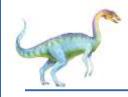
Chapter 7: Deadlocks





In a multiprogramming environment, several processes may compete for a finite number of resources.

A process requests resources; if the resources are not available at that time, the process enters a waiting state.

Sometimes, a waiting process is never again able to change state, because the resources it has requested are held by other waiting processes.

This situation is called a **deadlock**.

In this chapter, we describe methods that an operating system can use to prevent or deal with deadlocks





An Example

- When two trains approach each other at a crossing, both shall come to a full stop, and neither shall start up again until the other has gone
- A law passed by the Kansas legislature early in the 20th century



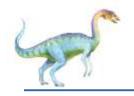




System Model

- System consists of a finite number of resources
- A number of competing processes
- Partitioned into several **resource types** R_1, R_2, \ldots, R_m
 - CPU cycles, memory space, I/O devices
- Each resource type R_i has W_i instances.
- Synchronization tools, such as mutex locks and semaphores are also considered system resources
 - A common source of deadlock
- Each process utilizes a resource in only the sequence:
 - request
 - use
 - release





Deadlock with Mutex Locks

☐ The locking tools (e.g., mutex locks, semaphores) are designed to avoid race conditions. However, inappropriate usage of them can lead to deadlocks.

Example?

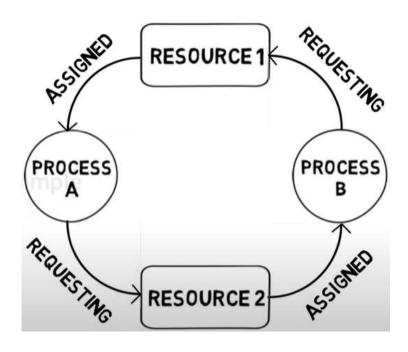
- Deadlock A set of processes is deadlocked when every process in the set is waiting for the resource that is currently allocated to another process in the set
- Let S and Q be two semaphores initialized to 1

```
P_0 P_1 wait(S); wait(Q); wait(Q); wait(S); ... signal(S); signal(Q); signal(S);
```

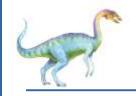




Deadlock Example







Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

- Mutual exclusion: at least one resource must be held in a non-sharable mode; that is, only one process at a time can use a resource
- Hold and wait: a process must be holding at least one resource and waiting to acquire additional resources held by other processes
- No preemption: Resources cannot be preempted; that is, a resource can be released only voluntarily by the process holding it, after that process has completed its task
- Circular wait: A set $\{P_0, P_1, ..., P_n\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1 , P_1 is waiting for a resource that is held by P_2 , ..., P_{n-1} is waiting for a resource that is held by P_0 .

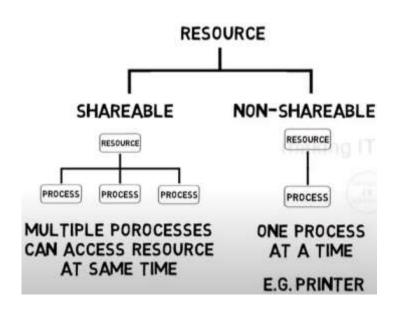
The circular-wait condition implies the hold-and-wait condition

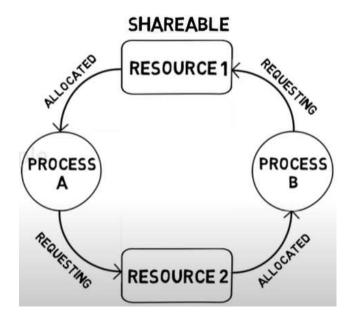




Mutual exclusion

Mutual exclusion: at least one resource must be held in a nonsharable mode; that is, only one process at a time can use a resource



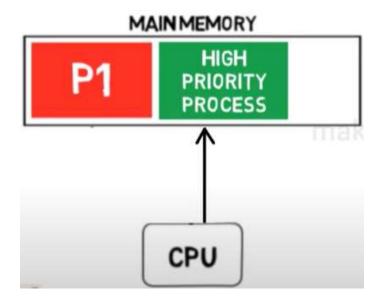




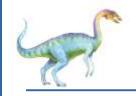
No preemption

■ No preemption: Resources cannot be preempted; that is, a resource can be released only voluntarily by the process holding it, after that process has completed its task

Preemption: force stopping a process

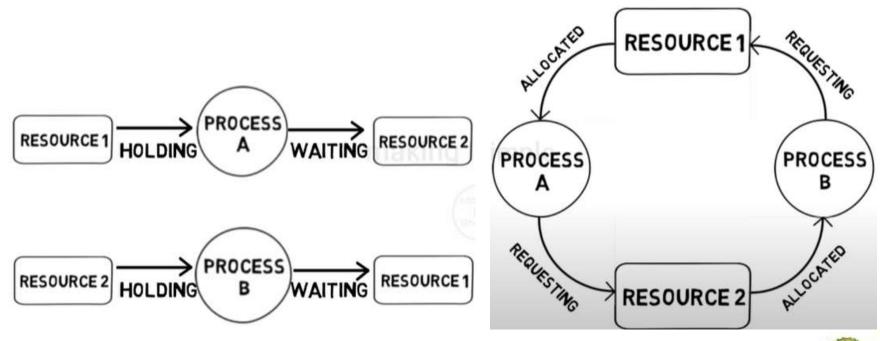


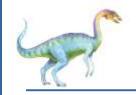




Hold and wait

■ Hold and wait: a process must be holding at least one resource and waiting to acquire additional resources held by other processes





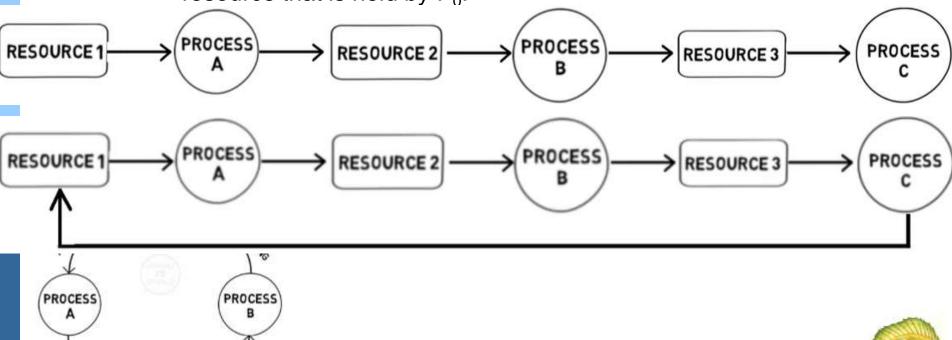
RESOURCE 2

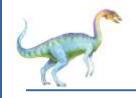
0

Circular wait

Deadlock can arise if four conditions hold simultaneously.

Circular wait: A set $\{P_0, P_1, ..., P_n\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1, P_1 is waiting for a resource that is held by $P_2, ..., P_{n-1}$ is waiting for a resource that is held by P_n , and P_n is waiting for a resource that is held by P_0 .





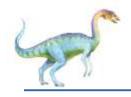
Resource-Allocation Graph

Deadlocks can be described more precisely in terms of a **directed graph** called a system resource-allocation graph

A set of vertices V and a set of edges E.

- - $P = \{P_1, P_2, ..., P_n\}$, the set consisting of all the processes in the system
 - $R = \{R_1, R_2, ..., R_m\}$, the set consisting of all resource types in the system
- □ request edge directed edge $P_i \rightarrow R_i$
- assignment edge directed edge $R_i \rightarrow P_i$





Resource-Allocation Graph (Cont.)

