FACE MASK DETECTION

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All the imports

```
In [1]: import numpy as np, cv2, os, yagmail import matplotlib.pyplot as plt, seaborn as sns import face_recognition from datetime import datetime, timedelta from scipy.spatial import distance import pytesseract, imutils import csv
```

from sklearn import tree

from sklearn.metrics import confusion_matrix, classification_report

from sklearn.svm import SVC

from sklearn.metrics import accuracy_score

from sklearn.model_selection import train_test_split

let:

join = os.path.join listdir = os.listdir scale=(100,100)

Send an Email

```
#!pip3 install yagmail[all]
 In [2]:
            sender_password = input("Type in your password here")
            def date and time():
                                     # This *datetime.now()* is necessary to get the current updated time
 In [3]:
               now = datetime.now()
               date = now.strftime("%Y-%m-%d") # Month is small m
               time = now.strftime('%H:%M:%S') # Minute is capital M
               return date, time
In [39]:
            #saves the image as NotWearingMaskAlert.jpg in the AI LAB Workplace Monitoring directory.
            save_img_location = r".\AI LAB Workplace Monitoring\NotWearingMaskAlert.jpg"
            sender_mail_addr = "youremail@gmail.com"
            receiver mail addr = ["youremail@gmail.com"] #can be a list of emails...
            subject = "Worker not wearing a mask; Date {}, Time: {}"
            contents = "There is high probability that a worker is not wearing a mask. Take action!"
            def sendEmailWithAttachment(frame,
                          save_img_location = save_img_location,
                          sender_mail_addr = sender_mail_addr,
                          sender_password = sender_password,
                          receiver_mail_addr = receiver_mail_addr,
                          subject
                                        = subject,
                          contents
                                         = contents
                               ):
                 cv2.imwrite(save img location, frame)
                 sent = False
                 try:
                     yag = yagmail.SMTP(sender_mail_addr, sender_password)
                      yag.send(to= receiver mail addr,
                          subject = subject,
                          contents = contents,
                          attachments=[save_img_location]
                      print(f"\nEmail sent successfuly Date: {date} Time: {time}\n")
                      sent = True
                 except Exception as e:
                     print(f"\nError in sending the mail. Here is the error message: \ln \{e\}")
                 return sent
            frame = cv2.imread(r".\AI LAB Workplace Monitoring\Workers Photos Use During Entry At Gate\train\biden\biden2
            date, time = date and time()
            sendEmailWithAttachment( frame,
                          subject= subject.format(date, time),
                          sender password=sender password,
                          receiver mail addr=receiver mail addr
```

Email sent successfuly Date: 2022-06-20 Time: 10:37:10

True Out[39]:

