

PHYS 2211 MNR - Test 1 - Fall 2022

Please clearly print your name & GTID in the lines below

Name: _____ GTID: _____

Key

Instructions

- This exam is closed internet/books/notes, except for the Formula Sheet which is included with the exam.
- You must work individually and receive no assistance from any person or resource.
- You are not allowed to post screenshots, files, or any other details of the test anywhere online, not even after the test is over.
- Work through all the problems first, then scan/upload your solutions after time is called.
 - Your uploaded files **must** be in either PNG, JPG, or PDF format.
 - Your uploaded files must be readable in order to be graded. Unreadable files will earn a zero.
 - You can upload a single file containing work for multiple problems as long as you upload the file for each problem individually.
 - Clearly label your work for each sub-part and box the final answers.
- To earn partial credit, your work must be legible and the organization must be clear.
 - Your solution should be worked out algebraically.
 - Numerical solutions should only be evaluated at the last step. Incorrect solutions that are not solved algebraically will receive an 80 percent deduction.
 - You must show all work, including correct vector notation.
 - **Correct answers without adequate explanation will be counted wrong.**
 - Incorrect work or explanations mixed in with correct work will be counted wrong. Cross out anything you do not want us to grade
 - Make explanations correct but brief. You do not need to write a lot of prose.
 - Include diagrams!
 - **Show what goes into a calculation, not just the final number, e.g.:** $\frac{a \cdot b}{c \cdot d} = \frac{(8 \times 10^{-3})(5 \times 10^6)}{(2 \times 10^{-5})(4 \times 10^4)} = 5 \times 10^4$
 - Give standard SI units with your numeric results. Your symbolic answers should not have units.

Unless specifically asked to derive a result, you may start from the formulas given on the formula sheet, including equations corresponding to the fundamental concepts. If a formula you need is not given, you must derive it.

If you cannot do some portion of a problem, invent a symbol for the quantity you can not calculate (explain that you are doing this), and use it to do the rest of the problem.

**“In accordance with the Georgia Tech Honor Code,
I have not given or received unauthorized aid on this test.”**

Sign your name on the line above

Hockey Puck [30 pts]

An ice hockey puck of mass $m = 170 \text{ g}$ enters the goal with a momentum of $\vec{p}_i = \langle -4.6, 2.9, 0 \rangle \text{ kg m/s}$, crossing the goal line at location $\vec{r}_g = \langle -27, 0, 0 \rangle \text{ m}$ relative to the origin which is located in the center of the rink. The puck had been hit by a player 0.4 seconds before reaching the goal.

1. [15 pts] What was the location of the puck \vec{r}_i when it was hit by the player? You can assume negligible friction between the puck and the ice (that is, constant velocity).

Initial: hit by the player

$$\vec{r}_i = ?$$

$$\vec{v}_i = \vec{v}_f = \vec{v}_{Avg} \text{ (b/c constant velocity)}$$

Final: entering the goal

$$\vec{r}_f = \vec{r}_g$$

$$\vec{v}_f = \vec{v}_{Avg} = \vec{v}_i = \frac{\vec{p}_i}{m}$$

$$\vec{r}_f = \vec{r}_i + \vec{v}_{Avg} \Delta t$$

$$\vec{r}_i = \vec{r}_f - \vec{v}_{Avg} \Delta t = \vec{r}_g - \frac{\vec{p}_i}{m} \Delta t =$$

$$= \langle -27, 0, 0 \rangle - \left(\frac{0.4}{0.170} \right) \langle -4.6, 2.9, 0 \rangle =$$

$$= \langle -16.18, -6.82, 0 \rangle \text{ m}$$

2. [15 pts] The player had hit the puck with a constant force for a very short time $\Delta t = 0.1$ s, which changed only the direction of motion of the puck, not its speed. Before it was hit, the velocity of the puck was along the $+\hat{y}$ axis. What is the force? Your answer must be a vector.

Hint: schematically draw the puck's momentum before and after it is hit by the player.