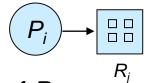
Process



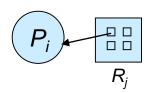
Resource Type with 4 instances



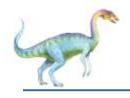
 \blacksquare P_i requests instance of R_i



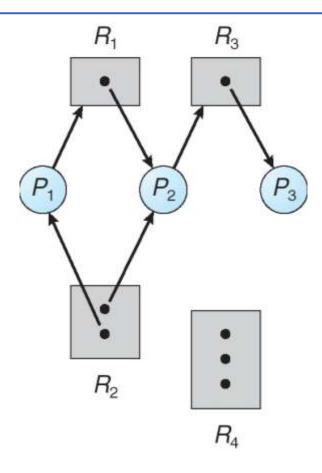
 \blacksquare P_i is holding an instance of R_j



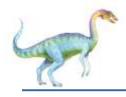




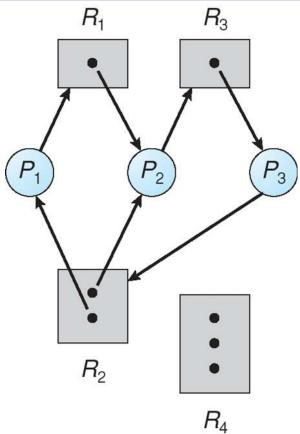
Example of a Resource Allocation Graph



- Do we have a deadlock here?
- □ It can be shown that if the graph contains no cycles, then no process in the system is deadlocked



Resource Allocation Graph With A Deadlock



Two minimal cycles:

$$P_1 \rightarrow R_1 \rightarrow P_2 \rightarrow R_3 \rightarrow P_3 \rightarrow R_2 \rightarrow P_1$$

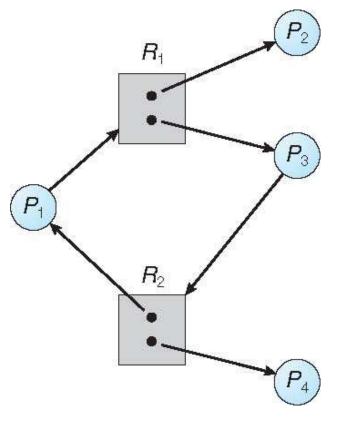
 $P_2 \rightarrow R_3 \rightarrow P_3 \rightarrow R_2 \rightarrow P_2$

Do we have a deadlock here?





Graph With A Cycle But No Deadlock

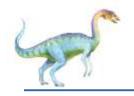


If the graph does contain a cycle, then a deadlock may exist

$$P_1 \rightarrow R_1 \rightarrow P_3 \rightarrow R_2 \rightarrow P_1$$

Do we have a deadlock here?

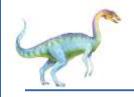




Basic Facts

- ☐ If graph contains no cycles ⇒ no deadlock
- If graph contains a cycle ⇒
 - > if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock





Methods for Handling Deadlocks

Deadlock prevention

Ensure that at least one of the necessary conditions cannot hold

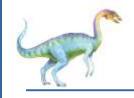
Deadlock avoidance

Requires that the OS be given additional information in advance concerning which resources a process will request and use during its lifetime

Detection & Recovery

Allow the system to enter a deadlock state, detect it, and then recover





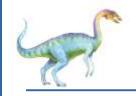
Deadlock Prevention

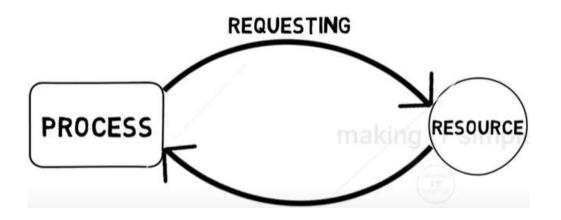
Prevention is better than cure

It's better to take preventive measures long before problem occurs

Idea: remove any one or all four conditions







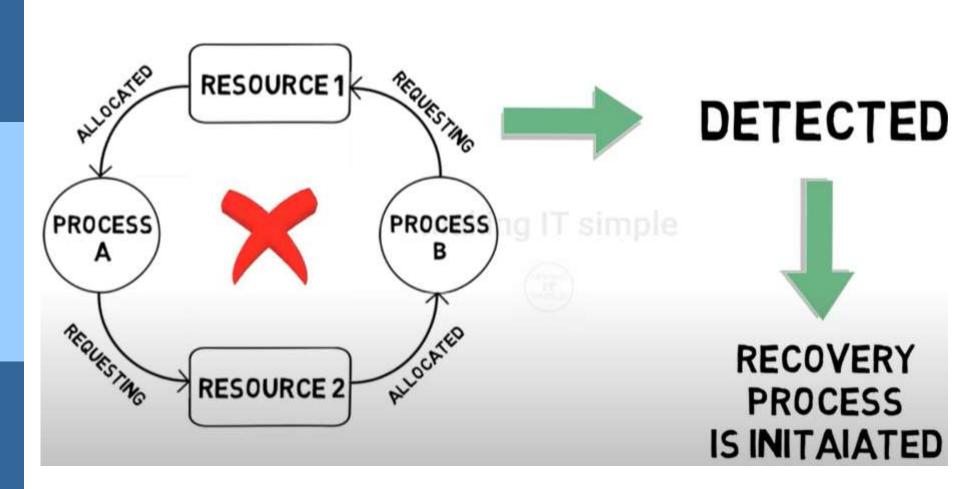
IS THE REQUESTED RESOURCE
ALLOCATED TO ANY
OTHER PROCESS?

IF WE ALLOCATE THE REQUESTED RESOURCE, WILL IT LEAD TO DEADLOCK?





Detection & Recovery







Deadlock Prevention

- Mutual Exclusion not required for sharable resources (e.g., read-only files); must hold for nonsharable resources
 - We cannot prevent deadlocks by denying the mutual-exclusion condition





Deadlock Prevention

- Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources
 - Method 1: Require process to request and be allocated all its resources before it begins execution, disadvantage?
 - Method 2: Allow process to request resources only when the process has none allocated to it.
 - Before request, first release all
 - Consider a process that copies data from a DVD driver to a file on disk, sorts the file, and then prints the results to a printer
 - Method 1: request all three resources in the beginning
 - Method 2: request DVD and disk file first; copy from DVD to disk file; release both DVD and file; and then request disk file and printer
 - Low resource utilization; starvation possible



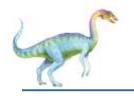


Deadlock Prevention (Cont.)

No Preemption –

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are preempted (released)
- Preempted resources are added to the list of resources for which the process is waiting
- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting





Deadlock Prevention (Cont.)

- ☐ Circular Wait impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration
 - \triangleright F(tape drive) = 1; F(disk drive) = 5; F(printer) = 12
 - A process can initially request any number of instances of a resource type---say, R_i . After that, the process can request instances of resource type R_i if and only if $F(R_i) > F(R_i)$
 - Alternatively, we can require that a process requesting an instance of resource type R_j must have released any resources R_i such that $F(R_i) > F(R_j)$

If these two protocols are used, then the circular-wait condition cannot hold



Deadlock Example

```
/* thread_one runs in this function */
void *do_work_one(void *param)
   pthread_mutex_lock(&first_mutex);
   pthread_mutex_lock(&second_mutex);
    * Do some work
   pthread_mutex_unlock(&second_mutex);
   pthread_mutex_unlock(&first_mutex);
   pthread_exit(0);
/* thread_two runs in this function */
void *do_work_two(void *param)
   pthread_mutex_lock(&second_mutex);
   pthread_mutex_lock(&first_mutex);
   /**
    * Do some work
   pthread_mutex_unlock(&first_mutex);
   pthread_mutex_unlock(&second_mutex);
   pthread_exit(0);
```

If the lock ordering was:

```
F(first_mutex) = 1
F(second_mutex) = 5
```

The thread_two could not request the locks out of order

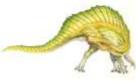


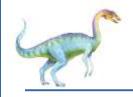


Requires that the system has some **additional information** available, about how resources are to be request

- □ Simplest and most useful model requires that each process declare the *maximum number* of resources of each type that it *may* need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circularwait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes

Need priori information





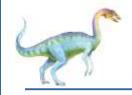




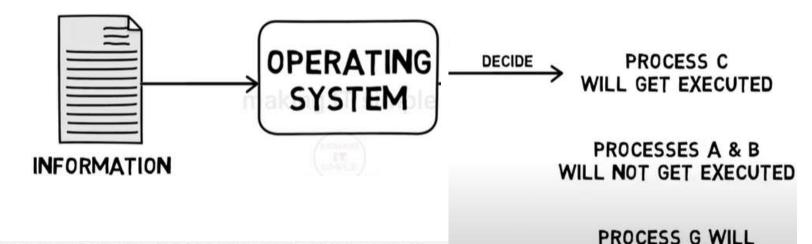
Process P will request first the tape drive and then the printer before releasing both resources?

