

# CS 354 - Machine Organization & Programming

## Tuesday, November 26, 2019

**Project p5 (4.5%):** DUE at 10 pm on Monday, December 2nd

**Project p6 (4.5%):** DUE at 10 pm on Saturday, December 14th

**Homework hw7 (1.5%):** DUE TOMORROW at 10 pm Wednesday, November 27th

**Homework hw8 (1.5%):** Assigned Tomorrow

### Last Time

- Kinds of Exceptions
- Transferring Control via Exception Table
- Exceptions in IA-32 & Linux
- Processes and Context
- User/Kernel Modes
- Context Switch
- Context Switch Example

### Today

- Meet Signals
- Three Phases of Signaling
- Processes IDs and Groups
- Sending Signals
- Receiving Signals

### Next Time

- Finish Signals
- Multifile Coding
- Linking and Symbols
- Read:** B&O 7.1 - 7.2

# Meet Signals

**What?** A signal is a small message sent to a process via the kernel

Linux: 30 standard signal each given a unique positive int.  
\$kill -l (list of signals)  
signal(7) \$man 7 signal

**Why?**

- ♦ to notify user processes about
  1. low level hardware exceptions
  2. high level events in kernel or user processes
- ♦ to enable user processes to communicate with each other
- ♦ to implement a high level software form of exceptional control flow.

## Examples

1. divide by zero

exception #0 interrupts to kernel handler

- kernel signals user proc with #8 SIGFPE

2. illegal memory reference

exception #13 interrupts to kernel handler

- kernel signals user proc with #11 SIGSEGV

3. keyboard interrupt

- ctrl-c interrupts to kernel handler which

signals #2 SIGINT signal, interrupts  $\Rightarrow$  for program process terminates by default

- ctrl-z interrupts to kernel handler which

signals #20 SIGTSTP terminal stop. . . . . suspend by default.

## Three Phases of Signaling

### Sending

- ♦ when the kernel ~~exception~~ handler runs in response to an exceptional event, or a signal from some process.
- ♦ is directed to a destination process.

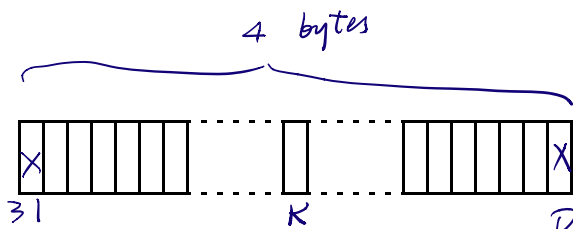
### Delivering

when the kernel records a sent signal for its destination process.

pending signal is delivered but not received

- ♦ each process has a bit vector for recording pending signals

bit vectors are kernel data structure where each bit has a distinct meaning



- ♦ bit  $k$  is set when signal  $k$  is delivered  
- - - - - cleaned - - - - - received

### Receiving

when the kernel causes the destination process to react to a pending signal.

- ♦ happens when the kernel transfers control back to a process
- ♦ multiple pending signals are done in order from low to high signal number

blocking prevent a signal from being received.