Face Recognition at the gate

```
imagesFolder = r".\AI LAB Workplace Monitoring\Workers Photos Use During Entry At Gate\test"
In [5]:
            csv file = r".\AI LAB Workplace Monitoring\Register 01.csv"
            # Work start at 8:00 and end at 18:00. But a worker can be registered if he comes even early, from 7:00
In [6]:
            # If a worker arrives untill at 8:30, he's not late according to the company's rules.
            # Elif he arrives from 8:30 to 10, he is late and a warning is sent.
            # Else, he is not registered and thus won't be paid the wage for that particular day.
            def markAttendance(name, csv file):
               late = False
               now = datetime.now()
               register_hr = ( now.hour >= 7 and now.hour <= 10 )
               if register hr:
                 with open(csv_file, 'r+') as f: #both read and write
                    register = f.readlines()
                    nameList = []
                    \# nameList = [ [line.split(',')[0], line.split(',')[1] ] for line in register if not line in [',,\n', '\n'] ]
                    for line in register:
                       if not line in [',,\n', '\n']:
                         entry = line.split(',')
                         nameList.append([entry[0], entry[1]])
                    date, time = date_and_time()
                    if [name, date] not in nameList and register hr:
                       f.writelines(f"\n{name},{date},{time}")
                       print(f"{name} registered successfuly at {time}")
                       # If the worker is late (comes after 08:30), send a warning to the Director
                       #But if a worker arrives after 10:00, he is too late and cannot be registered
                       now = datetime.now()
                       hr = now.hour
                       if (hr > 8 and hr \le 10) or (hr == 8 and now.minute > 30): late = True
                       print(f"{name} is already registered for today {date} at {entry[-1]}")
               else:
                 late = True
                 print(f'It is outside registration hour, mr. {name}. So we cannot register you for today. Registration is allowed or
               return late
            def findEncodings(imagesFolder = imagesFolder):
               workersNames = []
               encodeListKnown = []
               for cl in os.listdir(imagesFolder):
                 if cl.endswith(".ini"):
                    continue
                 name = os.path.splitext(cl)[0] \# split and leave out the extension part.
                 curImg = cv2.imread(os.path.join(imagesFolder,cl), cv2.COLOR_BGR2RGB) #read in rgb mode directly without the curImg = cv2.imread(os.path.join(imagesFolder,cl), cv2.COLOR_BGR2RGB)
```

```
#curImg = cv2.cvtColor(curImg, cv2.COLOR_BGR2RGB)

encode = face_recognition.face_encodings(curImg)

if not len(encode) > 1: # If there are more than 1 face in the image, then skip it
    workersNames.append(name)
    encodeListKnown.append(encode[0])

print(workersNames)
print("Encoding Complete")

return workersNames, encodeListKnown

#findEncodings(imagesFolder)
```

```
In [40]:
            def faceDetectionAtGate():
               workersNames, encodeListKnown = findEncodings(imagesFolder)
               cap = cv2.VideoCapture(0)
                 while cap.isOpened():
                    _, img = cap.read()
                    facesCurFrame = face recognition.face locations(img)
                    encodeCurFrame = face recognition.face encodings(img, facesCurFrame)
                    for encodeFace, faceLoc in zip(encodeCurFrame, facesCurFrame):
                      matches = face_recognition.compare_faces(encodeListKnown, encodeFace) #return True/False
                      faceDis = face recognition.face distance(encodeListKnown, encodeFace) #return distance
                      name = "stranger"
                      color = (0,0,255)
                      late = 0 # Stranger at the gate = 0
                      matchIndex = np.argmin(faceDis)
                      if matches[matchIndex]:
                         name = workersNames[matchIndex].upper()
                         color = (255,0,0)
                         late = markAttendance(name, csv file)
                         late = 1 if late else 2 # Worker is late = 1
                         subject = "{} is late Date: {}, Time: {}"
                         contents = f"{name} has just arrived"
                      else:
                         subject="A {} at the gate Date: {}, Time: {}"
                         contents = f"There is a {name} waiting at the gate. See if you prefer opening the gate for him/her"
                      top, right, bottom, left = faceLoc
                      cv2.rectangle(img, (right, top), (left, bottom), color, 2)
                      cv2.putText(img, name, (left+5, bottom+30), cv2.FONT HERSHEY COMPLEX, 1, color, 2)
                      # If a person visits after working hours, perhaps, he is a robber
                      now = datetime.now()
                      working_hrs = (now.hour >= 7 and now.hour <= 19)
                      if not working hrs:
                         subject="{} at the gate outside working hours Date: {}, Time: {}"
                         contents = f"There is {name} at the gate. Perhaps, he is a robber, etc. If necessary, alert the police"
```

['alex_lacamoire1', 'johnsnow_test1', 'obama1', 'Tim_CV', 'biden', 'Rose', 'GiorgiaBarboni', 'EliseBaturone', 'saur', 'Yus upha']

Encoding Complete

YUSUPHA is already registered for today 2022-06-20 at 09:25:32

YUSUPHA is already registered for today 2022-06-20 at 09:25:32

YUSUPHA is already registered for today 2022-06-20 at 09:25:32

YUSUPHA is already registered for today 2022-06-20 at 09:25:32

YUSUPHA is already registered for today 2022-06-20 at 09:25:32

YUSUPHA is already registered for today 2022-06-20 at 09:25:32

SAUR registered successfuly at 10:38:48

Email sent successfuly Date: 2022-06-20 Time: 10:37:10

SAUR is already registered for today 2022-06-20 at 10:38:48 SAUR is already registered for today 2022-06-20 at 10:38:48 YUSUPHA is already registered for today 2022-06-20 at 10:38:48 CPU times: total: 1min 33s Wall time: 1min 39s

Number plate recognition and extraction.