Initial: right before the player hits the puck

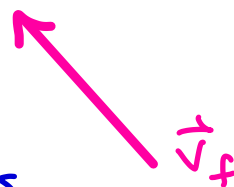

$$\vec{v}_i = |\vec{v}_i| \hat{y} = |\vec{v}_f| \hat{y} \quad (\text{b/c speed did not change})$$

Final: right after the puck loses contact with the hockey stick

* Since the puck moved at constant velocity after that (see previous part), then \vec{v}_f here equals \vec{v} in the previous part of the problem

$$\vec{v}_f = \vec{v}_{\text{from part 1}} = \frac{\vec{p}_i}{m} =$$

$$= \frac{\langle -4.6, -2.9, 0 \rangle}{0.170} = \langle -27.06, 17.06, 0 \rangle \text{ m/s}$$



$$|\vec{v}_f| = \sqrt{(27.06)^2 + (17.06)^2} = 31.99 \text{ m/s}$$

$$\Rightarrow \vec{v}_i = \langle 0, 31.99, 0 \rangle \text{ m/s}$$

$$\vec{F}_{\text{net}} = \frac{\Delta \vec{p}}{\Delta t} = \frac{m \Delta \vec{v}}{\Delta t} = \frac{m}{\Delta t} (\vec{v}_f - \vec{v}_i) =$$

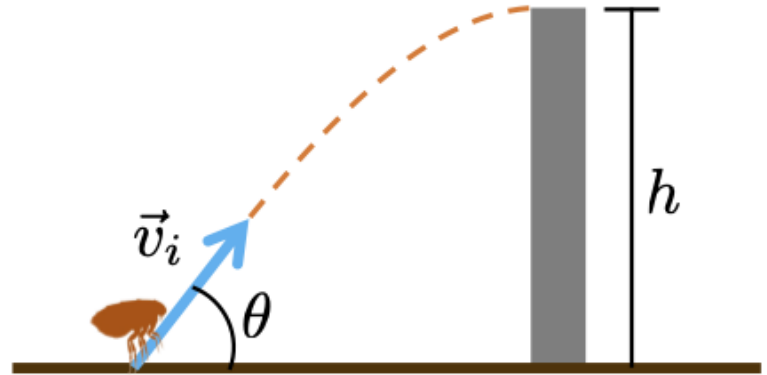
$$= \left(\frac{0.170}{0.1} \right) \left[\langle -27.06, 17.06, 0 \rangle - \langle 0, 31.99, 0 \rangle \right] =$$

$$= \langle -46.00, -25.38, 0 \rangle \text{ N}$$

Flea [30 pts]

Fleas are some of the best jumpers in the Animal Kingdom, relative to body size. A flea with mass $m = 0.001 \text{ g}$ is seen jumping with unknown initial speed $|\vec{v}_i|$ at an angle $\theta = 60^\circ$ above the horizontal. At the maximum height of its trajectory, the flea lands on an obstacle that is $h = 14 \text{ cm}$ tall.

Throughout this problem you should keep 2 decimal places in all calculations. You can assume there is no air resistance.



1. [10 pts] What is the initial speed $|\vec{v}_i|$ of the flea?

Initial: when the flea jumps

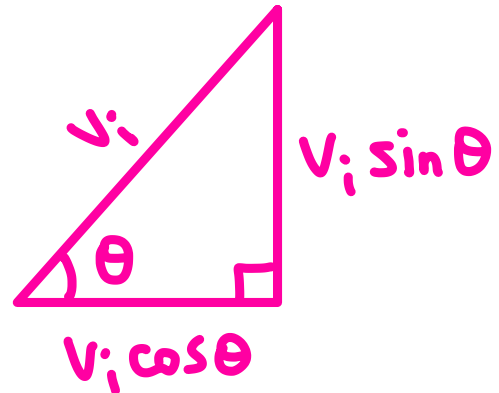
$$\vec{r}_i = \langle 0, 0, 0 \rangle$$

$$\vec{v}_i = \langle v_i \cos \theta, v_i \sin \theta, 0 \rangle$$

Final: at max height

$$\vec{r}_f = \langle r_{fx}, h, 0 \rangle \quad (r_{fx} \text{ unknown})$$

$$\vec{v}_f = \langle v_i \cos \theta, 0, 0 \rangle \quad (\text{b/c max height})$$



