= a \cdot \cos \theta - b \sin \theta$$

$$\text{For } B b B^\dagger \quad C_0 = A = b \Rightarrow C_1 = a$$

$$\Rightarrow C_2 = -b \Rightarrow C_3 = -a \dots$$

$$\Rightarrow B b B^\dagger = \sum_{n=0}^{\infty} \frac{\theta^n}{n!} C_n$$

$$= \sum_{n=0}^{\infty} \frac{(i\theta)^{2n}}{(2n)!} \cdot b - \sum_{n=0}^{\infty} \frac{i(i\theta)^{2n+1}}{(2n+1)!} \cdot a$$

$$= b \cdot \cos\theta + a \sin\theta$$

$$B|00\rangle = |00\rangle$$

$$B|01\rangle = B \cdot a^\dagger |00\rangle = B \cdot a^\dagger \underbrace{B^\dagger B}_{\mathbb{I}} |00\rangle$$

$$= (a^\dagger \cos\theta - b^\dagger \sin\theta) \cdot B|00\rangle$$

$$= a^\dagger \cos\theta |00\rangle - b^\dagger \sin\theta |00\rangle$$

$$= \cos\theta |01\rangle - \sin\theta |10\rangle$$

$$\Rightarrow B \cdot |\hat{0}\rangle = \cos\theta \cdot |\hat{0}\rangle - \sin\theta |\hat{1}\rangle$$

$$B|10\rangle = B \cdot b^\dagger |00\rangle = B b^\dagger B^\dagger B |00\rangle$$

$$= (b^\dagger \cos\theta + a^\dagger \sin\theta) B \cdot |00\rangle$$

$$= \cos\theta |10\rangle + \sin\theta |01\rangle$$

$$\Rightarrow B \cdot |\hat{1}\rangle = \sin\theta |\hat{0}\rangle + \cos\theta |\hat{1}\rangle$$

$$\Rightarrow B \text{ in matrix form } \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$B = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} = e^{-i\theta Y} \quad Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

$$e^{-i\theta Y} \stackrel{?}{=} \cos\theta \cdot I - i\sin\theta \cdot Y \stackrel{?}{=} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$e^{-i\theta Y} = \sum_{n=0}^{\infty} \frac{(-i\theta Y)^n}{n!} = \sum_{n=0}^{\infty} \frac{(-i\theta)^n}{n!} \cdot Y^n$$

$$Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \quad Y^2 = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \\ = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$\Rightarrow e^{-i\theta Y} = \sum_{\substack{n=0 \\ \text{even}}}^{\infty} \frac{(-i\theta)^n}{n!} \cdot I + \sum_{\substack{n=0 \\ \text{odd}}}^{\infty} \frac{(-i\theta)^n}{n!} \cdot Y$$

$$\begin{aligned} &= \cos\theta \cdot I - i \cdot \sin\theta \cdot Y \\ &= \begin{bmatrix} \cos\theta & 0 \\ 0 & \cos\theta \end{bmatrix} - i \begin{bmatrix} 0 & -i\sin\theta \\ i\sin\theta & 0 \end{bmatrix} \\ &= \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \end{aligned}$$

(C)

$$|01\rangle = |\tilde{0}\rangle$$

$$B \cdot |\hat{0}\rangle = \cos\theta \cdot |\hat{0}\rangle - \sin\theta |\hat{1}\rangle$$

$$\Rightarrow B \cdot |01\rangle = \cos\theta \cdot |01\rangle - \sin\theta |10\rangle$$

The upper π shift will make the state

$$\cos\theta \cdot |01\rangle - \sin\theta \cdot e^{-i\pi} \cdot |10\rangle$$

$$= \cos\theta \cdot |01\rangle + \sin\theta |10\rangle$$

$$= \boxed{\frac{\sqrt{2}}{2} |01\rangle + \frac{\sqrt{2}}{2} |10\rangle} \quad (\text{for this special beam splitter})$$

$$|10\rangle = |\tilde{1}\rangle$$

$$B \cdot |\hat{1}\rangle = \sin\theta \cdot |\hat{0}\rangle + \cos\theta |\hat{1}\rangle$$

$$\Rightarrow B \cdot |10\rangle = \sin\theta |01\rangle + \cos\theta |10\rangle$$

The upper π shift will make the state

$$\frac{\sqrt{2}}{2} |01\rangle + \frac{\sqrt{2}}{2} \cdot e^{-i\pi} \cdot |10\rangle = \boxed{\frac{\sqrt{2}}{2} (|01\rangle - |10\rangle)}$$