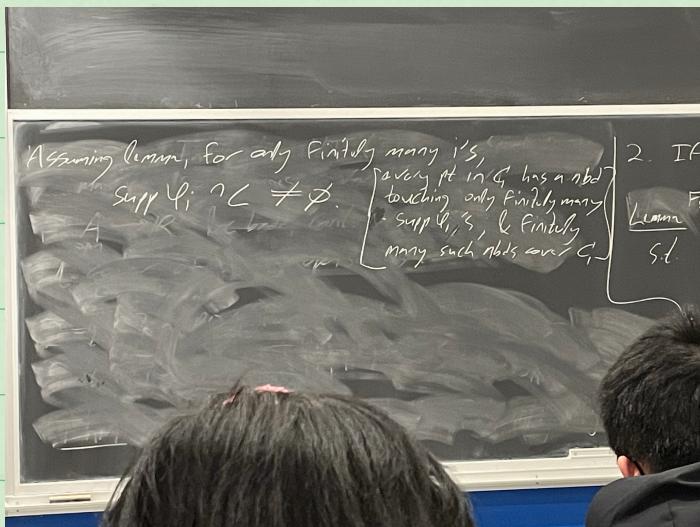


• $\forall f, \exists$ compact C , s.t. $\text{vol}(f \setminus C) < \varepsilon$. ($\Rightarrow \lim \sum \int \varphi_i f = \lim \int \sum \varphi_i f$)

任意紧集而被 Biger for N 盖住



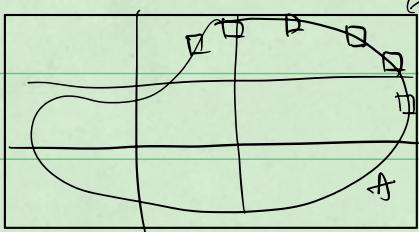
Fix $N \geq 1$, $\forall i$
 $\sum_{i=1}^N \varphi_i = 1$ on G .

補充

$$\left| \int_A^{\text{old}} F - \sum_{i=1}^N \int_A^{\text{old}} \varphi_i F \right| = \left| \int_A^{\text{old}} F - \sum_{i=1}^N \varphi_i F \right| \leq \int_A |F| (1 - \sum \varphi_i) \stackrel{\text{補充}}{\leq} \int_A M (1 - \sum \varphi_i) \leq M \int_A (1 - \sum \varphi_i) \leq M \int_{A \setminus C} 1 \leq \varepsilon.$$

在 C 上是 1, 其它地方 $(0, 1)$

Lemma? 作业 \hookrightarrow (前提 f Jordan measurable)



\hookrightarrow 由 A 等分 \Leftrightarrow \times 可积.

\hookrightarrow 由 partition, $U - L < \varepsilon$.

\Rightarrow 在边界上的 rectangle 的面积和宽幅中.

\hookrightarrow C 为 蓝色 而 那些 rectangle.

Facts: ① $\int (fg) = \int_A f + \int_A g$

$$\int_A cf = c \int_A f \quad (\text{if } f \text{ 可积})$$

$$\int_A^{\text{old}} fg = \sum_{i=1}^{\infty} \int_{\text{old}}^{\text{old}} \varphi_i (fg) \hookrightarrow \text{old 逻辑中是 } M$$

$$= \sum_{i=1}^{\infty} \int_{\text{old}}^{\text{old}} \varphi_i f + \varphi_i g$$

$$= \int \varphi_i f + \int \varphi_i g = \int f + \int g.$$

② (Fubini - NT)

若 $A \subset \mathbb{R}^n$ 且, $B \subset \mathbb{R}^m$ 且.

$f: A \times B \rightarrow \mathbb{R}$, f locally bounded, / continuous except finite points.

可以交换

好像
不

$$\int_{A \times B} f(x,y) dx dy = \int_B \left(\int_A f(x,y) dx \right) dy$$

若被积函数在 \$A \times B\$ 上可积，则等号左右两边不一定一样？

若 \$U, V\$ open cover \$A, B\$, \$\Psi = \{\psi_i\}, \Psi^* = \{\psi_j^*\}\$ 对应的 \$\mathcal{D}\sigma_1\$.

\$W = \{w \times v \mid w \in U, v \in V\}\$, 由 \$W\$ open cover \$A \times B\$.

\$\Lambda = \{\psi_i(x) \psi_j^*(y)\}\$ 是 \$W\$ 的 \$\mathcal{D}\sigma_1\$.

$$\text{且 } \sum_{i,j} \lambda_{i,j}(x,y) = \sum_i \psi_i(x) \sum_j \psi_j^*(y) = \sum_i \psi_i(x) = 1$$

③ If \$B \subset A\$, \$f: A \rightarrow \mathbb{R}\$ 可积, 则 \$f|_B\$ 可积,

且 \$f \geq 0\$, 则 \$\int_B f \leq \int_A f\$

PF: NTS, 若 \$\psi_i^B\$ 是 \$B\$ 的 \$\mathcal{D}\sigma_1\$ 且 subordinate \$\{U_\beta\}_{\beta \in B}\$,

$$\text{则 } \sum_{i=1}^N \int_{U_i} |\psi_i^B| f \text{ 有界.}$$

只需证 \$\sum_{i=1}^N \int_{U_i} |\psi_i^B| f\$ 有界, 实际上,

$$\sum_{i=1}^N \int_{U_i} |\psi_i^B| f = \int \left(\sum_{i=1}^N |\psi_i^B| f \right) \leq \int_A \left(\sum_{i=1}^N |\psi_i^B| \right) |f| \leq \int_A |f| < \infty$$

$\sum_{i=1}^N \int_{U_i} |\psi_i^B| f$ 上界

④ 设 \$\{f_n\}\$ 为一个递减的开集序列. Let \$A = \bigcap_{n=1}^{\infty} A_n\$

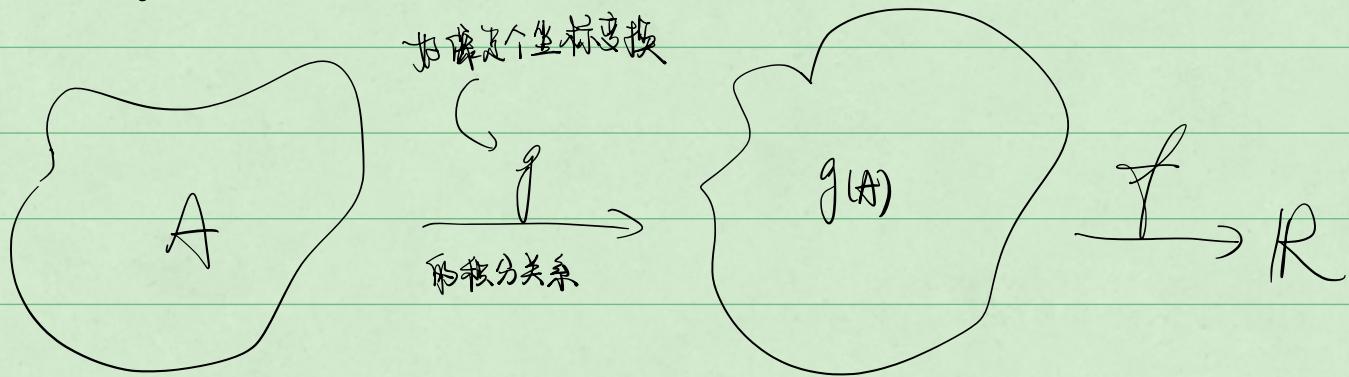
设 \$f: A \rightarrow \mathbb{R}\$ 可积, 则 \$f\$ 在任意 \$A_n\$ 上可积, 且 \$\int_{A_n} f\$ 收敛至 \$\int_A f\$

e.g. \$A = (0, \infty)\$, \$A_n = (0, n)\$, 设 \$f: (0, \infty) \rightarrow \mathbb{R}\$, 令 \$\int_{(0, \infty)}^N f = \lim_{n \rightarrow \infty} \int_{(0, n)}^N f = \lim_{n \rightarrow \infty} \int_0^n f

$\int_A f = \sum_{i=1}^{\infty} \int_{U_i} f$ 对于 \$N\$ 大 enough, \$\int f \sim \sum_{i=1}^N f\$ (差 \$\varepsilon\$)

$\text{supp} \sum_{i=1}^N \psi_i^A \subset \bigcup_{i=1}^N \text{supp} \psi_i^A$, compact \$\Rightarrow A_n\$ 有极限 \$\Rightarrow \bigcap_{n=1}^{\infty} A_n\$

• Change of variables



$$\int_{g(A)} f \stackrel{?}{=} \int_A f \circ g \quad \text{X}$$

“积分”? “体积”
所以 $\int_A f \circ g$ 是啥?

每个点都映到了同样位置 (虽然!)

但这里的平行四边形 (体)
也 g 变形，反映过来后就不同。

Prop: 若 $L: \mathbb{R}^n \rightarrow \mathbb{R}^n$, R is a rectangle in \mathbb{R}^n ,

$$\text{def } \text{Vol}(L(R)) = |\det(L)| \cdot \text{Vol}(R)$$

(行列式值的本质就是体积)

所以在 这里 需要上修正量。

$$\Rightarrow \int_{g(A)} f = \int_A f \circ g \cdot |\det g'|$$

range of variables

Thm (C 0 V): 设 $A \subset \mathbb{R}^n$, $g: A \rightarrow \mathbb{R}^n$, 为 continuously differentiable, 且 $\nabla g \neq 0$,

$g'(a)$ 在小区间内可逆 \Rightarrow 这个保证了 $g(A)$ 是开的, 所以在上面可积.

若 $f: g(A) \rightarrow \mathbb{R}$ 可积, 则 $\int_{g(A)} f = \int_A f \circ g \cdot |\det g'|$

Example: "most important integral"

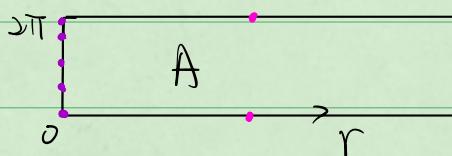
$$I_1 = \int_{-\infty}^{\infty} e^{-\frac{x^2}{2}} dx \quad I_n = \int_{\mathbb{R}^n} e^{-\frac{|x|^2}{2}} dx,$$

考虑 I_2 .

$$\begin{aligned} ① \quad I_2 &= \int_{\mathbb{R}^2} e^{-\frac{x^2+y^2}{2}} dx dy. \stackrel{\text{"Fubini" ①}}{=} \int_{\mathbb{R}_x} dx \int_{\mathbb{R}_y} dy e^{-\frac{x^2}{2}} \cdot e^{-\frac{y^2}{2}} \\ &= \int_{\mathbb{R}_x} dx e^{-\frac{x^2}{2}} \int_{\mathbb{R}_y} dy e^{-\frac{y^2}{2}} \\ &= \left(\int_{\mathbb{R}_x} dx e^{-\frac{x^2}{2}} \right) I_1 \end{aligned}$$

$$= I_1^2$$

② use COV



$$g(r, \theta) = (r \cos \theta, r \sin \theta)$$



$A = [0, \infty) \times [0, 2\pi]$, 但不单 (图中...) \Rightarrow $A = (0, \infty) \times [0, 2\pi]$ 重合的
由 ②

$$g' = \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix}$$

$$A = (0, \infty) \times (0, 2\pi)$$

$$|\det g'| = r \quad (\text{回忆 } f)$$

$$-(e^{-\frac{r^2}{2}})' = re^{-\frac{r^2}{2}}$$

$$(f \circ g)(r, \theta) = e^{-\frac{r^2}{2}}, \text{ by COV,}$$

$$I_2 = \int_A e^{-\frac{r^2}{2}} \cdot (r) \cdot dr d\theta \stackrel{\text{Fubini ①}}{=} \int_0^{2\pi} dr \int_0^\infty r e^{-\frac{r^2}{2}}$$

$$= \int_0^{2\pi} 1$$

$$= 2\pi \Rightarrow I_1 = \sqrt{2\pi}$$

①: 单层实义域方法用 Fubini $\int_{\mathbb{R}^2} e^{-\frac{x+y^2}{2}} dx dy$:

$$a_N \rightarrow \int_{[-N, N]^2} e^{-\frac{x+y^2}{2}} dx dy = \int_{[-N, N]} e^{-\frac{x^2}{2}} dx \int_{[-N, N]} e^{-\frac{y^2}{2}} dy \quad \text{是时的, 只需证 } N \rightarrow \infty \text{ 时收敛}$$

$$\int_{\mathbb{R}^2} e^{-\frac{x+y^2}{2}} dx dy = \sum_{i=1}^{\infty} \int_{\mathbb{R}} \varphi_i f = \lim_{P \rightarrow \infty} \sum_{i=1}^P \int_{\mathbb{R}} \varphi_i f = \lim_{P \rightarrow \infty} \int_{\mathbb{R}} \left(\sum_{i=1}^P \varphi_i \right) f$$

a_N, b_P 均单薄, 且 $\forall N, \exists P$ s.t. $b_P \geq a_N$. 反之亦然, 即可证收敛至同值

固若 N, φ_i 在 $[-N, N]$ 上和为 1, φ_i 可累, 则有限个 φ_i 可覆盖

反之, 覆盖住所有 φ_i 的 N .

②: "You can always ignore closed sets with measure 0"

方程:

有界: $\text{vol content} = 0$.

$$\sigma_n = \text{Vol}(S^n) . S^n = \{x \in \mathbb{R}^{n+1}, |x|=1\}$$

$$I_{n+1} = \int_{\mathbb{R}^{n+1}} e^{-\frac{|z|^2}{2}} dz = I_1^{n+1} = \sqrt{2\pi}^{n+1}$$



到原点距离

$$S_r = \int_{\mathbb{R}^n} dr (S_r) \cdot e^{-\frac{r^2}{2}}$$

$$\text{Vol}(S_r) = r^n \cdot \text{Vol}(S^n)$$

这里和前面的
工具这个函数，我
和之前的步骤了。

$$I_{n+2} = \int_0^\infty r^{n+2} e^{-\frac{r^2}{2}} dr = - \int_0^\infty \left(\frac{1}{n+1}\right) r^{n+1} \cdot (-re^{-\frac{r^2}{2}}) dr + uv \Big|_0^\infty$$

$$\begin{aligned} \text{分部积分} &= \frac{1}{n+1} \int_0^\infty r^n e^{-\frac{r^2}{2}} dr \\ &= \frac{1}{n+1} I_n \quad (n \geq 1) \end{aligned}$$

$$\sigma_n = 2\pi^{\frac{n+1}{2}} / I_n = \frac{2\pi \cdot 2\pi^{\frac{n-1}{2}}}{(n+1) I_{n-2}} = \frac{2\pi}{n+1} \cdot \sigma_{n-2} \Rightarrow \sigma_n = \frac{2\pi}{n+1} \sigma_{n-2}$$

$$\sigma_0 = 2, \quad \sigma_2 = 4\pi$$

$$\sigma_1 = 2\pi \quad \sigma_3 = 2\pi^2$$

$$\text{设 } \beta_n = \text{Vol}(B_1(0) \subset \mathbb{R}^n), \text{ 证 } \beta_n = \frac{\sigma_{n-1}}{n}$$

$$\beta_0 = 0 \quad \beta_2 = \pi$$

$$\beta_1 = 2 \quad \beta_3 = \frac{4}{3}\pi$$

$$\begin{aligned} \beta_n &= \int_0^1 \text{Vol}(S_r^{n-1}) dr, \quad \text{而 } \text{Vol}(S_r^{n-1}) = r^{n-1} \text{Vol}(S^{n-1}) \\ &= \int_0^1 r^{n-1} \text{Vol}(S^{n-1}) dr \\ &= \sigma_{n-1} \int_0^1 r^{n-1} dr \\ &= \sigma_{n-1} \left(\frac{r^n}{n}\right) \Big|_0^1 \\ &= \frac{\sigma_{n-1}}{n} \end{aligned}$$

Proof of COV: WTS: 把 g 拆成 N 个“简单”的 map.

$$\text{Lemma: } A \xrightarrow{h} O \xrightarrow{l} O \xrightarrow{k} \mathbb{R}$$

$$\text{cov}(g), \text{cov}(h) \stackrel{?}{\Rightarrow} \text{cov}(g \circ h)$$

layer-preserving map: $\overbrace{\text{---}}^{\text{l.p.}} \rightarrow \overbrace{\text{---}}^{\text{l.p.}}$ (也可能旋转类的)

$g: \mathbb{R}^n \rightarrow \mathbb{R}^n, g(x_1, x_2, \dots, x_n) = (\dots, x_n)$ (最后一坐标不变)

好处：可以分步积分（“这是哪层？”→ 按层积分） $\xrightarrow{\text{② Fubini}} \text{COV}(n-1) \Rightarrow \text{cov}(n)$ for l.p. maps.

③ every g is a l.p. map. [only locally]

$g: \mathbb{R}_{x_i}^n \rightarrow \mathbb{R}_{y_i}^n, y_i = g_i(x_1, x_2, \dots, x_n)$

$$\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_{i-2} \\ x_{i+1} \\ x_n \end{pmatrix} \xrightarrow{\alpha} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_{i-2} \\ x_{i+1} \\ x_n \\ y_i \end{pmatrix} \xrightarrow{\beta} \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

Q. P. 为 l.p. (只算同一层)

④ local $\xrightarrow{\text{PO1}}$ global. i.e. $\text{cov}(\text{small sets}) \Rightarrow \text{cov}(\text{large set})$

⑤ cov(1D) ⑥ $R \xrightarrow{\text{restricted}} \text{COV} \Rightarrow \text{COV}$ 连续. ⑦ holds for swaps coordinates.

从中间进

① Lemma: $\text{f} \circ h$

Now to show: $\text{f} \circ h$

$$\text{NTS: } \int_{(g \circ h)(A)} f = \int_A (f \circ g \circ h) | \det(g \circ h)' |$$

如果已经对 g 和 h 成立.

这里因为对 h, g , COV 成立

$$\begin{aligned} \int_{(g \circ h)(A)} f &= \int_{h(A)} (f \circ g) | \det g' | f \\ &= \int_A (\bar{f} \circ h) | \det h' | \end{aligned}$$

$$\begin{aligned} \text{再令 } \bar{f} &= \int_A (\bar{f} \circ g \circ h) | \det g \circ h | | \det h' | \end{aligned}$$

$$= \int_A (\bar{f} \circ g \circ h) | \det((g \circ h) \cdot h') |$$

$$= \int_A (\bar{f} \circ g \circ h) | \det(g \circ h)' |$$

③ Lemma: Assume COV holds for $n-1$ dim. 这个地方要连续.

Let $g: U \rightarrow \mathbb{R}^n$. 有界 be a l.p. map. s.t. $g(u)$ 仍有界.

$$(g(x_1, x_2, \dots, x_n) = (\dots, x_n) / g_n(x_1, x_2, \dots, x_n) = x_n)$$

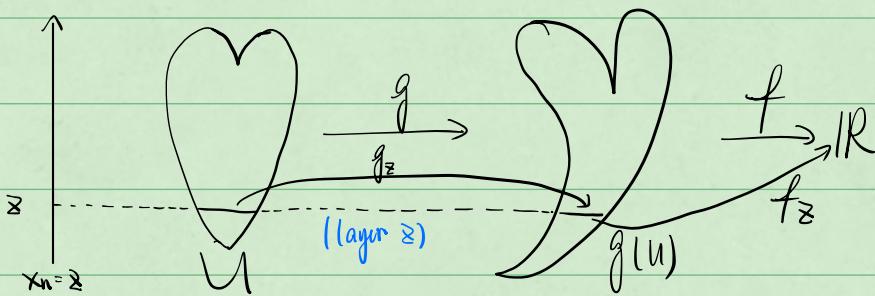
And, a restricted COV(g) holds: If $f: g(U) \rightarrow \mathbb{R}$

is continuous and $\text{supp}(f) \subset g(U)$

$$\int_{\mathbb{R}^n} f = \int_U (f \circ g) |\det g'|$$

因为 $\int_{\mathbb{R}^n} f = \int_U (f \circ g) |\det g'|$ (同理)

$$U \xrightarrow{g} g(U) \xrightarrow{f} \mathbb{R}$$



$\forall z \in \mathbb{R}$, define $g_z : \mathbb{R}^{n-1} \rightarrow \mathbb{R}^{n-1}$ by $g_z(x) = (g_1(x, z), g_2(x, z), \dots, g_{n-1}(x, z))$

$f_z : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ by $f_z(x) = f(x, z)$ \rightarrow 这俩是“第z层的函数”

$$\int_{\mathbb{R}^n} f = \int_{\mathbb{R}} d\bar{z} \int_{\mathbb{R}^{n-1}} dx f(x, \bar{z}) = \int_{\mathbb{R}} d\bar{z} \int_{\mathbb{R}^{n-1}} dx f_z(x) = \int_{\mathbb{R}} d\bar{z} \int_{\mathbb{R}^{n-1}} (f_z \circ g_z) |\det g_z'|$$

Fubini

$|\det g_z'|$ 是什么?

$$g_z' = \begin{pmatrix} \frac{\partial g_1}{\partial x_1} & \cdots & \frac{\partial g_1}{\partial x_{n-1}} & \frac{\partial g_1}{\partial z} \\ \vdots & & \vdots & \vdots \\ \frac{\partial g_n}{\partial x_1} & \cdots & \frac{\partial g_n}{\partial x_{n-1}} & \frac{\partial g_n}{\partial z} \end{pmatrix}$$

最后一行是 $(0, 0, \dots, 0, 1)$ 因为 g l.p.

$$= \int_{\mathbb{R}} d\bar{z} \int_{\mathbb{R}^{n-1}} f_z \circ g_z |\det g_z'| \stackrel{\text{fubini}}{=} \int_{\mathbb{R}}$$

③ Lemma: $\forall a \in \mathbb{R}^n$ $\exists U \xrightarrow{\text{open}}$ s.t. on U , g is a composition of l.p. maps and coordinate swaps.

$$T_{ij} : \mathbb{R}^n \rightarrow \mathbb{R}^n, T_{ij}(x_1, \dots, x_i, \dots, x_j, \dots, x_n) = (x_1, \dots, x_j, \dots, x_i, \dots, x_n).$$

$$pf: y_i = g_i(x_1, x_2, \dots, x_n).$$

$$\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \xrightarrow{\alpha_k} \begin{pmatrix} x_1 \\ \vdots \\ x_{n-1} \\ y_k \end{pmatrix} \xrightarrow{\beta_k = g \circ \alpha_k^{-1}} \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

α_k, β_k invertible?

