Introduction Problem formulation GPS-based estimator Simulation

Causal inference with interference

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December 6, 2018

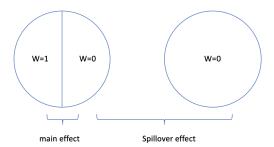
Outline

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Definition of interference

Interference

Potential outcomes of a unit depend on its treatment and on the treatments of other local units.



Problems and Goals

Problems:

- Potential outcomes (SUTVA → SUTNVA)
- Assignment mechanisms (Unconfoundness → extension)
- Estimand (Biased naive estimand → extension)
- Estimation method (Propensity Score → Generalized PS)

Goals:

- Known network + unknown assignment mechanism
- Estimate: main effect and spillover effect

Notations

- Treatment $W_i \in \{0,1\}$
- ullet Outcome $Y_i \in \mathcal{Y}$
- Covariate $X_i \in \mathcal{X}$;

Notations

- Treatment $W_i \in \{0,1\}$
- Outcome $Y_i \in \mathcal{Y}$
- Covariate $\mathbf{X}_i \in \mathcal{X}$; individual $\mathbf{X}_i^{ind} \in \mathcal{X}^{ind}$; neighborhood $\mathbf{X}_i^{neigh} \in \mathcal{X}^{neigh}$
- Undirected network $G = (\mathcal{N}, \mathcal{E})$
- For node *i* consider partitions $(i, \mathcal{N}_i, \mathcal{N}_{-i})$: $(W_i, \mathbf{W}_{\mathcal{N}_i}, \mathbf{W}_{\mathcal{N}_{-i}}), (Y_i, \mathbf{Y}_{\mathcal{N}_i}, \mathbf{Y}_{\mathcal{N}_{-i}})$

SUTNVA and potential outcomes

Assumption 1 No Multiple Versions of Treatment(Consistency)

$$Y_i = Y_i(\mathbf{W})$$

Assumption 2 Neighborhood Interference

Given a function $g_i : \{0,1\}^{N_i} \to \mathcal{G}_i$, $\forall i \in \mathcal{N}$, $\forall \mathbf{W}_{\mathcal{N}_{-i}}, \mathbf{W}'_{\mathcal{N}_{-i}}$ and $\forall \mathbf{W}_{\mathcal{N}_i}, \mathbf{W}'_{\mathcal{N}_i}, g_i(\mathbf{W}_{\mathcal{N}_i}) = g_i(\mathbf{W}'_{\mathcal{N}_i})$, the following equality holds:

$$Y_i(W_i, \mathbf{W}_{\mathcal{N}_i}, \mathbf{W}_{\mathcal{N}_{-i}}) = Y_i(W_i, \mathbf{W}'_{\mathcal{N}_i}, \mathbf{W}'_{\mathcal{N}_{-i}})$$

Potential outcomes

$$Y_i(w,g) = Y_i(W_i = w, G_i = g)$$

for a subset of nodes $V_g = \{i : g \in \mathcal{G}_i\}$ where $G_i = g_i(\mathbf{W}_{\mathcal{N}_i})$

Assignment mechanism

Assignment mechanism

$$P(\mathbf{W}, \mathbf{G} | \mathbf{X}, \{ \mathbf{Y}(w, g), w = 0, 1; g \in \mathcal{G} \}) =$$

$$\begin{cases} P(\mathbf{W} | \mathbf{X}, \{ \mathbf{Y}(w, g), w = 0, 1; g \in \mathcal{G} \}) & \text{if } \mathbf{G} = g(\mathbf{W}) \\ 0 & \text{otherwise} \end{cases}$$

Assumption 3 Unconfoundness of Individual and Neighborhood Treatment

$$Y_i(w,g) \perp \!\!\! \perp W_i, G_i | \mathbf{X}_i \ \forall w \in \{0,1\}, g \in \mathcal{G}_i, \forall i$$

Causal estimands

Main effect $\tau(g)$ and overall main effect τ

$$au(g) = E[Y_i(W_i = 1, G_i = g) - Y_i(W_i = 0, G_i = g)|i \in V_g]$$

 $au = \sum_{g \in \mathcal{G}} \tau(g) P(G_i = g)$

Spillover effect $\delta(g; w)$ and overall spillover effect $\Delta(w)$

$$\delta(g; w) = E[Y_i(W_i = w, G_i = g) - Y_i(W_i = w, G_i = 0) | i \in V_g]$$

$$\Delta(w) = \sum_{g \in G} \delta(g; w) P(G_i = g)$$

Total effect TE

$$\sum_{g \in \mathcal{G}} E[Y_i(W_i = 1, G_i = g) - Y_i(W_i = 0, G_i = 0) | i \in V_g] P(G_i = g)$$

$$= \tau + \Delta(0)$$

Generalized propensity score

$$\psi(w; g; x) = P(W_i = w, G_i = g | \mathbf{X}_i = \mathbf{x})$$

$$= P(G_i = g | W_i = w, \mathbf{X}_i^g = \mathbf{x}^g) P(W_i = w | \mathbf{X}_i^w = \mathbf{x}^w)$$

$$= \lambda(g; w; x^g) \phi(w; x^w)$$

- Joint propensity score: $\psi(w; g; x)$
- Neighborhood propensity score: $\lambda(g; w; x^g)$
- Individual propensity score: $\phi(w; x^w)$

Assumption 1-3

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Assumption 2 Neighborhood Interference

