# Home Assignment: Deep Learning from Scratch

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```
In [11]: # Install a conda package in the current Jupyter kernel
import sys
import numpy as np
import matplotlib.pyplot as plt
import scipy
import warnings
warnings.simplefilter("ignore")
from scipy import io
import matplotlib.pyplot as plt
```

## Part I: the classifier and optimizer

## Subsection I - Softmax and its gradient

For start, we will load the datasets PeaksData and GMMData to the working environment.

```
In [1]: import scipy.io
        mat = scipy.io.loadmat('PeaksData.mat')
        mat2 = scipy.io.loadmat('GMMData.mat')
In [2]: | X = mat['Yt']
        Y = mat['Ct']
        X_val = mat['Yv']
        Y val = mat['Cv']
        print(X.shape)
        print(Y.shape)
        X2 = mat2['Yt']
        Y2 = mat2['Ct']
        X2_val = mat2['Yv']
        Y2 val = mat2['Cv']
        print(X2.shape)
        print(Y2.shape)
        (2, 25000)
        (5, 25000)
        (5, 25000)
        (5, 25000)
```

We will now, define the softmax function, and its gradient with respect to the weights, baises and data. softmax function definition is :  $\frac{e^{x_i}}{\sum_i e^{x_j}}$ 

```
In [6]: import numpy as np

class softmax:
    def gradient(self, X, Y, error, W):
        M = X.shape[1]
        grad_theta = 1/M * error @ X.T
        grad_b = 1/M * np.sum(error, axis=1)
        grad_data = 1/M * W.T @ error
        return grad_theta, grad_b, grad_data

def __call__(self, x):
        exp = np.exp(x)
        return (exp / np.sum(exp, axis=0))
```

The next part of the code will define our loss function which is the cross entropy loss.

We assume that the predicted data provided to this function went through a softmax function as its most recent process before applying this loss function.

Cross entropy checks the diffrence between two probabilities in the following way :

 $\frac{1}{M}\sum(Y_{true}*log(Y_{predicted}))$  where m is the size of the dataset , and Y\_true is 1 hot encoded vector with size L(number of classes)

```
In [7]: def cross_entropy_loss(y_true, y_predicted, epsilon=1e-10):
    predictions = np.clip(y_predicted, epsilon, 1. - epsilon)
    M = predictions.shape[1]
    return -np.sum(y_true * np.log(predictions)) / M
```

The class linear\_layer is a wrapper around simple linear layer which will later be used as a building block to our nueral network.

Linear layer consists of activation function and linear function in the form :  $\sigma(AX + B)$ .

The function update\_weigths and gradient will be later used in the SGD. Notice that the gradient function is just a wrapper around the activation layer gradient function.

```
In [115]: class linear_layer:
              def __init__(self, dim_in, dim_out, activation):
                  self._A = np.random.normal(.5, .5, size=(dim_out, dim_in))
                  self._B = np.random.normal(.5, .5, size=(dim_out, 1))
                  self. activation = activation
                  self._dim_in = dim_in
                  self._dim_out = dim_out
              def update_weigths(self, gradient_theta, gradient_b, learning_rate):
                  gradient_b = gradient_b.reshape(self._dim_out, 1)
                  self._A = self._A - learning_rate * gradient_theta
                  self. B = self._B - learning_rate * gradient_b
              def gradient(self, X, Y, error):
                  return self._activation.gradient(X, Y, error, self._A)
              def dim in(self):
                  return self._dim_in
              def dim_out(self):
                  return self._dim_out
              def activate with weigths change(self, d, X):
                  return self. activation((self. A + d) @ X + self. B)
              def activate with biases change(self, d, X):
                  return self. activation(self. A @ X + (self. B + d))
              def jacobian(self, X, Y, vec, kind):
                  return self._activation.jacobian(X, Y, self._A, vec, kind)
              def __call__(self, X):
                  return self._activation(self._A @ X + self._B)
```

In general the gradient test is defined as follows : we know that  $|f(x+\epsilon*d)-f(x)|=O(\epsilon)$ , we want to check that  $|f(x+\epsilon*d)-f(x)-\epsilon*d*grad(x)|=O(\epsilon^2)$ 

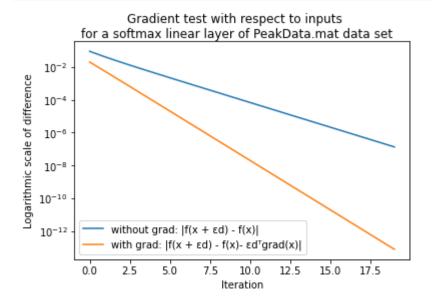
We can now check that our linear function with softmax activation passes the gradient test, where  $f(x) = Loss(Y_{true}, Y_{predicted})$ .

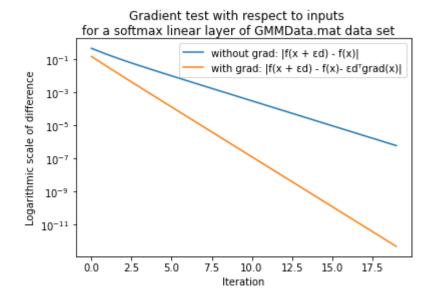
We will start by checking the gradient with respect to the data.

Notice that since we only check the gradient with respect to the data , the random vector  $\epsilon*d$  is added the data in the following way  $f(\sigma(W(X+\epsilon*d)+b))$ 

