

Chapter 1

Real Analysis and Topology

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Season Year

Introduction

The following are complementary reading for the course.

- G. Grimmett and D. J. A. Welsh, Probability: An Introduction, 1986
- J. K. Blitzstein and J. Hwang, Introduction to Probability, 2019
- D. F. Anderson et al, Introduction to Probability, 2018
- S. M. Ross, Introduction to Probability Models, 2014
- G. Grimmett and D. Stirzaker, Probability and Random Processes, 2001
- G. Grimmett and D. Stirzaker, One Thousand Exercises in Probability, 2009

Notation. Unbracketed superscripts are used to label the components of vectors, with unbracketed subscripts labelling different vectors.

Contents

	1	Real Analysis and Topology	1
L1	1	Euclidean spaces	3
	1.1	Euclidean norm	3
	1.2	Convergence in \mathbb{R}^n	3
	2	Continuity and limits of functions	4
	2.1	Open sets	4
	2.2	Continuity	4
	3	Derivative of maps of Euclidean spaces	4
	3.1	Total derivatives	4
	3.2	Directional and partial derivatives	4
	3.3	Higher order derivatives	5
	4	Inverse and implicit function theorems	5
	4.1	Inverse function theorem	5
	4.2	Implicit function theorem	5
	5	Metric spaces	5
	5.1	Introduction	5
	5.2	Normed vector spaces	5
	5.3	Sets in metric spaces	5
	5.4	Continuous maps of metric spaces	5
	6	Topological spaces	5
	6.1	Topologies and their spaces	5
	6.2	Convergence and Hausdorff property	5
	6.3	Closed sets	5
	6.4	Continuous maps	5
	7	Connectedness	5
	7.1	Definition	5
	7.2	Continuous maps	5
	7.3	Path connected sets	5
	8	Compactness	5
	8.1	Covers	5
	8.2	Sequential compactness	5
	8.3	Continuous maps	5
	8.4	Arzelá-Ascoli theorem	5
	9	Completeness	5
	9.1	Banach spaces	5
	9.2	Fixed point theorem	5

1 Euclidean spaces

Definition 1.0.1 (\mathbb{R}^n). The set $\mathbb{R}^n = \{(x^1, x^2, \dots, x^n) : x^i \in \mathbb{R}, \forall i \in [1, n]\}$ will be considered with the operations to make it a real vector space.

1.1 Euclidean norm

Definition 1.1.1 (Inner product). We will have the **inner product** on \mathbb{R}^n by $\langle \cdot, \cdot \rangle : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ satisfying:

$$\langle x, y \rangle := \sum_{i=1}^n x^i y^i,$$

with the **Euclidean norm** given by,

$$\|\cdot\| : \mathbb{R}^n \rightarrow [0, \infty) \text{ with } \|x\| = \sqrt{\langle x, x \rangle}.$$

Proposition 1.1.2 (Properties of the Euclidean norm). The Euclidean norm satisfies the following properties:

(N1) for all $x \in \mathbb{R}^n$, $\|x\| \geq 0$ achieving equality iff $x = 0$,

(N2) for all $x \in \mathbb{R}^n$ and $\lambda \in \mathbb{R}$, $\|\lambda x\| = |\lambda| \cdot \|x\|$,

(N3) for all $x, y \in \mathbb{R}^n$: $\|x + y\| \leq \|x\| + \|y\|$,

Theorem 1.1.3 (Cauchy-Swartz inequality). For all $x, y \in \mathbb{R}^n$, $|\langle x, y \rangle| \leq \|x\| \cdot \|y\|$.

Theorem 1.1.4 (Reverse triangle inequality). For all $x, y \in \mathbb{R}^n$, $|\|x\| - \|y\|| \leq \|x - y\|$.

