

Math 3435 - HW 1

①

1.1.2 (a)(e) are linear the others are nonlinear
I will demonstrate (b) and (e).

(b) Check $L(u+v) = Lu + Lv$

$$\begin{aligned} L(u+v) &= (u+v)_x + (u+v)(u+v)_y \\ &= u_x + v_x + (u+v)(u_y + v_y) \end{aligned}$$

(Used the linearity of taking partial derivatives)

$$= u_x + v_x + uu_y + vu_y + uv_y + vv_y$$

$$Lu + Lv = u_x + uu_y + v_x + vv_y$$

$\Rightarrow L(u+v) \neq Lu + Lv$, thus nonlinear.

(e) Check $L(u+v) = Lu + Lv$

$$L(u+v) = \sqrt{1+x^2} \cos y (u+v)_x + (u+v)_{xy} - \operatorname{atan}(x/y)(u+v)$$

$$= \sqrt{1+x^2} \cos y (u_x + v_x) + u_{xy} + v_{xy} - \operatorname{atan}(x/y)(u+v)$$

$$Lu + Lv = \sqrt{1+x^2} \cos y u_x + u_{xy} - \operatorname{atan}(x/y) u +$$

$$\sqrt{1+x^2} \cos y v_x + v_{xy} - \operatorname{atan}(x/y) v$$

$$\Rightarrow L(u+v) = Lu + Lv \quad \checkmark$$

Check $L(cu) = cLu$ c constant

$$L(cu) = \sqrt{1+x^2} \cos y (cu)_x + (cu)_{xy} - \operatorname{atan}(x/y)(cu)$$

$$= \sqrt{1+x^2} \cos y \cdot c u_x + c u_{xy} - \operatorname{atan}(x/y) \cdot c \cdot u$$

$$cLu = c(\sqrt{1+x^2} \cos y u_x + u_{xy} - \operatorname{atan}(x/y) u)$$

$$\Rightarrow L(cu) = cLu \quad \checkmark \Rightarrow \text{Linear!}$$

1.1.3 (a) 2nd order; either nonlinear or linear inhomogeneous

(2)

(b) 2nd order; linear homogeneous

(c) 3rd order; nonlinear

(d) 2nd order; either nonlinear or linear inhomogeneous

(e) 2nd order; linear homogeneous

(f) 1st order; nonlinear

(g) 1st order; linear homogeneous

(h) 4th order; nonlinear

I will demonstrate (d).

Two points of view: (1) $\mathcal{L}u = u_{tt} - u_{xx} + x^2 = 0$

Then $\mathcal{L}u$ is nonlinear: check $\mathcal{L}(u+v) = \mathcal{L}u + \mathcal{L}v$:

$$\begin{aligned}\mathcal{L}(u+v) &= (u+v)_{tt} - (u+v)_{xx} + x^2 \\ &= u_{tt} + v_{tt} - (u_{xx} + v_{xx}) + x^2\end{aligned}$$

$$\mathcal{L}u + \mathcal{L}v = u_{tt} - u_{xx} + x^2 + v_{tt} - v_{xx} + x^2$$

$$\mathcal{L}(u+v) \neq \mathcal{L}u + \mathcal{L}v \Rightarrow \text{nonlinear!}$$

(2) Or we may rewrite the equation into

$$\mathcal{L}u = u_{tt} - u_{xx} = -x^2$$

Then $\mathcal{L}u = u_{tt} - u_{xx}$ is linear (check omitted)
and the equation becomes linear inhomogeneous.

1.1.4. Let u_1, u_2 be two solutions of $\mathcal{L}u = g$. Thus

$$\mathcal{L}u_1 = g, \quad \mathcal{L}u_2 = g. \quad \text{Let } u = u_1 - u_2. \quad \text{Then}$$

$$\mathcal{L}u = \mathcal{L}(u_1 - u_2) = \mathcal{L}u_1 + \mathcal{L}(-u_2) = \mathcal{L}u_1 - \mathcal{L}u_2 = g - g = 0.$$

by $\mathcal{L}(u+v) = \mathcal{L}u + \mathcal{L}v$ by $\mathcal{L}(cu) = c\mathcal{L}u$

Thus u is the solution to $\mathcal{L}u = 0$.

(3)

1.1.10 $u''' - 3u'' + 4u = 0$ is a linear homogeneous ODE with constant coefficients. There are systematic methods of solving this type of ODE:

→ associated equation $X^3 - 3X^2 + 4 = 0$

$$\Rightarrow (X+1)(X-2)^2 = 0$$

$X = -1$ is a root with multiplicity 1

→ associated solution is $u(x) = e^{-x}$

$X = 2$ is a root with multiplicity 2

→ associated solutions are $u(x) = e^{2x}, xe^{2x}$

General solutions are $C_1 e^{-x} + C_2 e^{2x} + C_3 xe^{2x}$, where C_1, C_2, C_3 are arbitrary constants.

