Xiao Ma

SEA AI Lab

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EDUCATION

National University of Singapore (NUS), Singapore

Aug. 2017 - Dec. 2021

Doctor of Philosophy in Computer Science

Advisor: Prof. David Hsu

Shanghai Jiao Tong University (SJTU), Shanghai

Sept. 2013 - July 2017

Bachelor of Engineering in Computer Science and Technology

Advisors: Prof. Xiaofeng Gao and Prof. Fan Wu

WORK EXPERIENCES

Research Scientist at SEA AI Lab

Jul. 2021 - present

- Human-level AI for multi-player online FPS games (core contributor)
- Offline reinforcement learning (principle investigator).
- Differentiable physics for robot learning (mentor).

Research Intern at SEA AI Lab (hosted by Dr. Min Lin)

Research Intern at SenseTime Research (hosted by Dr. Shuai Yi)

Software Engineer Intern at Intel Asia Pacific R & D Center

Apr. 2021 - Jun. 2021

Oct. 2019 - Sept. 2020

May 2016 - Dec. 2016

RESEARCH

My research focuses onreinforcement learning, representation learning, graph neural networks and their applications to vision-based decision-making systems, such as robots and games. I aim to build robust models of the world for decision making in unstructured environments.

My work about learning composable robot systems with Differentiable Algorithm Networks (DAN) was selected as the **best system paper finalist** and **best student paper finalist** at the *Robotics: Science and Systems* (RSS), 2019.

PREPRINTS

Yang Yue, Bingyi Kang, **Xiao Ma**, Zhongwen Xu, Gao Huang, Shuicheng Yan. "Boosting Offline Reinforcement Learning via Data Rebalancing", arXiv preprint arXiv:2210.09241

Xiao Ma*, Bingyi Kang*, Zhongwen Xu, Min Lin, Shuicheng Yan. "Mutual Information Regularized Offline Reinforcement Learning", *arXiv preprint arXiv:2210.07484* (*equal contribution)

Siwei Chen, Xiao Ma, Zhongwen Xu. "Imitation Learning via Differentiable Physics", arXiv preprint arXiv:2206.04873

PUBLICATIONS

Siwei Chen*, Cunjun Yu*, Yiqing Xu*, Linfeng Li, **Xiao Ma**, Zhongwen Xu, David Hsu. "Benchmarking Deformable Object Manipulation with Differentiable Physics", *International Conference on Learning Representations (ICLR)*, 2023 (**oral**, *equal contribution)

Jiawei Ren*, Cunjun Yu*, Siwei Chen, Xiao Ma, Liang Pan, Ziwei Liu. "DiffMimic: Efficient Motion Mimicking with Differentiable Physics", *International Conference on Learning Representations (ICLR)*, 2023 (*equal contribution)

Wei Qiu, Xiao Ma, Bo An, Svetlana Obraztsova, Shuicheng Yan, Zhongwen Xu. "RPM: Generalizable Behaviors for Multi-Agent Reinforcement Learning", International Conference on Learning Representations (ICLR), 2023

Hai Nguyen*, Zhihan Yang*, Andrea Baisero, **Xiao Ma**, Robert Platt, Christopher Amato. "Hierarchical Reinforcement Learning under Mixed Observability", *Workshop on the Algorithmic Foundations of Robotics (WAFR)*, 2022 (*equal contribution)

Xiao Ma, David Hsu, Wee Sun Lee. "Learning Latent Graph Dynamics for Visual Manipulation of Deformable Objects", International Conference on Robotics and Automation (ICRA), 2022

Daisheng Jin*, **Xiao Ma***, Chongzhi Zhang, Yizhuo Zhou, Jiashu Tao, Mingyuan Zhang, Zhoujun Li, Xiaolong Liu. "Towards Overcoming False Positives in Visual Relationship Detection", *British Machine Vision Conference (BMVC)*, 2021 (*equal contribution)

Xiao Ma, Siwei Chen, David Hsu, Wee Sun Lee. "Contrastive Variational Model-Based Reinforcement Learning for Complex Observations", *The 4nd Conference on Robot Learning (CoRL)*, 2020

Jiawei Ren, Cunjun Yu, Shunan Sheng, **Xiao Ma**, Haiyu Zhao, Shuai Yi, Hongsheng Li. "Balanced Meta-Softmax for Long-Tailed Visual Recognition", *Advances in Neural Information Processing Systems* (NeurIPS), 2020

Siwei Chen, **Xiao Ma**, David Hsu. "DinerDash Gym: A Benchmark for Policy Learning in High-Dimensional Action Space", *In IL workshop, Robotics: Science and Systems (RSS)*, 2020

Cunjun Yu*, Xiao Ma*, Jiawei Ren, Haiyu Zhao, Shuai Yi. "Spatio-Temporal Graph Transformer Networks for Pedestrian Trajectory Prediction", European Conference on Computer Vision (ECCV), 2020 (*equal contribution)

Zuowu Zheng, Xiaofeng Gao, Xiao Ma, Guihai Chen. "Predicting Hot Events in the Early Period through Bayesian Model for Social Networks", IEEE Transactions on Knowledge and Data Engineering (TKDE), 2020

Xiao Ma, Peter Karkus, David Hsu, Wee Sun Lee, Nan Ye. "Discriminative Particle Filter Reinforcement Learning for Complex Partial Observations", *International Conference on Learning Representations (ICLR)*, 2020

Xiao Ma*, Peter Karkus*, David Hsu, Wee Sun Lee. "Particle Filter Recurrent Neural Networks", AAAI Conference on Artificial Intelligence (AAAI), 2020 (*equal contribution)

Peter Karkus, Xiao Ma, David Hsu, Leslie Pack Kaelbling, Wee Sun Lee, Tomas Lozano-Perez. "Differentiable Algorithm Networks for Composable Robot Learning", Robotics: Science and Systems (RSS), 2019 (Best Student/System Paper Finalist)

Xiao Ma, Peter Karkus, David Hsu, Wee Sun Lee "PF-LSTM: Belief State Particle Filter for LSTM", In RLPO Workshop, Advances in Neural Information Processing Systems (NeurIPS), 2018

Xiao Ma, Xiaofeng Gao, Guihai Chen. "BEEP: a Bayesian perspective Early state Event Prediction model for online social networks", *IEEE International Conference on Data Mining (ICDM)*, 2017

Xiao Ma, Zhenzhe Zheng, Fan Wu and Guihai Chen. "Trust-Based Time Series Data Model for Mobile Crowdsensing", IEEE International Conference on Communications (ICC), 2017

AWARDS

NUS School of Computing Research Achievement Award	2020
Robotics: Science and Systems Best Student Paper Finalist	2019
Robotics: Science and Systems Best System Paper Finalist	2019
Second Prize in iNTUition Hackathon	2017
NUS Research Scholarship	2017
Excellent Project of the National Undergraduate Training Programs for Innovation	2016
Academic Excellence Scholarship, SJTU	2016, 2014
Honorable Mention of Mathematical Contest In Modeling	2015, 2016

PROFESSIONAL ACTIVITIES

Reviewer

- Conferences: NeurIPS (2020,2021,2022), WACV (2021, 2022), ICRA (2021, 2022), AAAI (2021), CVPR (2021), ICLR (2022), ICML (2022, 2023)
- Journals: RA-L (2021, 2022)

Teaching

- CS3243: Introduction to Artificial Intelligence (Spring 2018)
- CS6244: Robot Motion Planning and Control (Winter 2018)
- CS5478: Intelligent Robots: Algorithms and Systems (Spring 2020)