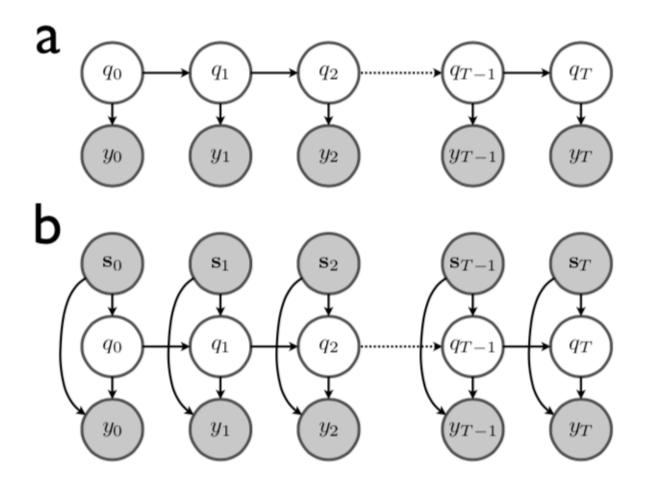
Stimulus-driven hidden Markov model

Introductions

- a. Typical hidden Markov model
- b. Stimulus-driven hidden Markov model



Notations

Variable/parameters	Mathematical expression	Comment
Stimulus	\mathbf{s}_t	size: [num_feature, num_time],

		continuous value		
	q_t	size: [1, num_time], discrete value,		
Hidden states		ranges in 1~num_state (might need a q_0		
		?)		
		size: [1, num_time], discrete value,		
Output	$\mid y_t \mid$	ranges in 1~num_out (might need a y_0		
		?)		
Transition filter	$\mathbf{F}_{m,n}$	size :[num_state, num_state,		
		num_feature], continuous value,		
		element (m,n): m to n		
Transition matrix	$lpha_{m,n,t} = rac{\exp(\mathbf{F}_{m,n}\mathbf{s}_t)}{\sum_l \exp(\mathbf{F}_{m,l}\mathbf{s}_t)}$	Size: [num_state, num_state,		
		num_time], time-varying transition		
		matrix, $\sum_n lpha_{m,n,t} = 1$		
Emission filter	$\mathbf{G}_{m,i}$	Size: [num_state, num_out,		
		num_feature]		
Emission matrix	$\eta_{m,i,t} = rac{\exp(\mathbf{G}_{m,i}\mathbf{s}_t)}{\sum_{j} \exp(\mathbf{G}_{m,j}\mathbf{s}_t)}$	Size: [num_state, num_out, num_time],		
		time-varying emission matrix		

Expectation-maximization

Expected complete log-likelihood (ECLL)

$$egin{aligned} \langle L(oldsymbol{ heta}|\mathbf{y},\mathbf{q},\mathbf{S})
angle_{\hat{p}(\mathbf{q})} &= \sum_{n=1}^N \hat{p}\ (q_0=n)\log\pi_n + \sum_{t=1}^T \sum_{n=1}^N \sum_{m=1}^N \hat{p}\ (q_{t-1}=n,q_t=m)\loglpha_{nm,t} \ &+ \sum_{t=0}^T \sum_{n=1}^N \hat{p}\ (q_t=n)\log\eta_{ny_t,t} \end{aligned}$$

To optimize ECLL, we can seperately optimize

$$\sum_{t=1}^T \sum_{m=1}^N \hat{p}(q_{t-1} = n, q_t = m) \log lpha_{n,m,t} \quad (2)$$

$$\sum_{t=1}^T \hat{p}(q_t=n) \log \eta_{n,y_t,t} \quad (3)$$

Denote: $U_{nmt}=\hat{p}\ (q_{t-1}=n,q_t=m)$, and $V_{nt}=\hat{p}\ (q_t=n)$, they are computed as follows

$$U_{nmt} = \hat{p}(q_{t-1} = n, q_t = m) = p(q_{t-1} = n, q_t = m | \mathbf{y}, \theta, \mathbf{S}) = \frac{a_{n,t} \alpha_{nmt} \eta_{my_t} b_{m,t+1}}{p(\mathbf{y} | \theta, \mathbf{S})}$$
 (4)

$$V_{nt} = \hat{p}(q_t = n) = p(q_t = n|\mathbf{y}, \theta, \mathbf{S}) = \frac{a_{n,t}b_{n,t}}{p(\mathbf{y}|\theta, \mathbf{S})}$$
 (5)

$$p(\mathbf{y}|\theta, \mathbf{S}) = \sum_{n=1}^{N} a_{n,T}$$
 (6)

For (2),

$$\sum_{t=1}^{T} \sum_{m=1}^{N} \hat{p} \left(q_{t-1} = n, q_{t} = m \right) \log \alpha_{n,m,t}$$

$$= \sum_{t=1}^{T} \sum_{m=1}^{N} U_{nmt} \log \left(\frac{\exp(\mathbf{F}_{n,m} \mathbf{s}_{t})}{\sum_{l} \exp(\mathbf{F}_{n,l} \mathbf{s}_{t})} \right)$$

$$= \sum_{t=1}^{T} \sum_{m=1}^{N} U_{nmt} \mathbf{F}_{n,m} \mathbf{s}_{t} - \sum_{t=1}^{T} \sum_{m=1}^{N} U_{nmt} \log(\sum_{l} \exp(\mathbf{F}_{n,l} \mathbf{s}_{t})) \quad (7)$$