```
In [9]: def create_random_vector(dim_in, dim_out):
            d = np.random.normal(.5, .5, size=(dim_in, dim_out))
            return d / np.linalg.norm(d)
        def gradient_test_with_respect_to_data(loss, linear_layer, X, Y):
            dim_out = Y.shape[0]
            dim in = X.shape[0]
            d_input = create_random_vector(dim_in, 1)
            without_gradient = []
            with gradient = []
            for i in range(20):
                e = np.power(0.5, i)
                vec = e * d_input
                predictions = linear_layer(X)
                predictions_d = linear_layer(X + vec)
                _, _, grad_data = linear_layer.gradient(X, Y, predictions - Y)
                diff_f = loss(Y, predictions_d) - loss(Y, predictions)
                without_gradient.append(np.abs(diff_f))
                with gradient.append(np.abs(diff f - vec.T.dot(grad data).reshape(1)))
            return without gradient, with gradient
```

In each iteration of the gradient test we define  $\epsilon=0.5^i$  where i is the number of the current iteration. We will then draw those 2 lines in log scale, and we expect that the second formula(with the gradient) will converge faster.



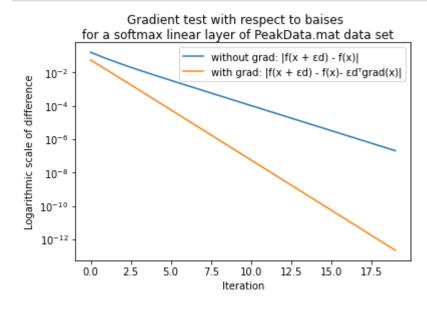


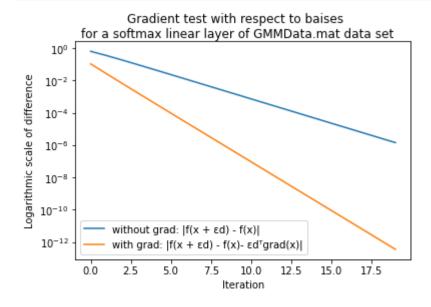
The following code test the gradient with respect to the baises, the basic idea of the gradient test applies here as well we only need to make small modifications, we need to add the random vector  $\epsilon*d$  to the baises instead of the data  $f(\sigma(WX+(b+\epsilon*d)))$ 

Regarding this test we will use the gradient of the softmax function with respect to the baises.

```
In [16]:
         def gradient_test_with_respect_to_baises(loss, linear_layer, X, Y):
             dim out = Y.shape[0]
             dim_in = X.shape[0]
             d = create_random_vector(dim_out, 1)
             without gradient = []
             with_gradient = []
             for i in range(20):
                 e = np.power(0.5, i)
                 vec = e * d
                 predictions = linear_layer(X)
                 predictions_d = linear_layer.activate_with_biases_change(vec, X)
                 diff_f = loss(Y, predictions_d) - loss(Y, predictions)
                 without_gradient.append(np.abs(diff_f))
                 _, grad_baises, _ = linear_layer.gradient(X, Y, predictions - Y)
                 with_gradient.append(np.abs(diff_f - vec.T.dot(grad_baises).reshape(1)))
             return without_gradient, with_gradient
```

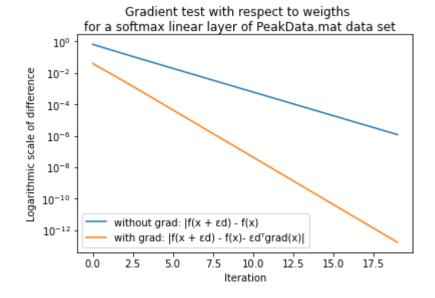
we expect the same result here as we got in the gradient test with respect to the data

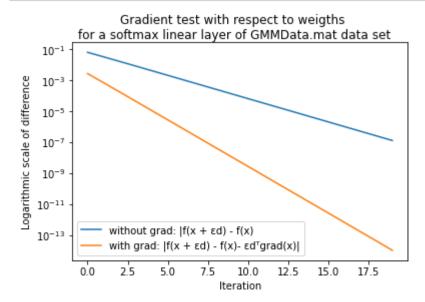




now for the final test, we will test the gradient with respect to the weights. we will now add the random vector  $\epsilon * d$  to the weights as follows :  $f(\sigma((W + \epsilon * d)X + b))$ 

```
In [21]:
         def gradient_test_with_respect_to_weigths(loss, linear_layer, X, Y):
             dim_out = Y.shape[0]
             dim_in = X.shape[0]
             d = create_random_vector(dim_out, dim_in)
             without_gradient = []
             with gradient = []
             for i in range(20):
                 e = np.power(0.5, i)
                 vec = e * d
                 predictions = linear_layer(X)
                 predictions_d = linear_layer.activate_with_weigths_change(vec, X)
                 diff f = loss(Y, predictions d) - loss(Y, predictions)
                 without_gradient.append(np.abs(diff_f))
                 grad_theta, _, _ = linear_layer.gradient(X, Y, predictions - Y)
                 with_gradient.append(np.abs(diff_f -
                         (np.ravel(vec) @ np.ravel(grad_theta)).reshape(1)))
             return without_gradient, with_gradient
```





As we can see, the test result shows a relation of square values between the subtraction results with and without the gradient for all three tests and for both data sets as expected.

we can clearly see that our linear\_layer passes the gradient test and we can move on to the second part, which is writing the SGD.

#### Subsection II - SGD

Before we start writing the SGD, we will define the class sequential\_model which is just a wrapper over some linear\_layers, and will help calculting the output of the model and the total gradient. Note that this class also saves the outputs after each layer to be later used in the gradient function.

