

# CS 354 - Machine Organization & Programming

## Tuesday, November 12, 2019

**Project p4b (~4%): DUE TOMORROW** at 10 pm on Wednesday, November 13th

### Last Time

- The Stack from a Programmer's Perspective
- The Stack and Stack Frames
- Instructions - Transferring Control

### Today

- Register Usage Conventions
- Function Call-Return Example
- Recursion
- Stack Allocated Arrays

### Next Time

- More Arrays, Structures, Pointers in Assembly

**Read:** B&O 3.8, 3.9

See pointers.pdf and recursion.pdf in Files section on course website

# Register Usage Conventions

## Return Value

`%eax` stores return value.

## Frame Base Pointer `%ebp`

callee uses to access its argument  $B(\%ebp)$  offset  $> 0$   
access its locals  $-4(\%ebp)$  offset  $< 0$

## Stack Pointer `%esp`

caller uses to set up arguments `movl ARG, D(%esp)`  
save return address `call`

distance  
 $D \geq 0$   
0: Arg 0  
4: Arg 1  
8: Arg 2

callee uses to restore return address `ret`  
save/restore callee's `%ebp` `pushl %ebp`  
`popl %ebp`

## Registers and Local Variables

→ Why use registers?

speed, but size is limited to 1, 2, 4 bytes

→ Potential problem with multiple functions using registers?

since registers are shared, conflicts can result.

caller & callee must have a consistent approach for saving & restoring registers.

## IA-32

caller-save: `%eax`, `%ecx`, `%edx`

caller must save before calling a function.

callee-save: `%ebx`, `%esi`, `%edi`

callee must save before using these.

## Function Call-Return Example

CALLER

```
int dequeue(int *queue, int *front, int rear, int *numitems, int size) {
    if (*numitem == 0) return -1;
    int dqitem = queue[*front];
    *front = inc(*front, size);
```

- 1ab setup calleE's args
- 2 call the calleE function
  - a save caller's return address
  - b transfer control to calleE
- 7 caller resumes, assigns return value

```
    *numitems -= 1;
    return dqitem;
}
```

CALLEE

```
int inc(int index, int size) {

    int incindex = index + 1;
    if (incindex == size) return 0;
    return incindex;
}
```

- 3 allocate callee's stack frame
  - a save caller's frame base
  - b set callee's frame base
  - c set callee's top of stack
- 4 callee executes ...
- 5 free callee's stack frame
  - a restore caller's top of stack
  - b restore caller's frame base
- 6 transfer control back to caller

CALLER

### CALL code in dequeue

```
1a 0x_07C  movl index, (%esp)
   b 0x_07E  movl size, 4(%esp)
2  0x_080  call inc
   a      pushl %eip (push program counter)
   b      jump 0x110 inc()
```

