

# CS161 Notes - Merge Sort

Yuren Hao

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## 1 Merge Sort

Divide-and-conquer sorting algorithm: recursively divide array into halves, sort each half, then merge.

**Algorithm:**

1. **Divide:** Split  $A[1..n]$  at midpoint  $\lfloor n/2 \rfloor$
2. **Conquer:** Recursively sort both halves
3. **Combine:** Merge sorted halves

## 2 Pseudocode

**MERGE-SORT**( $A, p, r$ ):

1. **if**  $p < r$ :
  - $q = \lfloor (p + r)/2 \rfloor$
  - **MERGE-SORT**( $A, p, q$ )
  - **MERGE-SORT**( $A, q + 1, r$ )
  - **MERGE**( $A, p, q, r$ )

**MERGE**( $A, p, q, r$ ):

1.  $n_1 = q - p + 1$ ,  $n_2 = r - q$
2. Create arrays  $L[1..n_1 + 1]$ ,  $R[1..n_2 + 1]$
3. Copy  $A[p..q] \rightarrow L[1..n_1]$ ,  $A[q + 1..r] \rightarrow R[1..n_2]$
4.  $L[n_1 + 1] = R[n_2 + 1] = \infty$
5.  $i = j = 1$
6. **for**  $k = p$  **to**  $r$ :
  - **if**  $L[i] \leq R[j]$ :  $A[k] = L[i++]$
  - **else**:  $A[k] = R[j++]$

## 3 Complexity Analysis

**Time:**  $T(n) = 2T(n/2) + \Theta(n) = \Theta(n \log n)$  (Master Theorem)

**Space:**  $\Theta(n)$  auxiliary arrays +  $\Theta(\log n)$  recursion stack =  $\Theta(n)$

## 4 Properties

**Advantages:** Stable, predictable  $O(n \log n)$ , parallelizable

**Disadvantages:**  $O(n)$  extra space, not in-place