```
In [25]: class sequential_model:
             def __init__(self, *layers):
                 self._layers = []
                 self._history = []
                 last_dim_out = 0
                 for layer in layers:
                     if last_dim_out != 0 and last_dim_out != layer.dim_in():
                         print('dimension dont match layer out dim {} , next layer dim in {}
                                format(last_dim_out, layer.dim_in()))
                         raise
                      self. layers.append(layer)
                     last_dim_out = layer.dim_out()
             def gradient(self, Y_true):
                 gradient = []
                 error = self._history[-1] - Y_true
                 for i in range(1, len(self._layers) + 1):
                     X = self._history[-i - 1]
                     Y = self. history[-i]
                     gradient_theta, gradient_b, error = self._layers[-i].
                         gradient(X, Y, error)
                     gradient.append((gradient_theta, gradient_b, error))
                 return gradient
             def call (self, X):
                 new_X = np.array(X, copy=True)
                 self._history = []
                 self. history.append(new X)
                 for layer in self. layers:
                     new X = layer(new X)
                      self. history.append(new X)
                 return new X
             def layers(self):
                 return self. layers
```

The accuracy function is defined as follows :  $\frac{argmax(Y_{true}) = argmax(Y_{predicted})}{size}$ 

Now we will define out SGD, this function receive the model as input and in each epoch, it update the weigths based on the gradient. Then it calculate the accuracy the and the loss for the train set and the validation set.

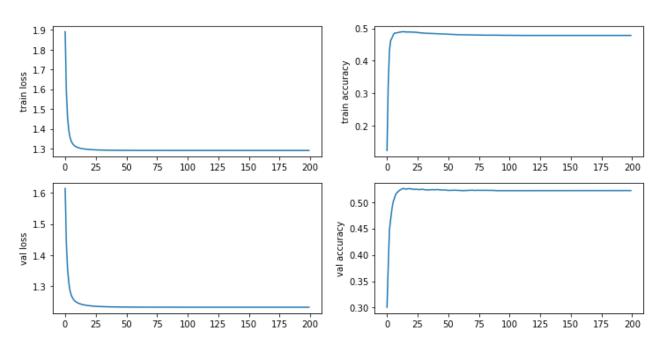
Importent thing to note is that each layer updates its own weights according to the gradient calculated up to this point.

```
In [27]: import math
         def update_weigths(model, learning_rate, Y_true):
             grad = model.gradient(Y_true)
             for i, (gradient_theta, gradient_b, error) in enumerate(reversed(grad)):
                 model.layers()[i].update_weigths(gradient_theta, gradient_b, learning_rate)
         def SGD(model, X, Y, X_val, Y_val, epoch, learning_rate, loss, batch_size):
             accuracy_train = []
             accuracy val = []
             loss_train = []
             loss_val = []
             number of iterations = math.ceil(X.shape[1] / batch size)
             for i in range(epoch):
                 iter_accuracy = 0
                 iter loss = 0
                 for j in range(0, X.shape[1], batch size):
                     Y_predicted = model(X[:, j:j+batch_size])
                     update_weigths(model, learning_rate, Y[:, j:j+batch_size])
                     iter_accuracy += accuracy(Y[:, j:j+batch_size], Y_predicted)
                     iter_loss += loss(Y[:, j:j+batch_size], Y_predicted)
                 Y predicted val = model(X val)
                 accuracy train.append(iter accuracy / number of iterations)
                 loss train.append(iter loss / number of iterations)
                 accuracy val.append(accuracy(Y val, Y predicted val))
                 loss_val.append(cross_entropy_loss(Y_val, Y_predicted_val))
             return loss_train, accuracy_train, loss_val, accuracy_val
```

We will now check that the SGD minimize the objective function.

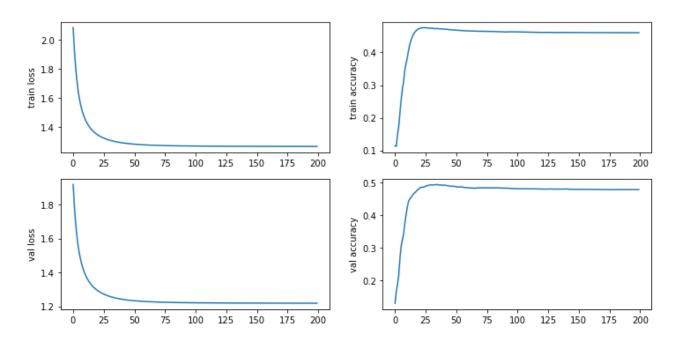
```
In [28]:
         import matplotlib.pyplot as plt
         model = sequential_model(
                 linear_layer(2, 5, activation=softmax())
         train_loss, train_accuracy, val_loss, val_accuracy =
                 SGD(model, X, Y, X_val, Y_val, 200, 0.1, cross_entropy_loss, 2500)
         fig, axs = plt.subplots(2, 2, figsize=(12,6))
         fig.suptitle('loss and accuracy function as a function of iteration')
         axs[0][0].plot(train_loss)
         axs[0][0].set_ylabel('train loss')
         axs[0][1].plot(train_accuracy)
         axs[0][1].set_ylabel('train accuracy')
         axs[1][0].plot(val_loss)
         axs[1][0].set_ylabel('val loss')
         axs[1][1].plot(val_accuracy)
         axs[1][1].set_ylabel('val accuracy')
         plt.show()
```

loss and accuracy function as a function of iteration



```
In [33]:
         model = sequential_model(
                 linear_layer(5, 5, activation=softmax())
         train_loss, train_accuracy, val_loss, val_accuracy =
                 SGD(model, X2, Y2, X2_val, Y2_val, 200, 0.1, cross_entropy_loss, 2500)
         fig, axs = plt.subplots(2, 2, figsize=(12,6))
         fig.suptitle('loss and accuracy function as a function of iteration')
         axs[0][0].plot(train_loss)
         axs[0][0].set_ylabel('train loss')
         axs[0][1].plot(train_accuracy)
         axs[0][1].set_ylabel('train accuracy')
         axs[1][0].plot(val_loss)
         axs[1][0].set_ylabel('val loss')
         axs[1][1].plot(val_accuracy)
         axs[1][1].set_ylabel('val accuracy')
         plt.show()
```

loss and accuracy function as a function of iteration



The SGD works as expected, but we see that the loss converges which probably means that we need to pick new hyper parameters or the model isn't expressive enought.

In the next section we will see how to choose the right hypter parameters using a grid search.

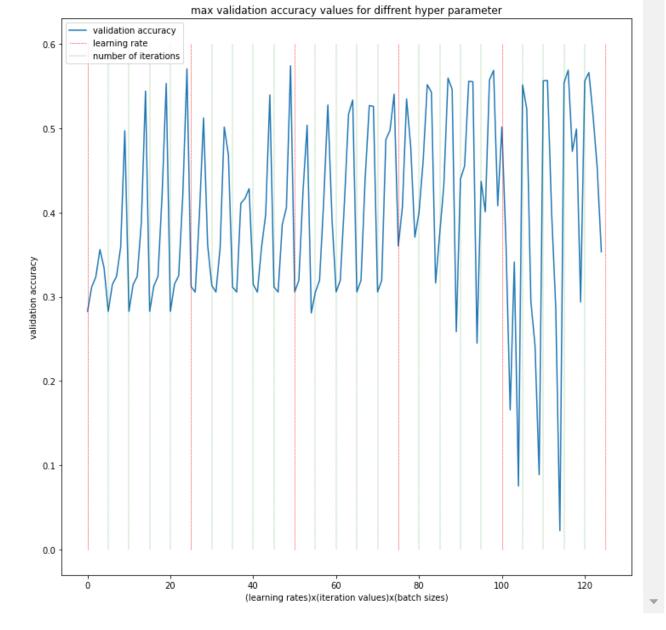
## **Subsection III - SGD Hyper Parameters**

In order to find the best parameters for the learning process, we will define a grid search function. Given some hyper parameters lists, the function will activate different combinations and will demonstrate the result, allowing us to find the best one.