α_k, β_k 不是 l.p. 但不完全不是 l.p. to coord. swaps

Let $\alpha_k(x_1, \dots, x_n) \rightarrow (x_1, \dots, x_{n-1}, g_k(x_1, \dots, x_n))$ 下证可逆。

$$\alpha_k' = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & 1 & 0 & \cdots & 0 & 0 \\ \vdots & & \vdots & & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & 0 \\ \frac{\partial f_k}{\partial x_1} & & & \cdots & -\frac{\partial f_k}{\partial x_n} & \end{pmatrix} \neq 0, \Rightarrow \text{只需 } \frac{\partial f_k}{\partial x_n} \text{ 不为 } 0. \text{ 但 } g \text{ 在小区间内可逆,}\\ \text{所以必能找到至少一个 } k \text{ 使 } \frac{\partial f_k}{\partial x_n} \text{ 不为 } 0.$$

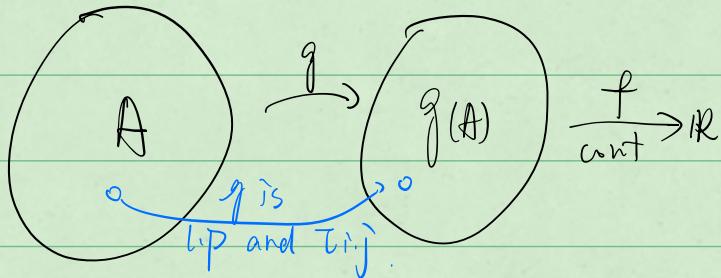
By IFT, α_k is invertible near a .

$$\begin{aligned} \text{near } a, \text{ set } \beta_k = g \circ \alpha_k^{-1}, \text{ then } g &= \beta_k \circ \alpha_k = T_{kn} \circ T_{kn} \circ \beta_k \circ T_{in} \circ T_{in} \circ \alpha_k \circ T_{in} \circ T_{in} \\ &= \underbrace{T_{kn} \circ (T_{kn} \circ \beta_k)}_{Lip} \circ T_{in} \circ \underbrace{(T_{in} \circ \alpha_k \circ T_{in})}_{Lip} \circ T_{in} \end{aligned}$$

④ local COV \Rightarrow global COV ^{连续} for continuous.

\hookrightarrow 若 g , 且 $a \in A$ ^有 局部 COV 成立.

β_k :



$$f_3(\gamma) = \left\{ \bigcup_{\text{open } V} g(A) : g(V) \text{ bounded, LIP, and TI} \right\}$$

γ is a cover of $g(A)$. 证明所有点都在.

$\forall b \in g(A)$. $g^{-1}(b) = a$ ^{由单}, 而 a 周围有 bdd , LIP map.

找 $POL \psi_i$ sub to γ

$\psi_i = \psi_i \circ g$ is a POL for A , sub to $U = \{g(V), V \in \gamma\}$

$$\int_{g(A)} f = \sum_i \int_{\text{some } V \in \gamma} \psi_i \circ f = \sum_i \int_A (\psi_i \circ g)(f \circ g) | \det g' | = \sum_i \int_A \psi_i(f \circ g) | \det g' | \stackrel{\text{定义}}{=} \int_A f \circ g | \det g' |$$

⑤ COV (1D). WLOG, $A = (a, b)$.

$g: (a, b) \rightarrow \mathbb{R}$ is 1-1, 且 cont \rightarrow 单调

$$g(A) = g((a, b)) = \left\{ \begin{array}{l} (g(a), g(b)) \\ \text{if } g'(a) > 0 \\ (g(b), g(a)) \\ \text{if } g'(b) < 0 \end{array} \right.$$

漫游:

$$\int_{g(A)} f = \int_{g(b)}^{g(a)} f \circ g \cdot g' = - \int_a^b f \circ g \cdot (-\det(g'))$$

$\rightarrow |\det(g')|$

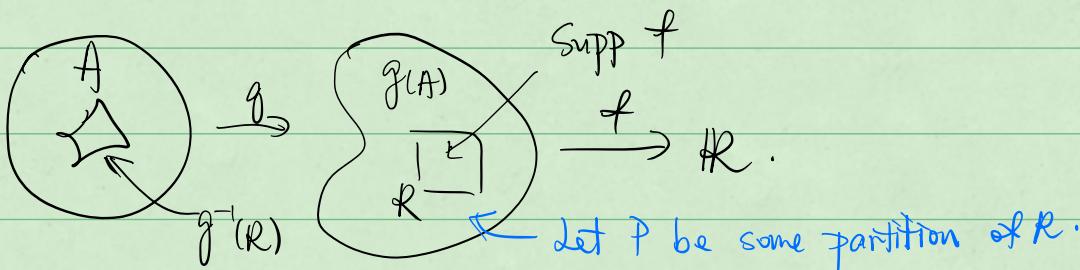
$$= \int_a^b f \circ g \cdot |\det(g')|$$

⑥ 若对于连续+成立, 则对于任意+成立.

$$O \xrightarrow{h} O \xrightarrow{g} O \xrightarrow[f \text{ constant}]{} \mathbb{R}$$

$$f = (fg) |\det g'| \leftarrow \propto \text{constant.}$$

We'll not prove the full theorem, only local version of COV for integral functions.



" $L(f, P) \dots L(f \circ g) \dots U(f \circ g) \dots U(f, P)$ " \leftarrow 希望.

$$L(f, P) = \sum_{S \in P} V(S) \cdot m_S(f) = \sum_{S \in P} \int_S m_S(f) \stackrel{\text{常值}}{\leq} \sum_{S \in P} \int_{g^{-1}(S)} m_S(f) |\det g'| \leq \sum_{S \in P} \int_{g^{-1}(S)} f \circ g |\det g'|$$

$$= \sum_{S \in P} \int_{g^{-1}(S)} f \circ g |\det g'| \leq \int_{g^{-1}(P)} \sum_{S \in P} \int_{g^{-1}(S)} (f \circ g) |\det g'| = \int_{g^{-1}(P)} (f \circ g) |\det g'| \leq \int_{g^{-1}(P)} (f \circ g) |\det g'|$$

(exercise: $\int h_1 + \int h_2 \leq \int (h_1 + h_2)$)

和前面一样, 反过来 $\rightarrow \leq U(f, P)$

f 可积 $\rightarrow L(f, P) \leq U(f, P)$ 任意接近 $\rightarrow f \circ g$ 可积.

⑦ COV holds for T_{ij}

NTS $\int_{T_{ij}(A)} f = \int_A f \circ T_{ij} (\det = \pm 1)$

e.g. $\int_A f \circ T = \int_A f$ ($\geq D, T(x, y) = (y, x)$)

过于显然 (rename)

Lij(A) You are viewing Dror's screen View Options TA A Talking:

Q How do you write the proof of something so disturbingly obvious?

A You go back to the LFS.

PF Given $A = [a_1, b_1] \times [a_2, b_2] ; TA = [a_2, b_2] \times [a_1, b_1]$

$P = ((a_1=t_{10}, t_{11}, \dots, t_{1n}=b_1), (a_2=t_{20}, \dots, t_{2n}=b_2)) \quad TP = \dots$

$$L(F \circ T, P) = \sum_{S \in P} V(S) m_S(F \circ T) = \sum_{S \in P} V(S) m_{TS}(F) =$$

$$\sum_{T \in TP} \overbrace{---}^{\text{measure-0}} = \sum_{S \in P} \overbrace{---}^{\text{measure-0}} = L(F, TP) \dots$$

\square \square COV

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Baby Sard Thm: $A \subset \mathbb{R}^n \nexists, g: A \rightarrow \mathbb{R}^n$, cont. diffable.

$C = \{x \in A \mid \det g'(x) = 0\}$. Then $g(C)$ is of
 "critical set of g " measure-0

Claim: C is closed. $g'(x) = n \times n$ array of cont functions.

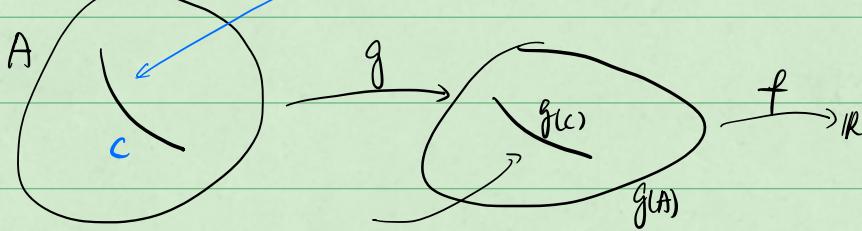
$\Rightarrow h(x)$ is cont.

$\therefore C = h^{-1}(0) \Rightarrow$ 闭集的像像也为闭集.

Cor (of Sard): In COV Thm, can drop the condition

that " g' is 1-1"

pf:



measure-0 and also closed?

$g(A) \setminus g(C) = g(A \setminus C)$ is open (IFT holds).

on which g' 可逆

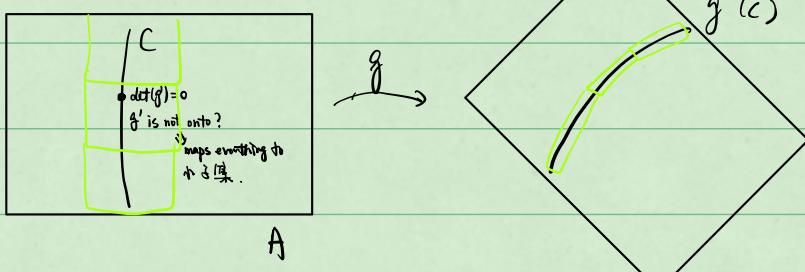
$$\int_A (f \circ g) |\det g'| \stackrel{?}{=} \int_{g(A)} f \quad \text{ignore } g(c) \text{ measure-0 + close = context = 0.}$$

for $c \in g^{-1}(c)$
 $A \neq \emptyset$

$$\int_A (f \circ g) |\det g'| \stackrel{?}{=} \int_{g(A)} f$$

old cov formula.

Pf of Baby Sand:



Adult Sand thm: $g: A \subset \mathbb{R}^n \xrightarrow{\text{open}} \mathbb{R}^m$

$$C = \{x \in A : \text{rank}(g'(x)) < m\}$$

g is k times cont diffable. $k = \max(1, n-m+1)$

Then $g(C)$ is measure-0 超薄！

DEF: \mathbb{V} 为 \mathbb{R} 上 向量 空间

$T: \mathbb{V}^k \rightarrow \mathbb{R}$ is called "multilinear" or " k -linear"

$$\text{if } T(u_1, \dots, \alpha u_i + \beta u_i'', \dots, u_k)$$

$$= \alpha T(u_1, \dots, u_i, \dots, u_k) + \beta T(u_1, \dots, u_i'', \dots, u_k)$$

e.g. 内积为 2-linear map

e.g. $M_{n \times n}(\mathbb{R}) \xrightarrow{\det} \mathbb{R}$

e.g. 1-linear map $\varphi: V \rightarrow \mathbb{R}$

"linear functional" $\varphi \in V^*$ dual space

e.g. 0-linear map.

$$W: V^0 = \{0\} \rightarrow \mathbb{R}$$

$$W(0) \in \mathbb{R} \quad 0\text{-linear} \cong \text{a element in } \mathbb{R}.$$

V 上向量空间

DEF: $\mathcal{J}^k(V) = \{k\text{-linear maps on } V\}$

对偶空间 V^* 是 V 到 \mathbb{R} 上
线性函数的集合。

Warning: many other sources call it $\mathcal{J}^k(V^*)$

$$\langle , \rangle \in \mathcal{J}^2(V), \quad \det \in \mathcal{J}^n(V) \quad \mathcal{J}^0 V \cong \mathbb{R}$$

$$\mathcal{J}^1 V = V^* = n\text{-dim} \quad (\dim \mathcal{J}^k V) ?$$

$$\xrightarrow{\text{设}} \dim(V) = n,$$

$\xrightarrow{\text{设}} v_1, v_2, \dots, v_n$ 为 V 的基 $\exists!$ 基 $\varphi_1, \varphi_2, \dots, \varphi_n$ of $V^* = \mathcal{J}^1 V$,

s.t. $\varphi_i(v_j) = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & \text{otherwise.} \end{cases}$ $\{\varphi_i\}$ is called the dual basis

e.g. 1: dual basis of $\left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 4 \end{pmatrix} \right\} \subset \mathbb{R}^2$?

$\mathbb{R}^2 = \{(\cdot)\} \Rightarrow (\mathbb{R}^2)^* = \{(*, *)\}$ linear maps from $\mathbb{R}^2 \rightarrow \mathbb{R}$

$$\varphi_1 = (-, -), \quad \varphi_2 = (-, -).$$

$$\begin{aligned} \varphi_1(v_1) &= 1, & \varphi_1(v_2) &= 0 \\ \varphi_2(v_1) &= 0, & \varphi_2(v_2) &= 1. \end{aligned}$$

$$\Rightarrow \begin{pmatrix} -\varphi_1 & - \\ -\varphi_2 & - \end{pmatrix} \begin{pmatrix} | & | \\ v_1 & v_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}^{-1} = \begin{pmatrix} -2 & \frac{3}{2} \\ 1 & -\frac{1}{2} \end{pmatrix}$$

$$\Rightarrow \varphi_1 = \left(-2, \frac{3}{2}\right), \quad \varphi_2 = \left(1, -\frac{1}{2}\right)$$

Claim: $\mathcal{J}^k(V)$ is a vector space.

$$T_1, T_2 \in \mathcal{J}^k, \quad (T_1 + T_2)(u_1, u_2, \dots, u_k) = T_1(u_1, \dots, u_k) + T_2(u_1, \dots, u_k)$$

$$(\alpha T_1)(u_1, u_2, \dots, u_k) = \alpha (T_1(u_1, \dots, u_k))$$

$$"0_T"=0.$$

"Tensor multiplication"

Also a map $\otimes : \mathcal{G}^k \times \mathcal{G}^l \rightarrow \mathcal{G}^{k+l}$

$$(T_1 \otimes T_2)(u_1, u_2, \dots, u_{k+l}) = T_1(u_1, \dots, u_k) \cdot T_2(u_{k+1}, \dots, u_{k+l})$$

$$T_1 \otimes T_2 = T_1 T_2 \in \mathcal{G}^{k+l}$$

\otimes is associative, distributive and non-commutative.

$$T_1(T_2 T_3) = (T_1 T_2) T_3. \quad \text{蕴涵}$$

要同维数. $(T_1 + T_2) T_3 = T_1 T_3 + T_2 T_3. \quad \text{展开后同样蕴涵.}$

$\Rightarrow \otimes$ is bilinear,

$T_1 T_2$ 一般不等于 $T_2 T_1$, 考虑 $V = \mathbb{R}^2$, e_1, e_2 为两个基, ψ_1, ψ_2 为

V^* 中对应的基. ($\psi_1, \psi_2 \in \mathcal{G}(V)$), 但

$$(\psi_1 \psi_2)(e_1 e_2) = \psi_1(e_1) \psi_2(e_2) = 1 \neq 0 = \psi_1(e_2) \psi_2(e_1)$$

Notation: $\underline{n} = \{1, 2, \dots, n\}$, $\underline{n}^k = \{\overline{i} = I = (i_1, i_2, \dots, i_k), i_\alpha \in \underline{n}\}$. ($|\underline{n}^k| = n^k$)

$$(v_j)_{j=1}^n \in V^n, \quad J \in \underline{n}^k \quad \text{"multi-index"}$$

$$v_J = (v_{j_1}, v_{j_2}, \dots, v_{j_k})$$

$$\psi_i \in V^*, i=1, 2, \dots, n, I \in \underline{n}^k \quad \psi_I = \psi_{i_1} \cdot \psi_{i_2} \cdots \psi_{i_n}$$

这里的意思是 \otimes

$$E.g. \quad \psi_1 \psi_2 = \psi_{(1,2)}, \quad \psi_2 \psi_1 = \psi_{(2,1)}$$

$$\psi_{(1,2)}(e_{(1,2)}) = 1, \quad \psi_{(2,1)}(e_{(1,2)}) = 0.$$

\vdash V is a vector space with basis v_1, \dots, v_n , \vdash dual basis $\psi_1, \psi_2, \dots, \psi_n$.

若 $I, J \in \underline{n}^k$,

$$g^k \rightarrow \psi_I(v_J) = (\psi_{i_1}, \dots, \psi_{i_k})(v_{j_1}, \dots, v_{j_k}) = \sum_{\alpha=1}^k \psi_{i_\alpha}(v_{j_\alpha}) = \sum_{\alpha=1}^k \delta_{i_\alpha j_\alpha} = \begin{cases} 1 & \text{if } I = J \\ 0 & \text{otherwise} \end{cases}$$

product of k tensors \uparrow a list of k vectors.

$= 1$ 素意味着 $I = J$

$$\begin{cases} 0 & i_\alpha \neq j_\alpha \\ 1 & i_\alpha = j_\alpha \end{cases}$$

Thm: V with basis v_1, \dots, v_n , dual basis $\varphi_1, \dots, \varphi_n$.

Then $\{\varphi_I \mid I \in \underline{n}^k\}$ is a basis of $\mathcal{J}^k(V)$. Hence,

$$\dim(\mathcal{J}^k(V)) = n^k$$

Proof: Lemma 1: If $T_1, T_2 \in \mathcal{J}^k(V)$, then $T_1 = T_2 \Leftrightarrow \forall I, T_1(v_I) = T_2(v_I)$

Pf: " \Rightarrow " 諸據.

$$\leq \forall I \in \underline{n}^k, T_1(v_I) = T_2(v_I)$$

set $T = T_1 - T_2$, 假設 $T \neq 0$.

$$T(u_1, \dots, u_k) = T(\sum a_{ij}v_j, \sum a_{ij}v_j, \dots, \sum a_{ij}v_j)$$

通過 multilinear 性質擴成全部 v_i , 得 $T \neq 0$

Lemma 2: $\{\varphi_I\}$ spans $\mathcal{J}^k(V)$

Given $T \in \mathcal{J}^k(V)$, 如何 $T = \sum a_I \varphi_I$? 考慮代入 v_J 的值

$$T(v_J) = \sum a_I \varphi_I(v_J)$$

$$= \sum a_J \delta_{IJ} = a_J.$$

Given $T \in \mathcal{J}^k$, set $a_I = T(v_I)$. Claim: $T = \sum a_I \varphi_I$

By Lemma 1, 假設 $T(v_J) = (\sum a_I \varphi_I)(v_J)$

$$\Rightarrow a_J = a_J, \text{ 矛盾.}$$

Claim: φ_I are linear independent:

設 $a_I \in \mathbb{R}$, 使 $\sum a_I \varphi_I = 0$. $\forall J \in \underline{n}^k$,

$$(\sum a_I \varphi_I)(v_J) = 0 (v_J) = 0.$$

$$\underbrace{\sum a_I \delta_{IJ}}_{= \sum a_I \delta_{IJ} = a_J} = a_J \Rightarrow \forall J, a_J = 0.$$

由以上證畢

$\xrightarrow{\text{若 } V \xrightarrow{L} W \text{ 为线性. 如何联系 } \mathcal{J}^k(w) \text{ 与 } \mathcal{J}^k(v) ?}$ $\mathcal{J}^k(v) \stackrel{L^*}{\leq} \mathcal{J}^k(w)$

$$T \in \mathcal{J}^k(w), \quad \underbrace{u_i \in V}_{\leftarrow u_i \in V} \\ \xrightarrow{\quad} (L^* T)(u_1, \dots, u_k) = T(Lu_1, \dots, Lu_k)$$

Claim 1. If $T \in \mathcal{J}^k(w)$, then $L^* T \in \mathcal{J}^k(v)$

($L^* T$ is multilinear)

$$\text{Pf: } (L^* T)(u_1, \dots, \alpha u_i + \beta u_j, \dots, u_k)$$

$$= T(Lu_1, \dots, L(\alpha u_i + \beta u_j), \dots, Lu_k)$$

$$\stackrel{\substack{T \text{ is} \\ \text{linear}}}{=} T(Lu_1, \dots, \alpha Lu_i + \beta Lu_j, \dots, Lu_k)$$

$$\stackrel{\substack{T \text{ is} \\ \text{multilin}}}{=} \alpha T(Lu_1, \dots, Lu_k) + \beta T(Lu_2, \dots, Lu_k)$$

Claim 2: $L^*: \mathcal{J}^k W \rightarrow \mathcal{J}^k V$ is linear.

$$\text{NTS: } \text{若 } T_1, T_2 \in \mathcal{J}^k(w), \text{ 且 } L^*(\alpha T_1 + \beta T_2) = \alpha L^* T_1 + \beta L^* T_2.$$

Claim 3: L^* is compatible with \otimes .

$$\text{i.e. if } T_1 \in \mathcal{J}^k(w), T_2 \in \mathcal{J}^l(w), \text{ then } \underbrace{L^*(T_1 \otimes T_2)}_{\substack{\uparrow \\ k+l \text{ tensor (w)}}} = L^*(T_1) \otimes L^*(T_2) \quad \substack{\downarrow \\ l \text{ tensor (V)}}$$

DEF: $T \in \mathcal{J}^k(V)$ is "alternating"

$$\text{if } T = (\dots, u, \dots, w, \dots) = -T(\dots, w, \dots, u, \dots)$$

$$\Lambda^k(V) := \{ T \in \mathcal{J}^k(V) \mid T \text{ is alternating} \} \quad (\Lambda^k(V^*))$$