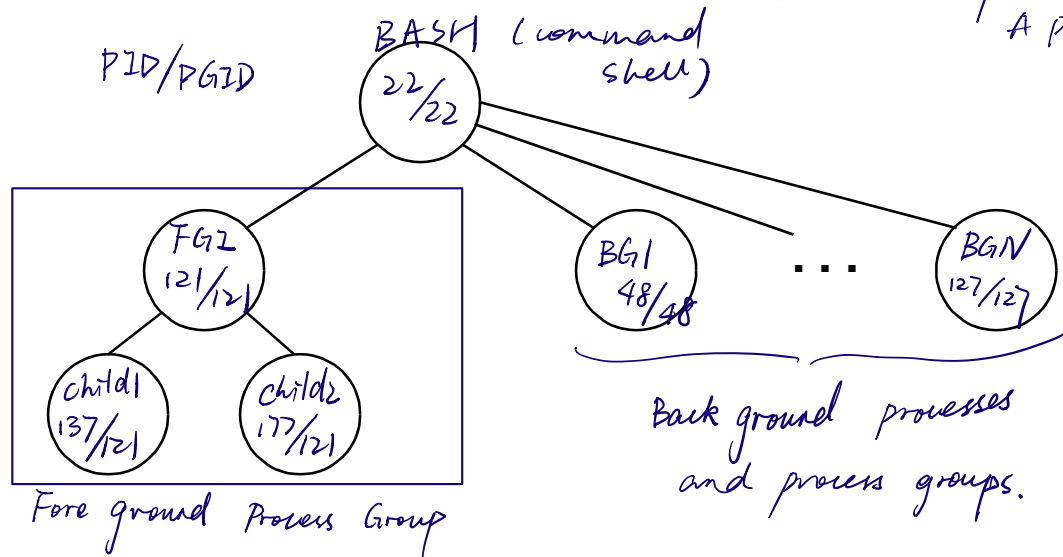
- ♦ enables a process to control which signal it pays attention to.

- ♦ each short process has a second bit vector to mark its blocked signals (1 == blocked)

## Process IDs and Groups

**What?** Each process

- is identified by a pid, process ID. A positive int
- belongs to exact one group identified by PGID.  
(Process Group ID  
A positive int).



**Why?** numbers are far easier than names

**How?**

Recall: `ps` lists processes  
`ps -U your processes`    `ps -al` all processes in long format  
`jobs` lists command line initiated processes

`getpid(2)` <sup>pgid</sup>  
`getpgid(2)`

`#include <unistd.h>`

`pid_t getpid(void)` returns calling processes PID

`pid_t getpgid(void)` - - - - - PGID.

## Sending Signals

**What?** A signal is sent by the kernel or a user process via the kernel

*From command line or in a program in a system using system calls*

**How? Linux Command**

kill(1) *sending a signal to specified destination process*  
*kill -9 <pid> 9 is sigkill (kill process)*

→ What happens if you kill your shell? *logout*

**How? System Calls**

kill(2) *sends any signal from a calling process to a specified destination process.*  
killpg(2) *sends to entire program group.*

```
#include <sys/types.h>
#include <signal.h>
int kill (pid_t pid, int sig)
```

↳ *signal name or number*  
↳ *destination process*  
↳ *returns 0 on process, -1 on error*

alarm(2) *sets an alarm which delivers a signal to calling process after a specified number of seconds.*

```
#include <unistd.h>
```

```
unsigned int alarm(unsigned int seconds)
```

↳ *delay till signal*  
↳ *number of seconds remaining if previous alarm still running. otherwise, return 0.*

## Receiving Signals

**What?** A signal is received by its destination process *by a default action or executing a programmer specified signal handler.*

### How? Default Actions

- ◆ Terminate the process *#2 sigint*
- ◆ Terminate the process and dump core *#11 sigsegv*
- ◆ Stop the process *#20 sigtstp*
- ◆ Continue the process if it's currently stopped *#18 sigcont.*
- ◆ Ignore the signal *#28 sigwrch*

### How? Signal Handler

1. *code a signal handler*
  - ◆ looks like a regular function *but it's called by the kernel.*
  - ◆ *should not make unsafe system calls*  
*E.g. printf okay in project pb.*

2. *Register the signal handler*
  - ◆ *catches one or more signals*

*signal(2) don't use*

*sigaction(2) posix was for examining & changing signal actions.*

### Code Example

```
#include <signal.h>
#include ...
#include <string.h> // for memset function

void handler_SIGALRM() { ... }

int main(...) {
    struct sigaction sa;
    memset(&sa, 0, sizeof(sa)); // sa.sa_flags = 0;
    sa.sa_handler = handler_SIGALRM;
    if (sigaction(SIGALRM, &sa, NULL) != 0) {
        printf("ERROR Binding SIGALRM HANDLER\n");
        exit(1);
    }
}
```