```
In [35]: | def grid_search(model_init, X, Y, X_val, Y_val,
                         learning rate values, iteration values, batch size values):
             train_accuracy = []
             val_accuracy = []
             val_loss = []
             train loss = []
             for learning_rate in learning_rate_values:
                 for iteration_num in iteration_values:
                     for batch_size in batch_size_values:
                         model = model_init()
                         loss_train, accuracy_train, loss_val, accuracy_val =
                                      SGD(model, X, Y, X_val, Y_val,
                                          iteration_num, learning_rate,
                                          cross_entropy_loss, batch_size)
                         train_accuracy.append(accuracy_train)
                         val_accuracy.append(accuracy_val)
                         train_loss.append(loss_train)
                         val loss.append(loss val)
             return train_accuracy, train_loss, val_accuracy, val_loss
```

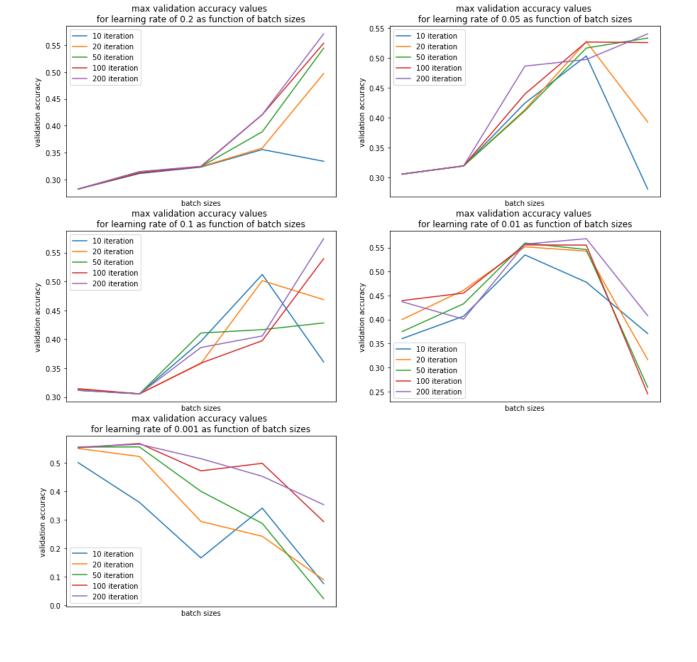
We will now test our grid function and plot the best results, according to the best validation accuracy.

```
In [37]: max_values = list(map(lambda x : max(x), val_accuracy))
         plt.figure(figsize=(12,12))
         plt.plot(max_values)
         plt.title("max validation accuracy values for diffrent hyper parameter")
         plt.ylabel('validation accuracy')
         plt.xlabel('(learning rates)x(iteration values)x(batch sizes)')
         plt.plot([25, 25], [0, 0.6], 'r--', lw=0.5, label="iteration values")
         a = plt.plot([5, 5], [0, 0.6], 'g--', lw=0.3, label="number of iterations")
         plt.plot([50, 50], [0, 0.6], 'r--', lw=0.5,)
         plt.plot([75, 75], [0, 0.6], 'r--', lw=0.5,)
         plt.plot([100, 100], [0, 0.6], 'r--', lw=0.5,)
         plt.plot([0, 0], [0, 0.6], 'r--', lw=0.5,)
         plt.plot([125, 125], [0, 0.6], 'r--', lw=0.5,)
         plt.plot([10, 10], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([15, 15], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([20, 20], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([30, 30], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([35, 35], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([40, 40], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([45, 45], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([55, 55], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([60, 60], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([65, 65], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([70, 70], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([80, 80], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([85, 85], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([90, 90], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([95, 95], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([105, 105], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([110, 110], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([115, 115], [0, 0.6], 'g--', lw=0.3,)
         plt.plot([120, 120], [0, 0.6], 'g--', lw=0.3)
         plt.legend(['validation accuracy', 'learning rate', 'number of iterations'],
                    loc='upper left')
         plt.show()
```