$\Lambda^k(V)$ is a subspace of $\mathcal{J}^k(V)$

Prop: $T \in \mathcal{J}^k$ Then T kills repetition $\Leftrightarrow T$ is alternating

Pf: T is alternating, $\Leftrightarrow u=w \Rightarrow \leq$

" \Rightarrow ":

$$0 = T(\dots, u+w, \dots, u+w) = T(\dots, u, \dots, u) + T(\dots, u, \dots, w)$$

$$+T(\dots w \dots u \dots) + T(\dots w \dots w \dots)$$

$$\Rightarrow 0 = T(\dots w \dots u \dots) + T(\dots u \dots w \dots)$$

eg1: $\det(M_{n \times n}(\mathbb{R})) \in \mathbb{J}^n(\mathbb{R}^n)$ — 每列为一基
 $\mathbb{R} \Lambda^n(\mathbb{R}^n)$

eg2: $k \leq n$, $\lambda_I \in \Lambda^k \mathbb{R}^n$, $I \in \underline{\mathbb{N}}^k$

$$n \left\{ \begin{pmatrix} & & & & \\ | & | & | & | & | \\ & & & & \end{pmatrix} \xrightarrow{\lambda_I} \det \begin{pmatrix} & & & \\ \dots & i_1 & \dots & \\ \dots & i_2 & \dots & \\ \vdots & & & \\ \dots & i_k & \dots & \end{pmatrix} \right.$$

$k \times k$ 行

由需考虑 $\{I \in \underline{\mathbb{N}}^k : i_1 < \dots < i_k\} = \underline{\mathbb{N}}_a^k = \binom{n}{k}$

$$|\underline{\mathbb{N}}_a^k| = C_n^k$$

DEF: A permutation of order k $\sigma: k \rightarrow k$ 映射

$$S_k = \{\sigma\} \quad |S_k| = k!$$

τ : identity

$$\text{sign } (\sigma) = \prod_{i < j} \text{sign}(\sigma_i - \sigma_j)$$

Claim: 若 $T \in \Lambda^k$, $\sigma \in S_k$, $T: V^k \rightarrow \mathbb{R}$

$$\text{且 } T \circ \sigma^* = (-1)^\sigma T.$$

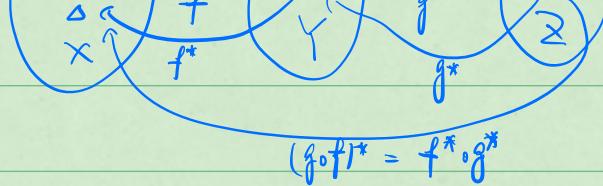
$$\sigma^*: V^k \rightarrow V^k, \quad \sigma^*(v_1, \dots, v_k) = (v_{\sigma(1)}, \dots, v_{\sigma(k)})$$

Aside: V^k (事实上) = {function: $k \rightarrow V$ }.

$$\text{So } \underline{k} \xrightarrow{\sigma} \underline{k} \xrightarrow{\downarrow} V$$

Aside \circ $(g \circ f)_* = g_* \circ f_*$





$$\text{特别地, } (\sigma \circ \tau)^* = \tau^* \circ \sigma^*$$

Pf of Claim: write $\sigma = \tau_1 \circ \dots \circ \tau_l$ \curvearrowleft transpositions.

$$\begin{aligned}
 T \circ \sigma^* &= T \circ (\tau_1 \circ \dots \circ \tau_l)^* \quad \text{这里用 pull back 为什么?} \\
 &= T \circ \tau_l^* \circ \dots \circ \tau_1^* \\
 &= (T \circ \tau_l^*) \circ \dots \circ \tau_1^* \quad T \text{ alternating.} \\
 &= -T \circ \tau_{l-1}^* \circ \dots \circ \tau_1^* \\
 &= (-1)^\sigma T.
 \end{aligned}$$

Basis for $\Lambda^k(V) = \{W_I : I \in \mathbb{N}_a^k\}$ ascending sequences.

DEF: $\forall I \in \mathbb{N}^k$ (especially if $I \in \mathbb{N}_a^k$)

$$W_I = \sum_{\sigma \in S_k} (-1)^\sigma \psi_I \circ \sigma^* \quad \text{"anti-symmetrization"}$$

本质上一样 ↗ e.g. $F: \mathbb{R}^2 \rightarrow \mathbb{R}$ is anti-symmetric if $F(x,y) = -F(y,x)$

若 $g: \mathbb{R}^2 \rightarrow \mathbb{R}$ is any function:

$$\text{let } F(x,y) = g(x,y) - g(y,x)$$

Claim: W_I is alternating.

$$\text{Pf: } W_I \circ \tau^* \stackrel{\text{transposition}}{=} \left(\sum_{\sigma} (-1)^\sigma \psi_I \circ \sigma^* \right) \circ \tau^*$$

$$= \sum_{\sigma} (-1)^\sigma \psi_I \circ \sigma^* \circ \tau^*$$

$$= \sum_{\sigma} (-1)^\sigma \psi_I \circ (\tau \circ \sigma)^*$$

$$= (-1) \sum_{\sigma} (-1)^{\sigma \tau} \psi_I \circ (\tau \circ \sigma)^*$$

$$= (-1) \sum_{\sigma} (-1)^{\sigma \tau} \psi_I \circ (\tau \circ \sigma)^*$$

$$= (-1) W_I$$

重点在于如果 I, J 中元素一样, 则通过重排是强相关的

Thm : $\{W_I \mid I \in \mathbb{N}_a^k\}$ is a basis of $\Lambda^k V$. So $\dim \Lambda^k V = C_n^k$

Pf: 1. $W_I(V_J) = \sum_{I,J} (\text{if } I, J \in \mathbb{N}_a^k)$ (V vs. v_1, \dots, v_n , $\varphi_1, \dots, \varphi_n$ 对应)

$$\text{Pf: } W_I(V_J) = \sum_{S \in k} (-1)^{\delta} \varphi_I(S^* V_J)$$

$$= \sum_{S \in k} (-1)^{\delta} (\varphi_{i_1}(v_{j_{i_1}}) \otimes \dots \otimes \varphi_{i_k}(v_{j_{i_k}})) (v_{j_{i_1}}, v_{j_{i_2}}, \dots, v_{j_{i_k}})$$

$$= \sum (-1)^{\delta} (\varphi_{i_1}(v_{j_{i_1}}) (\varphi_{i_2}(v_{j_{i_2}}) \cdots (\varphi_{i_k}(v_{j_{i_k}})))$$

$$= \sum (-1)^{\delta} \cdot \begin{cases} 1 & \text{if } i_1 = j_{i_1}, i_2 = j_{i_2}, \dots, i_k = j_{i_k} \Leftrightarrow (i_1, \dots, i_k) = (j_{i_1}, \dots, j_{i_k}) \\ 0 & \text{otherwise} \end{cases}$$

$$= \sum_{S \in k} (-1)^{\delta} \delta_{I,J} = \delta_{I,J}$$

\checkmark $\delta \neq 0$ if and only if I and J are ascending.

2: $\lambda_1, \lambda_2 \in \Lambda^k V$, $\lambda_1 = \lambda_2 \Leftrightarrow \forall I \in \mathbb{N}_a^k$, $\lambda_1(V_I) = \lambda_2(V_I)$

" \Rightarrow " 通过

$$\Leftrightarrow \text{NTS } (\lambda_1 - \lambda_2)(v_1, \dots, v_k) = 0$$

$$\Leftrightarrow (\lambda_1 - \lambda_2)(v_{i_1}, \dots, v_{i_k}) = 0 \quad \forall i_1, \dots, i_k$$

$$\Leftrightarrow (\lambda_1 - \lambda_2)(v_{i_1}, \dots, v_{i_k}) = 0 \quad \forall (i_1, \dots, i_k) \in \mathbb{N}_a^k$$

$$\Leftrightarrow \lambda_1(V_I) = \lambda_2(V_I) \quad \forall I \in \mathbb{N}_a^k \quad \text{即得证}$$

3. Span: given $\lambda \in \Lambda^k$, find a_I s.t. $\lambda = \sum a_I W_I$

$$\text{let } a_I = \lambda(V_I) \quad \text{NTS } \lambda = \sum a_I W_I$$

$$\text{只需证 } \lambda(V_J) = (\sum a_I W_I)(V_J) \quad \forall I, J \in \mathbb{N}_a^k$$

$$= \sum a_I \delta_{IJ}$$

$$= a_J$$

4 线性无关

$$\sum b_I W_I = 0$$

$$\sum b_I W_I(V_J) = 0$$

$$\Rightarrow b_J = 0 \quad \forall J \in \mathbb{N}_a^k$$

e.g. $V = \mathbb{R}^3$, $v_1 = e_1$, $v_2 = e_2$, $v_3 = e_3$, $\varphi_1 = x$, $\varphi_2 = y$, $\varphi_3 = z$

$$\mathbb{R}^3 = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

\checkmark $(1,0,0) \quad (0,1,0) \quad (0,0,1)$

basis for $\Lambda^0 \mathbb{R}^3, \Lambda^1 \mathbb{R}^3, \Lambda^2 \mathbb{R}^3, \Lambda^3 \mathbb{R}^3, \dots$

$$\hookrightarrow \Lambda^0 \mathbb{R}^3 : W_0$$

$$C_3^1 \quad \Lambda^1 \mathbb{R}^3 : W_1, W_2, W_3$$

$$C_3^2 \quad \Lambda^2 \mathbb{R}^3 : W_{12}, W_{23}, W_{13}$$

$$C_3^3 \quad \Lambda^3 \mathbb{R}^3 : W_{123}$$

Aside: $\underline{\Lambda}_n^k = \{(i_1, \dots, i_k) \mid 1 \leq i_1 < i_2 < \dots < i_k \leq n\}, \quad |\underline{\Lambda}_n^k| = \binom{n}{k}$

$$\left| \{(i_1, \dots, i_k) \mid 1 \leq i_1 \leq i_2 \leq \dots \leq i_k \leq n\} \right| = \underline{\Lambda}_{n,k}^k \text{ non-decreasing}$$

$$|\underline{\Lambda}_{n,k}^k| = \binom{n+k-1}{k} \leftarrow \text{插板} \quad \left\{ (1 \underset{\textcolor{blue}{\downarrow}}{+} 2 \underset{\textcolor{blue}{\downarrow}}{+} 3 \underset{\textcolor{blue}{\downarrow}}{+} 4 \underset{\textcolor{blue}{\downarrow}}{+} 5 \underset{\textcolor{blue}{\downarrow}}{+}) \right\} \quad (12355)$$

Theorem: $\exists ! (\lambda, \gamma) \mapsto (\lambda \wedge \gamma)$ "wedge product"

$$\begin{array}{c} \uparrow \\ \Lambda^k \\ \uparrow \\ \Lambda^k \\ \uparrow \\ \Lambda^{k+1} \end{array} \quad \text{s.t.}$$

$$0. \text{ bilinear} \quad (\alpha \lambda_1 + \beta \lambda_2 \wedge \gamma) = \alpha \lambda_1 \wedge \gamma + \beta \lambda_2 \wedge \gamma$$

$$1. \text{ associative} \quad (\lambda \wedge \gamma) \wedge \varphi = \lambda \wedge (\gamma \wedge \varphi)$$

$$2. \text{ super-commutative} \quad (\text{graded commutative})$$

$$\lambda \wedge \gamma = (-1)^{k \cdot l} \gamma \wedge \lambda \quad \lambda \in \Lambda^k, \gamma \in \Lambda^l$$

$\forall \gamma \in \Lambda^k$

$$3. \quad W_I = \psi_{i_1} \wedge \psi_{i_2} \wedge \dots \wedge \psi_{i_k} \quad \text{if} \quad I \in \underline{\Lambda}_n^k$$

Pf uniqueness: if w, y given, by $w \wedge y$ ~~是唯一的~~ - 确定

$$\psi_i \wedge \psi_j = \begin{cases} W_{(ij)} & \text{if } i < j \quad (ij) \in \underline{\Lambda}_n^k \\ -W_{(ji)} & \text{if } j < i \\ 0 & \text{if } i = j \end{cases}$$

$$\psi_i \wedge \psi_i = -\psi_i \wedge \psi_i = 0$$

$$\# I \in \underline{\Lambda}_n^k, \quad J \in \underline{\Lambda}_n^l$$

$$w_I \wedge w_J = \begin{cases} \text{def} & (\varphi_{i_1} \wedge \dots \wedge \varphi_{i_k}) \wedge (\varphi_{j_1} \wedge \dots \wedge \varphi_{j_l}) \\ \text{def} & \varphi_{i_1} \wedge \dots \wedge \varphi_{i_k} \wedge \varphi_{j_1} \wedge \dots \wedge \varphi_{j_l} \end{cases}$$

$$= \begin{cases} 0 & \text{if } I \cap J \neq \emptyset \\ \pm w_{I \cup J} \text{ (同时 sort)} & \text{if } I \cap J = \emptyset \end{cases}$$

$$w_{23} \wedge w_{14} = (-1)^2 w_{1234}$$

$$w_I \wedge w_{14} = (-1)^1 w_{1234}$$

$$w^\wedge \eta \quad w = \sum a_I w_I$$

$$\eta = \sum b_J w_J$$

$$\Rightarrow w^\wedge \eta = (\sum a_I w_I) \wedge (\sum b_J w_J)$$

$$= \sum a_I b_J (w_I \wedge w_J) \quad \text{know how to do.}$$

仍然需要证在基 $\{w_I\}$ 下保持不变 (well-defined)

Existence: need a basis-independent formula for $\lambda^\wedge \eta$

$$(\lambda \in \Lambda^k, \eta \in \Lambda^l)$$



DEF: $(\lambda^\wedge \eta)(u_1, \dots, u_{k+l}) = \frac{1}{k!l!} \sum_{S \subseteq \{u_1, \dots, u_{k+l}\}} (-1)^{|S|} \lambda(u_{\sigma(1)}, \dots, u_{\sigma(k)}) \eta(u_{\sigma(k+1)}, \dots, u_{\sigma(k+l)})$

$$= \sum_{\substack{S \subseteq \{u_1, \dots, u_{k+l}\} \\ \sigma_1 < \dots < \sigma_k \\ \sigma_{k+1} < \dots < \sigma_{k+l}}} (-1)^k \lambda(u_{\sigma(1)}, \dots, u_{\sigma(k)}) \eta(u_{\sigma(k+1)}, \dots, u_{\sigma(k+l)})$$

有 $k!$ ways 来 permute $\lambda(u_{\sigma(1)}, \dots, u_{\sigma(k)})$, 每一次的值都一样, 所以只选了一个.

$$\text{e.g., } \lambda \in \Lambda^3, \eta \in \Lambda^2$$

$$(\lambda^\wedge \eta)(u_1, u_2, u_3, u_4, u_5) = \sum \text{选 2 个放 } \eta \quad \text{C}_5^2$$

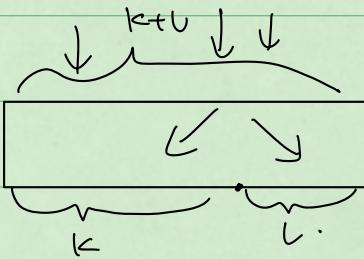
Σ (alternating)

NTS: properties 0-3 holds.

Σ : same as $w_I \in \Lambda^k$

D: trivial

| ~3:



$$= \sum_{\substack{G \in S_{k+l} \\ G_1 < \dots < G_k}} (-1)^{\delta}$$



$$(\lambda^{\wedge} y)(u_1, \dots, u_{k+l}) = \boxed{\lambda \quad y}$$

1: (Associativity)

$$(\lambda^{\wedge} y)^n \psi = \lambda^{\wedge} (y^{\wedge n} \psi)$$

LHS =

A diagram showing a rectangle representing a closed loop. Inside the rectangle, there are three curved arrows pointing clockwise, indicating the direction of current flow around the loop.

$$= \boxed{k \quad \leftarrow \quad l+m}$$

A horizontal rectangle with a double-headed arrow inside. The left end of the arrow is labeled 'C' and the right end is labeled 'm'.

$$3. W_I = \left((\varphi_{i_1} \wedge \varphi_{i_2}) \wedge \varphi_{i_3} \right) \wedge \dots \wedge \varphi_{i_k}$$

$$(\varphi_{i_1} \wedge \varphi_{i_2} \wedge \dots \wedge \varphi_{i_k}) (u_1, \dots, u_k) =$$

↙ ↘

ANSWER

11

1

$\begin{array}{|c|c|c|c|c|c|c|} \hline & \swarrow & \searrow & \cdots & \cdots & \searrow \\ \hline \end{array}$ permutation

$$= \sum (-1)^6 (\varphi_{i_1} \dots \varphi_{i_k}) (u_{\sigma_1} \dots u_{\sigma_k})$$

$$= w_1$$

$$2. \lambda^n y = (-1)^{kl} y^l \lambda$$

$$\text{LHS} = \boxed{k, l}$$

$$\pi \leftarrow \gamma$$

$$RHS = (-1)^{k \times k} \begin{array}{c|cc} & l & l \\ \hline l & & n \end{array}$$

$$= (-1)^{k^2} \begin{array}{c|cc} & l & l \\ \hline l & & n \end{array}$$

Pullbacks $V \hookrightarrow W \quad \wedge^k V \leftarrow^* \wedge^k W$

e.g. $\dim V = n, \wedge^n V = \wedge^{\text{top}} V$
 \uparrow
 $1\text{-d space}, (\psi_1, \psi_2, \dots, \psi_n)$

Thm: $L: V \rightarrow V, L^*: \wedge^{\text{top}} V \rightarrow \wedge^{\text{top}} V$. is multiplication of $\det(L)$

If $w \in \wedge^{\text{top}}$, then $L^* w = \det(L) w$.

pf: $WLOG, w = w_{123\dots n} = \psi_1 \wedge \psi_2 \wedge \dots \wedge \psi_n$, where ψ_i s are dual basis
 for v_i s \leftarrow basis of V

(With) LOG: $n=3 \rightarrow$ 可以推广

$$L: V \rightarrow V = A \in M^{3 \times 3} \rightarrow \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

$$L^* w_{123}(v_{123}) = L^* w_{123}(v_1, v_2, v_3) \xrightarrow{\text{要一维的, 所以只需要验证一个 vector.}}$$

$$= w_{123}(Lv_1, Lv_2, Lv_3)$$

$$= \psi_1 \wedge \psi_2 \wedge \psi_3 (Lv_1, Lv_2, Lv_3)$$

拿定义直接就填

行列式

$$= \psi_1 \wedge \psi_2 \wedge \psi_3 \begin{pmatrix} a_{11}v_1 & a_{21}v_1 & a_{31}v_1 \\ a_{12}v_2 & a_{22}v_2 & a_{32}v_2 \\ a_{13}v_3 & a_{23}v_3 & a_{33}v_3 \end{pmatrix}$$

$$= \det(L) w_{123}.$$

DEF: An "orientation" of a dimension- n vector space is a

choice (v_1, \dots, v_n) of an ordered basis, two such

choices are considered the same if they change of basis matrix between them has determinant > 0

1. if (v_1, \dots, v_n) is a choice, $\overset{A}{\sim} (v'_1, \dots, v'_n) \overset{\text{same orientation}}{\sim} (v''_1, \dots, v''_n)$

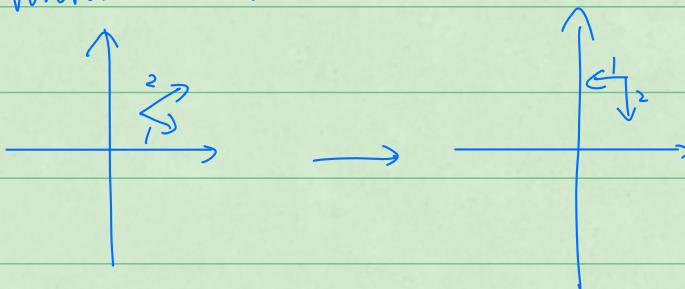
$\det A > 0, \det B > 0 \Rightarrow \det AB > 0$, so 1, 2 same.

2. Symmetric . $(v_1, \dots, v_n) \sim (v'_1, \dots, v'_n) \Rightarrow (v'_1, \dots, v'_n) \sim (v_1, \dots, v_n)$

3. $(v_1, \dots, v_n) \sim (v_n, \dots, v_1)$

e.g. Right (left) hand represent well-defined orientations in \mathbb{R}^3 in which we live

e.g.



e.g. Orientation of \mathbb{R}^1



(正向/負向)

every finite-dim vector space has exactly 2 orientation.

DEF: An "orientation" of the same vector space is a choice of $W \in \Lambda^{\text{top}} V$, $W \neq 0$.

W_1, W_2 is considered equivalent when $W_1 = \alpha W_2$ ($\alpha > 0$)

Thm: The two def are equivalent.

i.e. \forall vector space V , $\{\text{orientation}\} = \{\text{orientation}'\}$

We say that an orientation $w \in \Lambda^{\text{top}} V$ agrees

with orientation (v_1, \dots, v_n) if $W(v_1, \dots, v_n) > 0$,

$V \rightarrow W$

push/pull?

neither and both
if L is invertible.

in general

Tangent space: (nearly just language)

$p \in \mathbb{R}^n$, $(p, \overset{\leftarrow}{v})$ point in \mathbb{R}^n vector (direction) in \mathbb{R}^n .

$\xi \overset{\parallel}{\rightarrow}$ tangent vector to \mathbb{R}^n at p .

given p , $\{(p, v) \mid v \in \mathbb{R}^n\} = T_p \mathbb{R}^n = \mathbb{R}_p^n \Rightarrow$ the tangent space to \mathbb{R}^n at p .

$T_p \mathbb{R}^n$ is a vector space. $(\alpha(p, v_1) + \beta(p, v_2)) = (p, \alpha v_1 + \beta v_2)$

\mathbb{R}_p^n has an inner product $\langle (p, v_1), (p, v_2) \rangle = \langle v_1, v_2 \rangle$

--- norm: $\| (p, v) \| = \| v \|$

push/pull?