1.1.12. $u(x, y) = \sin nx \sinh ny$

$$\Rightarrow u_x = n \cos nx \sinh ny, u_y = n \sin nx \cosh ny$$

$$u_{xx} = -n^2 \sin nx \sinh ny, u_{yy} = n^2 \sin nx \cosh ny$$

$$\Rightarrow u_{xx} + u_{yy} = 0.$$

1.2.1. Characteristic curves : $\frac{dx}{dt} = \frac{3}{2}$

$$\Rightarrow X = \frac{3}{2}t + C \Leftrightarrow C = X - \frac{3}{2}t$$

$$\Rightarrow u = f(C) = f\left(X - \frac{3}{2}t\right)$$

$$u(x, 0) = f(x) = \sin x.$$

$$\Rightarrow u = \sin\left(x - \frac{3}{2}t\right) \text{ is the solution.}$$

1.2.2. Let $V = U_y$ then $3U_y + U_{xy} = 0$

becomes

$$\begin{cases} 3V + Vx = 0 & \textcircled{1} \\ U_y = V & \textcircled{2} \end{cases}$$

(4)

$\textcircled{1}$ is an ODE w.r.t. the variable x .

Solutions to $3y + y' = 0$ are $y = Ce^{-3x}$

\Rightarrow Solutions to $3V + Vx = 0$ are $V = C(y) e^{-3x}$

Then $\textcircled{2} \Rightarrow$

$$U_y = C(y) e^{-3x} \quad \begin{pmatrix} \text{constant w.r.t. } x \\ \text{depending on } y \end{pmatrix}$$

$$U = \int U_y dy = \int C(y) e^{-3x} dy$$

$$= e^{-3x} \int C(y) dy + B(x)$$

$$\text{Let } A(y) = \int C(y) dy,$$

(constant w.r.t. y)
depending on x

$$\text{then } U = e^{-3x} A(y) + B(x)$$

check: $U_y = e^{-3x} A'(y)$, $U_x = -3e^{-3x} A(y) + B'(x)$

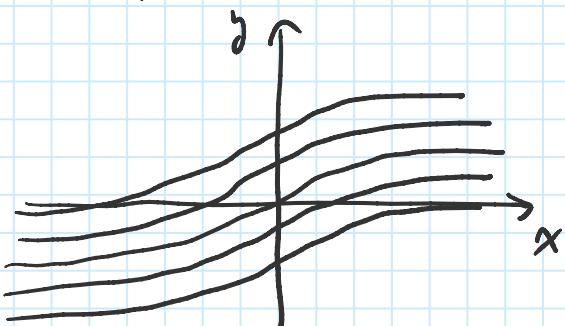
$$U_{xy} = -3e^{-3x} A'(y), \Rightarrow 3U_y + U_{xy} = 0.$$

Conclusion: Solutions are $U = e^{-3x} A(y) + B(x)$,

where $A(y)$ and $B(x)$ are differentiable.

1.2.3. Characteristic curves $\frac{dy}{dx} = \frac{1}{1+x^2}$

$$\int dy = \int \frac{dx}{1+x^2} \Rightarrow y = \arctan x + C$$



$$\Rightarrow u = f(C) = f(y - \arctan x)$$

(f differentiable)

(5)

2. ① $U_{xxx} = 0$ is an ODE w.r.t the x variable.

Solutions to $y'''(x) = 0$ are $y = C_1 + C_2 x + C_3 x^2$

$$\Rightarrow \text{Solutions to } U_{xxx} = 0 \text{ are } u = C_1(y) + C_2(y)x + C_3(y)x^2$$

By checking, $u = C_1(y) + C_2(y)x + C_3(y)x^2$ indeed gives the solutions.

$$\textcircled{2} \quad U_{xx}y = 0 \Leftrightarrow (U_{xx})_y = 0 \Leftrightarrow U_{xx} = f(x)$$

$$\Leftrightarrow U_x = \underbrace{\int f(x) dx}_{F(x)} + g(y) \quad \left(\begin{array}{l} \text{constant w.r.t. } x \\ \text{depending on } y \end{array} \right)$$

$$\begin{aligned} \Leftrightarrow U &= \int (F(x) + g(y)) dx + h(y) \\ &= \underbrace{\int F(x) dx}_{k(x)} + g(y)x + h(y) \end{aligned}$$

By checking, $u = k(x) + g(y)x + h(y)$ indeed are solutions. (k, g, h differentiable)

$$3. \quad U_{xyz} = 0 \Leftrightarrow U_{xy} = f(x, y)$$

$\left(\begin{array}{l} \text{constant w.r.t. } z \\ \text{depending on } x, y \end{array} \right)$

$$\Leftrightarrow U_x = \underbrace{\int f(x, y) dy}_{F(x, y)} + \underbrace{g(x, z)}_{\begin{array}{l} \text{(constant w.r.t. } y \text{)} \\ \text{(depending on } x, z \text{)}}}$$
(6)

$$\Leftrightarrow U = \underbrace{\int F(x, y) dx}_{k(x, y)} + \underbrace{\int g(x, z) dx}_{G(x, z)} + \underbrace{h(y, z)}_{\begin{array}{l} \text{(constant w.r.t. } x \text{)} \\ \text{(depending on } y, z \text{)}}}$$

By checking. $U = k(x, y) + G(x, z) + h(y, z)$
 indeed one solutions. (k, G, h differentiable)