```
In [38]: max_values = list(map(lambda x : max(x), val_accuracy))
         batch_sizes_1 ,batch_sizes_2, batch_sizes_3 ,batch_sizes_4,
                     batch_sizes_5 = [],[],[],[],[]
         batch_sizes_1B , batch_sizes_2B , batch_sizes_3B ,batch_sizes_4B,
                     batch_sizes_5B = [],[],[],[],[]
         batch_sizes_1C ,batch_sizes_2C ,batch_sizes_3C ,batch_sizes_4C,
                     batch_sizes_5C = [],[],[],[],[]
         batch_sizes_1D, batch_sizes_2D ,batch_sizes_3D ,batch_sizes_4D ,
                     batch_sizes_5D = [],[],[],[],[]
         batch_sizes_1E ,batch_sizes_2E ,batch_sizes_3E ,batch_sizes_4E ,
                     batch_sizes_5E = [],[],[],[],[]
         for i in range(5):
             batch_sizes_1.append(max_values[i])
             batch_sizes_2.append(max_values[i+5])
             batch_sizes_3.append(max_values[i+10])
             batch_sizes_4.append(max_values[i+15])
             batch_sizes_5.append(max_values[i+20])
             batch_sizes_1B.append(max_values[i+25])
             batch_sizes_2B.append(max_values[i+5+25])
             batch_sizes_3B.append(max_values[i+10+25])
             batch_sizes_4B.append(max_values[i+15+25])
             batch_sizes_5B.append(max_values[i+20+25])
             batch_sizes_1C.append(max_values[i+50])
             batch_sizes_2C.append(max_values[i+5+50])
             batch_sizes_3C.append(max_values[i+10+50])
             batch_sizes_4C.append(max_values[i+15+50])
             batch_sizes_5C.append(max_values[i+20+50])
             batch_sizes_1D.append(max_values[i+75])
             batch_sizes_2D.append(max_values[i+5+75])
             batch_sizes_3D.append(max_values[i+10+75])
             batch_sizes_4D.append(max_values[i+15+75])
             batch_sizes_5D.append(max_values[i+20+75])
             batch_sizes_1E.append(max_values[i+100])
             batch_sizes_2E.append(max_values[i+5+100])
             batch_sizes_3E.append(max_values[i+10+100])
             batch_sizes_4E.append(max_values[i+15+100])
             batch_sizes_5E.append(max_values[i+20+100])
         print('batch sizes are 50, 100, 500, 1000, 25000')
         fig, axs = plt.subplots(3,2, figsize=(15,15))
         plt.title("max validation accuracy values for diffrent hyper parameter")
         axs[0][0].plot(batch sizes 1)
         axs[0][0].plot(batch_sizes_2)
         axs[0][0].plot(batch_sizes_3)
         axs[0][0].plot(batch_sizes_4)
         axs[0][0].plot(batch_sizes_5)
         axs[0][0].set_ylabel('validation accuracy')
         axs[0][0].set xlabel('batch sizes')
         axs[0][0].set_title("max validation accuracy values \nfor learning rate of 0.2 as f
         axs[0][0].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
         axs[0][0].set_xticks([])
```

```
axs[1][0].plot(batch_sizes_1B)
axs[1][0].plot(batch_sizes_2B)
axs[1][0].plot(batch_sizes_3B)
axs[1][0].plot(batch_sizes_4B)
axs[1][0].plot(batch_sizes_5B)
axs[1][0].set_ylabel('validation accuracy')
axs[1][0].set_xlabel('batch sizes')
axs[1][0].set_title("max validation accuracy values \nfor learning rate of 0.1 as for
axs[1][0].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[1][0].set_xticks([])
axs[0][1].plot(batch_sizes_1C)
axs[0][1].plot(batch_sizes_2C)
axs[0][1].plot(batch_sizes_3C)
axs[0][1].plot(batch_sizes_4C)
axs[0][1].plot(batch_sizes_5C)
axs[0][1].set_ylabel('validation accuracy')
axs[0][1].set_xlabel('batch sizes')
axs[0][1].set_title("max validation accuracy values \nfor learning rate of 0.05 as
axs[0][1].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[0][1].set_xticks([])
axs[1][1].plot(batch_sizes_1D)
axs[1][1].plot(batch_sizes_2D)
axs[1][1].plot(batch_sizes_3D)
axs[1][1].plot(batch_sizes_4D)
axs[1][1].plot(batch_sizes_5D)
axs[1][1].set_ylabel('validation accuracy')
axs[1][1].set_xlabel('batch sizes')
axs[1][1].set_title("max validation accuracy values \nfor learning rate of 0.01 as
axs[1][1].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[1][1].set xticks([])
axs[2][0].plot(batch_sizes_1E)
axs[2][0].plot(batch_sizes_2E)
axs[2][0].plot(batch_sizes_3E)
axs[2][0].plot(batch sizes 4E)
axs[2][0].plot(batch_sizes_5E)
axs[2][0].set_title("max validation accuracy values \nfor learning rate of 0.001 as
axs[2][0].set_ylabel('validation accuracy')
axs[2][0].set_xlabel('batch sizes')
axs[2][0].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[2][0].set xticks([])
axs[2][1].set_visible(False)
plt.ylabel('validation accuracy')
plt.show()
```



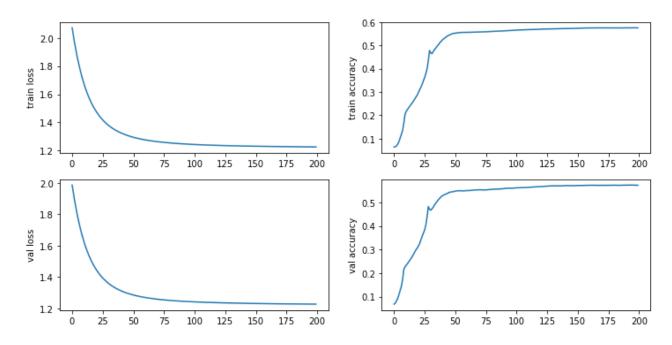
We can see that increasing the batch size relly effect the performence of the model.

Also smaller learning rates with very small number of iterations results in an underfitted model as we expected.

