- Big O recap
 - EXT: master theorem
 - (A proof is in Levitin's Appendix B.)

For integer constants $(a \ge 1)$ and (b > 1), and function (f) with (f(n) in $\Theta(n^d)$), $(d \ge 0)$, the recurrence :

$$T(n) = aT\left(rac{n}{h}
ight) + f(n)$$

(with (T(1)=c)) has solutions, and

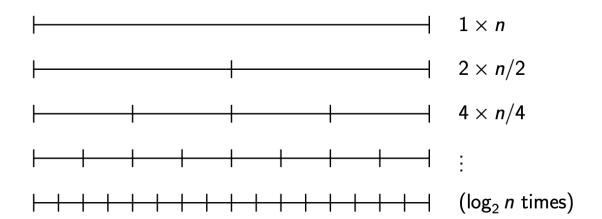
$$T(n) = egin{cases} \Theta(n^d) & ext{if } a < b^d \ \Theta(n^d \log n) & ext{if } a = b^d \ \Theta(n^{\log_b a}) & ext{if } a > b^d \end{cases}$$

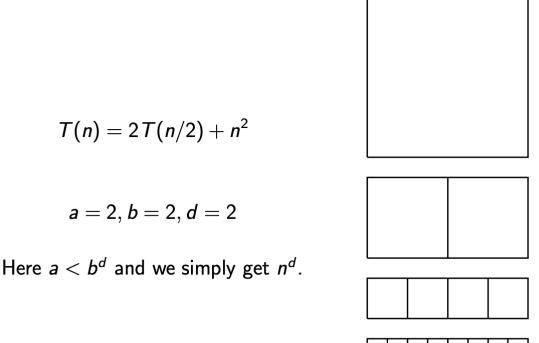
Note that we also allow a to be greater than b.

e.g.

$$T(n) = 2T(n/2) + n$$
 $a = 2, b = 2, d = 1$

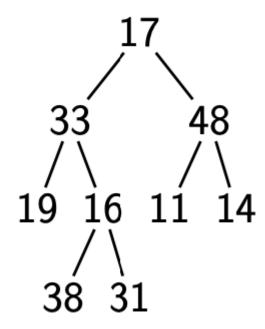






(source : Algorithm and data structure lecture slide 2022)

- Searching
 - Linear search
 - Binary search
- Sorting -- See slides
 - Insertion
 - Selection
 - quick
 - Merge -- merge sort.c
 - Can also do a bottom up merge
 - Heap --- Maybe later, let's get the idea first
 - Binary tree
 - A full binary tree: Each node has 0 or 2 children.
 - A complete tree: Each level filled left to right.
 - Height of a tree: starting from 0, empty tree has height -1
 - BT traversal :
 - **Preorder traversal** visits the root, then the left subtree, and finally the right subtree : 17, 33, 19, 16, 38, 31, 48, 11, 14 -- Create/copy tree
 - **Inorder traversal** visits the left subtree, then the root, and finally the right subtree: 19, 33, 38, 16, 31, 17, 11, 48, 14 -- Sorted array
 - **Postorder traversal** visits the left subtree, the right subtree, and finally the root: 19, 38, 31, 16, 33, 11, 14, 48, 17 -- delete node
 - Level-order traversal visits the nodes, level by level, starting from the root: 17, 33, 48, 19, 16, 11, 14, 38, 31 -- Nice for printing, help



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- heap condition: The parents is bigger than the children
 - Heapify
 - https://visualgo.net/en/heap?
 fbclid=lwAR1WX9g46cVWIFO09hHQVAAmO309B5ng23mDzbnlDbuC7A
 Gm7_HFkzsDvZg
- Properties of tree:
 - The root of the tree H[1] holds a maximal item; the cost of Eject is O(1) plus time to restore the heap.
 - The height of the heap is [log2 n].
 - Each subtree is also a heap.
 - The children of node i are 2i and 2i + 1 -- We can utilise the completeness of the tree and place its elements in level-order in an array H. (H[0] = Null)
 - Heap condition :

$$orall i \in 0,1,\ldots,n, ext{we must have } H[i] \leq H[i/2]$$

- The nodes which happen to be parents are in array positions 1 to [n/2].
- FINALLY, heap sort:
 - Simply heapify then eject(O(logn)) the largest element n times
- Counting sort
 - non-comparison-based sorting algorithm, ideal for strings in a limited range,
 e.g. alphabets .
 - occurrences of each value,
 - place elements directly into their sorted position

- efficient for small integer ranges but uses extra space
- Time complexity is O(n+k), n number of elements and k is the range of input.

Sorting summary

Insertion Sort:

- Best Time Complexity: (O(n)) (already sorted array).
- Average, Worst Time Complexity: (O(n^2)) (average or reverse sorted array).
- Space Complexity: (O(1)) (in-place).

Selection Sort:

- Best, Average, Worst Time Complexity: (O(n^2)) (irrespective of input order).
- Space Complexity: (O(1)) (in-place).

Merge Sort:

- Best, Average, Worst Time Complexity: (O(n \log n)).
 - Example: Any array gets split into halves and merged in sorted order.
- Space Complexity: (O(n)) (not in-place due to additional arrays).

Quick Sort:

- Best, Average Time Complexity: (O(n \log n)) (pivot splits array into equal halves).
- Worst Time Complexity: (O(n^2)) (pivot is the smallest or largest element).
- Space Complexity: (O(\log n)) (in-place but stack space for recursion).

Heap Sort:

- Best, Average, Worst Time Complexity: (O(n \log n)) (heapify operations).
- Space Complexity: (O(1)) (in-place).

Counting Sort:

- Best, Average, Worst Time Complexity: (O(n+k)) where (n) is the number of elements in the input array and (k) is the range of the input.
 - Example: Sorting an array of English letters (k is small, 26).
- Space Complexity: (O(k)) for the count array.