Given a function $g_i : \{0,1\}^{N_i} \to \mathcal{G}_i$, $\forall i \in \mathcal{N}$, $\forall \mathbf{W}_{\mathcal{N}_{-i}}, \mathbf{W}'_{\mathcal{N}_{-i}}$ and $\forall \mathbf{W}_{\mathcal{N}_i}, \mathbf{W}'_{\mathcal{N}_i}, g_i(\mathbf{W}_{\mathcal{N}_i}) = g_i(\mathbf{W}'_{\mathcal{N}_i})$, the following equality holds:

$$Y_i(W_i, \mathbf{W}_{\mathcal{N}_i}, \mathbf{W}_{\mathcal{N}_{-i}}) = Y_i(W_i, \mathbf{W}_{\mathcal{N}_i}', \mathbf{W}_{\mathcal{N}_{-i}}')$$

Assumption 3 Unconfoundness of Individual and Neighborhood Treatment

$$Y_i(w,g) \perp \!\!\! \perp W_i, G_i | \mathbf{X}_i \ \forall w \in \{0,1\}, g \in \mathcal{G}_i, \forall i$$

Properties of GPS

Properties

• Balancing:

$$P(W_i, G_i | \mathbf{X}_i, \psi(w; g; \mathbf{X}_i)) = P(W_i, G_i | \psi(w; g; \mathbf{X}_i))$$

Conditional Unconfoundedness(joint)

$$Y_i(w,g) \perp \!\!\! \perp W_i, G_i | \psi(w;g; \mathbf{X}_i) \ \forall w \in \{0,1\}, g \in \mathcal{G}_i$$

Conditional Unconfoundedness

$$Y_i(w,g) \perp \!\!\! \perp W_i, G_i | \lambda(g;w;\mathbf{X}_i^g), \phi(1;\mathbf{X}_i^w) \ \forall w \in \{0,1\}, g \in \mathcal{G}_i$$

GPS estimator

$$E[E[Y_i|W_i = w, G_i = g, \psi(w; g; \mathbf{X}_i)]|W_i = w, G_i = g]$$

$$E[E[Y_i|W_i = w, G_i = g, \lambda(g; w; \mathbf{X}_i^g), \phi(1; \mathbf{X}_i^w)]|W_i = w, G_i = g]$$

Estimating procedure Subclassification and GPS

- Subclassification on $\phi(1; \mathbf{X}_i^w)$
 - Estimate $\phi(1; \mathbf{X}_i^w)$: logistic regression $W_i \sim \mathbf{X}_i^w$
 - 2 Predict $\phi(1; \mathbf{X}_{i}^{w})$
 - **3** Subclassify J subclasses B_j by $\phi(1; \mathbf{X}_i^w)$ where $\mathbf{X}_i^w \perp \!\!\! \perp W_i | i \in B_j$
- ② Within B_j , estimate $\mu_j(w,g) = E[Y_i(w,g)|i \in B_j^g]$ where $B_j^g = V_g \cap B_j$
 - Estimate $\lambda(g; w; \mathbf{X}_i^g)$: $G_i \sim W_i + \mathbf{X}_i^g$
 - 2 Estimate outcome model $Y_i \sim \lambda(g; w; \mathbf{X}_i^g) + W_i + G_i$

 - **3** Estimate $\hat{\mu}_j(w,g) = \sum_{i \in B_i^g} \hat{Y}_i(w,g)/|B_j^g|$
- ullet Estimate $\hat{\mu}(w,g)=\sum_{j=1}^J\hat{\mu}_j(w,g)\pi_j^{\mathcal{g}}$ where $\pi_j^{\mathcal{g}}=|B_j^{\mathcal{g}}|/v_g$

Notice:
$$\mu(w,g) = E[Y_i(w,g)|i \in V_g], \forall w \in \{0,1\}, g \in \mathcal{G}$$

Simulation

A friendship network from Facebook is obtained from Stanford Network Analysis Project(SNAP). It consists of 10 egocentric networks of over 4000 nodes and 80000 edges.

- Individual covariates $X_i^{ind} = (Age_i, Gender_i)$
- Neighborhood covariates

$$X_i^{neighbor} = (\frac{\sum_{j \in V_i} Age_j}{N_i}, \frac{\sum_{j \in V_i} Gender_j}{N_i}, N_i)$$

Simulate 2 scenarios on this real network

- $Z \perp \!\!\! \perp G \mid X^{ind}, X^{neighbor}$

Data Generation Mechanism

Assignment Generation Mechanism

2
$$logit(P(Z_i = 1)) = -4.5 + 0.4gender_i + 0.1age_i + 2.5friends.gender_i + 0.3friends.age_i$$

Outcome Generation Mechanism

$$Y_i(z,g) \sim \mathcal{N}(\mu(z,g,X_i^{ind},X_i^{neighbor}),1)$$

$$\mu(z,g,X_i^{ind},X_i^{neighbor}) = 15 - 7I(\phi(1,X^{ind}) \geq 0.85) - 15z + 3zI(\phi(1,X^{ind}) \geq 0.85) + \delta g$$

Results

Comparison Procedure

- A simple difference in mean outcome of treated and untreated.
- ② A regression estimator on individual treatment Z_i & covariates
- 3 Subclassification on individual propensity score & covariates

Scenarios	δ	1	2	3	GPS
$Z \perp \!\!\! \perp G X^{ind}$	low	-2.3	-0.58	-0.37	-0.02
	med	-2.46	-0.60	-0.41	-0.05
	high	-2.52	-0.53	-0.38	-0.01
$Z \perp \!\!\! \perp \!\!\! \perp \!\!\! \subseteq \!\!\! \mid \!\!\! \! \! \! \! \! \! \! \! \! \! \! \!$	low	-2.47	-1.80	-1.90	-0.7
	med	-2.78	-2.06	-2.18	-0.69
	high	-2.99	-2.23	-2.37	-0.69

Table 1: Bias of Estimators