

Evaluate Temporal Overlap using Absolute Encounter Intensity

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Model Daily Activity Pattern using Time Inhomogeneous Poisson Process with Periodic Intensity Function

Detection of camera trapping can be viewed as time-to-event data. One common selection to model this type of process is Poisson point process. Two main assumptions for Poisson point process are:

- Independency: Number of events in any disjoint time intervals are independent
- Ordinarity:

$$P(N(t + \delta t) - N(t) = 1) = \lambda(t)\delta t + o(\delta t)$$

$$P(N(t + \delta t) - N(t) > 1) = o(\delta t)$$

From assumption 1, we can derive the waiting time ($T - T_0$, how long did it take from time T_0 to next event)'s distribution to be:

$$P(T - T_0 > t) = \exp\left(-\int_{T_0}^T \lambda(u)du\right)$$

Denote $\int_0^t \lambda(u)du = \Lambda(t)$, then $\int_{T_0}^T \lambda(u)du = \Lambda(T) - \Lambda(T_0)$. The $\lambda(t) \geq 0$ is called *intensity function* and $\Lambda(t)$ is called *leading function* of the process. The *intensity function* can be understand as in a short time period, how many events (e.g. detections) should be expect.

From assumption 1 and 2, we derive the likelihood function for time-at-event. Denote time to the i th event as T_i , then $X_i = T_i - T_{i-1}$ and $X_0 = T_0$

$$f_{T_1, T_2 \dots T_n} = \exp(-\Lambda(T_n)) \prod_{i=0}^n \lambda(T_i)$$

To model daily activity pattern from time-to-event data, we can consider a family of periodic intensity function with period of $P = 1 \text{ day} = 86400s$. To construct this family of positive periodic functions, we could use an exponential of Fourier series with amplitude parameters A_i and phase parameters ϕ_i and N terms, i.e.

$$\lambda(t) = \exp\left(\frac{T_0}{2} + \sum_{i=1}^N A_i \cos\left(\frac{2\pi it}{P} - \phi_i\right)\right)$$

Then plug into likelihood function, we can have a MLE for parameters of the Fourier series and also an AIC to help us choose N .

Result from the intensity function

From the intensity function of different species, we can derive different probabilities. Denote $\lambda_i(t)$ as the detection intensity of species i .

Then

$$\int_0^P \lambda(u) du$$

is the detection probability for a day.

Also we have:

$$P(\text{it is spp } i | \text{detect spp } i \text{ or } j \text{ at } t) = \frac{\lambda_i(t)}{\lambda_i(t) + \lambda_j(t)}$$

Some results with APIS, Stockton data:

AIC table for number of Fourier terms:

Table 1: Sample AIC table

| | Bear_black | Coyote | Fox_red |
|-----|------------|----------|----------|
| N=3 | 9375.146 | 3642.153 | 351.5552 |
| N=4 | 9377.779 | 3645.593 | 348.8128 |

Absolute intensity of fox and coyote:

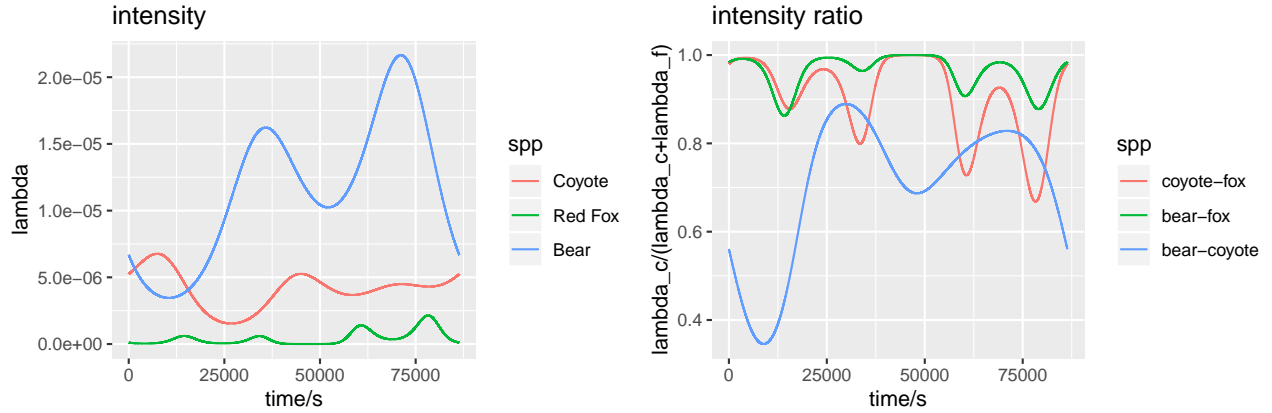


Table 2: Daily Detection Probability

| | P |
|------------|-----------|
| Bear_black | 0.6324003 |
| Coyote | 0.3001481 |
| Fox_red | 0.0374846 |

For fox, the intensity did not changed so much compare with coyote, and in most of the time, we should expect to see a coyote rather than a red fox.