Proposition 1.1.5. For $x = (x^1, x^2, \dots, x^n) \in \mathbb{R}^n$,

$$\max_{k \in [1, n]} |x^k| \leq \|x\| \leq \sqrt{n} \max_{k \in [1, n]} |x^k|.$$

Proof. Exercise □

1.2 Convergence in \mathbb{R}^n

Definition 1.2.1 (Open ball). In \mathbb{R}^n we define the **open ball** around $x \in \mathbb{R}^n$ of size $r \in \mathbb{R}$ as

$$B_r(x) := \{y \in \mathbb{R}^n : \|x - y\| < r\}.$$

This will be analogous to the notion of open intervals used throughout analysis 1.

Definition 1.2.2 (Sequence in \mathbb{R}^n). A **sequence** in \mathbb{R}^n is an ordered list $x_0, x_1, \dots, x_i \dots$ with $x_i \in \mathbb{R}^n$ for all $i \in \mathbb{N}$, written $(x_i)_{i=0}^\infty$

Definition 1.2.3 (Convergence in \mathbb{R}^n). We say a sequence in \mathbb{R}^n , $(x_i)_{i=0}^\infty$ **converges to** $x \in \mathbb{R}^n$ iff

$$\forall \epsilon > 0 \exists N \in \mathbb{N} \text{ such that, } \forall n \geq N, \|x_i - x\| < \epsilon$$

and we write $x_i \rightarrow x$ as $i \rightarrow \infty$ or $\lim_{i \rightarrow \infty} x_i = x$.

Lemma 1.2.4. The sequence of vectors in \mathbb{R}^n , $(x_i)_{i=0}^\infty$, converges to some $x = (x^1, x^2, \dots, x^n) \in \mathbb{R}^n$ iff each component of x_i converges to the corresponding component in x :

$$\forall k \in [1, n] \lim_{i \rightarrow \infty} x_i^k = x^k.$$

Proof. (\implies) Given $\lim_{i \rightarrow \infty} x_i^k = x^k$ for all $k \in [1, n]$ we have that for all $\epsilon > 0$, $|x_i^k - x^k| < \frac{\epsilon}{\sqrt{n}}$ for all $i \geq N_k$ for each $k \in [1, n]$ respectively. We take $N = \max_{k \in [1, n]} N_k$ and now have:

$$\max_{k \in [1, n]} |x_i^k - x^k| < \frac{\epsilon}{\sqrt{n}} \implies \|x_i - x\| \leq \sqrt{n} \max_{k \in [1, n]} |x_i^k - x^k| < \epsilon.$$

(\impliedby) Similarly, given $\lim_{i \rightarrow \infty} x_i = x \implies \|x_i - x\| < \epsilon$ for all $\epsilon > 0$:

$$|x_i^k - x^k| \leq \max_{k \in [1, n]} |x_i^k - x^k| \leq \|x_i - x\| < \epsilon,$$

therefore $\lim_{i \rightarrow \infty} x_i^k = x^k$ for all $k \in [1, n]$. □

2 Continuity and limits of functions

2.1 Open sets

Definition 2.1.1 (Open set in \mathbb{R}^n). A subset $U \subseteq \mathbb{R}^n$ is **open** in \mathbb{R}^n iff:

$$\forall x \in U, \exists r > 0 \text{ such that } B_r(x) \subseteq U.$$

2.2 Continuity

Definition 2.2.1 (Continuity). Let $A \subseteq \mathbb{R}^n$ then we have $f : A \rightarrow \mathbb{R}^m$ **continuous at** some $p \in A$ iff

$$\forall \epsilon > 0, \exists \delta > 0 \text{ such that } \forall x \in A \text{ with } \|x - p\| < \delta, \|f(x) - f(p)\| < \epsilon.$$

If f is continuous at all $p \in A$ we say f is **continuous on** A .

Theorem 2.2.2. Let $A \subseteq \mathbb{R}^n$ and $B \subseteq \mathbb{R}^m$ with $f : A \rightarrow B$ continuous at $p \in A$. Suppose $g : B \rightarrow \mathbb{R}^l$ is continuous at $f(p)$, then $g \circ f : A \rightarrow \mathbb{R}^l$ is continuous at p .

