Derivation of Kinematics formulas

$$X_{f} = X_{i} + V_{ix} \Delta t$$

$$Y_{f} = Y_{i} + V_{iy} \Delta t - \frac{1}{2}g(\Delta t)^{2}$$

Nithout explicit calculus

Newton's 2nd:
$$V_f = V_i + \frac{3}{fnet} \Delta t$$

Now we equate this if to Newton's 2nd's if

$$2\overrightarrow{V}_{AVg} = \overrightarrow{V}_{i} + \overrightarrow{V}_{i} + \overrightarrow{F}_{net} \Delta t$$

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$$\overrightarrow{V}_{AVg} = \overrightarrow{V}_{i} + \frac{1}{2} \overrightarrow{F}_{net} \Delta t$$

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$$\overrightarrow{V}_{AVg} = \overrightarrow{V}_{i} + \overrightarrow{V}_{avg} \Delta t$$

$$\overrightarrow{V}_{f} = \overrightarrow{V}_{i} + \overrightarrow{V}_{avg} \Delta t$$

$$\overrightarrow{V}_{f} = \overrightarrow{V}_{i} + (\overrightarrow{V}_{i} + \frac{1}{2} \overrightarrow{F}_{net} \Delta t) \Delta t$$

$$\overrightarrow{V}_{f} = \overrightarrow{V}_{i} + (\overrightarrow{V}_{i} \Delta t + \frac{1}{2} \overrightarrow{F}_{net} \Delta t) \Delta t$$

$$\overrightarrow{V}_{f} = \overrightarrow{V}_{i} + \overrightarrow{V}_{i} \Delta t + \frac{1}{2} \overrightarrow{F}_{net} \Delta t$$

$$\overrightarrow{V}_{f} = \overrightarrow{V}_{i} + \overrightarrow{V}_{i} \Delta t + \frac{1}{2} (-\frac{1}{2} - \frac{1}{2} - \frac{1}{2}$$

Derivation using calculus explicitly Fret = constant Finet = dp Friet dt = dp birst integration JFnet dt = Sdp Finet $\int_{0}^{t_{f}} dt = \int_{0}^{p_{f}} dp$ Note: we'll let to = 0 be Finet (t) $\begin{vmatrix} t_f \\ 0 \end{vmatrix} = \vec{p} \begin{vmatrix} \vec{p}_f \\ \vec{p}_f \end{vmatrix}$ the initial time to simplify the devivation. Later Fret to = Po-Pi on, you can replace t with tf-tj and it's the same thing Fret $t_f = \frac{\hat{p}_e}{m} - \frac{\hat{p}_i}{m}$ Fret tf = vf -vi Let $t = t_f$ and $\vec{J} = \vec{J}_f$, then: Vi is constant (initial conditions) Friet t = 3 - 7;

Finet
$$t + \vec{v}_i = \vec{v}$$
 $\vec{V} = \vec{V}_i + \vec{F}_{net} + \vec{v}_i$

Remember that $\vec{V} = \vec{dr}$
 $\vec{dr} = \vec{V}_i + \vec{F}_{net} + \vec{v}_i$
 $\vec{dr} = \vec{V}_i + \vec{F}_{net} + \vec{v}_i$
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 $\vec{v}_i = \vec{v}_i + \vec{v}_i + \vec{v}_i + \vec{v}_i$
 $\vec{v}_i = \vec{v}_i + \vec{v}_i + \vec{v}_i + \vec{v}_i$
 $\vec{v}_i = \vec{v}_i + \vec{v}_i + \vec{v}_i + \vec{v}_i + \vec{v}_i + \vec{v}_i$
 $\vec{v}_i = \vec{v}_i + \vec{v}_i$

$$\vec{r}_f - \vec{r}_i = \vec{v}_i t + \frac{1}{2} \frac{\vec{r}_{net}}{m} t^2$$

$$\vec{r}_f = \vec{r}_i + \vec{v}_i t + \frac{1}{2} \frac{\vec{r}_{net}}{m} t^2$$
With $\vec{r}_{net} = \langle o, -mg, o \rangle$, then:
$$|x_f = x_i + v_{ix} t|$$

$$|y_f = y_i + v_{iy} t + \frac{1}{2} \left(\frac{-mg}{m} \right) t^2 = \frac{1}{2} y_f = y_i + v_{iy} t - \frac{1}{2} y_f t^2$$

And thus we arrive at the same Kinematics equations that we did in the other devivation.