$$y_f = y_i + v_{iy} \Delta t - \frac{1}{2} g (\Delta t)^2$$

$$h = v_i \sin \theta \left(\frac{v_i \sin \theta}{g} \right) - \frac{1}{2} g \frac{(v_i \sin \theta)^2}{g^2}$$

$$h = \frac{(v_i \sin \theta)^2}{g} - \frac{1}{2} \frac{(v_i \sin \theta)^2}{g}$$

$$h = \frac{(v_i \sin \theta)^2}{2g}$$

$$2gh = (v_i \sin \theta)^2$$

$$v_i^2 = \frac{2gh}{(\sin \theta)^2}$$

$$v_i = \frac{\sqrt{2gh}}{\sin \theta} = \frac{\sqrt{(2)(9.8)(0.14)}}{\sin(60^\circ)} =$$

$$v_{fy} = v_{iy} + \frac{F_{nety}}{m} \Delta t$$

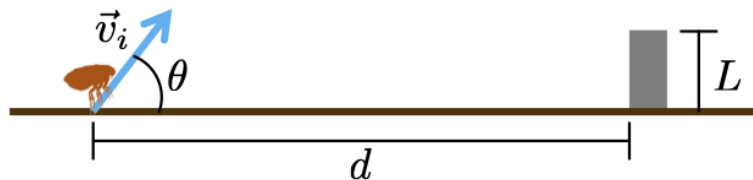
$$0 = v_i \sin \theta - \frac{mg}{m} \Delta t$$

$$g \Delta t = v_i \sin \theta$$

$$\Delta t = \frac{v_i \sin \theta}{g}$$

$$1.91 \text{ m/s}$$

2. [20 pts] Our little flea once again jumps in exactly the same way that it did before (i.e., same initial velocity). This time, however, there's a low wall $L = 3 \text{ cm}$ tall at a distance $d = 31 \text{ cm}$ away from the flea. Can the flea fly above this obstacle?



Hint: Find the x and y coordinates of the flea at the position of the obstacle.

Initial: when the flea jumps

$$\vec{r}_i = \langle 0, 0, 0 \rangle$$

$$\vec{v}_i = \langle v_i \cos \theta, v_i \sin \theta, 0 \rangle$$

$$|\vec{v}_i| = 1.91 \text{ m/s (from part 1)}$$

$$\theta = 60^\circ$$

final: at the wall

$$\vec{r}_f = \langle d, y_f, 0 \rangle$$

* if $y_f = L$ then the flea lands on the wall

* if $y_f > L$ then the flea overshoots the wall

* if $y_f < L$ then SPLAT!

Time to travel horizontal distance d

$$x_f = x_i + v_{ix} \Delta t$$

$$d = v_i \cos \theta \Delta t$$

$$\Delta t = \frac{d}{v_i \cos \theta}$$

y-coordinate of flea at $x_f = d$

$$y_f = y_i + v_{iy} \Delta t - \frac{1}{2} g (\Delta t)^2 = v_i \sin \theta \left(\frac{d}{v_i \cos \theta} \right) - \frac{1}{2} g \left(\frac{d}{v_i \cos \theta} \right)^2 =$$

$$= \frac{d v_i \sin \theta}{v_i \cos \theta} - \frac{g d^2}{2 v_i^2 (\cos \theta)^2} = \frac{d \sin \theta}{\cos \theta} - \frac{g d^2}{2 v_i^2 (\cos \theta)^2} =$$

$$= \frac{(0.31) \sin(60^\circ)}{\cos(60^\circ)} - \frac{(9.8)(0.31)^2}{(2)(1.91)^2 (\cos(60^\circ))^2} = \boxed{0.02 \text{ m}}$$