$\mathbb{R}^n \xrightarrow{F} \mathbb{R}^m$, $\xi = (p, v) \xrightarrow{F} (F(p), F'(p)v)$

可导

Claims: 1. $F_*: T_p \mathbb{R}^n \rightarrow T_{F(p)} \mathbb{R}^m$ is a linear map. (显然 - p 是良导)

2. $\boxed{\mathbb{R}^n} \xrightarrow{F} \boxed{\mathbb{R}^m} \xrightarrow{G} \boxed{\mathbb{R}^k}$

$(G \circ F)_*: T_p \mathbb{R}^n \rightarrow T_{G(F(p))} \mathbb{R}^k$.

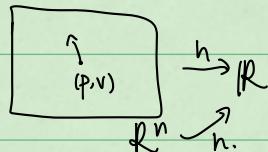
\downarrow
 $G_* \circ F_*$

$p \not\models: \xi = (p, v) . (G \circ F)_*(\xi) = (g(f(p)), (g \circ f)'(p)v)$

$= (g(f(p)), g'(f(p)) \cdot f'(p) \cdot v)$

$= g(f(\xi))$

$T_p \mathbb{R}^n \Leftrightarrow$ "directional derivatives at p "



$D_{(p,v)} h = D_{\vec{\zeta}}(h) =$ "directional derivative... of h in the direction of $\vec{\zeta}$ "

$$= \frac{d h(p+tv)}{dt} \Big|_{t=0}$$

If $p = (x_1, \dots, x_n)$, $v = (v_1, \dots, v_n)$,

$$\hookrightarrow \frac{d}{dt} h(x_1 + tv_1, \dots, x_n + tv_n) \Big|_{t=0}$$

$$\star = \frac{dh}{dx_1}(p) \cdot v_1 + \frac{dh}{dx_2}(p) \cdot v_2 + \dots + \frac{dh}{dx_n}(p) \cdot v_n.$$

$$= h'(p) \cdot v$$

i the instructors' answer, where instructors collectively construct a single answer

We view the function in 2 steps:

$$t \mapsto (x_1 + tv_1, \dots, x_n + tv_n) \mapsto h(x_1 + tv_1, \dots, x_n + tv_n)$$

The first map has derivative $\begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix}$ and the second map is h , so it has derivative $Dh = \left(\frac{\partial h}{\partial x_1}, \dots, \frac{\partial h}{\partial x_n} \right)$

So using the chain rule, the derivative of the whole things is $Dh \cdot \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} = \frac{\partial h}{\partial x_1} v_1 + \dots + \frac{\partial h}{\partial x_n} v_n$

thanks! | 1

followup discussions for lingering questions and comments

Claims : 1. "bilinear" $D_{\alpha\vec{\zeta}+\beta\vec{y}} h = \alpha D_{\vec{\zeta}} h + \beta D_{\vec{y}} h$.

\Rightarrow "D" 的本意是把 $h'(p)$ 作用在 v 上, 而 p 是同一个.

$$D_{\vec{\zeta}}(h) = D_{(v,p)} h$$

即 \vec{y} 只起系数作用

$$= h'(p) \cdot v.$$

$$D_{\vec{\zeta}}(\alpha h_1 + \beta h_2) = \alpha D_{\vec{\zeta}} h_1 + \beta D_{\vec{\zeta}} h_2.$$

$$2. Leibniz : D_{\vec{\zeta}}(f \cdot g) = f(p) D_{\vec{\zeta}} g + D_{\vec{\zeta}}(f) g(p)$$

$$\vec{\zeta} = (p, v)$$

前导后不得 + 后导前不得

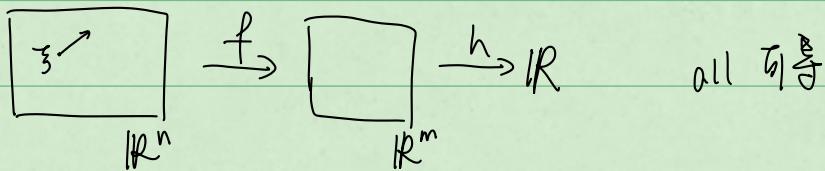
$$= \underbrace{\left(\sum_i v_i \frac{\partial}{\partial x_i} h \right)}_{\vec{\zeta}} \Big|_P$$

$$(P, \vec{\zeta}) \sim 2 \frac{\partial}{\partial x} + 3 \frac{\partial}{\partial y}$$

$$\sim 2 \partial_x + 3 \partial_y$$

$\sim 2\partial_1 + 3\partial_2$.

Claim: pushing vectors is compatible with pulling functions.



$$v \in T_p \mathbb{R}^n, \quad h: \mathbb{R}^m \rightarrow \mathbb{R} \quad f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$D_{f^*v} h = D_v (f^* h)$$

$$\text{pf: } D_{f^*v} h = D_{(f \circ \varphi)^*(\varphi(p))} h \quad D_{(\varphi, v)} h = h'(\varphi) \cdot v$$

$$= h'(f(\varphi)) \cdot (f'(\varphi) \cdot v)$$

$$= (h \circ f)'(\varphi) \cdot v$$

$$= D_v (h \circ f)$$

$$= D_v (f^* h)$$

DEF: a vector field on \mathbb{R}^n is

$$F: \mathbb{R}^n \rightarrow \bigcup_{p \in \mathbb{R}^n} T_p \mathbb{R}^n, \text{ s.t. } F(p) \in T_p \mathbb{R}^n$$

$$F(p) = (p, \sum F^i(p) e_i), \quad F^i(p): \mathbb{R}^n \rightarrow \mathbb{R}, \text{ the component functions of } F.$$

$$= \sum F^i(p) \frac{\partial}{\partial x_i}$$

F is continuous/differentiable \Rightarrow $\forall i, F^i$ is continuous/differentiable.

$$(D_F h)(p) = D_{F(p)} h$$

可以求向量场 (标量或函数). i.e. $g: \mathbb{R}^n \rightarrow \mathbb{R}$, $F \mapsto gF = (g p, v)$.

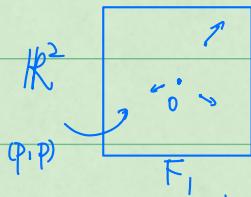
可以计算两个向量场的内积: 在点 p 算 v, v 的内积, 就变成了 $\mathbb{R}^n \rightarrow \mathbb{R}$ 的 map

$T_p \mathbb{R}^n$

该这个也有怪异感.

$$F(p) = \sum_{i=1}^n F_i(p)(p, e_i) = \sum_i F_i(p) \partial_i \quad (\text{本段是 v.F. } \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ 的函数})$$

e.g.



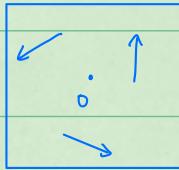
$$\text{at } p = (x, y), \quad v = (x, y) = x(\downarrow) + y(\uparrow) \\ = x\partial_x + y\partial_y$$

the radial v.F.

$$D_{F_1}(x^2+y^2) = x\partial_x(x^2+y^2) + y\partial_y(x^2+y^2) = 2x^2+2y^2$$

在每一点或导会越大值所以是 function.

e.g.



垂直相等

$$p = (x, y) \quad v = \begin{pmatrix} \cos 90^\circ, -\sin 90^\circ \\ \sin 90^\circ, \cos 90^\circ \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ x \end{pmatrix}$$

 F_2

$$F_2 = -y\partial_x + x\partial_y$$

$$D_{F_2}(x^2+y^2) = -y\partial_x x^2 + x\partial_y y^2 = 0.$$

DEF: A k -form on \mathbb{R}^n is a function $W: \mathbb{R}^n \rightarrow \bigcup_{p \in \mathbb{R}^n} \Lambda^k(T_p \mathbb{R}^n)$

$$\text{s.t. } W(p) \in \Lambda^k(T_p \mathbb{R}^n)$$

同构!

$$W_I(p)((p, v_1), \dots, (p, v_k)) = W_I(v_1, \dots, v_k)$$

端那个

因为依赖于 p 的位置

$$\text{Now, given a } k\text{-form, } W, \quad W(p) = \sum_{I \in \Lambda^k} \lambda_I(p) W_I(p)$$

 $\hookrightarrow \mathbb{R}^n \rightarrow \mathbb{R}$, coefficient functions.

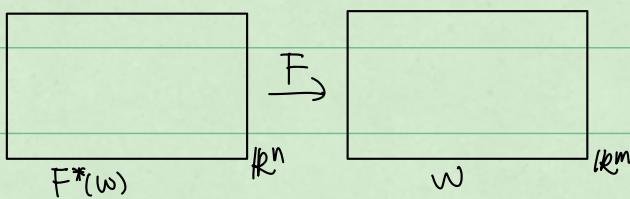
DEF: W is cont. / diffable / C^r if $\forall I, \lambda_I(p)$

is

DEF: $\Omega^k(\mathbb{R}^n) = \left\{ \text{all } C^\infty \text{ k-forms in } \mathbb{R}^n \right\} = \text{"difiable k-forms"}$

Technologies: +, $\times S$ (scalar), $\times g$ (function), $\wedge: \Omega^k(\mathbb{R}^n) \times \Omega^l(\mathbb{R}^n) \rightarrow \Omega^{k+l}(\mathbb{R}^n)$
 $w \stackrel{+}{\mapsto} w$, $w \stackrel{\times S}{\mapsto} w$, $w \stackrel{\times g}{\mapsto} w$, $w \stackrel{\wedge}{\mapsto} w$
 $w^\gamma(p) = w(p)^\gamma \eta(p) \quad (p \in \mathbb{R}^n)$
 这意味着乘法被包含在 \wedge 里的。

difiable forms pull. $F: \mathbb{R}^n \rightarrow \mathbb{R}^m \Rightarrow F^*: \Omega^k(\mathbb{R}^m) \rightarrow \Omega^k(\mathbb{R}^n)$



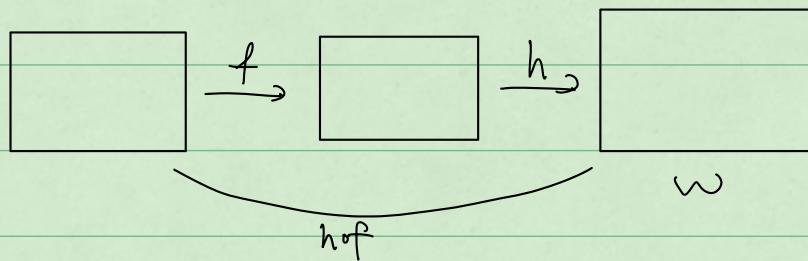
$w \quad ? \quad F^*w$

$$f^*(w)(p) (\xi_1, \xi_2, \dots, \xi_k) = w(f(p)) (f^*(\xi_1), \dots, f^*(\xi_k)) \quad (f^*(v_p) = (Df(p)v)_{f(p)})$$

31的p相同
 $f^*(w)$ 是 $\mathbb{R}^n \rightarrow \mathbb{R}^k$ 的, 所以 $f^*(w)(p)$ 才是一个 k , 从而才能喂 (ξ_1, \dots, ξ_k)

Thm: pulling diff forms is compatible with everything (all the operations above)

- $F^*(w_1 + w_2) = F^*(w_1) + F^*(w_2)$
- $F^*(7w) = 7F^*(w)$
- if $g: \mathbb{R}^n \rightarrow \mathbb{R}$, $F^*(gw) = F^*(g) \cdot F^*(w)$
- $F^*(w^\gamma) = F^*(w)^\gamma F^*(\gamma)$
- contravariance.



$$(h \circ f)^*(w) = f^*(h^*(w))$$

If $f \in \Omega^0(\mathbb{R}^n) = C^\infty(\mathbb{R}^n)$,

这个就是f和w的加起来。

$w \in \Omega^k \mathbb{R}^n$, then $f^* w \in \Omega^{k-1} \mathbb{R}^n$

就是相当 w 和 f function 的 compose

Claim: If $w \in \Omega^k \mathbb{R}^n$, $\eta \in \Omega^l \mathbb{R}^m$, $g: \mathbb{R}^n \rightarrow \mathbb{R}^m$ smooth.

$$(i) g^*(w^\wedge \eta) = g^*(w) \wedge g^*(\eta) \in \Omega^{k+l}(\mathbb{R}^m)$$

pf: By def: $g^*(w^\wedge \eta)(\xi_1, \dots, \xi_{k+l}) \quad \xi_i \in T_p \mathbb{R}^n$

$$= w^\wedge \eta(g\xi_1, \dots, g\xi_{k+l})$$

$$= \frac{1}{k!l!} \sum_{\sigma \in S_{k+l}} (-1)^\sigma w(g\xi_{\sigma(1)}, \dots, g\xi_{\sigma(k)}) \cdot \eta(g\xi_{\sigma(k+1)}, \dots, g\xi_{\sigma(k+l)})$$

$$\text{RHS} = (g^* w) \wedge (g^* \eta)(\xi_1, \dots, \xi_{k+l})$$

$$= \frac{1}{k!l!} \sum_{\sigma} (-1)^\sigma g^* w(\xi_{\sigma(1)}, \dots, \xi_{\sigma(k)}) \cdot g^* \eta(\xi_{\sigma(k+1)}, \dots, \xi_{\sigma(k+l)})$$

相等.

$$d: \underbrace{\Omega^0(\mathbb{R}^n)}_{\text{functions}} \rightarrow \underbrace{\Omega^1(\mathbb{R}^n)}_{\text{tangent vectors}}$$

(later: $\Omega^k \rightarrow \Omega^{k+1}$)

$\frac{\partial}{\partial x_i}$ - i tangent vector,

at \vec{x} .

DEF: $(dF)(\vec{x}) = D_{\vec{x}} F \stackrel{\vec{v}}{=} F(p) \cdot \vec{v}$ 在 p 点的向量 v 的 directional derivative.

$$= \sum v_i \frac{\partial F}{\partial x_i}$$

$$= \sum_{i=1}^n \lambda_i(p) w_i = \sum_{i=1}^n \lambda_i(p) \psi_i(v) = \sum_{i=1}^n \lambda_i(p) v_i$$

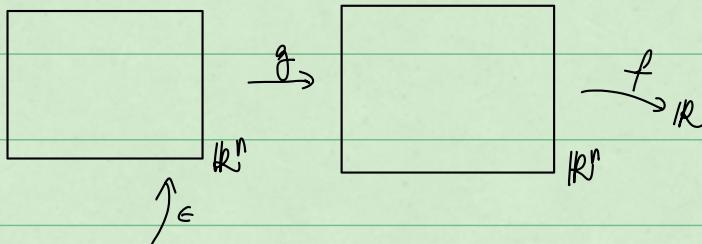
$$\lambda_i = \frac{\partial F}{\partial x_i}$$

$$dF = \sum \frac{\partial F}{\partial x_i} \cdot \psi_i \quad (\text{projection map}), \mathbb{R}^n \rightarrow \mathbb{R}, p \mapsto \vec{v}$$

$$F = x_j \Rightarrow dF = \psi_j.$$

$$dF = \sum \frac{\partial F}{\partial x_i} dx_i$$

- d is linear. $d(\alpha f + \beta g) = \alpha df + \beta dg$
- Leibniz Rule: $d(f \cdot g) = (df)g + f(df)$
- Compatible with pull-backs: $d(g^*f) = g^*(df)$



$$\begin{aligned} d(g^*f)(\xi) &= D_g(g^*f) && \text{LHS} \\ &\stackrel{?}{=} && \text{前面已经证明过等式成立了.} \\ g^*df(\xi) &= df(g(\xi)) = Dg(\xi)(f) && \text{RHS} \end{aligned}$$

e.g.

$$\begin{array}{ccc} \boxed{\quad} & \xrightarrow{g: (\rho) \rightarrow \left(\begin{matrix} r \cos \theta \\ r \sin \theta \end{matrix} \right)} & \boxed{\quad} \\ \mathbb{R}_{>0}^2 & & \mathbb{R}_{>0}^2 \times \mathbb{S}^1 \end{array}$$

$$\begin{cases} dx, dy \text{ are 1-forms.} \\ = \psi_1 \wedge \psi_2 = \omega_{12}. \end{cases}$$

Can we compute $g^*(dx \wedge dy)$?

$$g^*(dx \wedge dy) = g^*(dx) \wedge g^*(dy)$$

$$= d(g^*x) \wedge d(g^*y)$$

$$= d(r \cos \theta) \wedge d(r \sin \theta)$$

$$= \left(\frac{\partial r \cos \theta}{\partial r} dr + \frac{\partial r \cos \theta}{\partial \theta} d\theta \right) \wedge \left(\frac{\partial r \sin \theta}{\partial r} dr + \frac{\partial r \sin \theta}{\partial \theta} d\theta \right)$$

$$= (r \cos \theta dr - r \sin \theta d\theta) \wedge (r \sin \theta dr + r \cos \theta d\theta)$$

$$= r \cos^2 \theta dr \wedge d\theta - r \sin^2 \theta d\theta \wedge dr.$$

$$= r dr \wedge d\theta$$

anti-symmetric for odd

$$d: \Omega^k(\mathbb{R}^n) \Rightarrow \Omega^{k+1}(\mathbb{R}^n)$$

这里的顺序重要，上面因为 commute 所以顺序无所谓。

DEF: $d\omega = \sum_{i=1}^n dx_i \wedge \frac{\partial \omega}{\partial x_i}$ ← 和之前不一致 agree.

if $\omega = \sum_{i=1}^n \lambda_i dx_i$, then $\frac{\partial \omega}{\partial x_i} = \sum_{i=1}^n \frac{\partial \lambda_i}{\partial x_i} dx_i$

$$\text{e.g.: } \theta = \frac{y}{x+y} dx - \frac{x}{x+y} dy \in \Omega^1(\mathbb{R}_{x,y})$$

$$d\theta = dx \wedge \frac{\partial \theta}{\partial x} + dy \wedge \frac{\partial \theta}{\partial y}$$

$$= dx \wedge \left(\underbrace{-dx - \frac{x^2+y^2-2xy}{(x^2+y^2)^2} dy}_{dx^2=0} \right) + dy \wedge \left(\frac{x^2+y^2-2x^2}{(x^2+y^2)^2} dx \right)$$

是-该也错了

$$= \frac{x^2-y^2}{(x^2+y^2)^2} dx \wedge dy - \frac{x^2-y^2}{(x^2+y^2)^2} dx \wedge dy$$

$$= 0$$

$$\begin{aligned} d(fdx + gdy) &= dx \frac{\partial f}{\partial x} + dy \frac{\partial g}{\partial y} \\ &= dx \frac{\partial g}{\partial x} + dy \frac{\partial f}{\partial y} \\ &= \left(\frac{\partial f}{\partial x} - \frac{\partial g}{\partial y} \right) dx \wedge dy \end{aligned}$$

Thm: d ← exterior derivative.

$$\textcircled{1} \text{ linear, } d(a\omega - b\eta) = ad\omega - bd\eta.$$

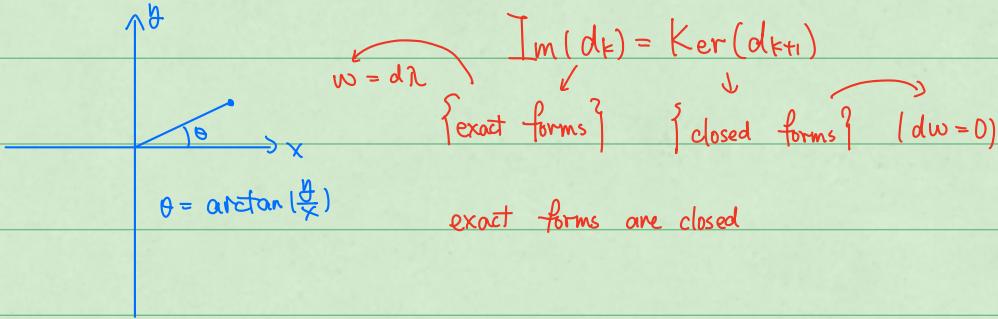
$$\textcircled{2} \text{ Leibniz } d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^{|\omega|} \omega \wedge d\eta$$

$$\textcircled{3} \quad d^2 \equiv 0 \quad (\text{really: } d_k : \Omega^k \rightarrow \Omega^{k+1})$$

$$\Omega^k \xrightarrow{d_k} \Omega^{k+1} \xrightarrow{d_{k+1}} \Omega^{k+2}$$

$$d_{k+1} \circ d_k \equiv 0$$

e.g.



$$d\theta = dx \frac{\partial \theta}{\partial x} + dy \frac{\partial \theta}{\partial y}$$

$$= \int \left(\frac{1}{1+y^2} \right) \frac{1}{x} dy$$

$$= -\frac{y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy \quad \text{和上题一样.}$$

$$\oplus g^* d(w) = d(g^* w)$$

pf of ②:

$$\begin{aligned} d(w \wedge \eta) &= \sum dx_i \wedge \left(\frac{\partial w \wedge \eta}{\partial x_i} \right) \\ &= \sum dx_i \wedge \left(\frac{\partial w}{\partial x_i} \wedge \eta + w \wedge \frac{\partial \eta}{\partial x_i} \right) \\ &= \sum \left(dx_i \wedge \frac{\partial w}{\partial x_i} \right) \wedge \eta + (-1)^w w \wedge dx_i \wedge \frac{\partial \eta}{\partial x_i} \\ &= (dw) \wedge \eta + (-1)^w w \wedge dy \end{aligned}$$

$$\text{claim: } \frac{\partial (w \wedge \eta)}{\partial x_i} = \left(\frac{\partial w}{\partial x_i} \right) \wedge \eta + w \wedge \left(\frac{\partial \eta}{\partial x_i} \right)$$

$$\text{WLOG: } w = f dx_i, \quad \eta = g dx_j$$

$$\begin{aligned} w \wedge \eta &= f g dx_i \wedge dx_j \\ \frac{\partial w \wedge \eta}{\partial x_i} &= \left(\frac{\partial f}{\partial x_i} g \right) dx_i \wedge dx_j \end{aligned}$$

$$= (f_{x_i} g + f g_{x_i}) dx_i \wedge dx_j$$

pf of 3: $d(dw) \stackrel{?}{=} 0$

$d(dx_i) = 0$, 因为 dx_i 为常数

$$\begin{aligned} d(dw) &= d\left(\sum dx_i \wedge \frac{\partial w}{\partial x_i}\right) \\ &\stackrel{\text{①}}{=} \sum d\left(dx_i \wedge \frac{\partial w}{\partial x_i}\right) \end{aligned}$$

$$\begin{aligned} &\stackrel{\text{②}}{=} \sum \underbrace{d(dx_i) \wedge \frac{\partial w}{\partial x_i}}_{0} - dx_i \wedge d\left(\frac{\partial w}{\partial x_i}\right) \\ &= - \sum dx_i \wedge d\left(\frac{\partial w}{\partial x_i}\right) \\ &= - \sum dx_i \wedge \left(\sum dx_j \wedge \frac{\partial^2 w}{\partial x_i \partial x_j} \right) \\ &= - \sum dx_i \wedge dx_j \wedge \left(\frac{\partial^2 w}{\partial x_i \partial x_j} \right) \\ &\stackrel{i,j, \text{ 成对出现}}{=} 0 \end{aligned}$$

pf of 4: WLOG: $w = f \wedge dy_I$

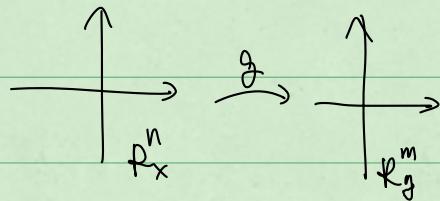
$$g^*(dw) = g^*\left((df) \wedge dy_I + f \wedge d(dy_I)\right)$$

$$= g^*((df) \wedge dy_I)$$

function.

$$= f^*(df) \wedge g^*(dy_I)$$

$$= d(f^* f) \wedge d(f^* y_{i_1}) \wedge \dots \wedge d(f^* y_{i_k})$$



$$dy_I = dy_{i_1} \wedge \dots \wedge dy_{i_k}$$

$$d(dy_I) = \sum (-1)^j dy_{i_1} \wedge \dots \wedge d(dy_{i_j}) \wedge \dots \wedge dy_{i_k}$$

易-边:

$\Rightarrow 0$

$$d(f^* w) = d(f^* f \wedge dy_1 \wedge \dots \wedge dy_k)$$

$$= d(f^* f \wedge g^* dy_1 \wedge \dots \wedge g^* dy_k)$$

$$= d(f^* f) \wedge g^* dy_1 \wedge \dots \wedge g^* dy_k$$

Liebnitz, 其它项都是0.