Proof. □

3 Derivative of maps of Euclidean spaces

3.1 Total derivatives

Definition 3.1.1 (Total derivative). Given open $\Omega \subset \mathbb{R}^n$, the function $f : \Omega \rightarrow \mathbb{R}^m$ is **differentiable at** $p \in \Omega$ iff there is a linear map $\Lambda : \mathbb{R}^n \rightarrow \mathbb{R}^m$ satisfying:

$$\lim_{x \rightarrow p} \frac{\|f(x) - f(p) - \Lambda(x - p)\|}{\|x - p\|} = 0.$$

Have $Df(p) := \Lambda$ be the **total derivative** of f at p .

Remark 3.1.2. Given $f : (a, b) \rightarrow \mathbb{R}$ differentiable at $p \in (a, b)$, we have

$$\begin{aligned} \lim_{x \rightarrow p} \frac{\|f(x) - f(p) - \Lambda(x - p)\|}{\|x - p\|} &= \lim_{x \rightarrow p} \frac{|f(x) - f(p) - \lambda \cdot (x - p)|}{|x - p|} = \lim_{x \rightarrow p} \left| \frac{f(x) - f(p)}{x - p} - \lambda \right| = 0 \\ \implies \lim_{x \rightarrow p} \left| \frac{f(x) - f(p)}{x - p} \right| &= \lambda, \text{ which satisfies the normal definition for a derivative.} \end{aligned}$$

Theorem 3.1.3 (Uniqueness of total derivative). If the total derivative of a function $f : \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ exists, then it is unique.

Proof. □

Theorem 3.1.4 (Chain rule). Let $\Omega \subset \mathbb{R}^n$, $\Omega' \subset \mathbb{R}^m$ be open and have $g : \Omega \rightarrow \Omega'$, $f : \Omega' \rightarrow \mathbb{R}^l$ differentiable at $p, g(p)$ respectively and let $h := f \circ g$, $Dh(p) = Df(g(p)) \circ Dg(p)$.

Proof. □

3.2 Directional and partial derivatives

Definition 3.2.1 (Directional derivative). Suppose $\Omega \subseteq \mathbb{R}^n$ is open with $f : \Omega \rightarrow \mathbb{R}^m$ differentiable at $p \in \Omega$. For all $v \in \mathbb{R}^n$ the **directional derivative** of f at p in the direction of v is:

$$\frac{\partial f}{\partial v}(p) := \lim_{t \rightarrow 0} \frac{f(p + tv) - f(p)}{t} = Df(p)[v].$$

With the partial derivatives of f given by:

$$D_i f(p) := \frac{\partial f}{\partial e_i}(p), \text{ for all } i \in [1, n].$$

Remark 3.2.2. If the total derivative of a function exists, then so do all of its directional derivatives.

Theorem 3.2.3. If $\Omega \subset \mathbb{R}^n$ is open with $f : \Omega \rightarrow \mathbb{R}$ with all partial derivatives existing for all $x \in \Omega$. If the map $x \mapsto D_i f(x)$ is continuous at $p \in \Omega$ for all partial derivatives, then f is differentiable at p .

3.3 Higher order derivatives

4 Inverse and implicit function theorems

4.1 Inverse function theorem

4.2 Implicit function theorem

5 Metric spaces

5.1 Introduction

5.2 Normed vector spaces

5.3 Sets in metric spaces

5.4 Continuous maps of metric spaces

6 Topological spaces

6.1 Topologies and their spaces

6.2 Convergence and Hausdorff property

6.3 Closed sets

6.4 Continuous maps

7 Connectedness

7.1 Definition

7.2 Continuous maps

7.3 Path connected sets

8 Compactness

8.1 Covers

8.2 Sequential compactness

8.3 Continuous maps

8.4 Arzelá-Ascoli theorem

9 Completeness

9.1 Banach spaces

9.2 Fixed point theorem