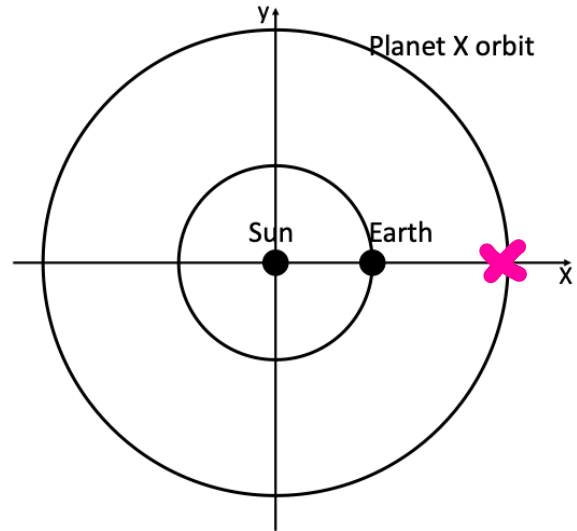
Since $L = 0.03$, then $y_f < L$, then the flea cannot fly above this obstacle

Planet X [40 pts]

We investigate what would be the (tiny) gravitational influence of an elusive 9th planet (Planet X) on the circular motion of the Earth around the Sun. Planet X is believed to make one full orbit around the Sun in 400 Earth years.

The mass of the Sun is M_S , the mass of Planet X is M_X , and the mass of Earth is m . The radius of Earth's orbit is R , and the radius of Planet X's orbit is R_X .

The diagram on the right shows the positions of the Sun and the Earth at time $t = 0$.



- [5 pts] At $t = 0$, where does Planet X have to be in its own orbit such that its gravitational influence on Earth is at its strongest value? Mark this position in the diagram with an **X**.
- [20 pts] Starting from the positions of the Sun, Earth, and Planet X at $t = 0$, determine the new position of the Earth a short time Δt later. The Earth was already moving counterclockwise with speed v_0 . You can assume Planet X has not moved.

Sun-Earth

$$\vec{r} = \vec{r}_E - \vec{r}_S = \langle R, 0, 0 \rangle$$

$$|\vec{r}| = R$$

$$\hat{r} = \frac{\vec{r}}{|\vec{r}|} = \frac{\langle R, 0, 0 \rangle}{R} = \langle 1, 0, 0 \rangle$$

$$\vec{F}_1 = \frac{GM_S m}{r^2} (-\hat{r}) = \frac{GM_S m}{R^2} \langle -1, 0, 0 \rangle$$

Planet X-Earth

$$\vec{r} = \vec{r}_E - \vec{r}_X = \langle R, 0, 0 \rangle - \langle R_X, 0, 0 \rangle$$

$$= \langle R - R_X, 0, 0 \rangle$$

$$|\vec{r}| = |R - R_X|$$

$$\hat{r} = \frac{\vec{r}}{|\vec{r}|} = \frac{\langle R - R_X, 0, 0 \rangle}{|R - R_X|} = \langle -1, 0, 0 \rangle$$

$$\vec{F}_2 = \frac{GM_X m}{r^2} (-\hat{r}) = \frac{GM_X m}{(R - R_X)^2} \langle 1, 0, 0 \rangle$$

Net force

$$\vec{F}_{\text{net}} = \vec{F}_1 + \vec{F}_2 = \frac{GM_S m}{R^2} (-\hat{x}) + \frac{GM_X m}{(R - R_X)^2} (\hat{x}) =$$

$$= \left\langle \frac{GM_X m}{(R - R_X)^2} - \frac{GM_S m}{R^2}, 0, 0 \right\rangle$$

Velocity update

$$\vec{v}_f = \vec{v}_i + \frac{\vec{F}_{\text{net}}}{m} \Delta t =$$

$$= \langle 0, v_0, 0 \rangle$$

$$+ \frac{\Delta t}{m} \left\langle \frac{GM_X m}{(R - R_X)^2} - \frac{GM_S m}{R^2}, 0, 0 \right\rangle =$$

$$= \left\langle \frac{GM_X \Delta t}{(R - R_X)^2} - \frac{GM_S \Delta t}{R^2}, v_0, 0 \right\rangle$$

Position update (non-constant force)

$$\vec{r}_f = \vec{r}_i + \vec{v}_f \Delta t =$$

$$= \langle R, 0, 0 \rangle$$

$$+ \Delta t \left\langle \frac{GM_X \Delta t}{(R - R_X)^2} - \frac{GM_S \Delta t}{R^2}, v_0, 0 \right\rangle =$$

$$= \left\langle R + \frac{GM_X (\Delta t)^2}{(R - R_X)^2} - \frac{GM_S (\Delta t)^2}{R^2}, v_0 \Delta t, 0 \right\rangle$$

3. [15 pts] Half an Earth year after $t = 0$, Planet X has moved an angle θ counterclockwise on its own circular orbit. Calculate the new net gravitational force on Earth. Your answer must be a vector. Note that $\theta < 90^\circ$.

