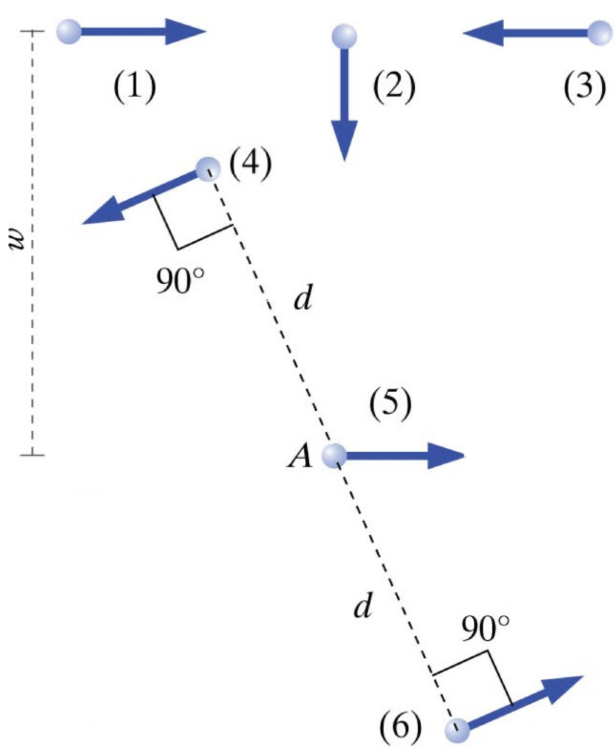
Physics 2211 GPS Week 13

Problem #1



In the diagram on the right, six identical particles of mass m and speed v are moving relative to a point A, the current location of particle (5). The distance of these particles from point A is indicated in the diagram. The arrows indicate the directions of the particle's velocities.

As usual, +x is to the right, +y is up and +z is out of the page, towards you.

In the following calculations, remember that angular momen-tum is a vector.

(a) Calculate the angular momentum of particle 1 with respect to A.

$$\vec{L}_{1A} = \vec{r}_{1A} \times \vec{p}_1 = wmv\,(-\hat{z})$$

(b) Calculate the angular momentum of particle 2 with respect to A.

$\vec{L}_{2A} = \vec{r}_{2A} \times \vec{p}_2 = 0$ because $\vec{r}_{2A}$ and p_2 are antiparallel.

(c) Calculate the angular momentum of particle 3 with respect to A.

$$\vec{L}_{3A} = \vec{r}_{3A} \times \vec{p}_3 = wmv\,(+\hat{z})$$

(d) Calculate the angular momentum of particle 4 with respect to A.

$$\vec{L}_{4A} = \vec{r}_{4A} \times \vec{p}_4 = dmv\,(+\hat{z})$$

(e) Calculate the angular momentum of particle 5 with respect to A.

$\vec{L}_{5A} = \vec{r}_{5A} \times \vec{p}_5 = 0$ because $\vec{r}_{5A} = 0$.

(f) Calculate the angular momentum of particle 6 with respect to A.

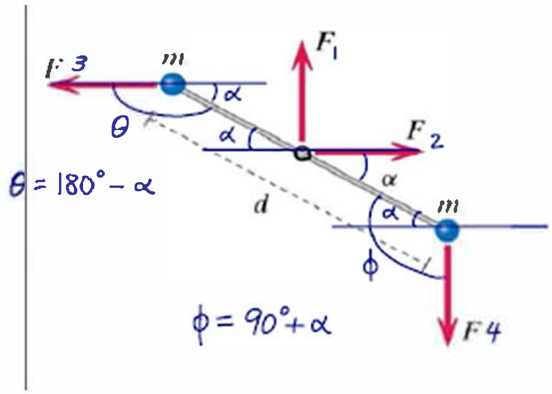
$$\vec{L}_{6A} = \vec{r}_{6A} \times \vec{p}_6 = dmv\,(+\hat{z})$$

(g) Calculate the total angular momentum of the system of particles with respect to A.

$$\vec{L}_A = \sum_i \vec{L}_{iA} = (wmv - wmv + dmv + dmv)\,\hat{z} = 2dmv\,(\hat{z})$$

Problem #2

A barbell is mounted on a nearly frictionless axle through its center of mass. The rod has negligible mass and a length d. Each ball has a mass m. At the instant shown, there are four forces of equal magnitude F applied to the system, with the directions indicated. At this instant, the angular velocity is ω_i, counterclockwise (positive), and the bar makes an angle α (which is less than 45 degrees) with the horizontal.