Link to pytesseract

```
In [9]: # This is very important. Search on google if you don't understand it.

pytesseract.pytesseract.tesseract_cmd = r"C:\Program Files\Tesseract-OCR\tesseract.exe"

In [10]: filename = r".\AI LAB Workplace Monitoring\Cars\image1.jpg"

filename = r".\AI LAB Workplace Monitoring\Cars\image4.jpg"
```

```
plate_date_file = r".\AI LAB Workplace Monitoring\plate_date.csv"
plate_count_file = r".\AI LAB Workplace Monitoring\plate_count.csv"
```

```
img = cv2.imread(filename)
In [41]:
            \#img = cv2.resize(img, (500,500))
            gray = cv2.cvtColor(img, cv2.COLOR BGR2GRAY)
            # Apply filter and find edges for localization
            bfilter = cv2.bilateralFilter(gray, d=11, sigmaColor=17, sigmaSpace=17) #noise reduction
            canny_image1 = cv2.Canny(bfilter, threshold1=100, threshold2=400)
                                                                                    # Edged detection
            # This sets the thresholds automatically
            # canny_image2 = imutils.auto_canny(bfilter)
            #Find Contours and apply mask. Now after detecting the edges of objects in the image, we would like to find the majo
            keypoints = cv2.findContours(canny image1, cv2.RETR LIST, cv2.CHAIN APPROX SIMPLE)
            contours = imutils.grab_contours(keypoints)
            # The above code would give us all the contours, which would include very small and insignificant ones as well so we
            contours=sorted(contours, key = cv2.contourArea, reverse = True)[:30]
            Number Plate Contour = 0
            #Now, we would like to find the contour that is rectangular in shape, and we would be using the function cv2.approxF
            for cont in contours:
               #perimeter = cv2.arcLength(cont, True)
              approx = cv2.approxPolyDP(cont, epsilon=10, closed=True)
              if len(approx) == 4:
                   Number Plate Contour = approx
                   \# new image = cv2.drawContours(img,[Number Plate Contour],0,255,2)
                   # cv2.imshow("Number Plate 1", cv2.cvtColor(new image, cv2.COLOR BGR2RGB))
                   # cv2.waitKey(1000)
                   # cv2.destroyAllWindows()
                   break
            #print(Number Plate Contour)
            mask = np.zeros(gray.shape,np.uint8)
            new image = cv2.drawContours(mask,[Number Plate Contour],contourIdx=0,color=255,thickness=-1,)
            new image =cv2.bitwise and(img,img,mask=mask)
            cv2.imshow("Masked", cv2.cvtColor( new_image, cv2.COLOR_BGR2RGB) )
            (x,y) = np.where(mask==255)
            (x1, y1) = (np.min(x), np.min(y))
            (x2, y2) = (np.max(x), np.max(y))
            cropped_image = gray[x1:x2+1, y1:y2+1]
            text = pytesseract.image to string(cropped image)
            print("Number is :", text)
            resized image = cv2.resize(cropped image, (500,500))
            cv2.imshow("croped Image", cv2.cvtColor(resized image, cv2.COLOR BGR2RGB))
            # cv2.drawContours(canny_image2, contours, -1, (0,255,0),5)
            # cv2.imshow("Number Plate 1",canny_image2)
            cv2.waitKey(0)
            cv2.destroyAllWindows()
```

Number is: HS982 FKL

```
def register plates(plate date file, plate count file, text=text):
In [12]:
                with open(plate date file, 'a') as f: #append mode to write at the end of the file
                  date, time = date and time()
                  f.writelines(f"{text},{date},{time}\n")
                fchanged = False
                with open(plate count file, 'r+') as f: #mode to read and write
                  plates = f.readlines()
                  plateList = []
                   # We create a list out of the file to find our plate and modify its count
                  for line in plates:
                     if not line in [',,\n', '\n']:
                        entry = line.split(',')
                        if '\n' in entry[1]: #otherwise the '\n' add up each time we call the function
                          entry[1] = entry[1][:-1]
                        plateList.append([entry[0], entry[1]])
                   #we look for our plate
                  for i in range(len(plateList)) :
                     (pnumb, count) = plateList[i]
                     now = datetime.now()
                     if pnumb == text: # it has to be within working hours for it to count
                        fchanged = True
                        if (now.hour \geq 7 and now.hour \leq 10):
                          count = str(int(count)+1) #we modify its count
                          plateList[i] = [pnumb, count]
                if fchanged:#if we had found our plate and modified our list we must input our list back into the file
                  with open(plate_count_file, 'w') as f: #write mode with pointer back at the start of the file
                     write = csv.writer(f)
                     write.writerows(plateList)
                #we haven't found our plate
                if not fehanged and (now.hour \geq 7 and now.hour \leq 10): # the plate has never been saved so we append it and see
                  with open(plate_count_file, 'a') as f: #append mode to write at the end of the file
                     f.writelines(f''\{text\},1\n'')
                return 1
             def reinitialise(plate date file, plate count file):
In [13]:
                   #reinitialasation of the files if needed
                  with open(plate date file, 'w') as f: #
                        #writting headers
                        n = "NUMBER PLATE"
                        d = "DATE"
                        t = "TIME"
                        f.writelines(f''\{n\},\{d\},\{t\}\n'')
                  with open(plate count file, 'w') as f: #
                        #writting headers
                        n = "NUMBER PLATE"
                        c = "COUNT"
                        f.writelines(f''\{n\},\{c\}\n'')
                   return 1
In [19]:
             # reinitialise
             reinitialise(plate_date_file, plate_count_file)
Out[19]:
```

```
In [45]: register_plates(plate_date_file, plate_count_file, text[:-1])
Out[45]: 

1
```

This is about calculating the distance b/t faces.

Detecting social distancing violations. This can be done by iterating over the coordinates of faces and calculating the distance for each possible pair, if the distance for a particular pair is less than MIN_DISTANCE then the bounding boxes for those faces are colored red.

MIN_DISTANCE must be manually initialized in such a way that it corresponds to the minimum allowable distance in real life (eg. 6ft).

