TP 2 – AOS1 Regularization Corrigé

In the following, we will study the differences between the classical linear regression model and their most popular regularized versions: the ridge regression model and the Lasso model. We will use the sklearn Python library and some tools from the scipy library.

```
from sklearn.linear_model import Ridge, LinearRegression
from scipy.linalg import svd
```

A custom class is provided in the file utils.py that models a linear random phenomena. You have to first create the random phenomena

```
from utils import Event
evt = Event(n_features=n_features, effective_rank=3, noise_level=1)
```

Then you can repeatedly sample from it

```
batch1_X, batch1_y = evt.sample(n_samples=100)
batch2_X, batch2_y = evt.sample(n_samples=200)
```

More formally the following model is implemented inside Event

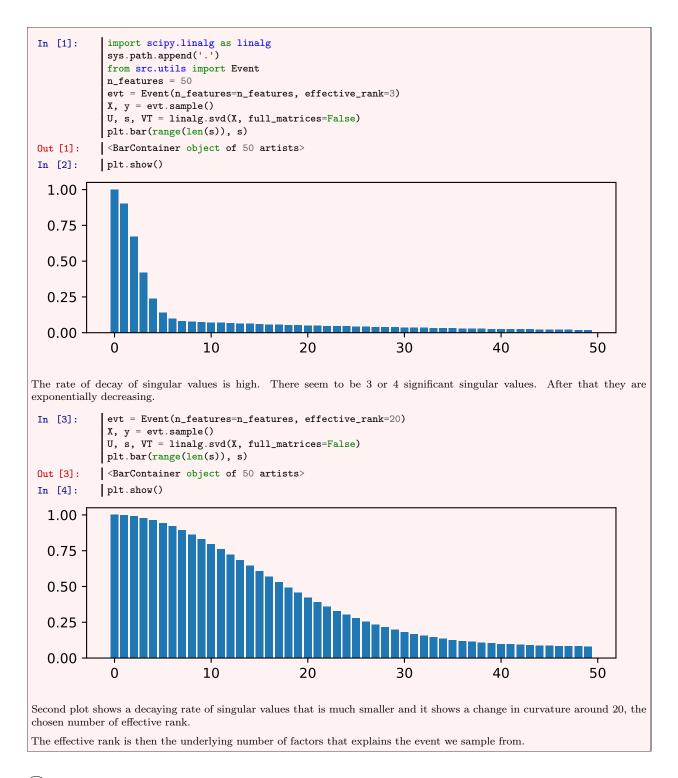
$$y = X\beta + \varepsilon$$
.

The coefficients are randomly generated unless given as argument to Event. They are accessible with evt.coefficients.

The matrix X is created on demand when getting samples with the sample method. It is controlled by the argument n_features (10 features by default) and the effective_rank integer that is the "denoised rank" of X.

The standard deviation σ of the noise ε is controlled by the noise_level parameter in Event. More precisely, noise_level indicates a ratio in percentage between σ and $\|\beta\|$.

① Using a SVD, compute the singular values d_i , $1 \le i \le k$ of X. What is the effect of the parameter effective_rank? What is the effective rank supposed to model?



(2) By repeatedly fitting each model on the same Event object, give an estimate of the bias, variance and risk of the estimator at a chosen point.

```
In [5]:
             import numpy as np
             from sklearn.linear_model import Ridge, LinearRegression, Lasso, LassoCV, RidgeCV
             n_features = 50
             n_samples = 200
             evt = Event(n_features=n_features, effective_rank=3, noise_level=1)
             X0 = np.random.randn(1, n_features)
             ntimes = 1000
Define a function risk that is returning an estimation of the variance, bias and risk of prediction at point XO.
             def compute_risk(model, evt, ntimes, n_samples, X0):
                 pred_model = []
                 y0 = np.dot(X0, evt.coefficients)
                 for i in range(ntimes):
                     X, y = evt.sample(n_samples=n_samples)
                     model.fit(X, y)
                     pred = model.predict(X0)
                     pred_model.append(pred)
                 bias = np.mean(pred_model) - y0
                 var = np.var(pred_model)
                 risk = np.mean((pred_model - y0)**2)
                 return (bias, var, risk)
             risk_lin = compute_risk(LinearRegression(), evt, ntimes, n_samples, X0)
             risk_ridge = compute_risk(Ridge(alpha=0.1), evt, ntimes, n_samples, X0)
             risk_lasso = compute_risk(Lasso(alpha=0.1), evt, ntimes, n_samples, X0)
             output = "Bias: %f\tVariance: %f\tRisk: %f"
             print("Linear regression: ", output % risk_lin)
             Linear regression: Bias: -4.256442
Out [6]:
                                                          Variance: 11454.814940
                                                                                         Risk:
             \hookrightarrow \quad 11472.932242
            print("Ridge regression: ", output % risk_ridge)
In [7]:
Out [7]:
            Ridge regression: Bias: 69.582132
                                                         Variance: 4.290764
                                                                                   Risk: 4845.963790
In [8]:
            print("Lasso regression: ", output % risk_lasso)
Out [8]:
            Lasso regression: Bias: 72.651781
                                                         Variance: 0.002695
                                                                                    Risk: 5278.283991
```

