

Xiao Ma

SEA AI Lab

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[Personal Website](#)

[Google Scholar](#)

EDUCATION

National University of Singapore (NUS), Singapore Aug. 2017 - Dec. 2021
Doctor of Philosophy in COMPUTER SCIENCE
Advisor: [Prof. David Hsu](#)

Shanghai Jiao Tong University (SJTU), Shanghai Sept. 2013 - July 2017
Bachelor of Engineering in COMPUTER SCIENCE AND TECHNOLOGY
Advisors: [Prof. Xiaofeng Gao](#) and [Prof. Fan Wu](#)

WORK EXPERIENCES

Research Scientist at SEA AI Lab Jul. 2021 - present

- Human-level AI for multi-player online FPS games ([Garena Free Fire](#)) (agent designer and core contributor)
- Offline reinforcement learning (principle investigator).
- Differentiable physics for robot learning (mentor).

Research Intern at SEA AI Lab (hosted by [Dr. Min Lin](#)) Apr. 2021 - Jun. 2021
Research Intern at SenseTime Research (hosted by [Dr. Shuai Yi](#)) Oct. 2019 - Sept. 2020
Software Engineer Intern at Intel Asia Pacific R & D Center May 2016 - Dec. 2016

RESEARCH

My research focuses on reinforcement learning, representation learning, graph neural networks and their applications to vision-based decision-making systems, such as robots and games. I aim to build robust models of the world for decision making in unstructured environments.

My work about learning composable robot systems with Differentiable Algorithm Networks (DAN) was selected as the **best system paper finalist** and **best student paper finalist** at the *Robotics: Science and Systems (RSS)*, 2019.

PREPRINTS

Yang Yue, Bingyi Kang, **Xiao Ma**, Zhongwen Xu, Gao Huang, Shuicheng Yan. “Boosting Offline Reinforcement Learning via Data Rebalancing”, *arXiv preprint arXiv:2210.09241*

Xiao Ma^{*}, Bingyi Kang^{*}, Zhongwen Xu, Min Lin, Shuicheng Yan. “Mutual Information Regularized Offline Reinforcement Learning”, *arXiv preprint arXiv:2210.07484* (*equal contribution)

Siwei Chen, **Xiao Ma**, Zhongwen Xu. “Imitation Learning via Differentiable Physics”, *arXiv preprint arXiv:2206.04873*

PUBLICATIONS

Siwei Chen^{*}, Cunjun Yu^{*}, Yiqing Xu^{*}, Linfeng Li, **Xiao Ma**, Zhongwen Xu, David Hsu. “Benchmarking Deformable Object Manipulation with Differentiable Physics”, *International Conference on Learning Representations (ICLR)*, 2023 (**oral**, *equal contribution)

Jiawei Ren^{*}, Cunjun Yu^{*}, Siwei Chen, Xiao Ma, Liang Pan, Ziwei Liu. “DiffMimic: Efficient Motion Mimicking with Differentiable Physics”, *International Conference on Learning Representations (ICLR)*, 2023 (*equal contribution)

Wei Qiu, **Xiao Ma**, Bo An, Svetlana Obraztsova, Shuicheng Yan, Zhongwen Xu. “RPM: Generalizable Behaviors for Multi-Agent Reinforcement Learning”, *International Conference on Learning Representations (ICLR)*, 2023

Hai Nguyen*, Zhihan Yang*, Andrea Baisero, **Xiao Ma**, Robert Platt, Christopher Amato. “Hierarchical Reinforcement Learning under Mixed Observability”, *Workshop on the Algorithmic Foundations of Robotics (WAFR)*, 2022 (*equal contribution)

Xiao Ma, David Hsu, Wee Sun Lee. “Learning Latent Graph Dynamics for Visual Manipulation of Deformable Objects”, *International Conference on Robotics and Automation (ICRA)*, 2022

Daisheng Jin*, **Xiao Ma***, Chongzhi Zhang, Yizhuo Zhou, Jiashu Tao, Mingyuan Zhang, Zhoujun Li, Xiaolong Liu. “Towards Overcoming False Positives in Visual Relationship Detection”, *British Machine Vision Conference (BMVC)*, 2021 (*equal contribution)