This is not used anymore. We used another function called checkDistance()

```
MIN DISTANCE = 130
In [ ]:
            def cal_Min_Dist_Between_Faces(faces):
              def minDist(face1, face2):
                top1, right1, bottom1, left1 = face1
                top2, right2, bottom2, left2 = face2
                points1 = [(left1,top1), (left1,bottom1), (right1,top1), (right1,bottom1)]
                points2 = [(left2,top2), (left2,bottom2), (right2,top2), (right2,bottom2)]
                 #The inner loop calculates the minimum distance between 1 point in face1 and all points in face2
                 #The outer loop repeats the above statement for all points in location1. Just 2 for loops
                dist = min( [min( [distance.euclidean( points1[i], points2[j]) for j in range(4)]) for i in range(4)])
                 violate = True if dist < MIN DISTANCE else False
                 return violate
              #If there is any distance violation in a frame, even between only 2 faces out of many, violate is True.
              violate = any([ any([minDist(faces[i], faces[j]) for j in range(i+1, l)]) for i in range(l-1)])
              return violate
```

The used distance checking functions.

```
#Employees encodings
classNames, encodeListKnown = findEncodings(imagesFolder)

#Return employees names if identified, else none
def identify(faceEnc, encodeListKnown = encodeListKnown, classNames = classNames):
    matches = face_recognition.compare_faces(encodeListKnown, faceEnc) #True/False
    faceDis = face_recognition.face_distance(encodeListKnown, faceEnc) #Distance
    #associate face to name if match with employee face at smallest distance is True
    matchIndex = np.argmin(faceDis)
    if matches[matchIndex]:
        return classNames[matchIndex].upper()
    return None
```

['alex_lacamoire1', 'johnsnow_test1', 'obama1', 'Tim_CV', 'biden', 'Rose', 'GiorgiaBarboni', 'EliseBaturone', 'saur', 'Yus upha']

Encoding Complete

```
\frac{distPixels}{dist} = \frac{faceWidthPixels}{faceWidthAvg}
```

```
def compute focalLength (faceWidthPixels, faceDist, faceWidthAvg):
In [21]:
               return (faceWidthPixels* faceDist) / faceWidthAvg
            def compute distToCamera(faceWidthAvg, faceWidthPixels, focalLength):
               return (faceWidthAvg * focalLength) / faceWidthPixels
In [22]:
            def distPixels to dist(distPixels, faceWidthPixels, faceWidthAvg):
               # distPixels : faceWidthPixels = dist : faceWidthAvg
               return (distPixels * faceWidthAvg) / faceWidthPixels
            # Calibrate camera depth on your own face; keep your face at 1 armlength distance and press a key to register face w
In [46]:
             def compute_faceWidthPixels():
               cap = cv2.VideoCapture(0)
               while True:
                    _{, img = cap.read()}
                    faceLoc = face recognition.face locations(img)
                    if len(faceLoc) > 0:
                      top, right, bottom, left = faceLoc[0]
                      faceWidthPixels = right - left
                      cv2.rectangle(img, (right, top), (left, bottom), (0,255,0), 2)
                      cv2.putText(img, f"width: {faceWidthPixels} pixels", (left-5, bottom+30), cv2.FONT HERSHEY COMPI
                      cv2.imshow("WebCam Image", img)
                    if cv2.waitKey(1) != -1:
                       break
               cap.release()
               cv2.destroyAllWindows()
               return faceWidthPixels
             faceWidthPixels = compute faceWidthPixels()
            faceDist= 30.0
In [24]:
                                             #in cm
             faceWidthAvg= 15.0
             focalLength = compute focalLength (faceWidthPixels, faceDist, faceWidthAvg)
             minDist = 2
             def checkDistance(img, faceLoc, namesViolPrev, unidentifiedNumPrev, dateTimeLastSent, faceWidth = faceWidthA
               namesViol = set()
               unidentifiedNum = 0
               num_faces = len(faceLoc)
               viol = False
               if num faces > 1:
                 #face encodings of faces in the frame for face recognition
                 faceEnc = face recognition.face encodings(img, faceLoc)
                 #compute face centers
                 def center(top, right, bottom, left):
```

```
return (left-right, top-bottom)
#iterate over all pairs of faces
for i in range(len(faceLoc)-1):
  for j in range(i+1, len(faceLoc)):
     #face location coordinates (top, right, bottom, left of rectangle bounding face)
     t1, r1, b1, 11 = faceLoc[i]
     t2, r2, b2, 12 = faceLoc[j]
     #center of bounding rectangles
     c1 = center(t1, r1, b1, 11)
     c2 = center(t2, r2, b2, 12)
     #face widths as bounding rectangles width
     faceWidthPixels1 = r1-l1
     faceWidthPixels2 = r2-12
     #depth = distance from camera in cm
     dist to cameral = compute distToCamera(faceWidth,faceWidthPixels1,focalLength)
     dist_to_camera2 = compute_distToCamera(faceWidth,faceWidthPixels2,focalLength)
     # vertical distance = depth difference
     dist faces vert = abs(dist to camera1-dist to camera2)
     # horizontal distance in pixels = difference of centers' axis 0 coordinates
     dist_faces_horizPixels = abs(c1[0] - c2[0])
     #horizontal distance in cm
     dist faces horiz = distPixels to dist(dist faces horizPixels,faceWidthPixels, faceWidth)
     #faces distance = L-2 norm of sum of positive-oriented vectors of norm equal to dist faces horiz and dist
     \underline{\text{dist} \text{ faces}} = \text{np.linalg.norm}(\underline{\text{dist} \text{ faces horiz*np.array}}([1,0]) + \underline{\text{dist} \text{ faces vert*np.array}}([0,1]))
     #check distance violation
     if dist faces < minDist:
        #identify returns name or None if person wasn't identified as one of the employees
       name1 = identify(faceEnc[i])
       name2 = identify(faceEnc[j])
       if name1 != None:
          #add name to list of people who are violating distance restrictions
          namesViol.add(name1)
        else:
          #add 1 to count of unidentified people who are violating distance restrictions
          unidentifiedNum+=1
       if name2 != None:
          namesViol.add(name2)
        else:
          unidentifiedNum+=1
        #draw rectangles displaying a warning on screen
       cv2.rectangle(img, (r1, t1), (11, b1), (0,0,255), 2)
        cv2.rectangle(img, (r2, t2), (12, b2), (0,0,255), 2)
       cv2.putText(img, f"{name1} violating distance", (11+5, b1+30), cv2.FONT_HERSHEY_COMPLEX, 1,
       cv2.putText(img, f"{name2} violating distance", (12+5, b2+30), cv2.FONT HERSHEY COMPLEX, 1,
       cv2.imshow("Webcam image", img)
# add offset to a datetime object
def datetimeObject plus offset(myDatetime, hours, minutes, seconds):
  return myDatetime + timedelta (hours=hours, minutes=minutes, seconds=seconds)
```

```
#check if email must be sent or was recently sent

now = datetime.now()

#send email if n seconds passed from last send

dateTimeLastSent_plusOffset = datetimeObject_plus_offset(dateTimeLastSent, hours=0, minutes=0, seconds=1;

if namesViol!= namesViolPrev or unidentifiedNum > unidentifiedNumPrev or now > dateTimeLastSent_plusOffset passed -> send email

#now > dateTimeLastSent_plusOffset even if same hours, minutes seconds but on a subsequent da

viol = True

namesViolPrev = namesViol

unidentifiedNumPrev = unidentifiedNum

return viol, namesViolPrev, unidentifiedNumPrev

# the result of this function will be used in openWebcam
```