```
In [40]: | index = np.argmax(max_values)
         print('the best val accuracy is obtained using learning rate = {}, number of iterat
               format(learning_rates[int(index / 25)], iteration_values[int(index / 5) % 5]
                      , batch_sizes[index % 5]))
         print('best accuracy : {}'.format(np.max(max_values)))
         fig, axs = plt.subplots(2, 2, figsize=(12,6))
         fig.suptitle('loss and accuracy function as a function of iteration')
         axs[0][0].plot(train_loss[index])
         axs[0][0].set_ylabel('train loss')
         axs[0][1].plot(train_accuracy[index])
         axs[0][1].set_ylabel('train accuracy')
         axs[1][0].plot(val_loss[index])
         axs[1][0].set_ylabel('val loss')
         axs[1][1].plot(val_accuracy[index])
         axs[1][1].set_ylabel('val accuracy')
         plt.show()
```

the best val accuracy is obtained using learning rate = 0.1, number of iterations = 200, batch size = 25000 best accuracy : 0.57408

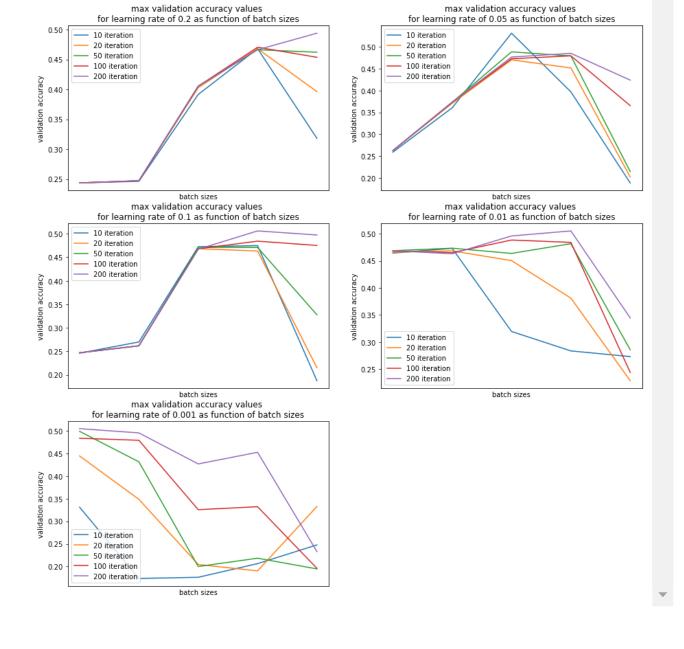
loss and accuracy function as a function of iteration



We will repeat that process for the GMM data.

```
In [44]: | max_values = list(map(lambda x : max(x), val_accuracy))
         batch_sizes_1 ,batch_sizes_2, batch_sizes_3 ,batch_sizes_4 ,
                 batch_sizes_5 = [],[],[],[],[]
         batch_sizes_1B , batch_sizes_2B , batch_sizes_3B ,batch_sizes_4B,
                 batch_sizes_5B = [],[],[],[],[]
         batch_sizes_1C ,batch_sizes_2C ,batch_sizes_3C ,batch_sizes_4C,
                 batch_sizes_5C = [],[],[],[],[]
         batch_sizes_1D, batch_sizes_2D ,batch_sizes_3D ,batch_sizes_4D ,
                 batch_sizes_5D = [],[],[],[],[]
         batch_sizes_1E ,batch_sizes_2E ,batch_sizes_3E ,batch_sizes_4E ,
                 batch_sizes_5E = [],[],[],[],[]
         for i in range(5):
             batch_sizes_1.append(max_values[i])
             batch_sizes_2.append(max_values[i+5])
             batch_sizes_3.append(max_values[i+10])
             batch_sizes_4.append(max_values[i+15])
             batch_sizes_5.append(max_values[i+20])
             batch_sizes_1B.append(max_values[i+25])
             batch_sizes_2B.append(max_values[i+5+25])
             batch_sizes_3B.append(max_values[i+10+25])
             batch_sizes_4B.append(max_values[i+15+25])
             batch_sizes_5B.append(max_values[i+20+25])
             batch_sizes_1C.append(max_values[i+50])
             batch_sizes_2C.append(max_values[i+5+50])
             batch_sizes_3C.append(max_values[i+10+50])
             batch_sizes_4C.append(max_values[i+15+50])
             batch_sizes_5C.append(max_values[i+20+50])
             batch_sizes_1D.append(max_values[i+75])
             batch sizes 2D.append(max values[i+5+75])
             batch_sizes_3D.append(max_values[i+10+75])
             batch_sizes_4D.append(max_values[i+15+75])
             batch sizes 5D.append(max values[i+20+75])
             batch_sizes_1E.append(max_values[i+100])
             batch_sizes_2E.append(max_values[i+5+100])
             batch_sizes_3E.append(max_values[i+10+100])
             batch_sizes_4E.append(max_values[i+15+100])
             batch_sizes_5E.append(max_values[i+20+100])
         print('batch sizes are 50, 100, 500, 1000, 25000')
         fig, axs = plt.subplots(3,2, figsize=(15,15))
         plt.title("max validation accuracy values for diffrent hyper parameter")
         axs[0][0].plot(batch_sizes_1)
         axs[0][0].plot(batch sizes 2)
         axs[0][0].plot(batch_sizes_3)
         axs[0][0].plot(batch_sizes_4)
         axs[0][0].plot(batch_sizes_5)
         axs[0][0].set_ylabel('validation accuracy')
         axs[0][0].set_xlabel('batch sizes')
         axs[0][0].set title("max validation accuracy values \nfor learning rate of 0.2 as f
         axs[0][0].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
         axs[0][0].set_xticks([])
```

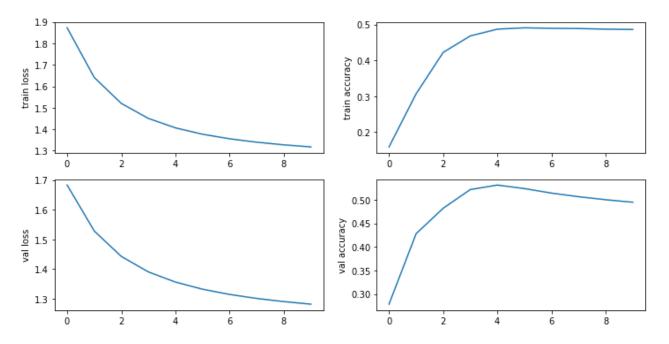
```
axs[1][0].plot(batch_sizes_1B)
axs[1][0].plot(batch_sizes_2B)
axs[1][0].plot(batch_sizes_3B)
axs[1][0].plot(batch_sizes 4B)
axs[1][0].plot(batch_sizes_5B)
axs[1][0].set_ylabel('validation accuracy')
axs[1][0].set_xlabel('batch sizes')
axs[1][0].set_title("max validation accuracy values \nfor learning rate of 0.1 as f
axs[1][0].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[1][0].set_xticks([])
axs[0][1].plot(batch_sizes_1C)
axs[0][1].plot(batch_sizes_2C)
axs[0][1].plot(batch_sizes_3C)
axs[0][1].plot(batch_sizes_4C)
axs[0][1].plot(batch_sizes_5C)
axs[0][1].set_ylabel('validation accuracy')
axs[0][1].set_xlabel('batch sizes')
axs[0][1].set_title("max validation accuracy values \nfor learning rate of 0.05 as
axs[0][1].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[0][1].set xticks([])
axs[1][1].plot(batch_sizes_1D)
axs[1][1].plot(batch_sizes_2D)
axs[1][1].plot(batch_sizes_3D)
axs[1][1].plot(batch_sizes_4D)
axs[1][1].plot(batch_sizes_5D)
axs[1][1].set_ylabel('validation accuracy')
axs[1][1].set_xlabel('batch sizes')
axs[1][1].set_title("max validation accuracy values \nfor learning rate of 0.01 as
axs[1][1].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[1][1].set_xticks([])
axs[2][0].plot(batch_sizes_1E)
axs[2][0].plot(batch_sizes_2E)
axs[2][0].plot(batch_sizes_3E)
axs[2][0].plot(batch_sizes_4E)
axs[2][0].plot(batch sizes 5E)
axs[2][0].set_title("max validation accuracy values \nfor learning rate of 0.001 as
axs[2][0].set_ylabel('validation accuracy')
axs[2][0].set xlabel('batch sizes')
axs[2][0].legend(['10 iteration','20 iteration','50 iteration','100 iteration','200
axs[2][0].set_xticks([])
axs[2][1].set_visible(False)
plt.show()
```