Whereas process Q will request first the printer and then the tape drive?

With this knowledge of the complete sequence of requests and releases for each process, the system can decide for each request whether or not the process should wait in order to avoid a possible future deadlock.



Just avoiding problem when it is about to happens



- 1) WHICH PROCESSES ARE READY FOR EXECUTION
- 2) WHAT RESOURCES ARE REQUIRED FOR PROCESSES
- 3) HOW MUCH OF TIME WILL THE PROCESS HOLD RESOURCES



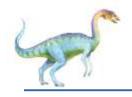
GET EXECUTED FIRST



Deadlock Avoidance Algorithm:

Banker's Algorithm





- A resource allocation and deadlock avoidance algorithm
 - Tests for safety by simulating the allocation for predetermined maximum possible amounts of all resources

Then makes a check to test for possible activities, before deciding whether allocation should be allowed to continue.





- □ Considering a system with 5 processes, and 3 resources of type A, B, C
 - A: 10 instances
 - B: 5 instances
 - □ C: 7 instances
- \square Suppose at time t_0 following snapshot of the system has been taken:

Process	Allocation	Max	Available
	АВС	АВС	АВС
P ₀	0 1 0	7 5 3	3 3 2
P_1	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	



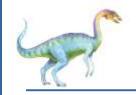
Process	Allocation	Max	Available	
	АВС	АВС	АВС	
P ₀	0 1 0	7 5 3	3 3 2	
P ₁	2 0 0	3 2 2		
P ₂	3 0 2	9 0 2		
P ₃	2 1 1	2 2 2		
P ₄	0 0 2	4 3 3		

Question1. What will be the content of the **Need matrix**?

Need = Max - Allocation

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	3	1





Question2. Is the system in a safe state? If Yes, then what is the safe sequence?

Process	Allocation	Max	Available
	АВ С	АВС	АВС
P ₀	0 1 0	7 5 3	3 3 2
P ₁	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	თ	1

For
$$P_0$$
: need = 7 4 3

available =
$$3 \ 3 \ 2$$





Process	Allocation	Max	Available
	АВС	АВС	АВС
P ₀	0 1 0	7 5 3	3 3 2
P ₁	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	3	1

For P_1 : need = 1 2 2

available = $3 \ 3 \ 2$

need < available

P₁ can be allocated to resources

After P1 is finished, all allocated resources must be released

available = $3 \ 3 \ 2 + 2 \ 0 \ 0 = 5 \ 3 \ 2$



Process	Allocation	Max	Available	
3	A B C	АВС	АВС	
Po	0 1 0	7 5 3	5 3 2	
Pi	2 0 0	3 2 2		
P ₂	3 0 2	9 0 2	1	
P ₃	2 1 1	2 2 2	1	
P ₄	0 0 2	4 3 3		

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	3	1

For P_2 : need = 6 0 0

available = 5 3 2

need > available

P₂ must wait





Process	Allocation	Max	Available
3	A B C	АВС	АВС
Po	0 1 0	7 5 3	5 3 2
Pi	2 0 0	3 2 2	1
P ₂	3 0 2	9 0 2	1
P ₃	2 1 1	2 2 2	1
P ₄	0 0 2	4 3 3	1

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	3	1

For
$$P_3$$
: need = 0 1 1

available = 5 3 2

need < available

P₃ can be allocated to resources

After P3 is finished, all allocated resources must be released

available =
$$5\ 3\ 2\ +\ 2\ 1\ 1\ = 7\ 4\ 3$$





Process	Allocation	Max	Available
	АВС	АВС	АВС
Po	0 1 0	7 5 3	7 4 3
Pi	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	3	1

For P_4 : need = 4 3 1

available = 743

need < available

P₄ can be allocated to resources

After P4 is finished, all allocated resources must be released

available = $7 \ 4 \ 3 + 0 \ 0 \ 2 = 7 \ 4 \ 5$





Process	Allocation	Max	Available
	АВС	АВС	A B C
Po	0 1 0	7 5 3	7 4 5
Pi	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P_4	0 0 2	4 3 3	.]

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	3	1

For P_0 : need = 7 4 3

available = 745

need < available

P₀ can be allocated to resources

After P0 is finished, all allocated resources must be released

available = $7 \ 4 \ 5 + 0 \ 1 \ 0 = 7 \ 5 \ 5$





Process	Allocation	Max	Available
	АВС	АВС	АВС
Po	0 1 0	7 5 3	7 5 5
P ₁	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	

Process	Need		
	Α	В	С
P ₀	7	4	3
P ₁	1	2	2
P ₂	6	0	0
P ₃	0	1	1
P ₄	4	3	1

For P_2 : need = 6 0 0

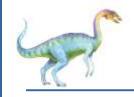
available = 755

need < available

P₂ can be allocated to resources

After P2 is finished, all allocated resources must be released

available = 755+302=1057



Hence, the system is in safe state!

The safe sequence is P1, P3, P4, P0, P2





Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
 - An algorithm that examines the state of the system to determine whether a deadlock has occurred
- Recovery scheme
 - Option 1: Process Termination----abort one or more processes to break the circular wait
 - Option 2: Process Preemption-----preempt some resources from one or more of the deadlocked processes





Recovery from Deadlock: Process Termination

- Abort all deadlocked processes
 - What's drawback?
 - Break, but at great expense
- Abort one process at a time until the deadlock cycle is eliminated
 - What's drawback?
 - Incurs considerable overhead, deadlock-detection algorithm invoked frequently
- In which order should we choose to abort?
 - Priority of the process
 - How long process has computed, and how much longer to completion
 - Resources the process has used
 - 4. Resources process needs to complete
 - 5. How many processes will need to be terminated
 - 6. Is process interactive or batch?

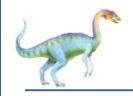




Recovery from Deadlock: Resource Preemption

- Successively preempt some resources from processes and give these resources to other processes until the deadlock cycle is broken
- □ Selecting a victim minimize cost
 - Number of resources is holding; amount of time has thus far consumed
- Rollback return to some safe state, restart process from that state
 - > Hard to determine, so total rollback
- Starvation same process may always be picked as victim, include number of rollback in cost factor