(3) Show the influence of the dataset's effective rank on the 3 algorithms and interpret.

TP 2 – AOS1

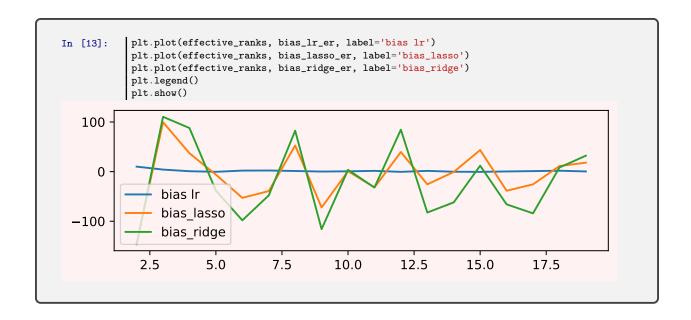
```
X, y = evt.sample(n_samples=100)
In [9]:
                            lasso_alpha = LassoCV(cv=5, random_state=0).fit(X, y).alpha_
Out [9]:
                            /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: $70:

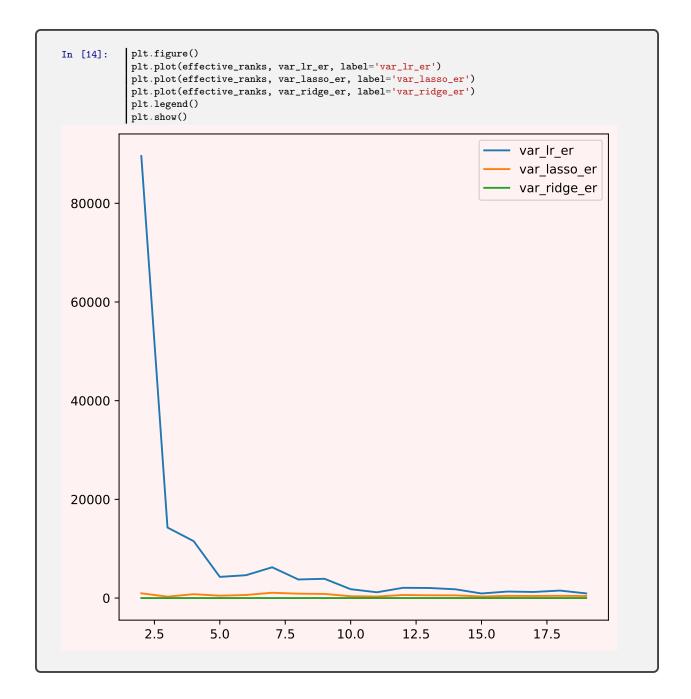
→ ConvergenceWarning: Objective did not converge. You might want to increase the

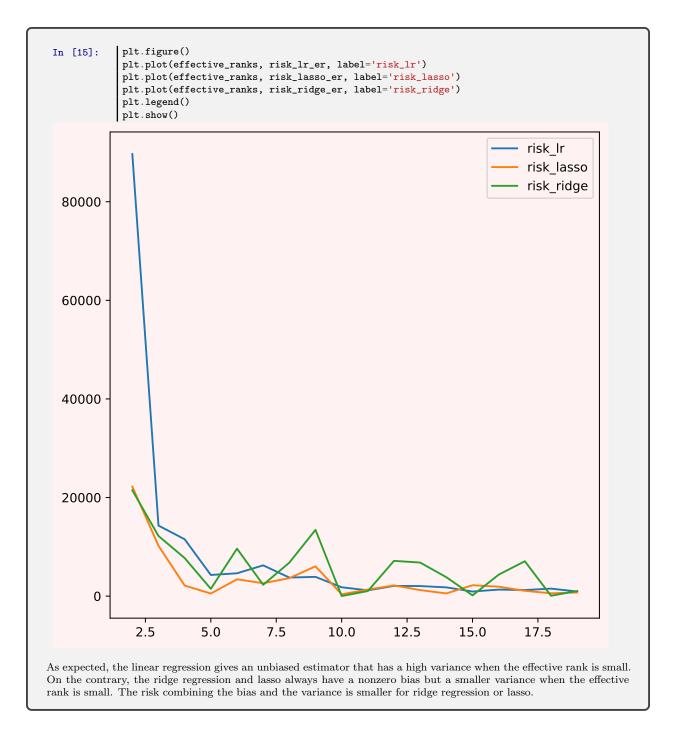
                             \hookrightarrow number of iterations. Duality gap: 0.013585333177825731, tolerance:
                             \hookrightarrow 0.006317653499993123
                               model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 10:
                             \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow\, number of iterations. Duality gap: 0.014613349221235694, tolerance:
                             \hookrightarrow 0.006317653499993123
                               model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 10:
                             → ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.015519848484395027, tolerance:
                             \hookrightarrow 0.006317653499993123
                               model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 10:
                             \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.015671298279517742, tolerance:
                             \hookrightarrow 0.006317653499993123
                                model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 10:
                             \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.01612506082045151, tolerance:
                             \hookrightarrow 0.006317653499993123
                                model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 10:
                             \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.015436443511065434, tolerance:
                             \hookrightarrow 0.006317653499993123
                               model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python 3.8/site-packages/sklearn/linear\_model/\_coordinate\_descent.py: $470: 100 and 100 and
                             → ConvergenceWarning: Objective did not converge. You might want to increase the
                             → number of iterations. Duality gap: 0.014798256902690099, tolerance:
                             \hookrightarrow 0.006317653499993123
                                model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python 3.8/site-packages/sklearn/linear\_model/\_coordinate\_descent.py: \cite{Monthson} 170: \cite{Monthson} 1
                             → ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.01416004803865789, tolerance:
                             \hookrightarrow 0.006317653499993123