```
In [45]:
         max_values = list(map(lambda x : max(x), val_accuracy))
         index = np.argmax(max_values)
         print('the best val accuracy is obtained using learning rate = {}, number of iterat;
               format(learning_rates[int(index / 25)], iteration_values[int(index / 5) % 5],
                 batch_sizes[index % 5]))
         print('best accuracy : {}'.format(np.max(max_values)))
         fig, axs = plt.subplots(2, 2, figsize=(12,6))
         fig.suptitle('loss and accuracy function as a function of iteration')
         axs[0][0].plot(train_loss[index])
         axs[0][0].set_ylabel('train loss')
         axs[0][1].plot(train_accuracy[index])
         axs[0][1].set_ylabel('train accuracy')
         axs[1][0].plot(val_loss[index])
         axs[1][0].set_ylabel('val loss')
         axs[1][1].plot(val_accuracy[index])
         axs[1][1].set_ylabel('val accuracy')
         plt.show()
```

the best val accuracy is obtained using learning rate = 0.05, number of iterations = 10, batch size = 500 best accuracy : 0.53136





In conclusion, we saw how to pick the right hyper parameters using grid search, this method is very time consuming but it's completly automated, so we can "just run it and go do somthing else". Since our models reached very low accuracy, we now know that those models arn't expressive enought and we need to add more layers.

In the next section we will define a complete NN and test it to see that our derivatives are correct.

## Part II: the neural network

#### **Subsection I: Jacobian Tests**

The following code defines the tanh activation function and it's Jacobian with respect to the biases, weights and data.

```
In [48]: class tanh:
    def gradient(self, X, Y, error, W):
        new_error = (1 - Y**2) * error
        grad_theta = new_error @ X.T
        grad_b = np.sum(new_error, axis=1)
        grad_data = W.T @ new_error
        return grad_theta, grad_b, grad_data

def __call__(self, x):
    return np.tanh(x)
```

We will now define the Jacobian test of a linear layer with tanh activation, the diffrence between the gradient test and the Jacobian test is that the function we are checking is a vector function and not scalar.

The direct Jacobian transposed test is defined as follows:

note : f(x) = tanh(AX + B) we will define new function  $g(x) = f(x)^T u$  where u is a random vector in the size of the output of f(x).

Now after we have the definition of g(x) we can again use the gradient test as we did in the first section, the only diffrence is the derevitive of g(x) is now  $J^T u$  where J is the Jacobian matrix.

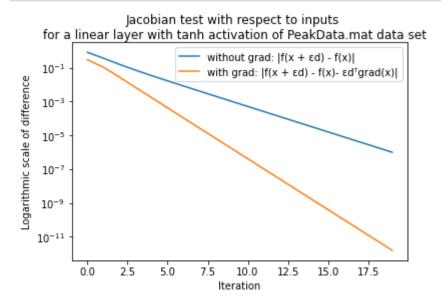
The derivative of tanh is defined as follows :  $tanh(x)' = (1 - tanh(x)^2)$ 

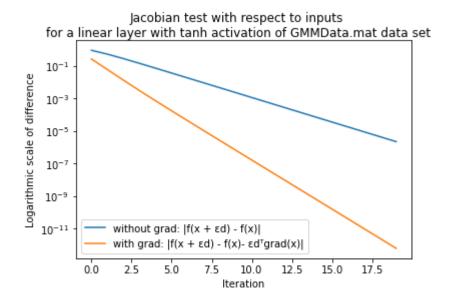
The Jacobian transpose u with respect to the inputs is defined as:

 $J^T u = W^T (\sigma'(WX + b) * u) = W^T ((1 - tanh(WX + b)^2) * u)$  where \* is just a element wise multiplication.

Since we are going to start with the test with respect to the inputs we need to add the random vector  $\epsilon * d$  to our X.