### RETURN code in dequeue

```
7  0x_085  movl %eax, (%ebx)
```

CALLEE

### CALL code in inc

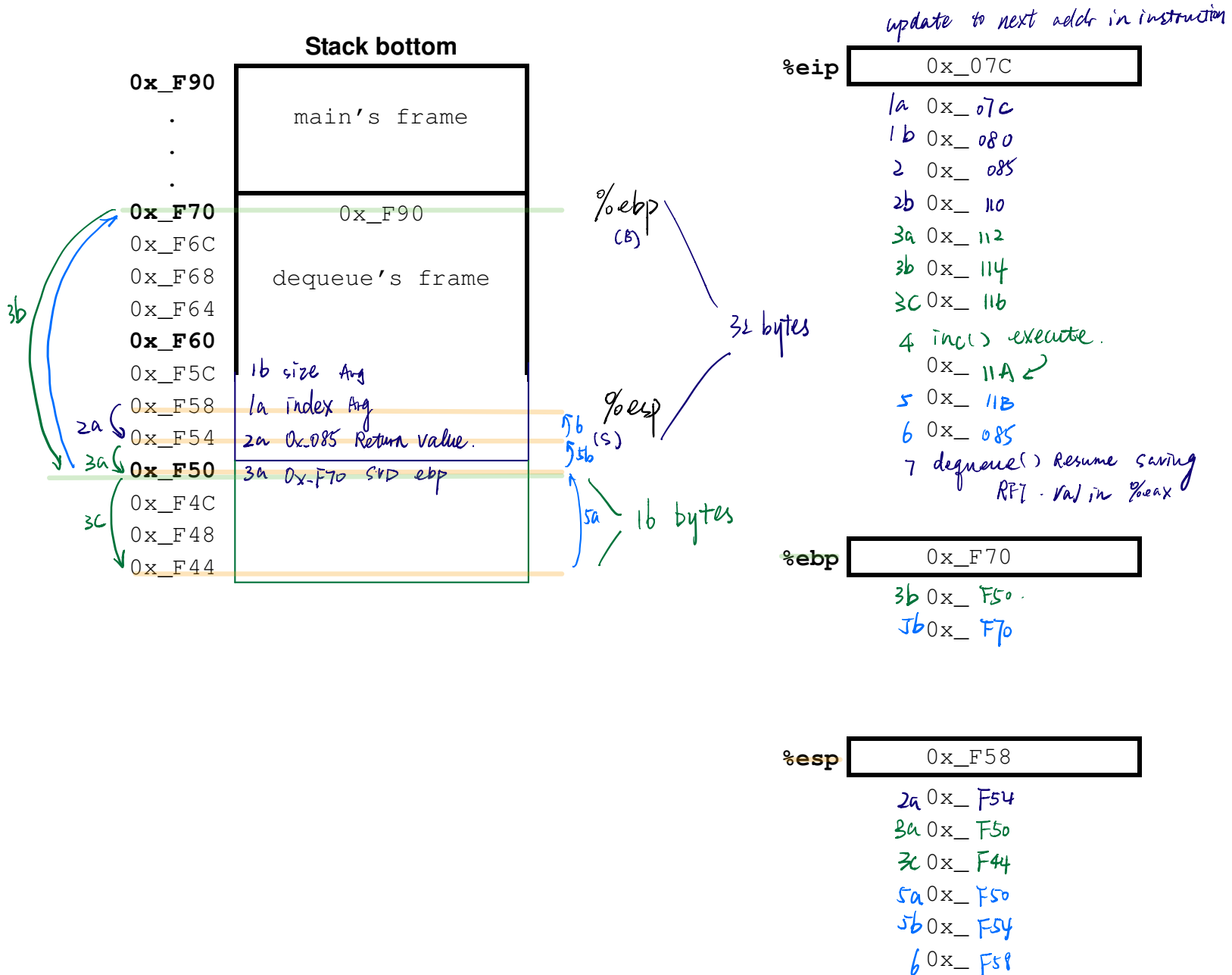
```
3a 0x_110  pushl %ebp
   b 0x_112  movl %esp, %ebp
   c 0x_114  subl $12, %esp
4  0x_116  execute inc function's body
```

### RETURN code in inc

```
5  0x_11A  leave movl %ebp, %esp
   a
   b      popl %ebp
6  0x_11B  ret
```

# Function Call-Return Example

## Execution Trace of Stack and Registers



# Recursion

Use a stack trace to determine the result of the call `fact(3)`:  $3! = 3 \times 2 \times 1 = 6$

```
int fact(int n) {
    int result;
    if (n <= 1) result = 1;   Base
    else      result = n * fact(n - 1);
    return result;
}
```

$$N! = N * (N-1)! \quad \text{Reuse}$$

if  $n \leq 1$

$$\begin{aligned} 3! &= 3 * 2! \\ &= 3 * 2 * 1! \\ &= 3 * 2 * 1 \end{aligned}$$



direct recursion when a func call itself

recursive case repeats the recursion

base case stop recursion.