Preprocess large amount of images in a folder

```
files_folder = r".\AI LAB Workplace Monitoring\Face Mask Dataset\Clear Datasets\test"
In [25]:
            #files folder = r".\AI LAB Workplace Monitoring\Face Mask Dataset\Blur Dataset\Train"
            files folder2 = r".\AI LAB Workplace Monitoring\Face Mask Dataset\Blur Dataset\Validation"
            # Read the images as array elements
            def readFolderData(files folder=files folder):
               with_mask = join(files_folder, "WithMask")
               without_mask = join(files_folder, "WithoutMask")
               data with mask = [cv2.imread(join(with mask, img)) for img in listdir(with mask) if not img.endswith(".ini"
               data without mask = [cv2.imread(join(without mask, img)) for img in listdir(without mask) if not img.endswit
               return data_with_mask, data_without_mask
            def preprocessEntireImageFolders(data with mask, data without mask, scale=scale):
               # Resize the images to have the same size
               data_with_mask
                                 = np.array( [cv2.resize(img, scale) for img in data_with_mask] )
               data_without_mask = np.array( [cv2.resize(img, scale) for img in data without mask] )
               #print(data with mask.shape, data without mask.shape, "----")
               # Change each image to gray
               # data with mask = np.array([cv2.cvtColor(img, cv2.COLOR_BGR2GRAY) for img in data with mask])
               # data without mask = np.array([ cv2.cvtColor(img, cv2.COLOR BGR2GRAY) for img in data without mask ])
               # Reshape to have each image as a 1D array
               data_with_mask = np.array([np.reshape(img, [-1]) for img in data_with_mask])
               data_without_mask = np.array([np.reshape(img, [-1]) for img in data_without_mask])
               print(data with mask.shape, data without mask.shape)
               stacked_data = np.r_[ data_without_mask, data_with_mask]
               labels = np.zeros(len(stacked data), dtype="uint8")
               labels[len(data without mask):] = 1
               #print(stacked_data.shape)
```

```
return stacked_data, labels

mask, no_mask = readFolderData()
%time stacked_data, labels = preprocessEntireImageFolders( mask, no_mask )

(97, 30000) (97, 30000)

CPU times: total: 31.2 ms

Wall time: 31.3 ms
```