$dW(\bar{z}_1, \dots, \bar{z}_{k+1})$ $\xrightarrow{k+1 \text{ form}}$ $\xrightarrow{k \text{-form}}$ $\xrightarrow{\text{相加个平面}} \quad \xrightarrow{\text{左边这个平行四边形积分}}$

$$= \sum_{i=1}^{k+1} \pm W_p(\bar{z}_1, \dots, \hat{\bar{z}_i}, \dots, \bar{z}_{k+1})$$

$$\pm W_{p+i}(\bar{z}_1, \dots, \hat{\bar{z}_i}, \dots, \bar{z}_{k+1})$$

$$\int_{P(\bar{z}_1, \dots, \bar{z}_{k+1})} dw = \int_{\partial P}$$

↑ don't use

Thm: with $\bar{z}_i = (p, v_i)$, $w \in \Omega^k(\mathbb{R}^n)$

$$(dw)(\bar{z}_1, \dots, \bar{z}_{k+1}) = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{k+1}} \sum_{i=1}^{k+1} (-1)^{i-1} \left(w(p + \varepsilon v_i) (\varepsilon v_1, \dots, \hat{\varepsilon v_i}, \dots, \varepsilon v_{k+1}) - w(p) (\varepsilon v_1, \dots, \hat{\varepsilon v_i}, \dots, \varepsilon v_{k+1}) \right)$$

pf: WLOG, $w = f \wedge \lambda$, λ has 常系数.

$$dw = d(f \wedge w) = df \wedge w + f \wedge dw$$

$$= (df) \wedge w$$

$$(dw)(\bar{z}_1, \dots, \bar{z}_{k+1}) = (df \wedge \lambda)(\bar{z}_1, \dots, \bar{z}_{k+1}) \quad (\text{LHS})$$

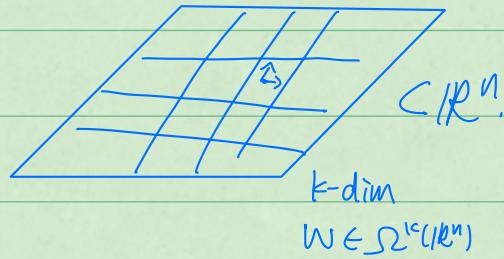
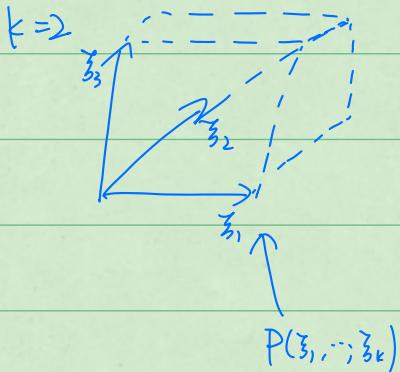
\downarrow \downarrow \downarrow
 $df(\cdot, \lambda(\dots))$
x x x x x x

$$= \sum_{i=1}^{k+1} (-1)^{i-1} df(\bar{z}_i) \cdot \lambda(\bar{z}_1, \dots, \hat{\bar{z}_i}, \dots, \bar{z}_{k+1})$$

$$= \sum_{i=1}^{k+1} (-1)^{i-1} D_{\vec{\zeta}_i}(f) \lambda(\vec{\zeta}_1, \dots, \hat{\vec{\zeta}_i}, \dots, \vec{\zeta}_{k+1})$$

用皮型ε消掉前面

$$\begin{aligned} RHS &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \sum_{i=1}^{k+1} (-1)^{i-1} \left(f(p + \varepsilon v_i) - f(p) \right) \lambda(v_1, \dots, \hat{v_i}, \dots, v_{k+1}) \\ &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \sum_{i=1}^{k+1} (-1)^{i-1} \left(f(p + \varepsilon v_i) - f(p) \right) \lambda(v_1, \dots, \hat{v_i}, \dots, v_{k+1}) \\ &= \sum_{i=1}^{k+1} (-1)^{i-1} \left(\lim_{\varepsilon \rightarrow 0} \frac{f(p + \varepsilon v_i) - f(p)}{\varepsilon} = D_{\vec{\zeta}_i} f \right) \lambda(v_1, \dots, \hat{v_i}, \dots, v_{k+1}) = LHS. \end{aligned}$$

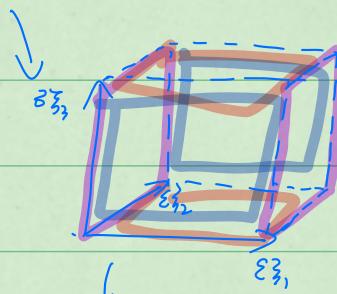
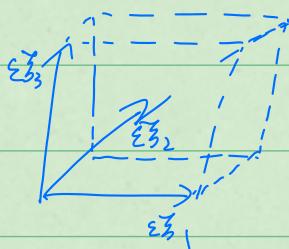


LHS: ~~$\lim_{\varepsilon \rightarrow 0} \sum_{i=1}^{k+1} (-1)^{i-1} (d w)(\varepsilon \vec{\zeta}_1, \dots, \varepsilon \vec{\zeta}_{k+1})$~~

$$\lim_{\varepsilon \rightarrow 0} \sum_{i=1}^{k+1} (-1)^{i-1} \left(w(p + \varepsilon v_i) (\varepsilon v_1, \dots, \hat{\varepsilon v_i}, \dots, \varepsilon v_{k+1}) - w(p) (\varepsilon v_1, \dots, \hat{\varepsilon v_i}, \dots, \varepsilon v_{k+1}) \right)$$

Small ε .

$(k+1) \times 2 \uparrow$ polygon



$i=1$
 $i=2$
 $i=3$

$$\int_P d w = LHS$$

$$\int_W$$

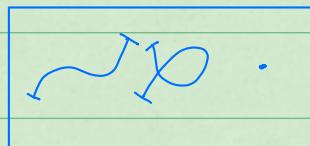
$$df(\vec{\zeta}) = \lim \frac{1}{\varepsilon} (f(p + \varepsilon v) - f(p))$$



DEF: A singular k -cube in $A \subset \overset{\text{open}}{R^n}$

is a cont function $I^k = [0,1]^k \rightarrow \mathbb{R}^n$

3 1-cube in \mathbb{R}^2 :



0-cube:

a point

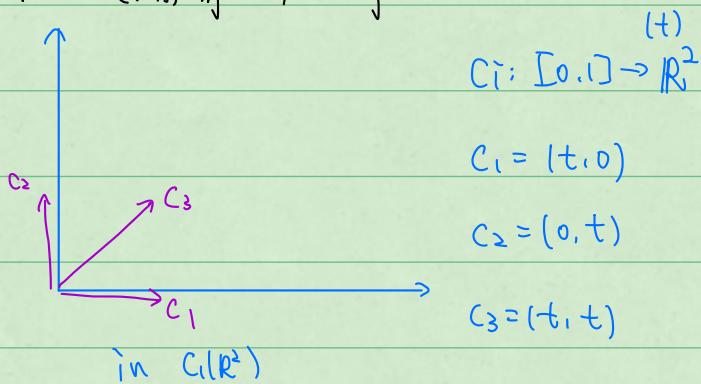
2-cube:



$C_k(A) = \left(\begin{array}{l} \text{space of} \\ k\text{-chains} \\ \text{in } A \text{ over } \mathbb{Z} \end{array} \right) = \left(\begin{array}{l} \text{The free abelian group} \\ \text{generated by all } k\text{-cubes in } A \end{array} \right)$

$$= \left\{ \sum_{i=1}^p \alpha_i c_i \mid \alpha_i \in \mathbb{Z}, c_i : I^k \rightarrow A \right\} \quad (\text{顺序不重要 / can drop 0's / 分配律})$$

• $\overline{\text{b}}_1$ 加, $C_k(A)$ 有 "+", "x", 无 "0"



goal
 $\partial: C_k(A) \rightarrow C_{k-1}(A)$

phase maps?

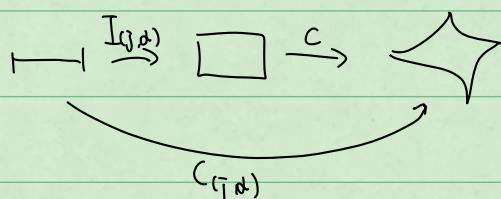
DEF: $I_{(j,\alpha)}^k \in C_{k-1}(I^k)$ $j \in \underline{k}$ $\alpha \in \{0,1\}^j$

$$\hookrightarrow I_{j,y_{j-1}}^{k-1} \rightarrow I_{x_1, \dots, x_k}^k$$

$$I_{(j,\alpha)}^k (y_1, \dots, y_{k-1}) = (y_1, \dots, y_{j-1}, \alpha_j, y_j, \dots, y_{k-1})$$

$$\text{if } c: I^k \rightarrow A, \quad C_{(j,\alpha)} = c \circ I_{(j,\alpha)}$$

C_k^1 (右导)



DEF: $\partial c = \sum_{j \in k} (-1)^{j+\alpha} C_{(j,\alpha)} \in C_{k-1}(A)$

Extend linearly to $C_k(A) : \partial(\sum a_i c_i) = \sum a_i \partial c_i$

$$C \in C_2(\mathbb{R}^2) \quad \text{---} \quad C(x, y) = (x, y)$$

$$\partial C = -C_{(1,0)} + (c_{1,1}) + C_{(2,0)} - C_{(2,1)}$$

$$= -(0, t) + (1, t) + (t, 0) - (t, 1) \quad \text{在第2个位置放1. 剩下保持}$$

$$C_0(\mathbb{R}^2) \ni \partial(\partial C) = -\partial(0, t) + \partial(1, t) + \partial(t, 0) - \partial(t, 1)$$

$$= -(\cancel{(0,1)} - \cancel{(0,0)}) + (\cancel{(1,1)} - \cancel{(1,0)}) + (\cancel{(1,0)} - \cancel{(0,0)}) - (\cancel{(1,1)} - \cancel{(0,1)})$$

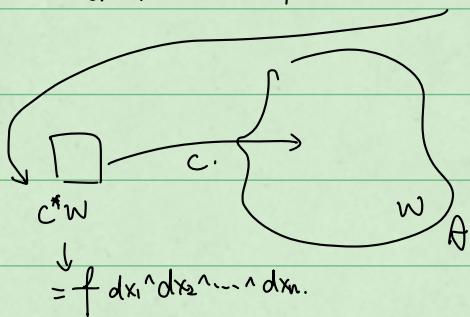
$$= 0$$

Thm: $\partial^2 = 0 \quad (C_k(A) \xrightarrow{\partial} C_{k-1}(A) \xrightarrow{\partial} C_{k-2}(A))$

$$\underbrace{\quad}_{\partial^2}$$

Integration: $\int_C w$

C is a k -chain, w is a k -form.



$$\text{DEF: } \int_{I_{x_1, \dots, x_k}}^k f dx_1 \wedge \dots \wedge dx_k = \int_{I^k} f$$

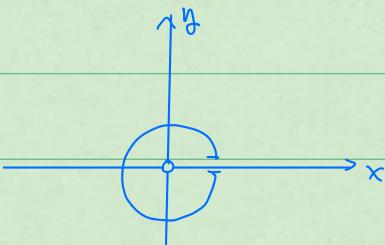
$$\int_C w = \int_{I^k} C^* w \quad (C^k : I^k \rightarrow A, w \in \Omega^k(A))$$

$$\int_{\sum a_i c_i} w = \sum a_i \int_{C_i} w$$

e.g. 1: $k=1, n=2, A=\mathbb{R}^2 \setminus \{0\}$

$$w = \frac{-y dx}{x^2+y^2} + \frac{x dy}{x^2+y^2}$$

$$C \in C_1(A) \quad C : I \rightarrow A = \mathbb{R}^2 \setminus \{0\}$$

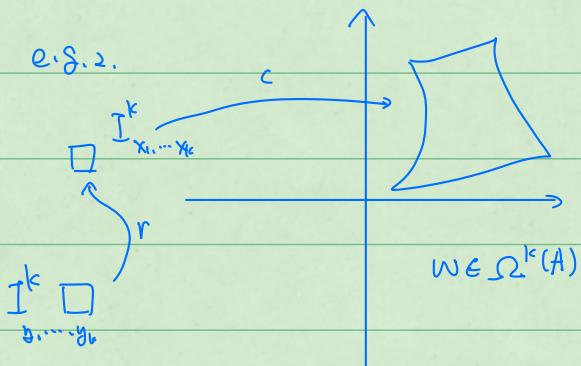


$$c(t) = \begin{pmatrix} \cos 2\pi t \\ \sin 2\pi t \end{pmatrix}$$

$$\begin{aligned} \int_C w &= \int_{I=[0,1]} c^* w = \int_0^1 \frac{-\sin 2\pi t \cos 2\pi t}{1} + \frac{\cos 2\pi t \sin 2\pi t}{1} dt \\ &= \int_0^1 2\pi (+\sin^2 2\pi t + \cos^2 2\pi t) dt \\ &= \int_0^1 2\pi dt = \int_0^1 2\pi (1) = 2\pi \end{aligned}$$

e.g. 0: $k=0$, w anything $w = f \sqcup$

$$\int_{\sum a_i p_i} f = \sum a_i f(p_i)$$



i) c 不重合, image(c) 重合

ii) $\int_C w = \int_{Cor} w$ provided $r: I^k \rightarrow I^k$, which is C^1 , 1-1 and onto,
 $\det(r') > 0$ (r is orientation-preserving).

pf: $\int_{Cor} w = \int_{I^k} (Cor)^* w = \int_{I^k} r^*(c^* w) = \int_{I^k} r^*(f dx_1 \wedge \dots \wedge dx_k)$

write $c^* w = f dx_1 \wedge \dots \wedge dx_k$

$$\begin{aligned} &= \int_{I^k} (f \circ r) \cdot r^*(dx_1 \wedge \dots \wedge dx_k) \\ &= \int_{I^k} (f \circ r) \cdot |\det(r')| \cdot dy_1 \wedge \dots \wedge dy_k \\ &\quad (\text{or } = \int_{r(I^k)} f dy_1 \wedge \dots \wedge dy_k) \\ &= \int_{I^k} f dy_1 \wedge \dots \wedge dy_k \\ &= \int_{I^k} c^* w \\ &= \int_C w \end{aligned}$$

\mathbb{R}^3

$$\mathcal{Q}^0 \rightarrow \mathcal{Q}^1 \rightarrow \mathcal{Q}^2 \rightarrow \mathcal{Q}^3$$

$$\begin{array}{c}
 \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\
 \left\{ f \right\} \xrightarrow{\text{grad}} \left\{ \begin{array}{l} f_1 dx_1 \\ + f_2 dx_2 \\ + f_3 dx_3 \end{array} \right\} \xrightarrow{\text{curl}} \left\{ \begin{array}{l} f_1 dx_1 dx_3 \\ + f_2 dx_2 dx_1 \\ + f_3 dx_1 dx_2 \end{array} \right\} \xrightarrow{\text{div}} \left\{ g dx_1 dx_2 dx_3 \right\}
 \end{array}$$

vector space

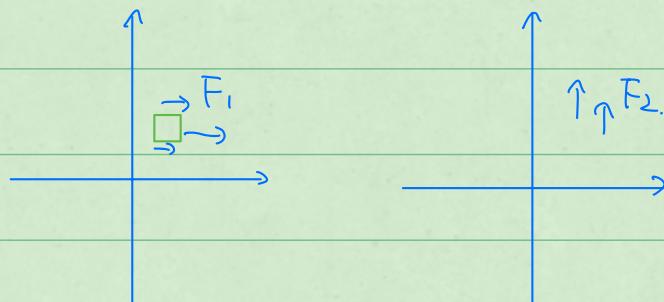
$$\text{div}(G) = \partial_1 G_1 + \partial_2 G_2 + \partial_3 G_3$$

$$\text{curl } F = \begin{pmatrix} \partial_2 F_3 - \partial_3 F_2 \\ \partial_3 F_1 - \partial_1 F_3 \\ \partial_1 F_2 - \partial_2 F_1 \end{pmatrix}$$

$$\text{grad } F = \begin{pmatrix} \partial_1 F \\ \partial_2 F \\ \partial_3 F \end{pmatrix}$$

↪ direction of fastest increasing

$$\text{div: } F = \begin{pmatrix} F_1 \\ F_2 \end{pmatrix}, \quad \text{div}(F) = \partial_1 F_1 + \partial_2 F_2$$

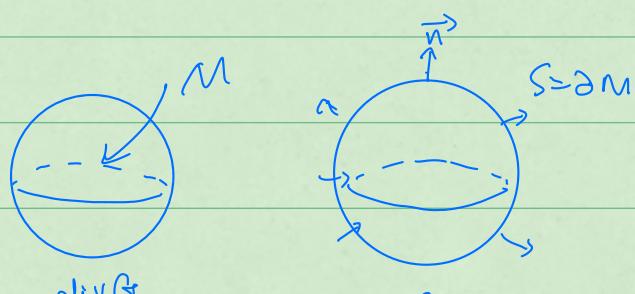


(在某一點測量了之後)

$$\text{curl: } (\text{Curl } F)_3 = \partial_1 F_2 - \partial_2 F_1$$

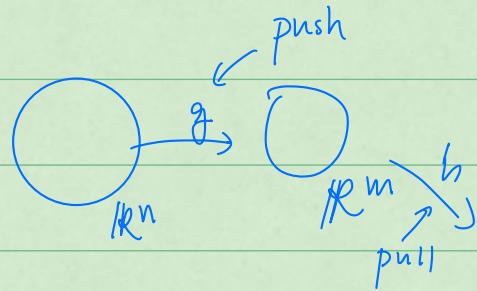
$\begin{pmatrix} F_1 \\ F_2 \end{pmatrix}$

measures spins.



$$\int_M \operatorname{div} G = \int_{\partial M} G \cdot \vec{n} dA \quad (\text{Gauss's Thm})$$

$\stackrel{M}{\int} \quad \stackrel{\partial M}{\int} \quad \stackrel{G}{\cdot}$

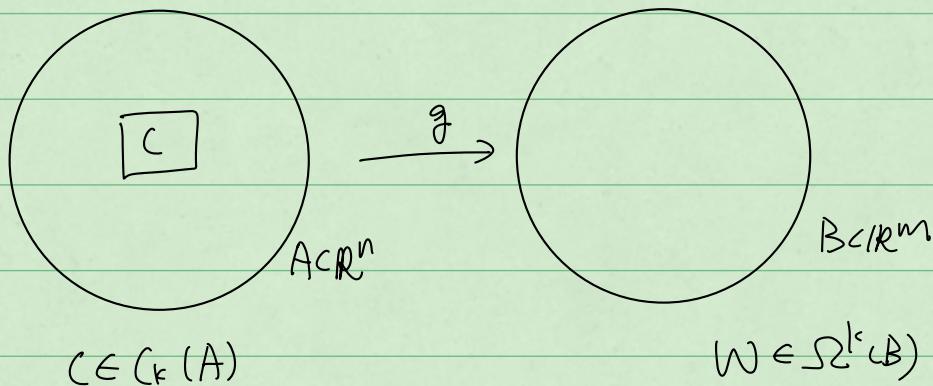
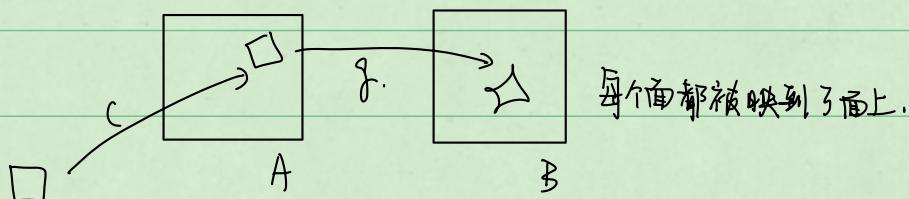


Cubes / Chains push.

$$g: A \xrightarrow{\cup R^n} B \Rightarrow g_*: C_k(A) \rightarrow C_k(B)$$

g_* is compatible with "+" " \times "

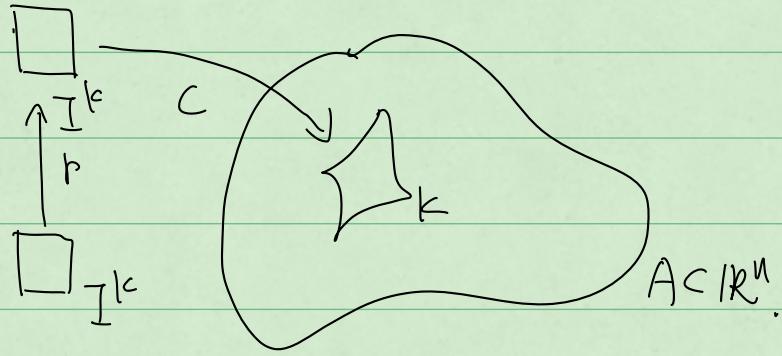
... - - - - " ∂ " i.e., $\partial(g_* c) = g_*(\partial c)$



prop: $\int_C g^* w = \int_{g^* C} w$

pf: LHS = $\int_{I^k} c^*(g^* w)$ $\stackrel{?}{=}$

RHS = $\int_{I^k} (g_* c)^* w$



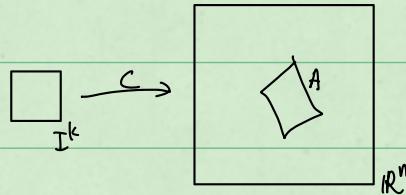
$C: I^k \rightarrow A$, $W \in \Omega^k(A)$, $r: I^k \rightarrow I^k$, 1-1, onto, $\det r^* > 0$

$$\int_C W = \int_{\partial C} w$$

Prop: $C: I^n \rightarrow \mathbb{R}^n_{(x_1, \dots, x_n)}$ one to one, $\det C' > 0$.