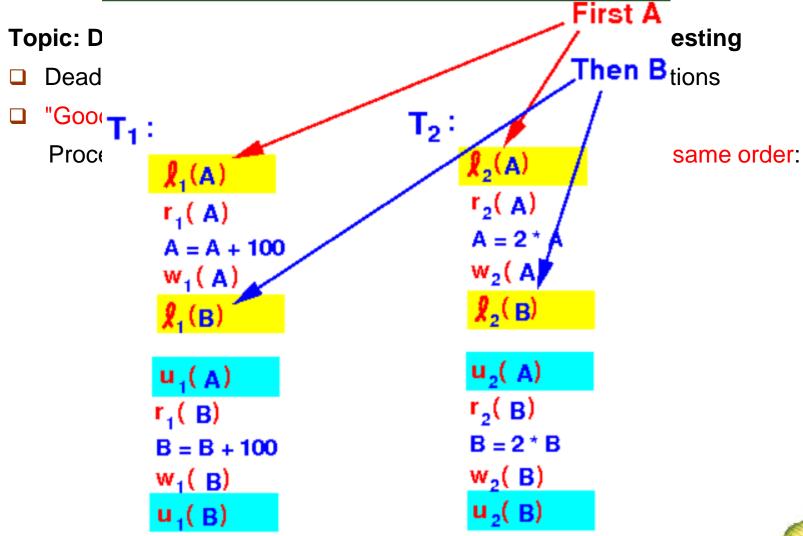




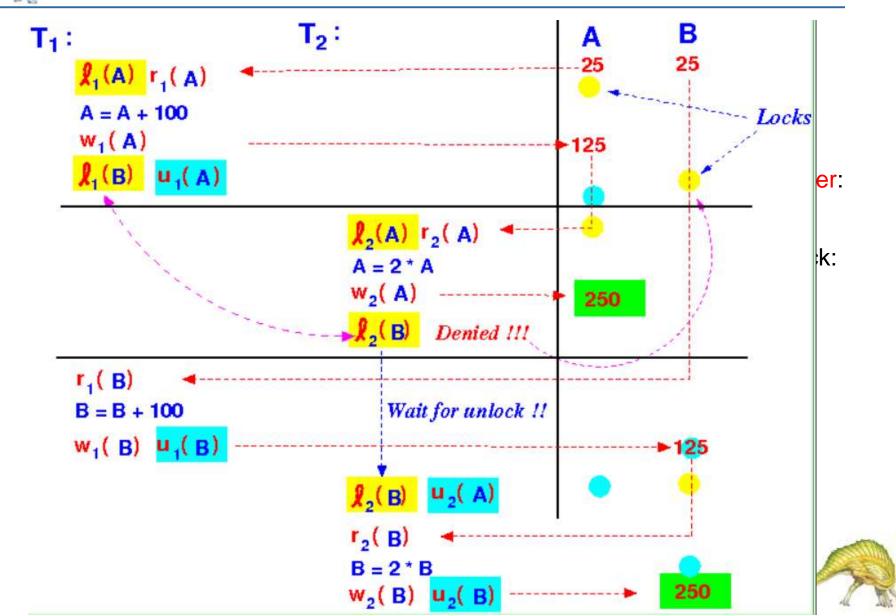
Deadlock prevention by ordering the resource requesting









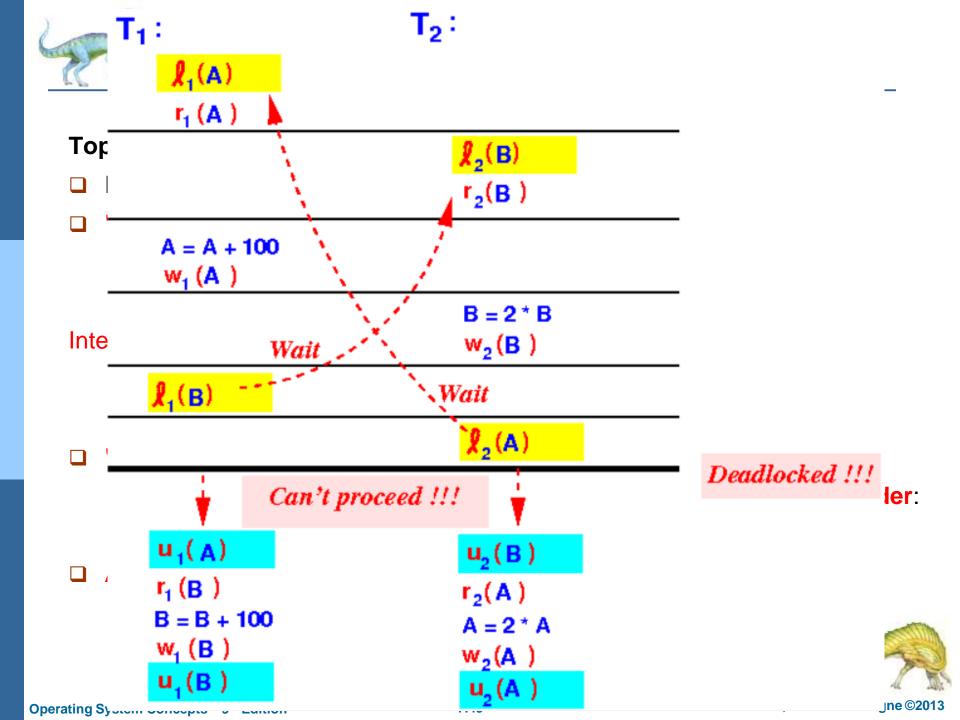




$T_{0}T_{1}$: $l_1(A)$ r, (A) A = A + 100 $W_1(A)$ 1 (B) In u1(A) r₁ (B) B = B + 100 $W_1(B)$ $u_{i}(B)$

```
T<sub>2</sub>:
     1,(B)
      r2(B)
                             Lock order
                             on A and B ler.
      B = 2 * B
                             is reversed!
      W_2(B)
      1, (A)
                                           ck:
      u,(B)
      r_2(A)
      A = 2 * A
      W_2(A)
                                           e order
      u, (A)
```







Topic: Deadlock prevention by ordering the resource requesting

☐ The cause of the deadlock:

The transactions T1 and T2 have each locked the shared variables in reverse order:

- T₁ locks A ⇒ B
- T₂ locks B ⇒ A
- □ Preventing deadlock by imposing an ordering on the shared variables Example ordering:
 - Consider shared variables (resources) as a binary number

Example ordering:

Processes must request locks on shared variables in the ordering of variables



Topic: Deadlock prevention by ordering the resource requesting

- □ Preventing deadlock by imposing an ordering on the shared variables Example ordering:
 - Consider shared variables (resources) as a binary number

Exam

A process T wants to lock the shared resources:

ng of

Prva

Printer 567 Disk 789 File 123

Lock request order made by transaction T:

File 123 Printer 567 Disk 789





☐ Theorem: Ordered locking on shared resources will prevent deadlock Claim:

If all processes request locks on shared resources in the order of the resources, then **deadlock** is **not possible**.

Proof: by contradiction:

Suppose that:

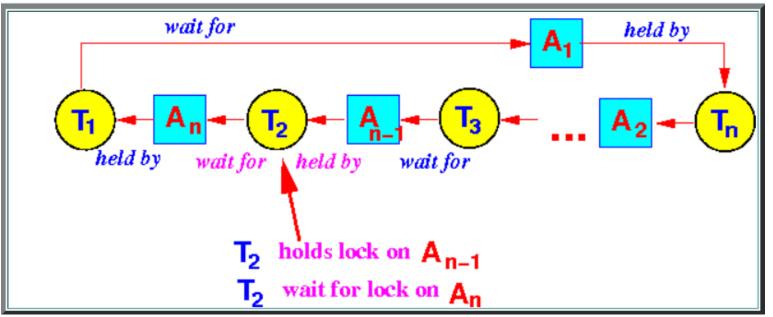
- Processes T1, T2, ..., Tn request locks on shared resources according to the ordering of the database elements and
- Transactions T1, T2, ..., Tn are deadlocked





Without lost of generality, let's assume that

The wait-for graph

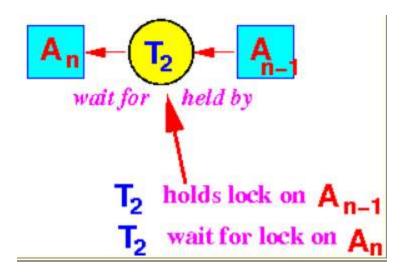


- > T1 has locked some variable An and T2 is waiting for a lock on An
- > T2 has locked some variable An-1 and T3 is waiting for a lock on An-1
- T3 has locked some variable An-2 and T4 is waiting for a lock on An-2
- **>** ...
- ➤ Tn-1 has locked some variable A2 and Tn is waiting for a lock on A2
- Tn has locked some variable A1 and T1 is waiting for a lock on A1