                               model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python 3.8/site-packages/sklearn/linear\_model/\_coordinate\_descent.py: \ref{prop:sylvain} 70: \ref{prop:sylvain} 1.0 to a finite formula of the packages of the packag
                             \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.013568568911857426, tolerance:
                             \hookrightarrow 0.006317653499993123
                                model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 170:
                             → ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.013907861210356032, tolerance:
                             \hookrightarrow 0.006317653499993123
                               model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 470:
                             → ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow\, number of iterations. Duality gap: 0.013343431582359955, tolerance:
                             \hookrightarrow 0.006317653499993123
                                model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 470:
                              \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.011726202251111317, tolerance:
                             \hookrightarrow 0.006317653499993123
                                model = cd_fast.enet_coordinate_descent_gram(
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py: 170:
                             → ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow\, number of iterations. Duality gap: 0.011198312620315676, tolerance:
                             \hookrightarrow 0.006317653499993123
                                                      <del>cd_fast.enet_coordinate_descent_gram(</del>
                             /home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py:470:
                             \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the
                             \hookrightarrow number of iterations. Duality gap: 0.010639265986736035, tolerance:
                             \hookrightarrow 0.006317653499993123
                                model = cd_fast.enet_coordinate_descent_gram(
```

/home/sylvain/.local/lib/python3.8/site-packages/sklearn/linear_model/_coordinate_descent.py:470:

 \hookrightarrow ConvergenceWarning: Objective did not converge. You might want to increase the







Problem: make elastic net outshine the lasso

The elastic net regression was invented to compensate for the lack of robustness of the lasso regression. The elastic net especially outshines the lasso when some variables are highly correlated and on the same scale. You have been shown in the last course's slides some intuitive arguments demonstrating why it should particularly be more robust in this case. But could you demonstrate this experimentally?

Design a regression dataset in which we want to select variables and where the elastic net gives better results in terms of stability of the set of selected variables.