Let $A = C(I^n)$. Suppose also $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is given,

$$\text{Then } \int_A f = \int_C f \, dx_1 \dots dx_n.$$



$$pf: \int_A f = \int_C (f \circ C) \cdot \det(C'), \text{ COV.}$$

Thm: Given $C \in C_k'(A \subset \mathbb{R}^n)$ & $w = \Omega^{k-1}(A)$, then $\int_C dw = \int_{\partial C} w$

pf: $WLGF$, C is a single cube,

$$\int_C dw = \int_{I^k} C^*(dw) = \int_{I^k} d(C^*w) \stackrel{?}{=} \int_{\partial I^k} C^*w = \int_{C(\partial I^k)} w$$

$$= \int_{\partial(C \cap I^k)} w = \int_{\partial C} w$$

So we only have to show "?".

Assume $w \in \Omega^{k-1}(I^k)$, WLOG, $w = f \cdot dx_1 \wedge \dots \wedge \hat{dx_i} \wedge \dots \wedge dx_k$

$$= f \cdot dx_{\text{no } i} \quad (\text{notation})$$

$$\text{LHS} = \int_{I^k} dw = \int_{I^k} (-1)^{i-1} \frac{\partial f}{\partial x_i} (dx_1 \wedge \dots \wedge dx_k) = (-1)^{i-1} \int_{I^k} \frac{\partial f}{\partial x_i} \frac{\text{Fubini}}{\text{FTC}}$$

Fundamental
thm calc

$$= (-1)^{i-1} \int_{I^{k-1}} \left[F(y_1, \dots, \overset{i}{\underset{\sim}{y}}, \dots, y_{k-1}) - F(y_1, \dots, 0, \dots, y_{k-1}) \right]$$

$$\text{RHS} = \int_{\partial I^k} f dx_{\text{no } i} = \sum_{j=1}^k \sum_{\alpha \in \{0,1\}^j} (-1)^{j+\alpha} \int_{I_{j,k}} f dx_{\text{no } i} =$$

$$\sum_{j,k} (-1)^{j+\alpha} \int_{I_{j,k}} (f \circ I_{j,k}) \cdot d(x_1 \circ I_{j,k}) \wedge \dots \wedge d(x_i \circ I_{j,k}) \wedge \dots \wedge d(x_{k+1} \circ I_{j,k})$$

the function x_j is constant on the image of $I_{j,k}$

So $(x_j \circ I_{j,k})$, $\rightarrow \text{constant} \rightarrow d(x_j \circ I_{j,k}) = 0$

$$\hookrightarrow j \text{ to } \hat{y}^k = i$$

$$= \sum_{\alpha} (-1)^{j+\alpha} \int_{I_{j,k}} f(y_1, \dots, \overset{i}{\underset{\sim}{y}}, \dots, y_{k-1}) dy_1 \wedge \dots \wedge dy_{k-1}$$

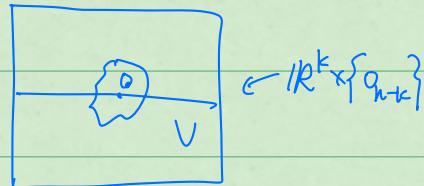
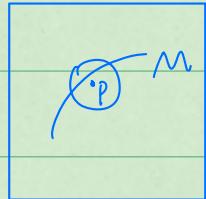
$$= \sum_{\alpha} (-1)^{i+\alpha}$$

Thm: given $k \leq n$, $M \subset \mathbb{R}^n$, $p \in M$, TFAE

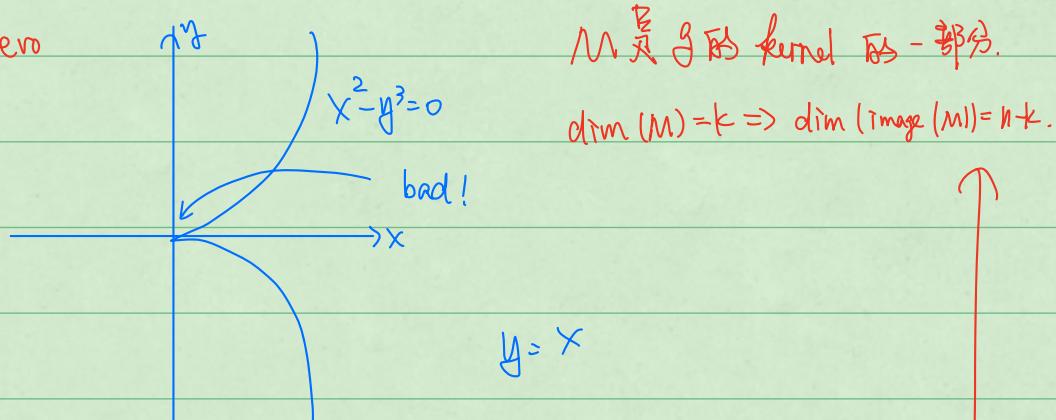
(M): \exists open $U \ni p$, open $V \subset \mathbb{R}^n$, $h: U \rightarrow V$. 局部和“标准”形式

$h: h^{-1}$, onto, smooth, h^{-1} smooth, 空间类似

$$h(U) \cap M = V \cap (\mathbb{R}^k \times \{0_{n-k}\}) \quad (\text{near } p, \text{ space is uniform})$$

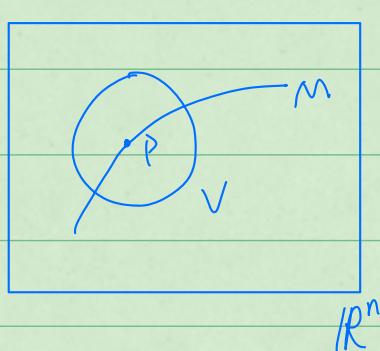


(2): evn



M 是 g 的 kernel 的一部分.

$$\dim(M) = k \Rightarrow \dim(\text{image}(M)) = n-k.$$



g

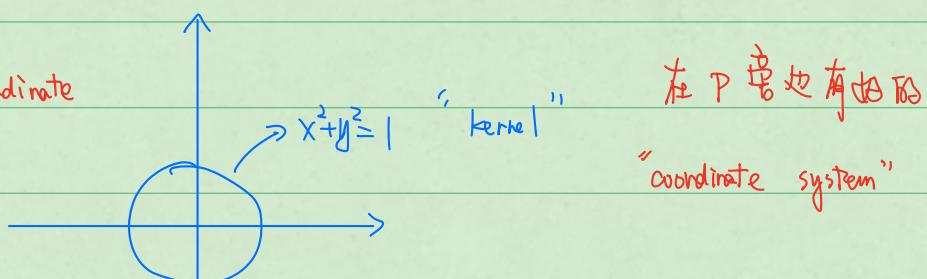
\mathbb{R}^{n-k}

C“好”的函数

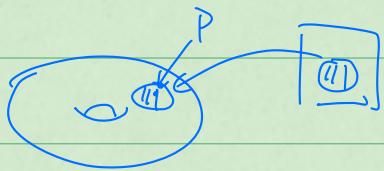
\exists open $U \ni p$, smooth $g: U \rightarrow \mathbb{R}^{n-k}$, s.t.

$$U \cap M = U \cap g^{-1}(0), \text{ and } \underbrace{\text{rank } g' = n-k}_{\text{at } p} \text{ at } p.$$

(C) coordinate



$\begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$ "image."



\exists open $U \ni p$, open $W \subset \mathbb{R}^k$, smooth, $H \vdash f$
 $f: W \rightarrow \mathbb{R}^n$, s.t.

$$\textcircled{1} \quad f(W) = U \cap M.$$

$$\textcircled{2} \quad f^{-1}: M \cap U \rightarrow W \quad \text{cont}$$

$$\textcircled{3} \quad \forall a \in W, \quad \text{rank}(f'(a)) = k.$$

DEF: $M \subset \mathbb{R}^n$ is a k -manifold ($k \leq n$) if ($M \neq \emptyset$) holds.

e.g.: $\textcircled{1} \quad S^2 \subset \mathbb{R}^3$ is a 2-manifold

$$\left\{ \begin{array}{l} \text{"2"} \\ x^2 + y^2 + z^2 - 1 = 0 \end{array} \right\} \Rightarrow \text{"2"} \quad \text{Satisfies "C" (經緯度)} \quad \text{rank}(g^1) = 1 ?$$

$$g^1(p) = (x \ y \ z) \neq 0.$$

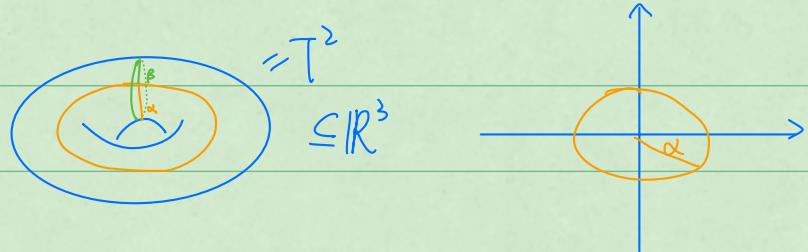
e.g. $S^1 \subset \mathbb{R}^2$

$$\left\{ \begin{array}{l} \text{"2"} \\ x^2 + y^2 - 1 = 0 \end{array} \right\}$$

$$\left\{ \begin{array}{l} \text{"2"} \rightarrow \checkmark \\ \text{"C":} \end{array} \right.$$

$$f(t) = \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} \quad \mathbb{R} \xrightarrow{f} S^1$$

e.g.



$$\text{"(C)"} \quad F(\alpha, \beta) = \begin{pmatrix} \cos \alpha \\ \sin \alpha \\ 0 \end{pmatrix} + \frac{1}{3} \left(\cos \beta \begin{pmatrix} \cos \alpha \\ \sin \alpha \\ 0 \end{pmatrix} + \sin \beta \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right)$$

$$= \begin{pmatrix} \cos \alpha + \frac{1}{3} \cos \beta \cos \alpha \\ \sin \alpha + \frac{1}{3} \cos \beta \sin \alpha \\ \frac{1}{3} \sin \beta \end{pmatrix}$$

e.g. $\text{SO}(3) \subseteq M_{3 \times 3}(\mathbb{R}) = \mathbb{R}^9$ \$\rightarrow\$ 3D-manifold (3个轴旋转)

\uparrow sets of rotations of \mathbb{R}^3

preserving orientation.

"(Σ)": $A \in \text{SO}(3) \Leftrightarrow A^T A = I, \det(A) = 1$

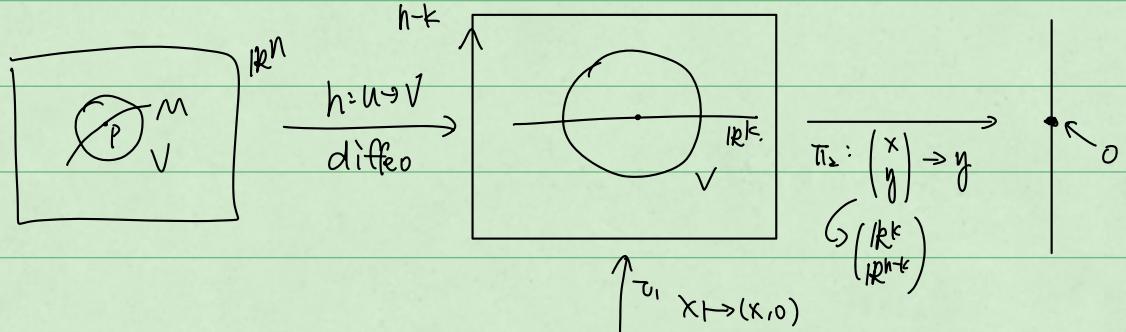
$$\begin{cases} A^T A - I = 0 \\ \det A - 1 = 0 \end{cases}$$

\hookrightarrow Symmetric matrices of $\mathbb{R}^{3 \times 3}$. So have 6 dimension.

可以推广到 $\text{SO}(n)$

pf:

① $M \Rightarrow \text{"Σ" and "C"}$

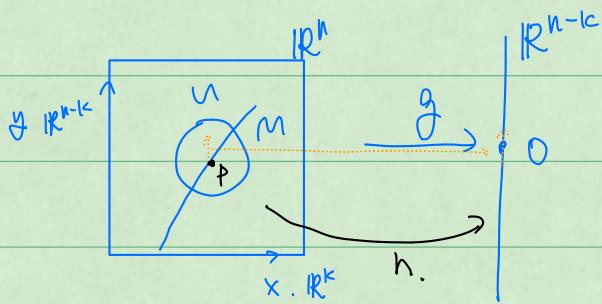


"Σ": $g = (\pi_2 \circ h)$

$\square \rightarrow \mathbb{R}^{n-k}$

$$\text{"C": } f = (h^{-1} \circ \varphi_1)$$

② "Z \Rightarrow M"



know: rank $g' = n-k \Rightarrow n-k \geq \text{维数} - k$

Name the variables in R^n : $\{x_1, \dots, x_k, y_1, \dots, y_{n-k}\}$ in some order

s.t. $\frac{\partial f}{\partial y}$ is non-singular

$$M^{(n-k) \times (n-k)}$$

Define: $h(x, y) = (x, f(x, y))$

$$h'(p) = \begin{pmatrix} \frac{\partial x}{\partial x} & \frac{\partial x}{\partial y} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \end{pmatrix} = \begin{pmatrix} I & 0 \\ ? & \frac{\partial f}{\partial y} \end{pmatrix}$$

↑ non-singular.
不知道, 无所谓

I, $\frac{\partial f}{\partial y}$ invertible $\Rightarrow h'(p)$ invertible.

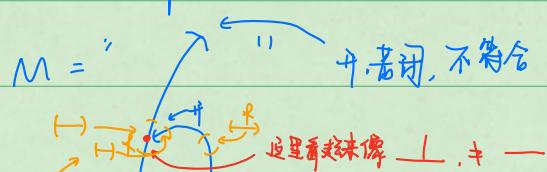
$\xrightarrow{\text{IFT}}$ $\exists U \ni p$ on which h is invertible. with smooth

inverse ($\frac{\partial f}{\partial y}$ to smooth)

$h: U \rightarrow V = h(U)$ is diffeomorphism

③ i) C - ② $\not\cong M$

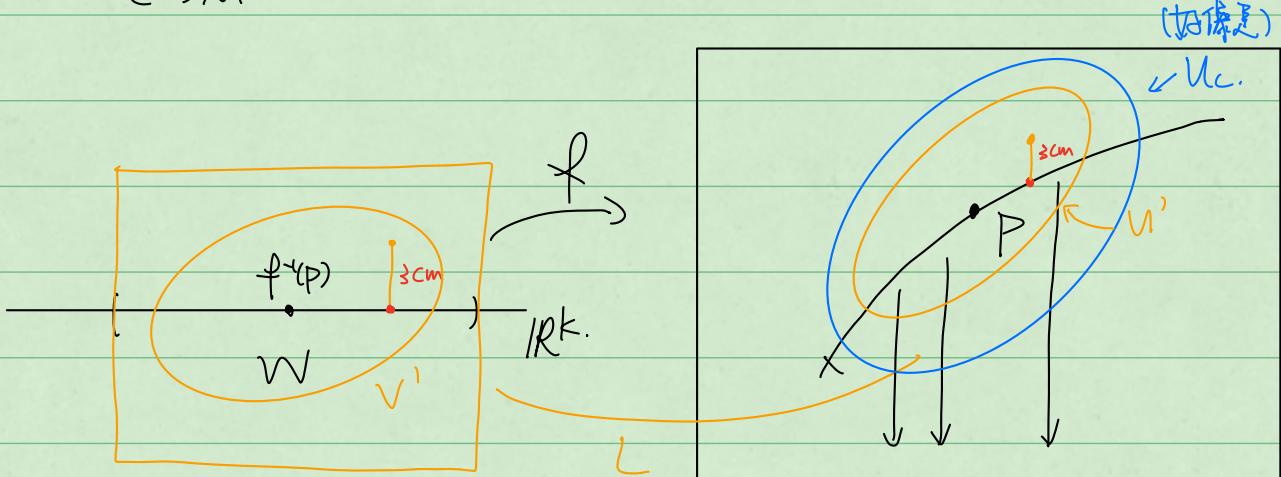
Counterexample f: $k=1, n=2$.





在这里 f 不连续

" $C \Rightarrow M$ "



extend W to \square to \circ

WLOG, $(\pi_{x_1, \dots, x_k} \circ f) = (\pi, \circ f)$ is of rank k , so invertible.

(找到那个 rank 为 k 的 x_1, \dots, x_k)

Define $l: W \times \mathbb{R}^{n-k} \rightarrow \mathbb{R}^n$. by $l(x, y) = f(x) + \begin{pmatrix} 0 \\ y \end{pmatrix}$

$$l^{-1} = \begin{pmatrix} \frac{\partial l_1}{\partial x} & \frac{\partial l_1}{\partial y} \\ \vdots & \vdots \\ \frac{\partial l_n}{\partial x} & \frac{\partial l_n}{\partial y} \end{pmatrix} = \begin{pmatrix} \frac{\partial F}{\partial x} & \sim \\ 0 & I \end{pmatrix} \Rightarrow \text{invertible.}$$

l' is invertible and so is l in some $V' \subset W \times \mathbb{R}^k$.

set $u' = l(V')$

Now to prove: $l(V \cap (\mathbb{R}^k \times \{0\})) = U \cap M$

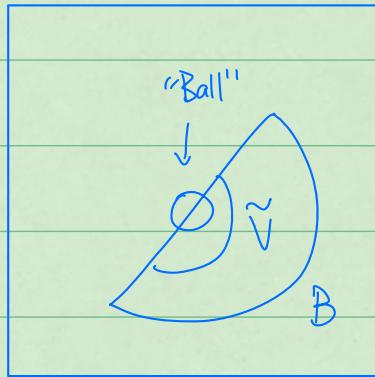
$$l(V \cap \mathbb{R}^k) = U \cap M \Leftrightarrow f(V \cap \mathbb{R}^k) = u \cap M$$

Reminder: $f: A \rightarrow B$ is cont

$\Leftrightarrow g^{-1}(\tilde{V})$ is open whenever $\tilde{V} \in \mathbb{R}^m$ is open.

in A

in B .



$\leftarrow \tilde{V} f$

$\Leftrightarrow " \tilde{V} \text{ is open in } B " \Leftrightarrow \exists \text{ open } V \in \mathbb{R}^m \text{ s.t.}$

$$\tilde{V} = B \cap V$$

$\tilde{g}^{-1}(V)$ is of the form $M \cap V$, V open $\in \mathbb{R}^n$, whenever

$V \subset \mathbb{R}^m$ open.

Up above, f^{-1} is cont

$\Rightarrow f$ is "open" $\Rightarrow f$ carries open sets to open sets.