(a) Calculate the magnitude of the net torque on the barbell about the center of mass.

$$\vec{\tau}_1 = \vec{r}_1 \times \vec{F}_1 = 0 \quad b/c \ \vec{r}_1 = 0$$

$$\vec{\tau}_2 = \vec{r}_2 \times \vec{F}_2 = 0 \quad b/c \ \vec{r}_2 = 0$$

$$\vec{\tau}_3 = \vec{r}_3 \times \vec{F}_3 = r_3 F_3 \sin\theta \ (\hat{z}) = \frac{d}{2} F \sin(180° - \alpha) \ (\hat{z}) = \frac{dF}{2} \sin\alpha \ (\hat{z})$$

$$\vec{\tau}_4 = \vec{r}_4 \times \vec{F}_4 = r_4 F_4 \sin\phi \ (-\hat{z}) = \frac{d}{2} F \sin(90° + \alpha) \ (-\hat{z}) = \frac{dF}{2} \cos\alpha \ (-\hat{z})$$

$$\vec{\tau}_{Net} = \vec{\tau}_1 + \vec{\tau}_2 + \vec{\tau}_3 + \vec{\tau}_4 = \frac{dF}{2} \sin\alpha \ (\hat{z}) + \frac{dF}{2} \cos\alpha \ (-\hat{z})$$

$$\Rightarrow \boxed{|\vec{\tau}_{Net}| = \frac{dF}{2} \left| \sin\alpha - \cos\alpha \right|}$$

Since $\alpha < 45°$, then $\cos\alpha > \sin\alpha$, which means $|\vec{\tau}_4| > |\vec{\tau}_3|$

$$\Rightarrow \boxed{\text{direction of } \vec{\tau}_{Net} \text{ is } (-\hat{z}), \text{ into the page}}$$

(b) Select the statement that accurately describes the situation in the figure:

A. α is less than 45 degrees, so the net torque on the system is in the clockwise direction. This means the torque is out of the page.

B. α is less than 45 degrees, so the net torque on the system is in the counterclockwise direction. This means the torque is into the page.

C. α is less than 45 degrees, so the net torque on the system is in the counterclockwise direction. This means the torque is out of the page.

D. α is less than 45 degrees, so the net torque on the system is in the clockwise direction. This means the torque is into the page.

(c) Determine the moment of inertia, about the center of mass, for the barbell.

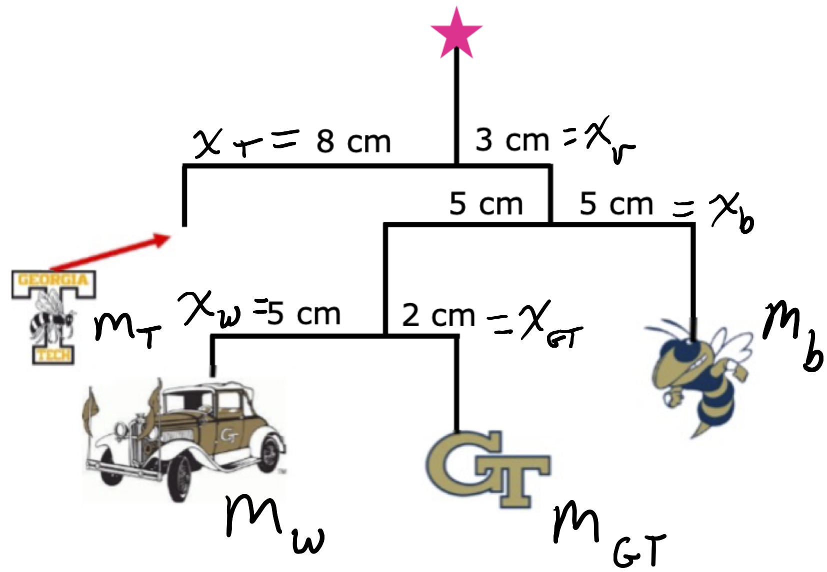
$$I_{CM} = m_1 r_1^2 + m_2 r_2^2 = m\left(\frac{d}{2}\right)^2 + m\left(\frac{d}{2}\right)^2 = \frac{md^2}{4} + \frac{md^2}{4} =$$

$$= \frac{\cancel{2}md^2}{\cancel{4}_{2}} = \boxed{\frac{1}{2}md^2}$$

Problem #3

1. You found a GT mobile in a store but it's missing a piece (a "T", of course). You buy it anyway and make a T to add to the mobile. You measure the lengths of all the (horizontal) arms of the mobile (measure-ments in the figure) and you find that Buzz has a mass of $m_b = 300$ g. What should be the mass of the T (m_T), so that when you at-tach it the mobile stays balanced (unmoving)?

Hints: (1) a balanced mobile experiences zero net gravitational torque; (2) notice that the Wreck and GT are attached to an arm that is the same length as the arm holding up Buzz; (3) remember to use standard SI units in your final answer.



Let's balance each level of the mobile.

$m_w x_w = m_{GT} x_{GT}$. Also,

$m_b x_b = (m_{GT} + m_w) x_b \Rightarrow m_b = m_{GT} + m_w$.

Therefore, the topmost right arm of the mobile has a combined mass of $2m_b$. Finally, balancing the top arms,

$$m_T x_T = (2m_b) x_r$$

$$\Rightarrow m_T = \frac{2 m_b x_r}{x_T} = \frac{2(.3\,\text{kg})(0.03\,\text{m})}{(0.08\,\text{m})} = \boxed{0.225\,\text{kg}}$$

Alternatively,

$$|\vec{\tau}_T| = |\vec{\tau}_r| \Rightarrow x_T F_T = x_r F_r$$

$$\Rightarrow x_T m_T \cancel{g} = x_r (m_w + m_{GT} + m_b)\cancel{g}. \quad m_b = m_w + m_{GT}$$

$$\Rightarrow m_T = \frac{2 m_b x_r}{x_T} = 0.225\,\text{kg}.$$