Consider the shared variables that **process T2 locks**:

- T2 has locked the variable An-1 (first) and
- T2 is waiting (trying to lock) for the variable An (next)



Since process T2 will lock variable according to their **order**, we conclude that:

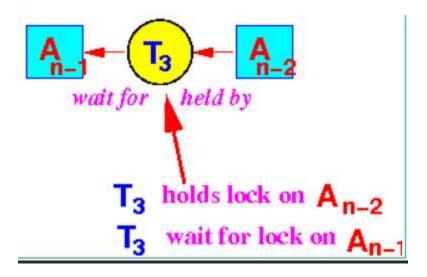
$$\blacksquare A_{n-1} < A_n$$





Consider the shared variables that **process T3 locks**:

- T3 has locked the variable An-2 (first) and
- T3 is waiting (trying to lock) for the variable An-1 (next)



Since process T3 will lock variable according to their **order**, we conclude that:

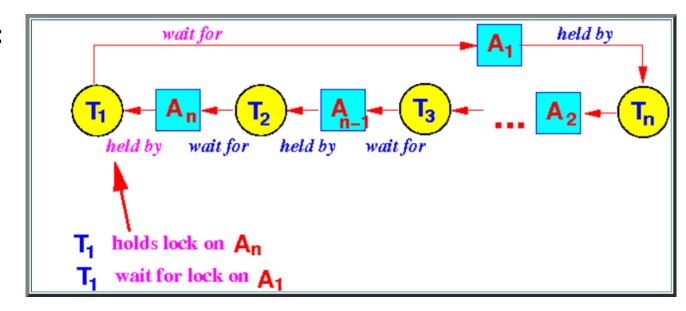
Therefore, we have that:







But we also have:



- T₁ has locked the A_n and
- T₁ is waiting for the A₁

we conclude that:





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Therefore, we have that:



we conclude that:





And we have a contradiction:

Therefore:

- The assumption that n processes can be involved in a deadlock is wrong
- So deadlock is not possible



Preventing deadlock with timestamps: the wait-die method





☐ Timestamped processes:

Each process is assigned a unique increasing timestamp

Important fact:

An earlier process receives a smaller timestamp

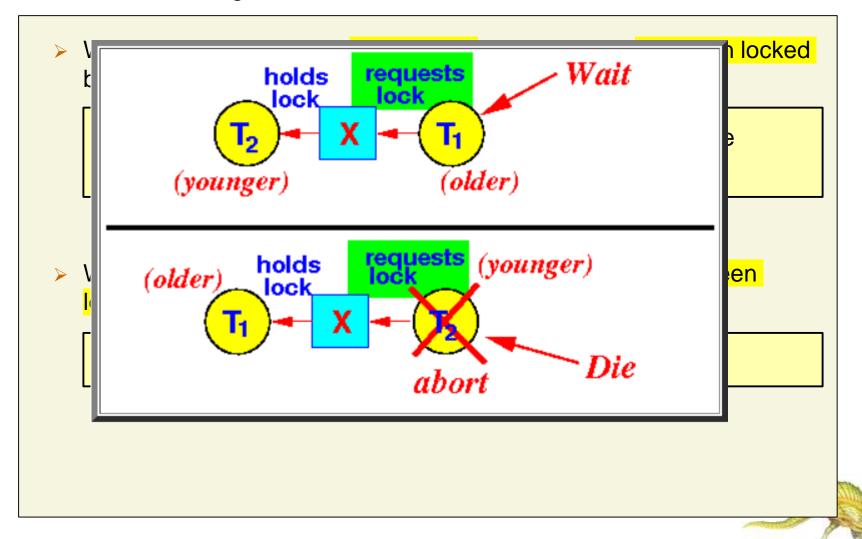
Purpose of the time stamp

To give older processes (= processes with smaller timestamps) a **higher priority** over "younger" processes



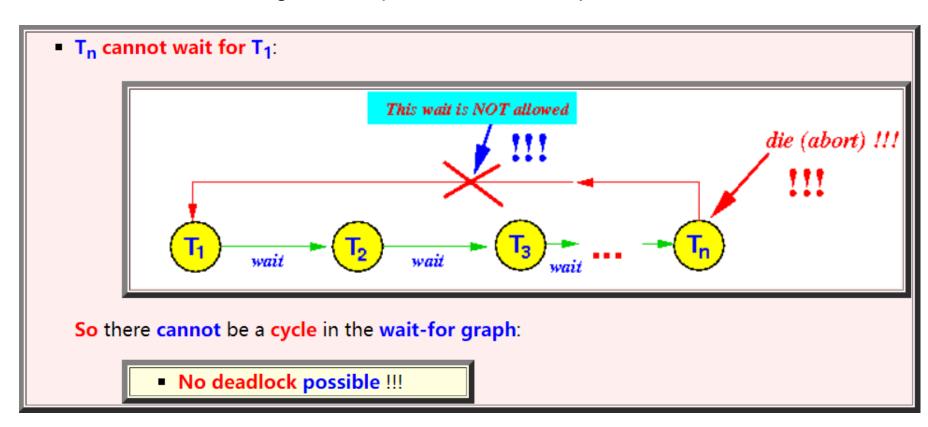


The Wait-die locking rule:

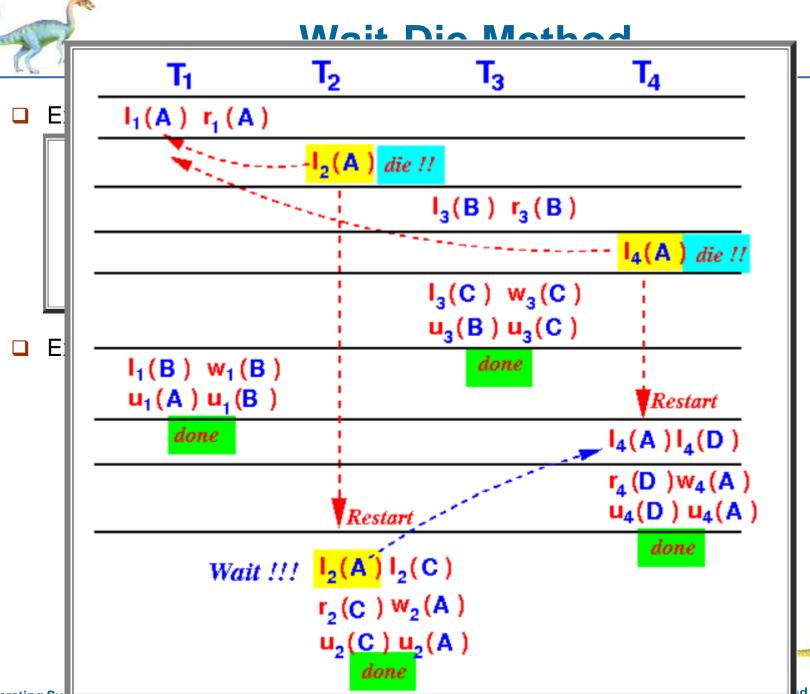




☐ The Wait-die locking rule will prevent the development of deadlock because:









Operating Sys

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■ Important note:

When a process is aborted and restarts

The process will retain its (old) timestamp !!!

> Therefore:

Eventually, a process will become the "oldest" process and will complete execution !!!

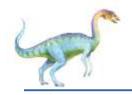




Processes	Allocation A B C	Max A B C	Available A B C
Р0	112	4 3 3	2 1 0
P1	2 1 2	3 2 2	
P2	4 0 1	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

What are safe sequences?