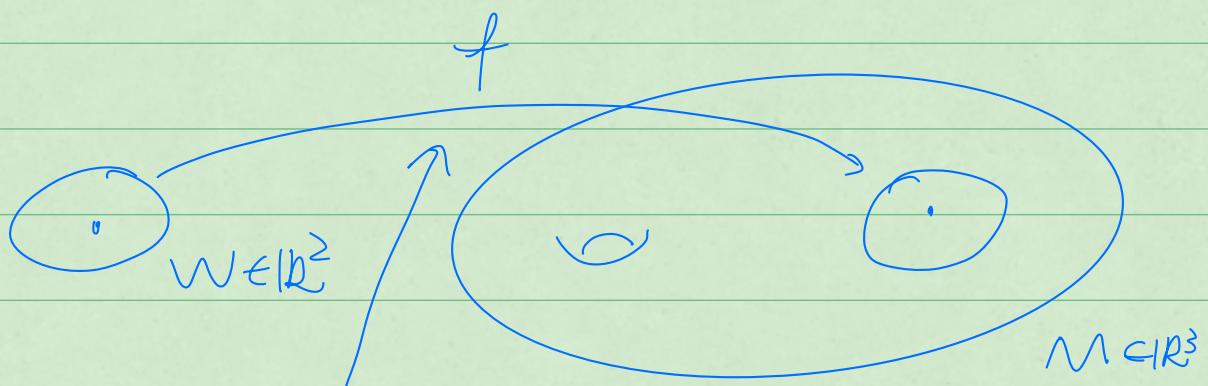
meaning in our context,

$f(V \cap \mathbb{R}^k)$ must be open in $M \cap U_c$.

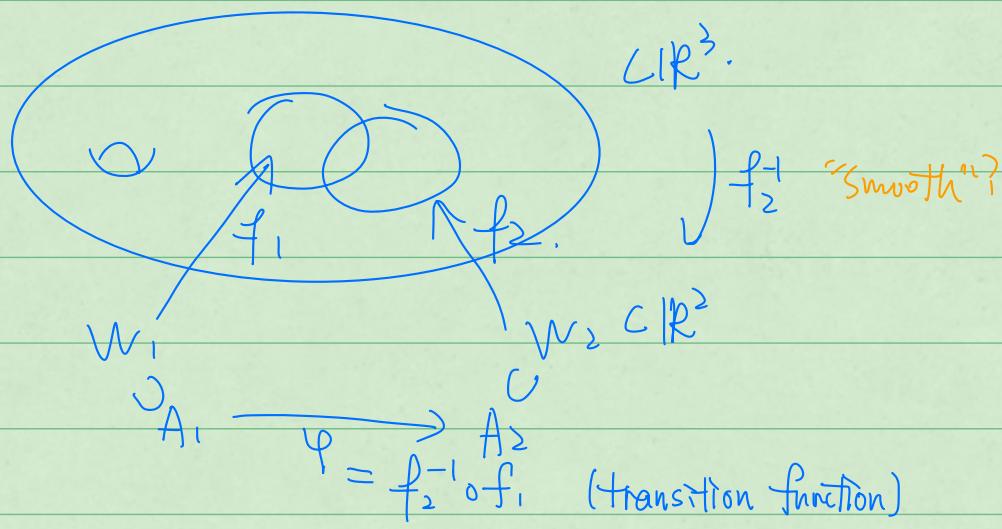
$\Rightarrow \exists$ open $U'' \subset \mathbb{R}^n$, s.t. $f(V \cap \mathbb{R}^k) = U'' \cap M \cap U_c = M \cap (U_c \cap U'')$

$$= M \cap U''$$

Now, set $V''' = f^{-1}(U'')$, done.



Coordinate patch.



A_1, A_2 : inverse image of $\text{image}(f_1) \cap \text{image}(f_2)$

φ is a diffeomorphism.

DEF: $\mathbb{R}_+^k = \{x \in \mathbb{R}^k; x_k \geq 0\}$

DEF: A " k manifold with boundary" is a subset $M \subset \mathbb{R}^n$,

s.t. $\forall p \in M, \exists \underset{\text{open}}{W} \subset \mathbb{R}_+^k$,

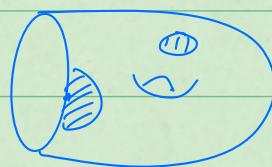
and an open $U \subset \mathbb{R}^n$, a

smooth, 1-1 function $f: W \rightarrow \mathbb{R}^n$, s.t.

$$\textcircled{1} f(W) = M \cap U,$$

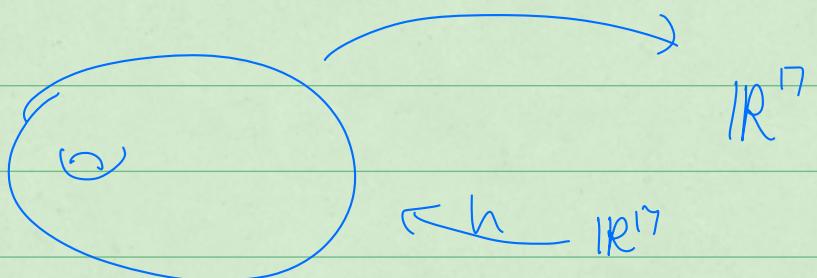
②

(As above)



DEF, if M is " k manifold with boundary".

then $\partial M = \{p \in M, \text{s.t. } \}$



g is smooth if \forall coordinate chart $f: \mathbb{R}^k \supset W \rightarrow M$

$g \circ f: W \rightarrow \mathbb{R}^7$ is smooth

h is smooth if \forall coordinate chart $f: W \rightarrow M$

$f^{-1} \circ h|_{h^{-1}(f(W))}: h^{-1}(f(W)) \rightarrow W$ is smooth.

Suppose $M^k, N^l \leftarrow$ manifolds of deg k/l .

$\varphi: M \rightarrow N$ is smooth if

$$\begin{array}{ccc} f_M & \nearrow & f_N \\ \mathbb{R}^k & \xrightarrow{\text{c.c.}} & \mathbb{R}^l \end{array}$$

for $\forall f_M, f_N$, the partially defined function,

$f_N^{-1} \circ \varphi \circ f_M$ is smooth.

$\forall p \in M$, \exists open $W \subset \mathbb{R}^k = \{x_k \geq 0\}$, open $p \in \partial W$,

smooth 1-1 function $f: W \rightarrow N$ s.t. ① ② ③

then M is "manifold with boundary."

Thm: If M is a manifold with boundary, then

$\forall p \in M$, either one of the 2 following is true.

① If $f: W \rightarrow M$ is coordinate chart s.t. $f(a) = p$,

then $a_k > 0$

② If $f: W \rightarrow M$ is coordinate chart s.t. $f(a) = p$,

then $a_k = 0$

Def: $\partial M = \{p \in M, \text{ s.t. } \textcircled{2} \text{ holds}\}$.

Warning:

① $\partial \neq \text{bd.}$

$$M = O \text{ (})$$

$$\partial M. \quad \text{bd } M = M.$$

② Every manifold is a "manifold with boundary"

$$(\text{即 } \partial M = \emptyset)$$

但反之不成立。

Thm: If M is a manifold with ∂ , then ∂M is a manifold. $M \text{ deg. } (k)$, $\partial M \text{ deg. } (k-1)$.

即 X_k .

$$\Rightarrow \partial^2 = 0.$$

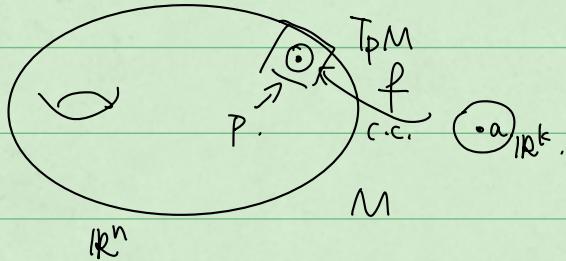
Let M be a k -dim manifold, (with ∂)

Let $p \in M$, if $f: W \rightarrow M$ is a coordinate chart

for m with $f(a) = p$, then the tangent space at

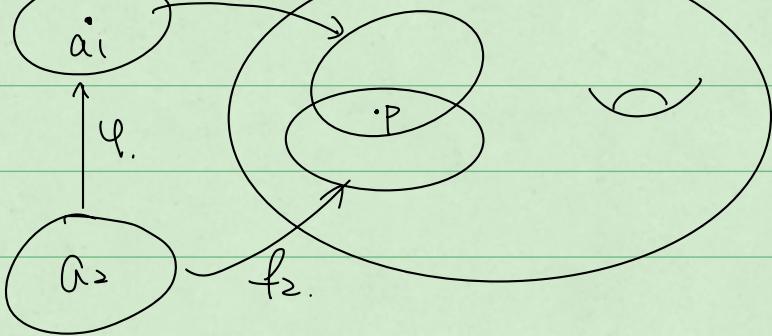
p of M

$$T_p M = f_* T_a (\mathbb{R}^k) \subset T_p \mathbb{R}^n$$



1. This is well-defined.

$$f_1$$



$$f_{1*} T_{a_1} \mathbb{R}^k = f_{2*} T_{a_2} \mathbb{R}^k.$$

$$f_2 = f_1 \circ \varphi_1.$$

$$f_{2*} T_{a_2} \mathbb{R}^k = (f_1 \circ \varphi_1)_* T_{a_2} \mathbb{R}^k.$$

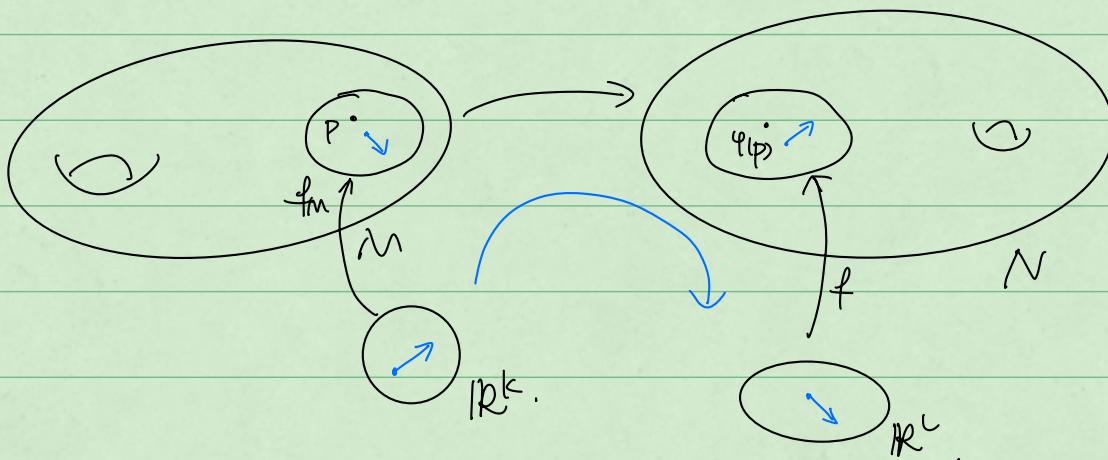
$$= f_{1*} (\varphi_* T_{a_1} \mathbb{R}^k)$$

$$= f_{1*} (T_{a_1} \mathbb{R}^k) \quad (\varphi_* \text{ is invertible, as } \varphi' \text{ is, as } \varphi \text{ is})$$

$$\therefore \dim T_p M = \text{rank}(f') = k.$$

Suppose $\Psi: M^k \rightarrow N^l$, smooth, $p \in M$.

Claim: $\exists \Psi_*: T_p M \rightarrow T_{\Psi(p)} N$.



Def: A vector field on M is

$$f: M \rightarrow \bigcup_{p \in M} T_p M,$$

$$f: \mathbb{R}^n \rightarrow \bigcup_{p \in \mathbb{R}^n} T_p \mathbb{R}^n,$$

$$f(p) \in T_p \mathbb{R}^n.$$

s.t. $f(p) \in T_p M$.

这里每一点的 $T_p \mathbb{R}^n$ 一样

Def: Such f is smooth if

这样不一样

$\boxed{b} \uparrow$.

~~Def:~~ $\Omega^k(M^k) \ni w$ if

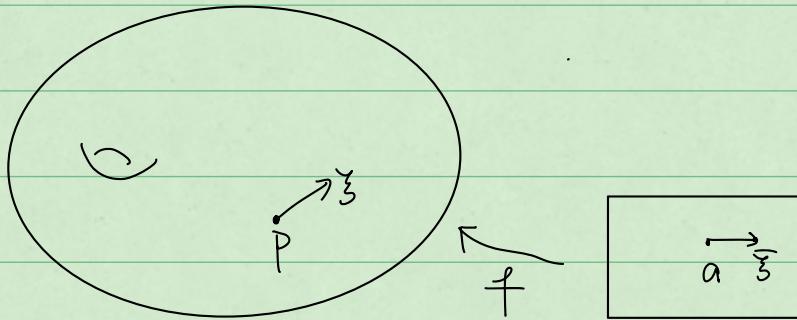
$w: M \longrightarrow \bigcup_{p \in M} \Lambda^k T_p M$.

s.t. $w(p) \in \Lambda^k T_p M$, smooth

Theme: a fish on a manifold is a fish on every coordinate chart, provided they agree.

$\bar{g} \in T_p M$, $g: M \rightarrow \mathbb{R}$ smooth

$D_{\bar{g}} g \in \mathbb{R}$



\bar{g} on W , $\not\vdash^* g$.

also cubes, chains,

\bar{g} on $T_p \mathbb{R}^n$

$\psi: M^k \rightarrow N^l$

Def: $D_{\bar{g}} g = D_{\bar{g}} \bar{g}$

$\Rightarrow \psi_* C_p(M) \rightarrow C_p(N)$

Compatible with ∂ .

On $\Omega(M)$, we have

\uparrow Stokes' thm (cube version) holds.

$+, ^\wedge, d: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$, ψ^* , ψ_*

Then obey all rules from \mathbb{R}^n , except $W = \sum f_i dx^i$

e.g. on $S^2 = [x^2 + y^2 + z^2 = 1]$

$$W_1 = x dy \wedge dz + y dz \wedge dx + z dx \wedge dy \in \Omega^2(S^2)$$

y is a function on S^2 , therefore 0-form. so make sense.

但協調性相关 (S^2 上), 所以非标准形式, 然而

但可以局部. 例如 $z=1$ 附近, 可以用 $dxdy$ 表示.

$$W_2 = x dx + y dy + z dz \in \Omega^1(S^2)$$

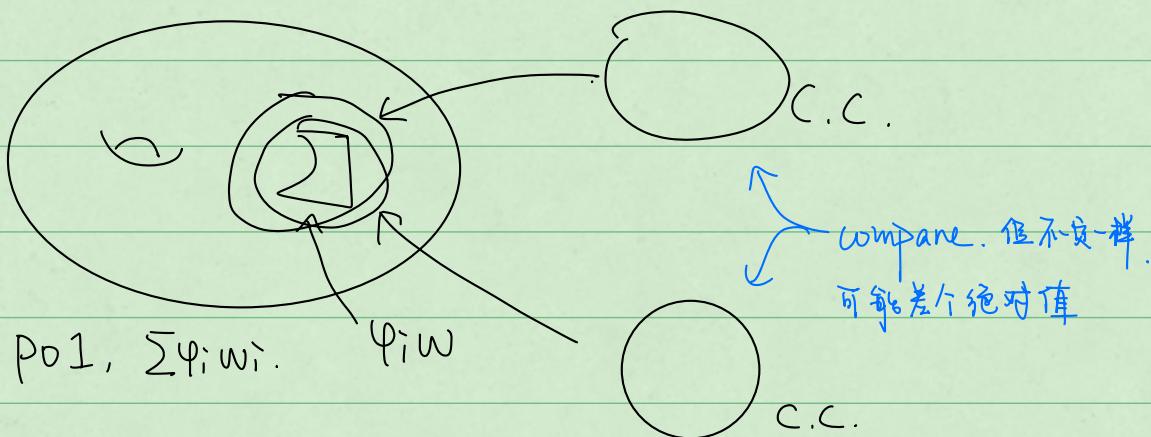
$= 0$ (as a form on S^2)

$$\text{Consider } g = x^2 + y^2 + z^2 = 1 \quad (\text{on } S^2)$$

$$0 = dg = 2x dx + 2y dy + 2z dz$$

So, 0-form.

$$\int_M dw = \int_{\partial M} w$$



Loose Def: An orientable manifold is a manifold

s.t. an atlas can be chosen, s.t. all

sys of coordinate

transition functions are orientation-preserving

i.e. $\forall \varphi, \det(\varphi') > 0$

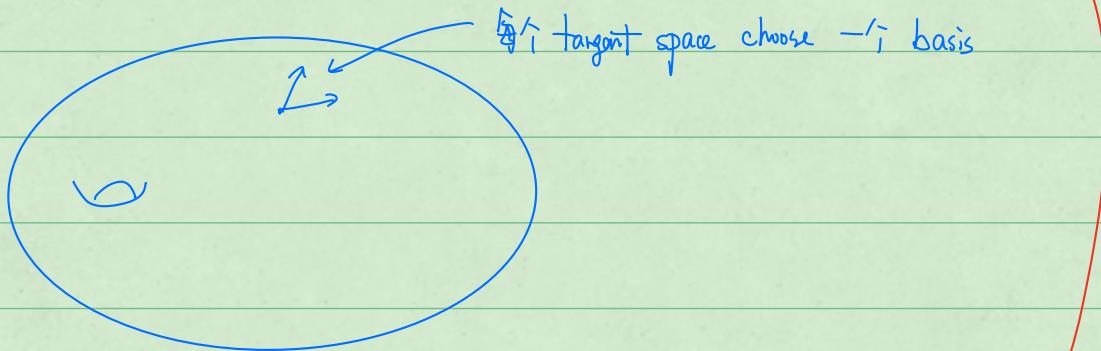
Remainder: Orientation of V^k : either an

① ordered basis 模掉 正的坐标变换.

② $0 \neq \eta \in \Omega^k(M)$ 模掉 “乘正真数倍”

Def: An orientation on M^k is a continuously varying

choice of orientation η_p for $T_p M$ for each $p \in M$



Namely: It is a choice of $\eta \in \Omega^k(M)$, s.t. $\eta(p) \neq 0 \quad \forall p$.

$\eta_1 \sim \eta_2$ if $\eta_1 = f \eta_2$. $f \neq 0$, f cont.

或等: $\{$ nowhere 0 top forms on $M\}$.

在 ordered basis 模掉下:

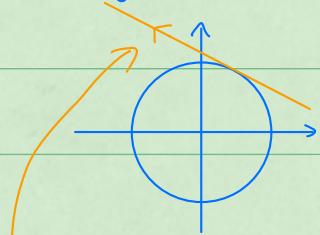
A choice O_p of an ordered basis of $T_p M$ (modulo positive det change of basis)
(~~和什么刻面 cont?~~)

s.t. $\forall p \in M$, There is a nbhd $U \ni p$, and vector fields

X_1, \dots, X_k , defined on U , s.t. $O_p' = (X_1(p), X_2(p), \dots, X_n(p))$

for every $p \in U$.

e.g. 1: $S^1 = [x^2 + y^2 = 1]$

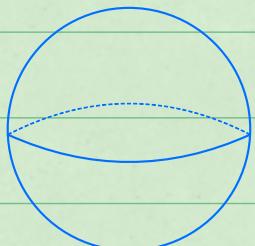


either } 1-form, nowhere 0. $\rightarrow \eta = \tilde{d\theta} = x dy - y dx \quad (x^2 + y^2 = 1)$
choice of a basis of $T_p M, \forall p.$

$$X_1(x) = \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} -y \\ x \end{pmatrix}$$

在上 check 这个, 发现是正数即可
★

e.g. 2: $S^2 = [x^2 + y^2 + z^2 = 1].$

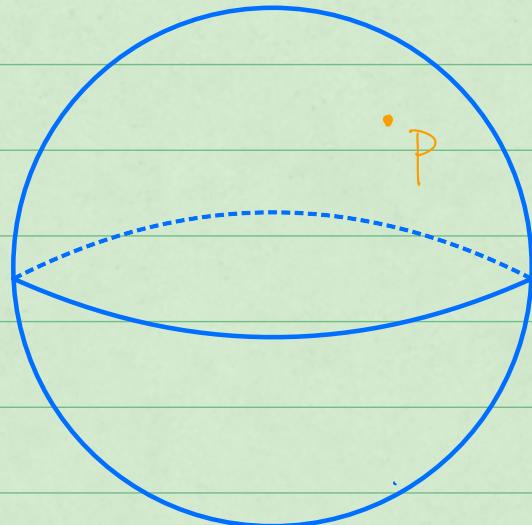


① $\eta = \sum_{ijk} x_i dy^j dz^k$

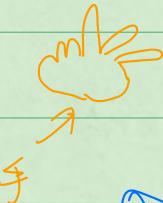
② find 2 vector field, 构成 $T_p M$ 的基.

但不可靠. 球对称.

由 a nowhere 0 vector field on S^2 . 但只要求 locally 即可



半径.
大拇指向外伸展, 中指构成 basis



e.g. 0: a pt $p \in \mathbb{R}^3$

In terms of top forms, namely, function.

a function on a point is just a scalar, y .

$$y_1 \sim y_2 \Leftrightarrow \frac{y_1}{y_2} > 0$$

e.g. m: Möb, 莫比乌斯环, 转一圈会转成反方向

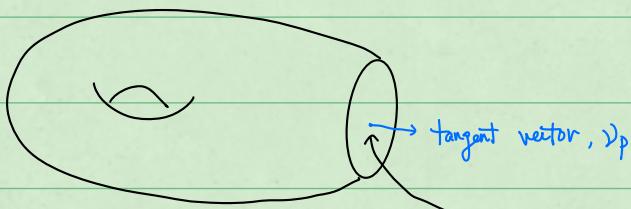
我tm画不出来莫比乌斯环啊啊啊啊啊啊啊啊啊啊啊啊啊啊

\Rightarrow 无法 oriente.

Def: M is oriented if it is given with choice of

a orientation, — Orientable.

Given a oriented M , there is a standard way to oriente ∂M .



A orientation O_p^M of ∂M at p is:

if you preprend to it the outward pointing normal vector to ∂M ,

then get the orientation O_p^M at p .

$$\text{i.e. } O_p^M = (v_p, O_p^{\partial M})$$

e.g. $S^2 = \partial D^3$ $D^3 = [x^2 + y^2 + z^2 \leq 1]$

$O^M = (\partial x, \partial y, \partial z)$. 在 S^2 上, 向上, 抱抱指向外.