Xiao Ma, Siwei Chen, David Hsu, Wee Sun Lee. “Contrastive Variational Model-Based Reinforcement Learning for Complex Observations”, *The 4th Conference on Robot Learning (CoRL)*, 2020

Jiawei Ren, Cunjun Yu, Shunan Sheng, **Xiao Ma**, Haiyu Zhao, Shuai Yi, Hongsheng Li. “Balanced Meta-Softmax for Long-Tailed Visual Recognition”, *Advances in Neural Information Processing Systems (NeurIPS)*, 2020

Siwei Chen, **Xiao Ma**, David Hsu. “DinerDash Gym: A Benchmark for Policy Learning in High-Dimensional Action Space”, *In IL workshop, Robotics: Science and Systems (RSS)*, 2020

Cunjun Yu*, **Xiao Ma***, Jiawei Ren, Haiyu Zhao, Shuai Yi. “Spatio-Temporal Graph Transformer Networks for Pedestrian Trajectory Prediction”, *European Conference on Computer Vision (ECCV)*, 2020 (*equal contribution)

Zuowu Zheng, Xiaofeng Gao, **Xiao Ma**, Guihai Chen. “Predicting Hot Events in the Early Period through Bayesian Model for Social Networks”, *IEEE Transactions on Knowledge and Data Engineering (TKDE)*, 2020

Xiao Ma, Peter Karkus, David Hsu, Wee Sun Lee, Nan Ye. “Discriminative Particle Filter Reinforcement Learning for Complex Partial Observations”, *International Conference on Learning Representations (ICLR)*, 2020

Xiao Ma*, Peter Karkus*, David Hsu, Wee Sun Lee. “Particle Filter Recurrent Neural Networks”, *AAAI Conference on Artificial Intelligence (AAAI)*, 2020 (*equal contribution)

Peter Karkus, **Xiao Ma**, David Hsu, Leslie Pack Kaelbling, Wee Sun Lee, Tomas Lozano-Perez. “Differentiable Algorithm Networks for Composable Robot Learning”, *Robotics: Science and Systems (RSS)*, 2019 (Best Student/System Paper Finalist)

Xiao Ma, Peter Karkus, David Hsu, Wee Sun Lee “PF-LSTM: Belief State Particle Filter for LSTM”, *In RLPO Workshop, Advances in Neural Information Processing Systems (NeurIPS)*, 2018

Xiao Ma, Xiaofeng Gao, Guihai Chen. “BEEP: a Bayesian perspective Early state Event Prediction model for online social networks”, *IEEE International Conference on Data Mining (ICDM)*, 2017

Xiao Ma, Zhenzhe Zheng, Fan Wu and Guihai Chen. “Trust-Based Time Series Data Model for Mobile Crowdsensing”, *IEEE International Conference on Communications (ICC)*, 2017

AWARDS

NUS School of Computing Research Achievement Award	2020
<i>Robotics: Science and Systems</i> Best Student Paper Finalist	2019
<i>Robotics: Science and Systems</i> Best System Paper Finalist	2019
Second Prize in iNTUition Hackathon	2017
NUS Research Scholarship	2017
Excellent Project of the <i>National Undergraduate Training Programs for Innovation</i>	2016
Academic Excellence Scholarship, SJTU	2016, 2014
Honorable Mention of Mathematical Contest In Modeling	2015, 2016

PROFESSIONAL ACTIVITIES

Reviewer

- Conferences: NeurIPS (2020,2021,2022), WACV (2021, 2022), ICRA (2021, 2022), AAAI (2021), CVPR (2021), ICLR (2022), ICML (2022, 2023)
- Journals: RA-L (2021, 2022)

Teaching

- CS3243: Introduction to Artificial Intelligence (Spring 2018)
- CS6244: Robot Motion Planning and Control (Winter 2018)
- CS5478: Intelligent Robots: Algorithms and Systems (Spring 2020)