Processes	Allocation A B C	Max A B C	Available A B C
Р0	112	4 3 3	210
P1	212	3 2 2	
P2	401	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

1. The Content of the need matrix can be calculated by using the formula given below:

Need = Max - Allocation

Process		Need		
	A	В	C	
P_0	3	2	1	
P_1	1	1	0	
\mathbf{P}_2	5	0	1	
P ₃	7	3	3	
P ₄	0	0	0	





Processes	Allocation A B C	Max A B C	Available A B C
Р0	112	4 3 3	2 1 0
P1	212	3 2 2	
P2	4 0 1	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

Process	Need		
	A	В	C
P ₀	3	2	1
P ₁	1	1	0
\mathbf{P}_2	5	0	1
P ₃	7	3	3
P ₄	0	0	0

For process P0, Need = (3, 2, 1) and Available = (2, 1, 0) Need <=Available = False So, the system will move to the next process.



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Processes	Allocation A B C	Мах А В С	Available A B C
Р0	112	4 3 3	2 1 0
P1	212	3 2 2	
P2	401	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

Process		Need		
	A	В	C	
\mathbf{P}_0	3	2	1	
\mathbf{P}_{1}	1	1	0	
\mathbf{P}_2	5	0	1	
\mathbf{P}_3	7	3	3	
P_4	0	0	0	

For Process P1, Need = (1, 1, 0) Available = (2, 1, 0) Need <= Available = True Request of P1 is granted. Available = Available +Allocation = (2, 1, 0) + (2, 1, 2)



Processes	Allocation A B C	Max A B C	Available A B C
Р0	112	4 3 3	2 1 0
P1	2 1 2	3 2 2	
P2	401	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

Process	Need		
	A	В	C
\mathbf{P}_0	3	2	1
P_1	1	1	0
\mathbf{P}_2	5	0	1
\mathbf{P}_3	7	3	3
P_4	0	0	0

For Process P2, Need = (5, 0, 1) Available = (4, 2, 2) Need <=Available = False So, the system will move to the next process.



Processes	Allocation A B C	Max A B C	Available A B C
Р0	112	4 3 3	2 1 0
P1	2 1 2	3 2 2	
P2	4 0 1	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

Process	Need		
	A	В	C
\mathbf{P}_0	3	2	1
P_1	1	1	0
\mathbf{P}_2	5	0	1
\mathbf{P}_3	7	3	3
P ₄	0	0	0

For Process P3, Need = (7, 3, 3) Available = (4, 2, 2) Need <=Available = False So, the system will move to the next process.





Processes	Allocation A B C	Max A B C	Available A B C
Р0	112	4 3 3	2 1 0
P1	2 1 2	3 2 2	
P2	401	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

Process	Need		
	A	В	C
\mathbf{P}_0	3	2	1
P_1	1	1	0
\mathbf{P}_2	5	0	1
\mathbf{P}_3	7	3	3
P_4	0	0	0

For Process P4, Need = (0, 0, 0)

Available = (4, 2, 2)

Need <= Available = True

Request of P4 is granted.

Available = Available + Allocation

= (4, 2, 2) + (1, 1, 2)

= (5, 3, 4) now, (New Available)



Processes	Allocation A B C	Мах А В С	Available A B C
Р0	112	4 3 3	2 1 0
P1	212	3 2 2	
P2	401	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

Process	Need		
	A	В	C
P ₀	3	2	1
P_1	1	1	0
\mathbf{P}_2	5	0	1
P ₃	7	3	3
P ₄	0	0	0

Now again check for Process P2, Need = (5, 0, 1)

Available = (5, 3, 4)

Need <= Available = True

Request of P2 is granted.

Available = Available + Allocation

= (5, 3, 4) + (4, 0, 1)

= (9, 3, 5) now, (New Available)



Processes	Allocation A B C	Мах А В С	Available A B C
Р0	112	4 3 3	2 1 0
P1	212	3 2 2	
P2	401	9 0 2	
Р3	0 2 0	7 5 3	
P4	112	112	

Process		Need		
	\mathbf{A}	В	C	
P_0	3	2	1	
P_1	1	1	0	
\mathbf{P}_2	5	0	1	
P_3	7	3	3	
P_4	0	0	0 NO	

The system allocates all the needed resources to each process. So, we can say that the system is in a safe state.

Now again check for Process P0, = Need

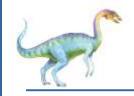
(3, 2, 1)

= Available (9, 5, 5)

Need <= Available = True

So, the request will be granted to P0.

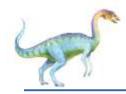
Safe sequence: < P1, P4, P2, P3, P0>



Deadlock prevention

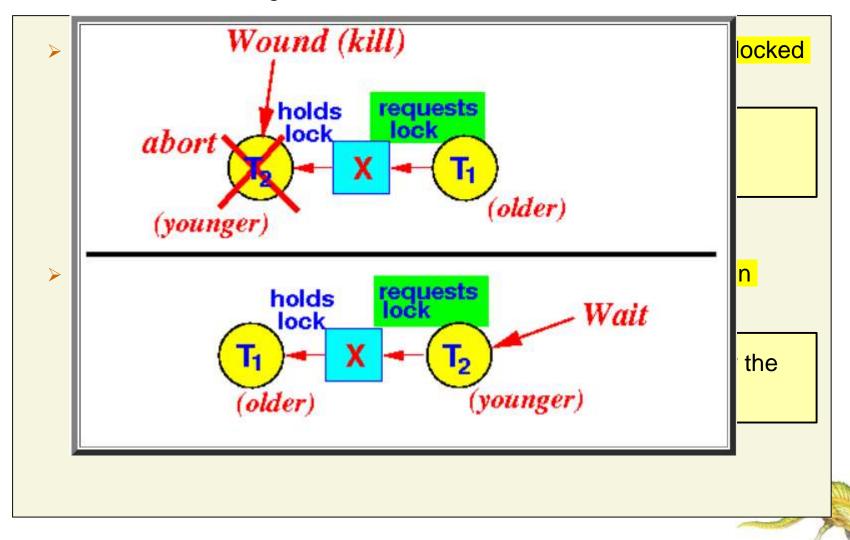
Preventing deadlock with timestamps: the wound-wait method





Wound-Wait Method

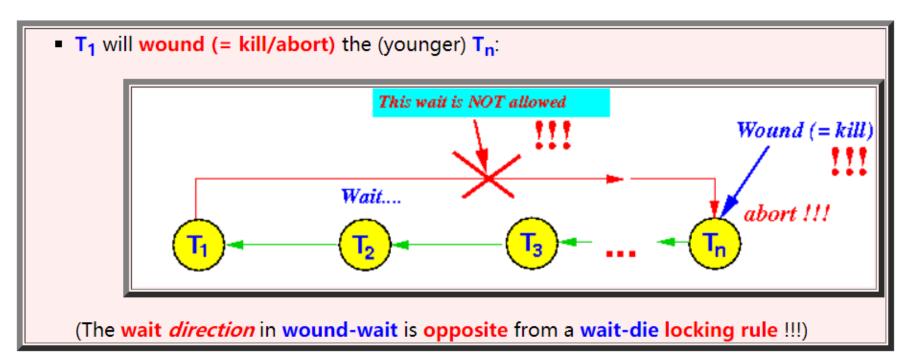
☐ The Wound-wait locking rule:





Wound-Wait Method

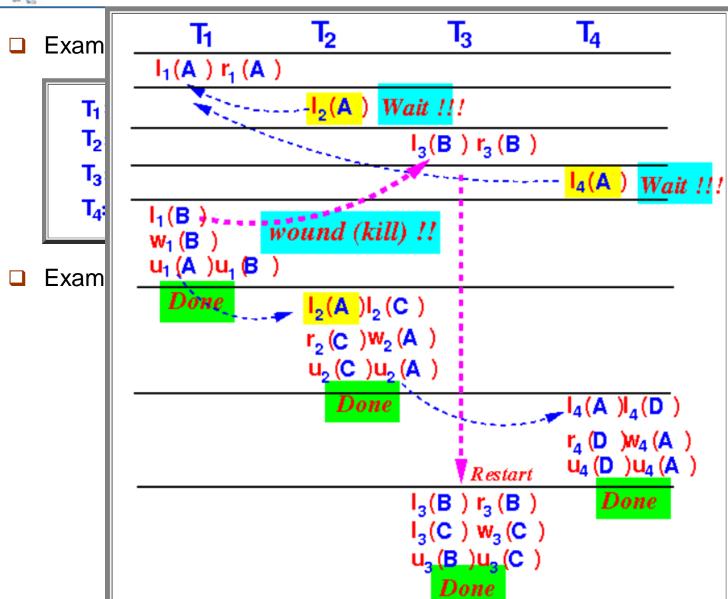
□ The Wound-wait locking rule will prevent (forbid) the development of deadlock because:



- In both schemes (wait-die and wound-wait), the younger process will get aborted
- The older transaction is not be aborted !!!