The gradient with regard to $\mathbf{F}_{n,j}$ is,

$$\frac{\partial(2)}{\partial \mathbf{F}_{nj}} = \sum_{t=1}^{T} \left(U_{njt} - \left(\sum_{m=1}^{N} U_{nmt} \right) \alpha_{njt} \right) \mathbf{s}_{t}$$

$$= \sum_{t=1}^{T} \left(U_{njt} - \left(\sum_{m=1}^{N} U_{nmt} \right) \frac{\exp(\mathbf{F}_{n,j} \mathbf{s}_{t})}{\sum_{l} \exp(\mathbf{F}_{n,l} \mathbf{s}_{t})} \right) \mathbf{s}_{t} \quad (8)$$

The second derivative is,

$$rac{\partial^2(2)}{\partial \mathbf{F}_{nj}^2} = -\sum_{t=1}^T ig(\sum_{m=1}^N U_{nmt}ig) rac{\partial lpha_{njt}}{\partial \mathbf{F}_{nj}} \mathbf{s}_t$$

(In fact you need to compute Hessian matrix ... Stop it...)

Similarly, (3) is

$$egin{aligned} \sum_{t=1}^T V_{nt} \log \eta_{ny_t,t} \ &= \sum_{t=1}^T V_{nt} \log \Big(rac{\exp(\mathbf{G}_{ny_t}\mathbf{s}_t)}{\sum_{j=1}^M \exp(\mathbf{G}_{nj}\mathbf{s}_t)} \Big) \ &= \sum_{t=1}^T V_{nt} \mathbf{G}_{ny_t}\mathbf{s}_t - \sum_{t=1}^T V_{nt} \log \Big(\sum_{j=1}^M \exp(\mathbf{G}_{nj}\mathbf{s}_t) \Big) \end{aligned}$$

(M is the total number of output choices, i.e. num_out in the previous table)

The gradient with regard to G_{ni} is,

$$\frac{\partial(3)}{\partial \mathbf{G}_{ni}} = \sum_{t=1}^{T} V_{nt} \delta_{y_t,i} s_t - \sum_{t=1}^{T} V_{nt} \frac{\exp(\mathbf{G}_{ni} \mathbf{s}_t)}{\sum_{j=1}^{M} \exp(\mathbf{G}_{nj} \mathbf{s}_t)} \mathbf{s}_t$$
$$= \sum_{t=1}^{T} (\delta_{y_t,i} - \eta_{ni,t}) V_{nt} \mathbf{s}_t \quad (9)$$

 $\delta_{y_t,i}$ is an identity function, i.e. = 0 if $y_t \neq i$, = 1, if $y_t = i$

Training with data from multiple trials

The ECLL is the sum of the trial-specific ECLLs:

$$\begin{aligned} \mathsf{ECLL} = & < L(\theta|\mathbf{Y}^1, \mathbf{q}^1, \dots, \mathbf{Y}^R, \mathbf{q}^R >_{\hat{p}(\mathbf{q}^1, \dots, \mathbf{q}^R)} \\ &= \sum_{r=1}^R \sum_{n=1}^N V_{r,n,0} \log \pi_n + \sum_{r=1}^R \sum_{t=1}^T \sum_{n=1}^N \sum_{m=1}^N U_{r,n,m,t} \log \alpha_{r,n,m,t} + \sum_{r=1}^R \sum_{t=1}^T \sum_{n=1}^N V_{r,n,t} \log \eta_{r,n,y_t^r,t} \end{aligned}$$

The gradients with regard to filters are

$$\nabla \mathbf{F}_{ni} = \sum_{r=1}^{R} \sum_{t=1}^{T} U_{r,n,i,t} \mathbf{s}_{t} - \sum_{r=1}^{R} \sum_{t=1}^{T} U_{r,n,i,t} \delta_{ni} \mathbf{s}_{t} - \sum_{t=1}^{T} \sum_{m=1}^{N} U_{nmt} \alpha_{nit} \left(1 - \delta_{ni} \right) \mathbf{s}_{t}$$

Regularization

The objective function

$$H = \mathsf{ECLL} - \lambda_F \sum_{m,n,l} F_{mnl}^2 - \lambda_G \sum_{p,q,r} G_{p,q,r}^2$$

