Command :

1. sudo apt install ros-noetic-turtlesim
2. roscore
3. rosrun turtlesim turtlesim_node
4. rosnode list
5. rostopic echo /turtle1/pose
6. rosrun turtlesim draw_square
7. cd catkin_ws/src/turtlemove/scripts/
8. chmod +x ~/catkin_ws/src/turtlemove/scripts/turtlemove.py
9. source ~/catkin_ws/devel/setup.bash
10. rosrun turtlemove turtlemove.py