Wound-Wait Method







Deadlock prevention

Comparing the wait-die and wound-wait schemes





□ Similarity:

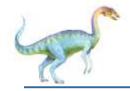
In both the wait-die and the wound-wait scheme

The older process will "win" over the younger process

Both schemes are fair

When processes restart, they keep their timestamps

Eventually, the aborted (younger) processes will become the oldest processes in the system



Difference:

Wait-die:

The younger processes are killed when:

It (= the younger process) makes a request for a lock being held by an older process

Wound-die:

The younger processes are killed when:

An older process makes a request for a lock being held by the younger processes



☐ The cost of aborting (younger/older) transactions:

Younger processes (having just started running) will typically:

hold fewer number of locks

and

has read/written fewer number of variables

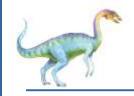
Older processes (having run longer) will typically

hold higher number of locks

and

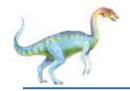
has read/written higher number of variables

Older processes (= that started earlier) are more expensive (costly) to be aborted !!!!



Which method has higher aborting rate?





- □ Comparing the **abort rates** of the wait-die and would-wait schemes:
 - The number of processes that will be aborted in the wound-wait method will be

lower than number of processes that will be aborted in the wait-die method

Reasons:

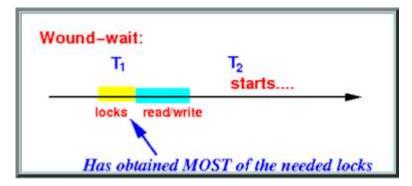
■ A younger process starts later than an older process:

Wound-wait:		
T ₁	T ₂	

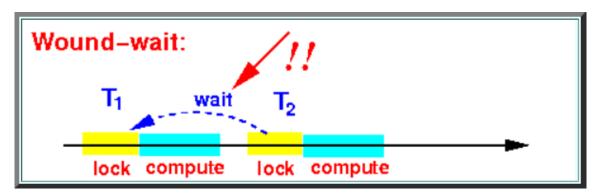




■ By the time that the younger process T2 starts, the older process T1 will have obtained most of their locks:



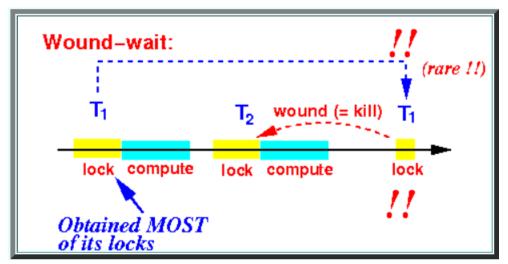
- □ A younger (just starting) process T2 will make many lock requests !!
- In the wound-wait method, a younger (just starting) process T2 will wait (and not abort) if T2 requests a lock held by the older process T1:







□ An older process (T1) that requests a lock can abort a younger process (T2)



However:

- The event that older processes (T1) will request a lock is rare
- (because older processes (T1) have obtained most of their locks already)

Therefore:

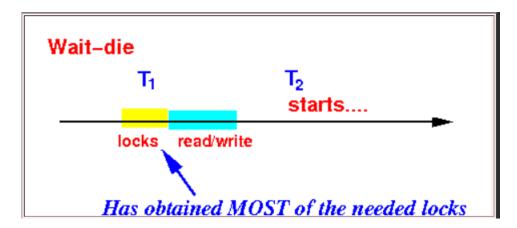
The number of aborts in wound-wait is relatively low



- Wait-die method will have more aborts:
- A younger process starts later than an older process:



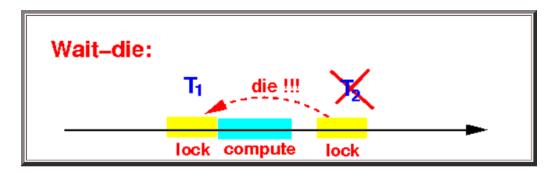
■ By the time that T2 starts, the older process T1 will have obtained most of their locks:



□ A younger (just starting) process T2 will make many lock requests !!



☐ In the wait-die method, a younger (just starting) process T2 will die (= abort) if T2 requests a lock held by the older process T1:



- □ Since younger processes makes many lock requests:
 - There will be more aborts (of young processes) in the wait-die method
- Comment:
 - It looks like that the wound-wait method will have better performance...

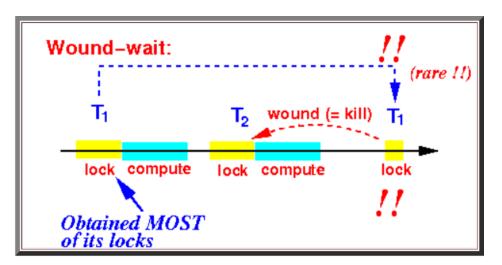


- Comparing the amount of waste work in aborted process in wait-die and wound-wait
- ☐ The wound-wait method may have fewer aborts, however; it's likely that:
 - An aborted (younger) process in the wound-wait method has performed more work than an aborted (younger) process in the waitdie method !!!



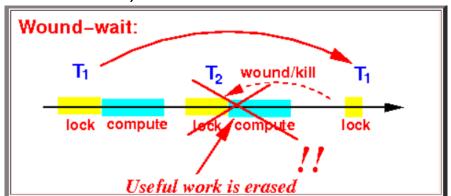


Consider a process in the wound-wait method that gets aborted:



Notice that the aborted process **must** hold some locks !!!

I.e.: the aborted process has performed some read/write operations (= useful work):



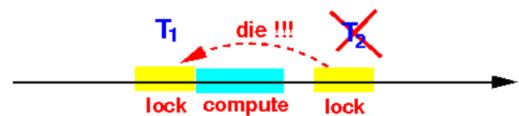
The useful work is erased (rolled back) !!!





Consider a process in the wait-die method that gets aborted:

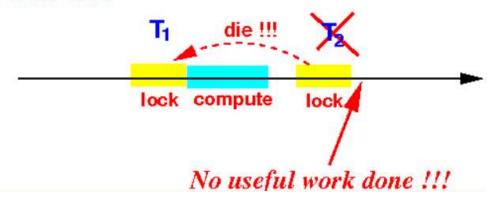
Wait-die:

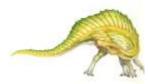


Notice that the aborted process may **not** hold any lock at all !!!