The gradients with regard to filters are

$$egin{aligned}
abla \mathbf{F}_{ni} &= \sum_{r=1}^R \sum_{t=1}^T U_{r,n,i,t} \mathbf{s}_t^r - \sum_{r=1}^R \sum_{t=1}^T U_{r,n,i,t} \delta_{ni} \mathbf{s}_t^r - \sum_{r=1}^R \sum_{t=1}^T \sum_{m=1}^N U_{r,n,m,t} lpha_{r,nit} \left(1 - \delta_{ni}
ight) \mathbf{s}_t^r \ &- 2 \lambda_F \mathbf{F}_{ni} \end{aligned}$$
 $egin{aligned}
abla \mathbf{G}_{mj} &= \sum_{r=1}^R \sum_{t=0}^T \sum_{n=1}^N V_{r,n,t} \Big(\delta_{y_t^r,j} (1 - \delta_{1,y_t^r}) - \eta_{r,m,j} (1 - \delta_{1,j}) \Big) \mathbf{s}_t^r \ &- 2 \lambda_G \mathbf{G}_{mj} \end{aligned}$

Trouble shooting

Non converging ECLL for long time series / α almost 1 in diagonal elements

First try: get diagonal elements in trans_filter 0.

Now if
$$m=n$$
, $lpha_{nmt}=rac{1}{1+\sum_{l
eq n}\exp(\mathbf{F}_{nl}\mathbf{s}_t)}$, else, $lpha_{nmt}=rac{\exp(\mathbf{F}_{nm}\mathbf{s}_t)}{1+\sum_{l
eq n}\exp(\mathbf{F}_{nl}\mathbf{s}_t)}$

Use the Kronecker delta function, we get one expression:

$$lpha_{nmt} = rac{\exp\Bigl(\mathbf{F}_{nm}\mathbf{s}_t(1-\delta(m,n))\Bigr)}{\sum_l \exp\Bigl(\mathbf{F}_{nl}\mathbf{s}_t(1-\delta(l,n))\Bigr)}$$

The gradients of Eq.(2) turn into:

$$\begin{split} \frac{\partial}{\partial \mathbf{F}_{ni}} \Big(\sum_{t=1}^T \sum_{m=1}^N \hat{p} \left(q_{t-1} = n, q_t = m \right) \log \alpha_{n,m,t} \Big) \\ &= \sum_{t=1}^T \sum_{m=1}^N U_{nmt} \Big(\frac{\partial}{\partial \mathbf{F}_{ni}} (\mathbf{F}_{nm} \mathbf{s}_t (1 - \delta(m,n))) - \frac{\partial}{\partial \mathbf{F}_{ni}} (\log(\sum_l \exp(\mathbf{F}_{nl} \mathbf{s}_t (1 - \delta(l,n))))) \Big) \\ &= \sum_{t=1}^T \sum_{m=1}^N U_{nmt} \Big(\delta_{im} (1 - \delta_{mn}) \mathbf{s}_t - \frac{\exp(\mathbf{F}_{ni} \mathbf{s}_t (1 - \delta(i,n))) \mathbf{s}_t (1 - \delta(i,n))}{\sum_l \exp(\mathbf{F}_{nl} \mathbf{s}_t (1 - \delta(l,n)))} \Big) \\ &= \sum_{t=1}^T \sum_{m=1}^N U_{nmt} \delta_{im} \mathbf{s}_t - \sum_{t=1}^T \sum_{m=1}^N U_{nmt} \delta_{im} \delta_{mn} \mathbf{s}_t - \sum_{t=1}^T \sum_{m=1}^N U_{nmt} \alpha_{nit} (1 - \delta_{ni}) \mathbf{s}_t \end{split}$$

Applying the properties of Kronecker delta function,

we have

$$rac{\partial}{\partial \mathbf{F}_{ni}}(2) = \sum_{t=1}^{T} U_{ni,t} \mathbf{s}_t - \sum_{t=1}^{T} U_{ni,t} \delta_{ni} \mathbf{s}_t - \sum_{t=1}^{T} \sum_{m=1}^{N} U_{nmt} lpha_{nit} \left(1 - \delta_{ni}
ight) \mathbf{s}_t$$

If n = i, it's zero!

for other i, it's
$$\sum_{t=1}^T U_{ni,t} \mathbf{s}_t - \sum_{t=1}^T \sum_{m=1}^N U_{nmt} \alpha_{nit} \mathbf{s}_t$$

After this, the trained α is close to the true one. Nice!

Let's do the similar thing on the lovely η , i.e. select one output as base, say, output 1, then we get

$$\eta_{m,i,t} = rac{\exp\Bigl(\mathbf{G}_{mi}\mathbf{s}_t(1-\delta_{1,i})\Bigr)}{\sum_l \exp\Bigl(\exp\Bigl(\mathbf{G}_{ml}\mathbf{s}_t(1-\delta_{1,l})\Bigr)\Bigr)}$$

The gradients of Eq.(3) turn into:

$$rac{\partial}{\partial \mathbf{G}_{mj}}(3) = \sum_{t=0}^{T} \sum_{n=1}^{N} V_{nt} \Big(\delta_{y_t,j} (1-\delta_{1,y_t}) - \eta_{m,j} (1-\delta_{1,j}) \Big) \mathbf{s}_t$$

Easily trapped in local minima

Train multiple times with different random initializations. And feed more data.

Not working: (