Split the data into train and test

```
In [26]: Xtrain, Xtest, ytrain, ytest = train_test_split(stacked_data, labels, shuffle=True, random_state=0, stratify=labels)
print( Xtrain.shape, Xtest.shape, ytrain.shape, ytest.shape)

(145, 30000) (49, 30000) (145,) (49,)
```

Calculate and Plot the confusion matrix, accuracy score, classification report

```
names = ["No Mask", "Mask"]
In [27]:
                                                                      def confusion_matrix_score(model, names=names, Xtest=Xtest, ytest=ytest):
                                                                                   model.fit(Xtrain, ytrain)
                                                                                   ypred = model.predict(Xtest)
                                                                                   print( f"\nAccuracy_score: {accuracy_score(ytest, ypred)}", end= "\n" )
                                                                                    \#print(f'' \land model.score function: \{model.score(Xtest, ytest)\}'', end = " \land n \land n = " \land 
                                                                                   mat = confusion matrix(ytest, ypred)
                                                                                    \#print(f''confusion\_matrix: \n\{mat\}'', end = ''\n\n'')
                                                                                   sns.heatmap(mat, square=True, annot=True, fmt='d', cbar=False,
                                                                                                                          xticklabels=names,
                                                                                                                          yticklabels=names)
                                                                                  plt.xlabel('true label')
                                                                                   plt.ylabel('predicted label');
                                                                                   plt.title('Classification Report')
                                                                                   # classification_report
                                                                                   print(f"classification_report: \n{ classification_report(ytest, ypred, target_names=names) }", end="\n\n")
```

This below cell was commented out because it take so much time to train

```
In []: #Use PCA for dimensionality reduction, that is to remove less important features, and SVC for the classification.

#We combine both in a pipeline manner.

#pca = PCA(n_components=0.8, svd_solver="full")

#svc_model = SVC(kernel='rbf', class_weight='balanced')

#model_pipeline = make_pipeline(pca, svc_model)

#param_grid = {'svc_C': [5, 10],

# 'svc_gamma': [0.0001, 0.0005, 0.001, 0.005]}

#grid = GridSearchCV(model_pipeline, param_grid)
```

```
# Fit the model and choose the model with the best parameters

# %time grid.fit(Xtrain, ytrain)

# print(grid.best_params_, grid.best_estimator_)

# model = grid.best_estimator_

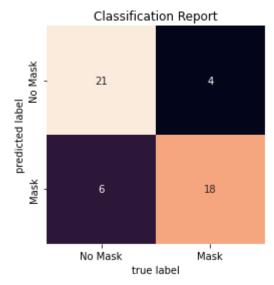
# from sklearn.model_selection import_cross_val_score

# print(cross_val_score(model, Xtrain, ytrain, cv=10))
```

Build Support Vector Classifier

```
# Fit the model using SVC
In [28]:
            sv_model = SVC(kernel='rbf', class_weight='balanced') # 'rbf' radial basis function
            %time confusion_matrix_score(sv_model)
            Accuracy_score: 0.7959183673469388
            classification report:
                    precision recall f1-score support
               No Mask
                                   0.84
                           0.78
                                           0.81
                                                   25
                 Mask
                          0.82
                                 0.75
                                         0.78
                                                  24
              accuracy
                                      0.80
                                               49
              macro avg
                           0.80
                                   0.79
                                          0.80
                                                   49
            weighted avg
                            0.80
                                    0.80
                                           0.80
                                                    49
```

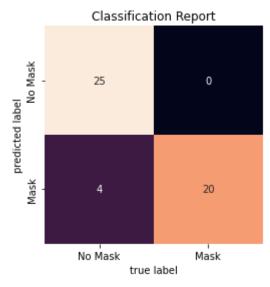
CPU times: total: 2.08 s Wall time: 610 ms



Build Decision Tree Classifier

Accuracy_score: 0.9183673469387755 classification report: precision recall f1-score support 0.93 25 No Mask 0.86 1.00 Mask 1.00 0.83 0.91 24 accuracy 0.92 49 macro avg 0.93 0.92 0.92 0.93 0.92 49 weighted avg 0.92

CPU times: total: 828 ms Wall time: 825 ms



Build Random Forest Classifier

In [30]: from sklearn import ensemble

rf_model = ensemble.RandomForestClassifier()

%time confusion_matrix_score(model=rf_model)