"infinite" recursion is like an infinite loop and results from a missing or bad base case

## Assembly Trace

fact:

```
pushl %ebp
movl %esp, %ebp
pushl %ebx
subl $4, %esp
```

callee save register

Arg = `movl 8(%ebp), %ebx`  $n$  is in `%ebx`  
local = `movl $1, %eax` result is in `%eax`.

```
cmpl $1, %ebx
jle .L1
```

if  $n \leq 1$

```
leal -1(%ebx), %eax
movl %eax, (%esp)
call fact
```

Recursive call.

```
imull %ebx, %eax
```

$n * \text{return value}$

.L1:

```
addl $4, %esp
popl %ebx
popl %ebp
ret
```

Stack bottom

1st's arg = 3	main
main's ret addr	
main's ebp saved	
callee saved ebx	1st fact
2nd's Arg = 2	
1st's return address	
ebp saved	
Saved ebx	2nd fact
ebp	
ebx	3rd fact

\* "Infinite" recursion causes stack overflow since each recursive call consumes a bit more of stack

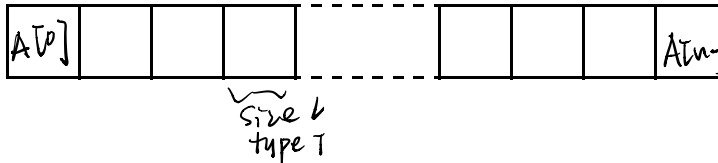
\* when tracing func in assembly code, often you can skip over the instructions that manage stack frame. and focus on the func's value (body)

# When tracing functions in assembly code

## Stack Allocated Arrays in C

### Recall Array Basics

$T \ A[N];$  where  $T$  is the element datatype of size  $L$  bytes and  $N$  is the number of elements



1. A contiguous region of stack of  $L \times N$  bytes that is allocated but not initialized.
2. the identifier "A" is associated with the starting address of array.

\* The elements of  $A$  are accessed add with which are implemented as mem type operands in ASM

### Recall Array Indexing and Address Arithmetic

$$\&A[i] = A + i = X_A + L * i$$

where  $X_A$  is starting addr of array  
 $L$  is element size.

→ For each array declarations below, what is  $L$  (element size), the address arithmetic for the  $i$ th element, and the total size of the array?

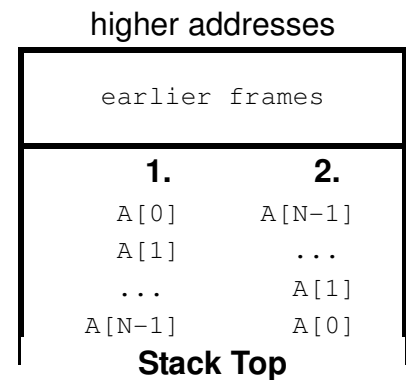
C code	$L$	address of $i$ th element	total array size
1. int I[11]	4	$X_I + 4 * i$	44
2. char C[7]			
3. double D[11]			
4. short S[42]	2	$X_S + 2 * i$	84
5. char *C[13]			
6. int **I[11]	4	$X_I + 4 * i$	44
7. double *D[7]			

# Stack Allocated Arrays in Assembly

## Arrays on the Stack

→ How is an array laid out on the stack? Option 1 or 2:

\* The first element (index 0) of an array is closest to the top of the stack.



## Accessing 1D Arrays in Assembly

IA-32 address modes are designed simply array access.

Assume array's start address in %edx and index is in %ecx

```
movl (%edx, %ecx, 4), %eax
```

$X_A \quad i \quad L$

→ Assume I is an int array, S is a short int array, for both the array's start address is in %edx, and the index i is in %ecx. Determine the element type and instruction for each:

C code	type	assembly instruction to move C code's value into %eax
→ 1. I	$m_t^*$	$X_1 \quad \text{movl } \%edx, \%eax$
→ 2. I[0]	$m_t$	$m[X_1] \quad \text{movl } (\%edx), \%eax \quad \text{first storing address.}$
3. *I		
→ 4. I[i]	$m_t$	$m[X_1 + 4i] \quad \text{movl } (\%eax, \%ecx, 4), \%eax$
5. &I[2]		
6. I+i-1		
- 7. *(I+i-3)	int	$m[X_1 + 4i - 4*3] \quad \text{movl } -12(\%eax, \%ecx, 4), \%eax$
8. S[3]		
9. S+1		
- 10. &S[i]	short*	$X_3 - 2i \quad \text{leal } (\%edx, \%ecx, 2), \%eax.$
11. S[4*i+1]		
12. S+i-5		