∂M is oriented.

$$\eta_{\partial M}(p) = i^*_{\partial M \rightarrow M} \circ \iota_M \circ \eta_M(p)$$

inner multiplication.

法向量

inclusion map.

If X is a vector field on M , ^(locally)

$T_X : \Omega^k(M) \rightarrow \Omega^{k-1}(M)$, "inner multiplication by X " as follows:

$$w \in \Omega^k(M), \vec{z}_i \in T_p(M)$$

$$T_X(w)(\vec{z}_1, \dots, \vec{z}_{k-1}) = w(X(p), \vec{z}_1, \dots, \vec{z}_{k-1})$$

Claim: The two def agree.

Assume $p \in \partial M$, $T_p M$ is oriented, say it is given by the outward pointing normal. (v_p) .

$$(v_p, \vec{z}_1, \dots, \vec{z}_{k-1}) \Rightarrow \vec{z}_i \in T_p \partial M.$$

Assume also that this orientation of $T_p M$ is given by $\eta_M \in \Omega^k(M)$

$$\Rightarrow \eta_M(v_p, \vec{z}_1, \dots, \vec{z}_{k-1}) > 0.$$

The orientation of ∂M is given by $(\vec{z}_1, \dots, \vec{z}_{k-1}) \stackrel{?}{\sim} i_{\partial M \rightarrow M}^* T_p \eta_M$.

$$\text{i.e., } \eta_{\partial M}(\vec{z}_1, \dots, \vec{z}_{k-1}) \stackrel{?}{>} 0$$

$$\hookrightarrow = i_{\partial M \rightarrow M}^* T_v \circ i_{\partial M \rightarrow M}^* \eta_M(\vec{z}_1, \dots, \vec{z}_m)$$

$$= T_v \circ \eta_M(\vec{z}_1, \dots, \vec{z}_m)$$

$$= \eta_M(v, \vec{z}_1, \dots, \vec{z}_m)$$

$$\leftarrow \overset{\rightarrow}{} \quad \overset{\rightarrow}{}$$

$$\text{e.g., } M = \begin{array}{c} \xleftarrow{} \\ \text{---} \\ \text{o} \end{array} \xrightarrow{} \begin{array}{c} \xrightarrow{} \\ \text{---} \\ \text{l} \end{array}$$

$\partial M = \{0, 1\}$. as an oriented manifold?

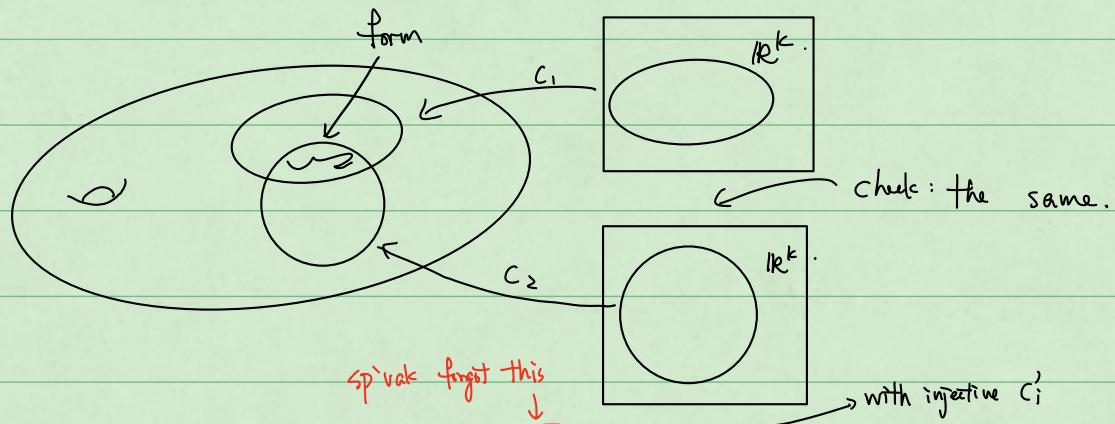
orientation at $\begin{cases} 0 : (+/-) \\ 1 : (+/-) \end{cases}$

$$\eta = dx$$

$$p=0 : \eta_{\partial M}(0) = i_{\partial M \rightarrow M}^* T_v. dx = T_{\partial x} dx = dx(-\partial x) = -1$$

Similarly: $p=1 \Rightarrow "+"$

Integration on an oriented manifold.



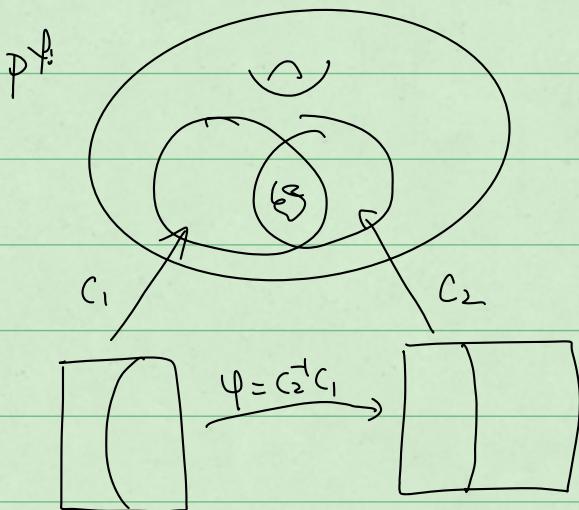
Prop: Let C_i ($i=1,2$) be smooth, injective, orientation preserving

k -cubes in an oriented manifold M^k . and assume

$w \in \Omega^k(M)$, s.t. $\text{supp } w \subset \text{img}(C_1) \cap \text{img}(C_2)$

$$\text{then. } \int_{C_1} w = \int_{C_2} w \\ \Downarrow \int_{I^k} c_i^* w$$

This means we can define $\int_{C_1} w = \int_{C_2} w = \int_M w$.



$$\int_{I^k} c_i^* w = \int_{I^k} (c_2 \circ \psi)^* w = \int_{I^k} \psi^* \circ c_2^* w \xrightarrow{\text{COV}} \int_{I^k} c_2^* w$$

ψ is orientation preserving. $\Leftrightarrow \det(\psi') > 0$

Suppose $w \in \Omega^k(M)$, choose P01, Ψ_i subordinate.

to open sets that can be covered by good cubes
as above.

Define $\int_M w = \sum_i \int_M \varphi_i w$

Comment:

① if M compact, then $\{\varphi_i\}$ could be finite, so finite sum,
no issue

② In general, first define "integrable forms"

Integrable: $\sum_i \int_M |\varphi_i| |w| < 0$.

$$\begin{aligned} &\hookrightarrow C^*(\varphi_i w) \in \Omega^k(I^k) \\ &\hookrightarrow \int_{I^k} |F| dx_1 \cdots dx_k \end{aligned}$$

Important: This is independent of φ_i .

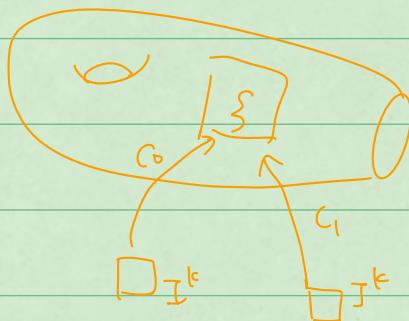
$$\int_M^{(\varphi_i)} w \sim \int_M^{(\varphi_j)} w$$

$$\begin{aligned} \int_M^{(\varphi_i)} w &= \sum_I \int_M \varphi_i w = \sum_{ij} \int_M \varphi_i \varphi_j w = \sum_j \int_M \varphi_j w = \int_M^{(\varphi_j)} w \\ &\quad \swarrow \qquad \qquad \qquad \searrow \\ &1 = \sum_j \varphi_j \qquad \qquad \qquad 1 = \sum_i \varphi_i \end{aligned}$$

Notes: 1. $\int_M w$ is linear in w .

$$2 \int_{-M} w = -\int_M w$$

" $-M$ " same manifold, reverse orientation.



$$C_0(x_1, \dots, x_k) = C_1(1-x_1, \dots, x_k)$$

Stokes' thm:

If M^k is compact / oriented, $w \in \Omega^{k-1}(M)$,

$$\text{then } \int_M dw = \int_{\partial M} w$$

p.f: Suppose we know the thm on w 's with "small"

support

$$\downarrow$$

$$\text{supp}(w) \subset \text{Im}(c) \text{ for some } c.$$

$$\rightarrow \int_M w = \sum_i \int_{\partial M} \varphi_i w \xlongequal{\varphi_i w \text{ small}} \sum_i \int_M d\varphi_i w = \sum_i \int_M d\varphi_i \cdot w + \sum_i \int_M \varphi_i dw.$$

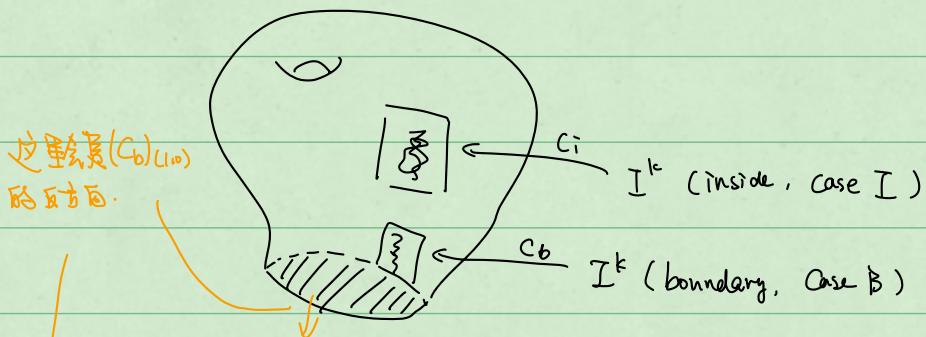
这里取 $\sup \varphi_i$.

take an P.D.I for M , is also for ∂M

$$\sum_i \int_M d\varphi_i \cdot w = \int_M d(\sum_i \varphi_i) w = \int_M (d1) w = 0.$$

finite sum

Now to prove "small" case



Case I: $\text{Supp}(w) \subset \text{int}(M)$, can be covered by C_i .

Case B: $\text{Supp}(w) \cap \partial M \neq \emptyset$, -- - - - -

Case I: $\int_{\partial M} w = 0$, 因为在内部

$$\int_M dw = \int_{C_i} dw = \int_{I^k} C_i^*(dw) = \int_{I^k} d(C_i^* w)$$

$$= \int_{\partial I^k} C_i^* w = \int_{C_i \cap I^k} w = 0 \quad (\text{因为 } C_i > w)$$

Case B: $\int_M dw = \int_{\partial I^k} C_b^* w = \int_{\partial C_b} w$

Choose C_b , such that only $C_b(0, x_1, \dots, x_k)$ intersects ∂M .

$$= - \int_{(C_0)_{(1,0)}} w = - \int_{\substack{(C_0)_{(1,0)} \\ g_1, \dots, g_{k-1}}} w = \int_M w.$$

每个面有自己的符号.

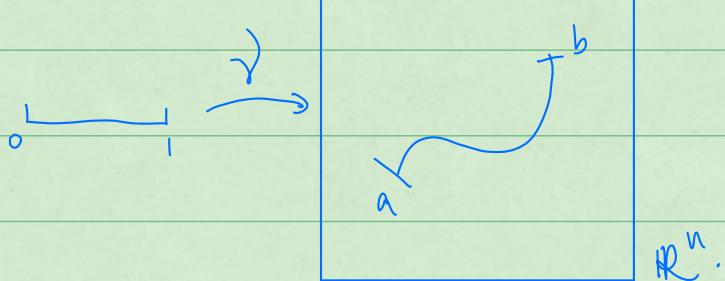
this cube is orientation reversing.

e.g. 1. $M^1 \subseteq \mathbb{R}^1$

$$M^1 = [a, b] \quad w = f. \quad \partial M = \{b\} \cup \{-a\} \quad dw = f' dx.$$

$$\int_a^b f' dx = \int_M dw = \int_{\partial M} w = f(b) - f(a)$$

e.g. 2: $M^n \subseteq \mathbb{R}^n$.



$$M = \gamma([0, 1]) \sim \gamma.$$

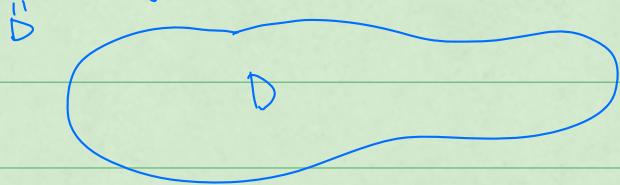
$$w = f: \mathbb{R}^n \rightarrow \mathbb{R}.$$

$$\begin{aligned} f(b) - f(a) &= \int_{\partial M} w = \int_{\gamma([0, 1])} dw = \int_{\gamma([0, 1])} \sum \frac{\partial f}{\partial x_i} dx_i \\ &= \int_{[0, 1]} \sum \frac{\partial f}{\partial x_i}(\gamma(t)) \cdot \dot{\gamma}(t) dt = \int_{[0, 1]} (\text{grad } f) \cdot \dot{\gamma}(t) dt. \end{aligned}$$

$$x_i = \gamma_i(t) \Rightarrow dx_i = \dot{\gamma}_i(t) dt$$

$$\dot{\gamma}(t) = \begin{pmatrix} \dot{\gamma}_1(t) \\ \vdots \\ \dot{\gamma}_n(t) \end{pmatrix}$$

e.g. 3. $M^2 \subseteq \mathbb{R}^2_{x,y}$.



$$\partial D = \gamma: [0, 1] \rightarrow \mathbb{R}^n.$$

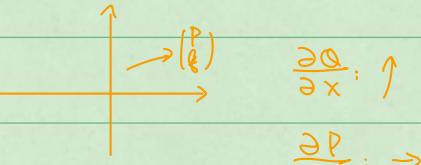
$$w = P dx + Q dy. \quad dw = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

$$\int_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \int_D \frac{\partial Q}{\partial x} - \int_D \frac{\partial P}{\partial y} = \int_M dw \quad) \text{ e.g. 2.}$$

$$= \int_{\partial D} \omega = \int_D P dx + Q dy = \int_{[0,1]} \begin{pmatrix} P \\ Q \end{pmatrix} \cdot \vec{v} dt$$

two interpretations:

$$1. F = \begin{pmatrix} P \\ Q \end{pmatrix}$$



$(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y})$: how much the flow

$$\frac{\partial Q}{\partial x}: \uparrow$$

$$\frac{\partial P}{\partial y}: \rightarrow$$

want to spin a particle.



$$2. Q \rightarrow P \quad P \rightarrow -Q$$

$$\text{by } \int_D (\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y}) = \int_{[0,1]} (-Q) \vec{v} dt \leftarrow \begin{pmatrix} P \\ Q \end{pmatrix} \text{ 转了 } 90^\circ.$$

$$= \int_{[0,1]} \begin{pmatrix} P \\ Q \end{pmatrix} \left(\vec{v} \text{ 顺时针转 } 90^\circ \right) \leftarrow \text{outward pointing normal.}$$

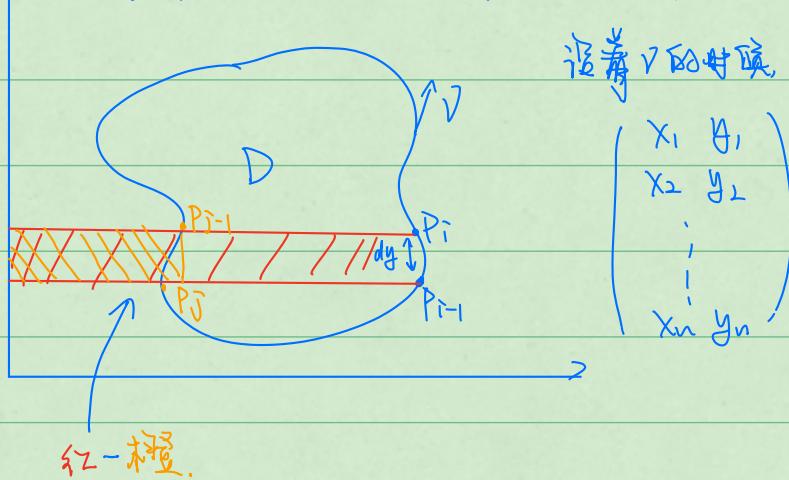
$$\text{div}(\vec{v}) \quad \text{how much flow is created at here.}$$

$$= \int_{[0,1]} \begin{pmatrix} P \\ Q \end{pmatrix} \cdot \vec{n} \quad (\text{因为 } \vec{v}(t) \text{ 是切向量})$$

how much flow comes out of the domain.

$$\text{Sub. e.g. } \omega = x dy. \quad d\omega = dx \wedge dy$$

$$\text{Area} = \int_D 1 = \int_D dw = \int_{\partial D} x dy \sim \sum_{i=1}^n x_i (y_i - y_{i-1})$$



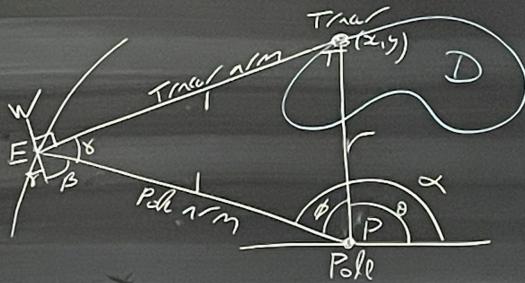
Mar 31, April 6 The planimeter, Volume forms, \mathbb{R}^3

Read Almgren: Spivak 126-8, Course evals due April 10.

Final exam info in Final class

M: conf space of the planimeter

w: how much W turns if the planimeter pushed a bit.



$$\alpha, \beta, \gamma, \psi, \theta, r, x, y : M \rightarrow \mathbb{R}.$$

$$w : \Omega^1(M)$$

$$\int_{\partial D} w = \int_D dw \quad "w"?$$

$$w = (d\alpha) \cos \gamma \quad \gamma = \pi - 2\psi$$

$$\begin{aligned} w &\stackrel{\uparrow}{=} (d\alpha) \cos(\pi - 2\psi) \\ &= \cos(\pi - 2\psi) d(\theta + \psi) \\ &= -\cos(2\psi) \cdot d(\theta + \psi) \end{aligned}$$

$$dw = 2\sin(2\psi) d\psi \wedge d\theta.$$

$$= \underbrace{2\cos\psi}_{r} \underbrace{2\sin\psi}_{-dr} d\psi d\theta.$$

$$= -r dr d\theta = -dx dy.$$

$$\rightarrow \int_D -dx dy = -\text{Area}.$$

The \mathbb{R}^3 thm:

$$\int_{M^3} \operatorname{div} F dV = \int_{\partial M^3} \overset{\text{normal}}{F \cdot n} dA \quad \text{"Gauss"}$$

area form
value form

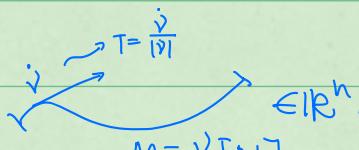
$$\int_{M^2} (\operatorname{curl} F) n dA = \int_{\partial M^2} F \cdot T \, ds. \quad \text{"Stokes"}$$

M^k oriented manifold in \mathbb{R}^n , with orientation given by

$$\gamma = \omega^k(M). \quad \gamma \neq 0.$$

Single symbol. $\{dV\}$: "The volume form on M . is that form for which

$dV(\xi_1, \xi_2, \dots, \xi_k) = 1$ if ξ_1, \dots, ξ_k makes a positive orthonormal basis of $T_p M$.

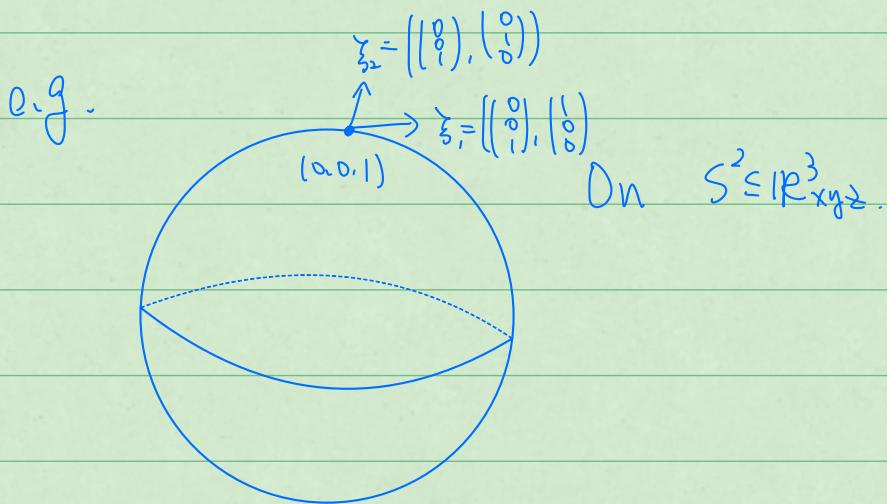
e.g 1: 

$$dV? \quad dV \in \Omega^k(M)$$

\Downarrow

$$dl = ds$$

$$ds(T) = 1$$



$$dV(\xi_1, \xi_2) = dA(\xi_1, \xi_2) \stackrel{\text{def}}{=} 1$$

$$dx \wedge dy (\xi_1, \xi_2) = 1$$

$$\Rightarrow \text{at } N = (0,0,1), \quad dA = dx \wedge dy$$

$M^3 \subset \mathbb{R}^3$, let $n(x) \in M$, be the positive unit normal
to M .

Def: $n: M \rightarrow \bigcup_{x \in M} T_x \mathbb{R}^3$

$$\text{s.t. } n(x) \in T_x \mathbb{R}^3$$

- $n(x) \perp T_x M$

- $|n(x)| = 1$

- if u, v are tangent to M at x , s.t.

(u, v) is positive relative to the orientation

of M , Then n, u, v is a positive basis
of \mathbb{R}^3 .

dA : volume form on M .

$$dA(u, v) = \begin{vmatrix} \text{--- } u \text{ ---} \\ \text{--- } v \text{ ---} \\ \text{--- } n \text{ ---} \end{vmatrix}$$

$$u, v \in T_x M$$