Hint: Think about where the Earth would be located half a year later.

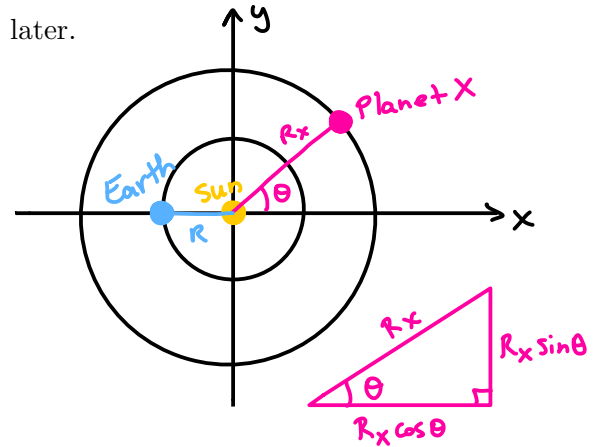
Sun-Earth

$$\vec{r} = \vec{r}_E - \vec{r}_S = \langle -R, 0, 0 \rangle$$

$$|\vec{r}| = R$$

$$\hat{r} = \frac{\vec{r}}{|\vec{r}|} = \frac{\langle -R, 0, 0 \rangle}{R} = \langle -1, 0, 0 \rangle$$

$$\vec{F}_1 = \frac{GM_S m}{R^2} \langle 1, 0, 0 \rangle = \left\langle \frac{GM_S m}{R^2}, 0, 0 \right\rangle$$



Planet X-Earth

$$\begin{aligned} \vec{r} &= \vec{r}_E - \vec{r}_X = \langle -R, 0, 0 \rangle - \langle R_x \cos \theta, R_x \sin \theta, 0 \rangle = \\ &= \langle -R - R_x \cos \theta, -R_x \sin \theta, 0 \rangle \end{aligned}$$

$$\begin{aligned} |\vec{r}| &= \sqrt{(R + R_x \cos \theta)^2 + (R_x \sin \theta)^2} = \sqrt{R^2 + 2RR_x \cos \theta + \underbrace{R_x^2 \cos^2 \theta + R_x^2 \sin^2 \theta}_{\text{trig: } \sin^2 \theta + \cos^2 \theta = 1}} = \\ &= \sqrt{R^2 + R_x^2 + 2RR_x \cos \theta} \end{aligned}$$

$$\hat{r} = \frac{\vec{r}}{|\vec{r}|} = \frac{\langle -R - R_x \cos \theta, -R_x \sin \theta, 0 \rangle}{\sqrt{R^2 + R_x^2 + 2RR_x \cos \theta}}$$

$$\begin{aligned} \vec{F}_2 &= \frac{GM_X m}{r^2} (-\hat{r}) = \frac{GM_X m}{R^2 + R_x^2 + 2RR_x \cos \theta} \frac{\langle R + R_x \cos \theta, R_x \sin \theta, 0 \rangle}{\sqrt{R^2 + R_x^2 + 2RR_x \cos \theta}} = \\ &= \left\langle \frac{GM_X m (R + R_x \cos \theta)}{(R^2 + R_x^2 + 2RR_x \cos \theta)^{3/2}}, \frac{GM_X m R_x \sin \theta}{(R^2 + R_x^2 + 2RR_x \cos \theta)^{3/2}}, 0 \right\rangle \end{aligned}$$

New net force

$$\vec{F}_{\text{net}} = \vec{F}_1 + \vec{F}_2 =$$

$$\left\langle \frac{GM_S m}{R^2} + \frac{GM_X m (R + R_x \cos \theta)}{(R^2 + R_x^2 + 2RR_x \cos \theta)^{3/2}}, \frac{GM_X m R_x \sin \theta}{(R^2 + R_x^2 + 2RR_x \cos \theta)^{3/2}}, 0 \right\rangle$$