Accuracy_score: 0.9387755102040817

Accuracy_score: 0.9387755102040817

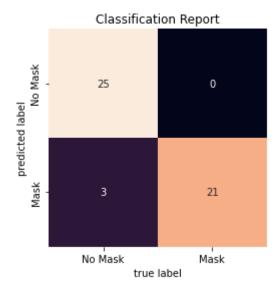
classification_report:

precision recall f1-score support

No Mask 0.89 1.00 0.94 25 Mask 1.00 0.88 0.93 24

accuracy 0.94 49 macro avg 0.95 0.94 0.94 49 weighted avg 0.95 0.94 0.94 49

CPU times: total: 406 ms Wall time: 408 ms



Build Naive Bayes Classifier

```
In [31]:
           from sklearn.naive_bayes import GaussianNB
            nb_model = GaussianNB()
            confusion_matrix_score(model=nb_model)
           Accuracy_score: 0.7959183673469388
           classification_report:
                   precision recall f1-score support
              No Mask
                                         0.80
                                                  25
                                  0.80
                         0.79
                Mask
                                0.79
                                        0.79
                                                24
                                     0.80
                                             49
              accuracy
                          0.80
                                  0.80
                                         0.80
                                                  49
             macro avg
```

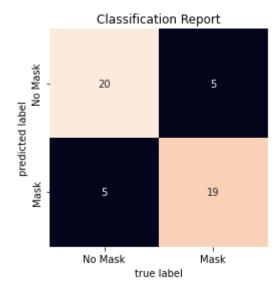
0.80

0.80

0.80

49

weighted avg



Logistic regression Classifier

```
In [32]:
```

from sklearn.linear_model import LogisticRegression
%time lr_model = LogisticRegression()
confusion matrix_score(lr_model)

CPU times: total: 0 ns Wall time: 0 ns

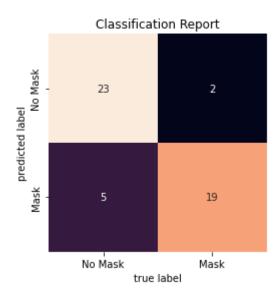
Accuracy_score: 0.8571428571428571

classification_report:

precision recall f1-score support

No Mask 0.82 0.92 0.87 25 Mask 0.90 0.79 0.84 24

accuracy 0.86 49 macro avg 0.86 0.86 0.86 49 weighted avg 0.86 0.86 0.86 49



K-Nearest Neighbors

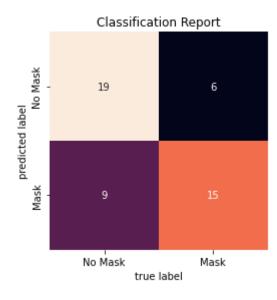
In [33]:

from sklearn.neighbors import KNeighborsClassifier
%time knn_model = KNeighborsClassifier() # n_neighbors=5 by default

confusion_matrix_score(knn_model)

CPU times: total: 0 ns Wall time: 0 ns

Accuracy_score: 0.6938775510204082 classification report: precision recall f1-score support 25 No Mask 0.68 0.76 0.72 Mask 0.71 0.62 0.67 24 0.69 49 accuracy macro avg 0.70 0.69 0.69 49 49 weighted avg 0.70 0.69 0.69



Load another dataset

(142,) (142, 30000) (142,)

```
In [34]: #Load another folder to test and see

blurred_photos_folder = r".\AI LAB Workplace Monitoring\Face Mask Dataset\Blur Dataset\Test"

clear_photos_folder = r".\AI LAB Workplace Monitoring\Face Mask Dataset\Clear Datasets\val"

mask_test, no_mask_test = readFolderData(clear_photos_folder) # image form
test_data, label_data = preprocessEntireImageFolders(mask_test, no_mask_test) #reshaped form of (1, n)

comb = np.r_[no_mask_test, mask_test]
print(comb.shape, test_data.shape, label_data.shape)

(71, 30000) (71, 30000)
```

C:\Users\Utente locale\anaconda3\lib\site-packages\numpy\core\fromnumeric.py:3162: VisibleDeprecationWarning: Creating an ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant to do this, you must specify 'dtype=object' when creating the ndarray. return asarray(a).ndim

C:\Users\Utente locale\anaconda3\lib\site-packages\numpy\lib\index_tricks.py:394: VisibleDeprecationWarning: Cre ating an ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-tuples-or ndarrays with different le ngths or shapes) is deprecated. If you meant to do this, you must specify 'dtype=object' when creating the ndarray. newobj = array(item, copy=False, subok=True, ndmin=ndmin)

All models in a list

```
In [35]: models = [sv_model, dt_model, rf_model, nb_model, lr_model, knn_model]
```