I.e.: the aborted process has not performed any read/write operations (= no useful work):

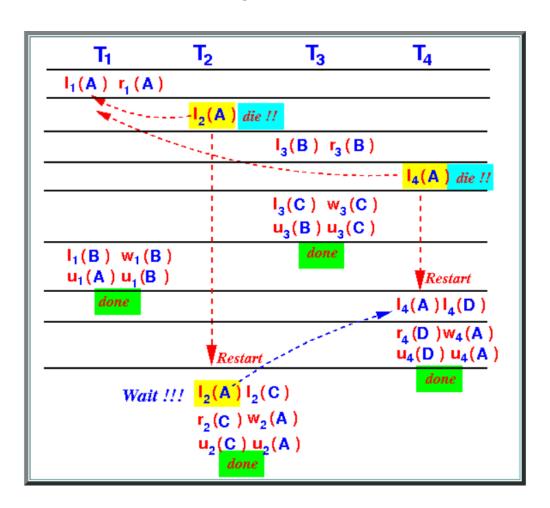
Wait-die:







- Consider the previous examples:
- Wait-die locking method



There are 2 transaction aborts (that's 50% of the # processes !!!)

However:

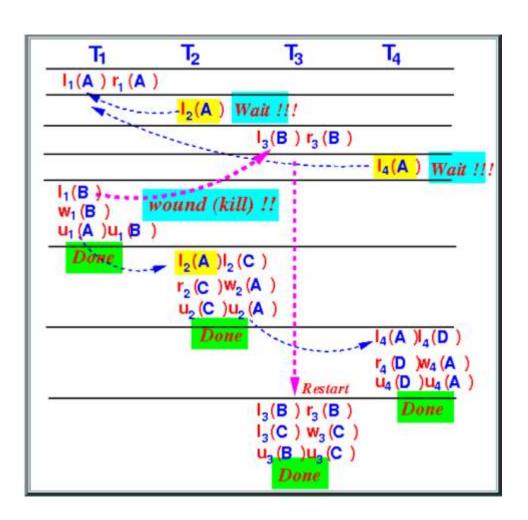
Both aborted processes has done no useful work !!!

(The aborted processes has **not** performed any read/write operation !!!)





Wound-wait locking method



There is only 1 process aborts (less than in wait-die!)

However:

The aborted processes has done some useful work !!!

(Process T3 has read B !!!)





Summary

Wait-die has more roll backs; but the processes have performed little to no work

Wound-wait has less roll backs; but the processes that got aborted has done some work !!!





Using timeout to detect deadlock





■ Fact:

- When a process T is involved in a deadlock, the transaction T will not finish
- □ Simple way to detect if a process is a candidate to be involved in a deadlock:
 - Set a timer for each operation
 - When the timer expires, the transaction is assumed to be involved in a deadlock
- Note:
 - This method is quite reliable because most operations (read/write) does not take very long!!!





Example:

MySQL uses timeout to detect deadlocks

Experiment:

User 1	User 2	
Don't do anything	START TRANSACTION; UPDATE employee SET salary=salary + 0 WHERE lname='Smith'; >> 1 row updated	
START TRANSACTION; UPDATE employee SET salary=salary + 0 WHERE lname='Smith'; >> Update HANGS !!! (WAIT about 1 min TIME) ERROR 1205: Lock wait timeout exceeded; try restarting transaction	Don't do anything	

- Open 2 windows and run sqlroot and log in as cheung:
- use companyDB
- · Employee:

fname	lname	salary	
John	Smith	20900.00	
Frankl	Wong	50000.00	
Alicia	Zelaya	25000.00	
lennif	Wallace	43000.00	
tamesh	Narayan	38000.00	
loyce	English	25000.00	
Ahmad	Jabbar	25000.00	
lames	Borg	55000.00	



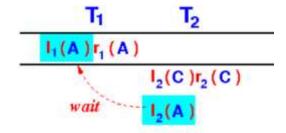


Detecting deadlocks using wait-for graphs

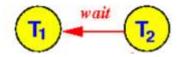




- Wait-for graph is a graph where::
 - Node represents a process
 - Edge i ⇒ j represents: the process i is waiting for a lock held by the process j



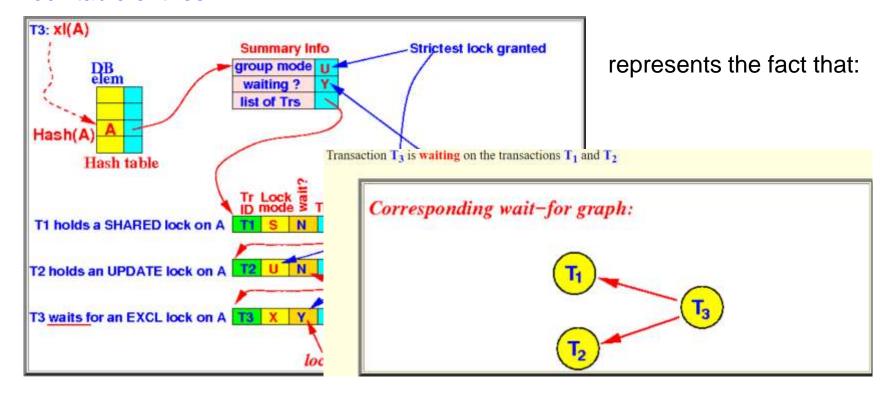
Wait-for graph:



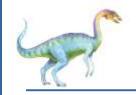




□ The wait-for graph can be constructed using the information stored in the lock table entries

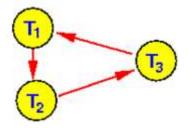






Deadlock occurs in a circular wait situation

Circular wait:



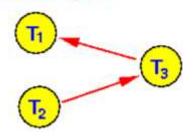
- Each process is waiting for some process to complete
- **☐** Result: No transaction can proceed forward



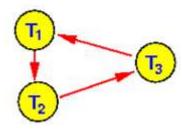


- If the wait-for graph has no cycles, then:
 - There is no deadlock

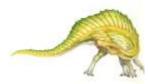
Wait-for graph with no cycle:



Circular wait:



- Completion order:
 - > T1 will complete first (and releases its locks)
 - Then T3 can obtain its locks after T1 unlocks and complete next (and releases its locks)
 - Finally, T2 can obtain its locks after T3 unlocks and complete next (and releases its locks)

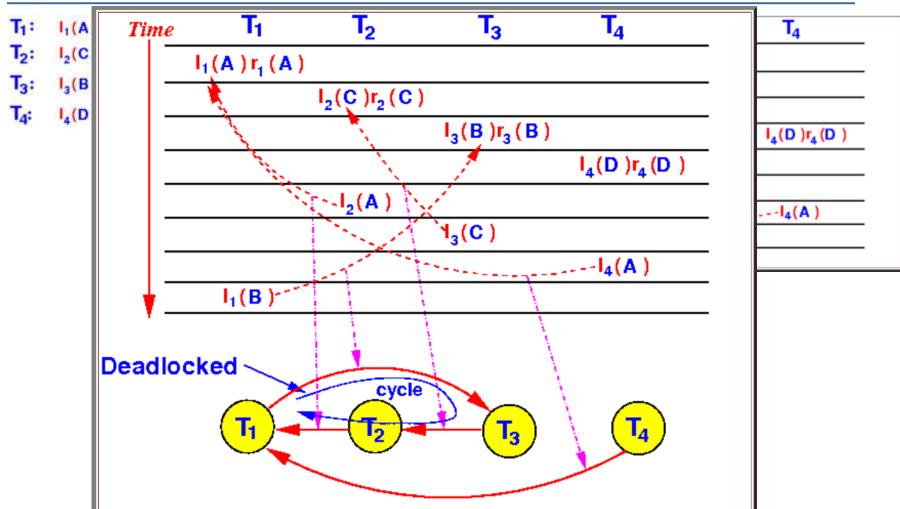




- Deadlock detect in a scheduler
 - > A process scheduler that uses locking to ensure serializability must
 - Maintain a wait-for graph on all processes
 - If the wait-for graph contains a cycle:
 - > The scheduler will abort one of the processes in the cycle







The process manager will now have to abort some process T1, T2 and T3 that are involved in the deadlock

End of Chapter 7