Load from disk. Here I use face-recognition module

```
def loadFromDisk(model, retry_if_not_sent=False):
In [49]:
                  for i in range(len(comb)):#-1,-1,-1): #I wanna first start with mask, so I reverse
                    frame = comb[i]
                    frame = cv2.resize(frame, (900,700))
                     face locations = face recognition.face locations(frame)
                    pred = model.predict(np.reshape(test data[i], (1,-1)))[0]
                    if pred == 0:
                       subject = "Worker not wearing a mask; Date {}, Time: {}"
                       contents = "There is high probability that a worker is not wearing a mask. Take action!"
                       name = "No Mask"
                       color = (0,0,255)
                    else:
                       name = "Mask"
                       color = (255,0,0)
                    for top, right, bottom, left in face locations:
                       cv2.rectangle(frame, (left, top), (right, bottom), color, 5)
                       cv2.putText(frame, f"{name} & pred = {pred}", (left+10, bottom+30), cv2.FONT_HERSHEY_COMPLEX
                    if not face locations:
                       text = f'' \{name\} \& pred = \{pred\} \setminus face not detected by face detector''
                       left, top = 50, 50
                       for i, line in enumerate(text.split('\n')):
                         y = (i+1)*top
                         cv2.putText(frame, line, (left,y), cv2.FONT HERSHEY SIMPLEX, 1, color, 2)
                     #If covid19 distance rule is not respected, then send an alert
                    violate = checkDistance(face locations) if len(face locations) >= 2 else False
                       subject = "Violating covid19 distance rules; Date {}, Time: {}"
                       contents = "mr. {} seems to be violating covid19 distance rules"
                    #Send an alert if a worker is not wearing a mask or is violating covid19 distance rules
                    if violate or not pred:
                       date, time = date and time()
                       sent = sendEmailWithAttachment(frame,
                                        subject=subject.format(date, time),
                                        sender password=sender password,
                                        contents=contents)
                       # Retry to send the the alert if it failed
                       if retry if not sent and not sent: resendIt(frame, sent)
                    cv2.imshow("frame", frame)
                    if cv2.waitKey(1000) != -1: break
               finally:
```

```
cv2.destroyAllWindows()

def resendlt(frame, sent):
    if sent:
        return
    else:
        sender_password = input("Retry the Password")
        sent = sendEmailWithAttachment(frame, sender_password = sender_password)
        return resendIt(frame, sent)

loadFromDisk(rf_model)

Email sent successfuly Date: 2022-06-20 Time: 10:37:10

Email sent successfuly Date: 2022-06-20 Time: 10:37:10

Email sent successfuly Date: 2022-06-20 Time: 10:37:10
```

Email soft successfully Date: 2022 00 20 Time: 10.57.10

Email sent successfuly Date: 2022-06-20 Time: 10:37:10

Webcam Mask Detection

```
def openWebcam(model, retry if not sent=False):
In [50]:
              #initialization for social distancing check
             unidentifiedNumPrev = 0
             namesViolPrev = set()
             dateTimeLastSent = datetime.now()
             cap = cv2.VideoCapture(0)
             try:
               while cap.isOpened():
                  , frame = cap.read()
                  img = cv2.resize(frame, scale)
                  pred = model.predict(np.reshape(img, (1,-1)))[0]
                  if pred == 0:
                    subject = "Worker not wearing a mask; Date {}, Time: {}"
                    contents = "{} There is high probability that a worker is not wearing a mask. Take action!"
                    name = "No Mask"
                    color = (0,0,255)
                  else:
                    name = "Mask"
                    color = (255,0,0)
                  face locations = face recognition.face locations(frame)
                  #If covid19 distance rule is not respected, then send an alert
                  if violate:
                    subject = "Violating covid19 distance rules; Date {}, Time: {}"
```

```
contents = "mr. {} seems to be violating covid19 distance rules'
          if pred == 0:
            subject = "Worker not wearing a mask and Violating covid19 distance rule; Date {}, Time: {}"
            contents = "{} violating covid19 distance rules and not wearing mask"
       #Send an alert if worker is not wearing a mask or is violating covid19 distance rules
       if violate or not pred:
          date, time = date_and_time()
         sent = sendEmailWithAttachment(frame,
                           subject=subject.format(date, time),
                           receiver_mail_addr = ["youremail@gmail.com"],
                           sender_password=sender_password,
                           contents=contents.format(namesViolPrev))
          # Retry to send the the alert if it failed
         if retry_if_not_sent and not sent: resendIt(frame, sent)
         dateTimeLastSent = datetime.now()
       for top, right, bottom, left in face locations:
          cv2.rectangle(frame, (left, top), (right, bottom), color, 5)
          cv2.putText(frame, f"{name} & pred = {pred}", (left+10, bottom+30), cv2.FONT HERSHEY COMPLEX
       if not face_locations:
         text = f''\{name\} \& pred = \{pred\} \setminus face not detected by face detector''
         left, top = 50, 50
          for i, line in enumerate(text.split('\n')):
            y = (i+1)*top
            cv2.putText(frame, line, (left,y), cv2.FONT_HERSHEY_SIMPLEX, 1, color, 2)
       cv2.imshow("frame", frame)
       if cv2.waitKey(1) != -1: break
  finally:
    cap.release()
    cv2.destroyAllWindows()
openWebcam(sv_model)
```

Email sent successfuly Date: 2022-06-20 Time: 10:37:10

Email sent successfuly Date: 2022-06-20 Time: 10:37:10