```
In [49]:
         def g(linear_layer, x, u):
             return (linear layer(x).T @ u).reshape(1)
         def Jacobian_test_with_respect_to_inputs(linear_layer, X):
             without Jacobian = []
             with_Jacobian = []
             dim_out = linear_layer.dim_out()
             dim in = linear layer.dim in()
             d = create random vector(dim in, 1)
             u = create_random_vector(dim_out, 1)
             for i in range(20):
                 e = np.power(0.5, i)
                 vec = e * d
                 predictions = g(linear_layer, X, u)
                 predictions_d = g(linear_layer, X + vec, u)
                 _, _, jacob_txv = linear_layer.gradient(X, linear_layer(X), u)
                 diff_f = predictions_d - predictions
                 without_Jacobian.append(np.abs(diff_f))
                 with_Jacobian.append(np.abs(diff_f - vec.T.dot(jacob_txv).reshape(1)))
             return without_Jacobian, with_Jacobian
```



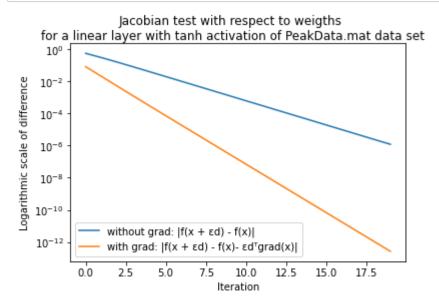


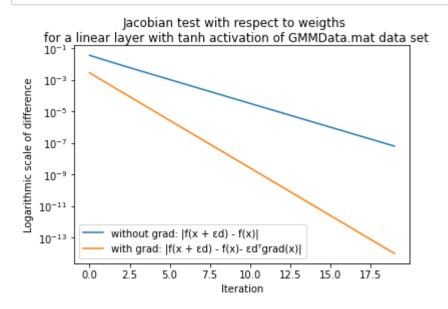
The jacobian test with respect to the weights is defined in the same way as the last test, the only thing we need to change is  $f(x) = \sigma((W+d)X+b)$  where d is a random vector with the same size as W and again we need to use the jacobian matrix with respect to the weights.

The jacobian transpose u is with respect to the weigths is defined as :

```
J^T u = (\sigma'(WX + b) * u)X^T = ((1 - tanh(WX + b)^2) * u)X^T
```

```
In [55]: def g(linear_layer, x, d, u):
             return linear_layer.activate_with_weigths_change(d, x),
                     (linear_layer.activate_with_weigths_change(d, x).T @ u).reshape(1)
         def jacobian_test_with_respect_to_weigths(linear_layer, X):
             without_jacobian = []
             with_jacobian = []
             dim_out = linear_layer.dim_out()
             dim_in = linear_layer.dim_in()
             d = create_random_vector(dim_out, dim_in)
             u = create_random_vector(dim_out, 1)
             for i in range(20):
                 e = np.power(0.5, i)
                 vec = e * d
                 Y, predictions = g(linear_layer, X, 0, u)
                 _, predictions_d = g(linear_layer, X, vec, u)
                 jacob_twu, _, _ = linear_layer.gradient(X, Y, u)
                 diff_f = predictions_d - predictions
                 without_jacobian.append(np.abs(diff_f))
                 with_jacobian.append(np.abs(diff_f -
                                 (np.ravel(vec) @ np.ravel(jacob_twu)).reshape(1)))
             return without jacobian, with jacobian
```



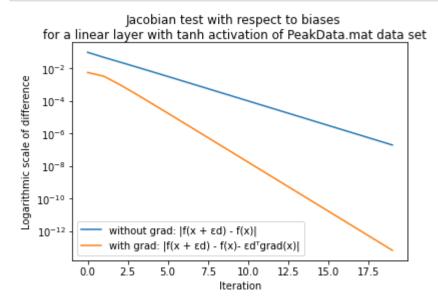


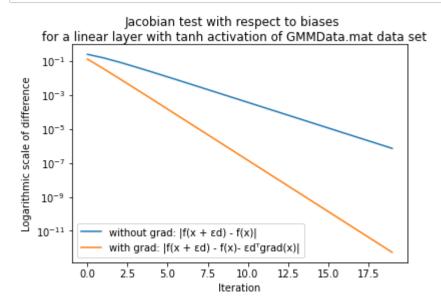
For the final test, the jacobian test with respect to the biases. Just like we did before we are going to add the random vector e \* d to our biases and multiply it by the jacobian transpose u.

The jacobian transpose u with respect to the biases is defined as:

```
J^{T}u = (\sigma'(WX + b) * u) = ((1 - tanh(WX + b)^{2}) * u)
```

```
In [58]: def g(linear_layer, x, d, u):
             return linear_layer.activate_with_biases_change(d, x),
                 (linear layer.activate with biases change(d, x).T @ u).reshape(1)
         def jacobian_test_with_respect_to_biases(linear_layer, X):
             without jacobian = []
             with_jacobian = []
             dim_out = linear_layer.dim_out()
             dim in = linear layer.dim in()
             d = create random vector(dim out, 1)
             u = create_random_vector(dim_out, 1)
             for i in range(20):
                 e = np.power(0.5, i)
                 vec = e * d
                 Y, predictions = g(linear_layer, X, 0, u)
                 _, predictions_d = g(linear_layer, X, vec, u)
                 _, jacob_tbu, _ = linear_layer.gradient(X, Y, u)
                 diff_f = predictions_d - predictions
                 without_jacobian.append(np.abs(diff_f))
                 with_jacobian.append(np.abs(diff_f - vec.T.dot(jacob_tbu).reshape(1)))
             return without_jacobian, with_jacobian
```





our linear layer with tanh activation passes all the tests and now we can move on to testing the entire network gradients.

#### Subsection II - Gradient Test For The Entire Network

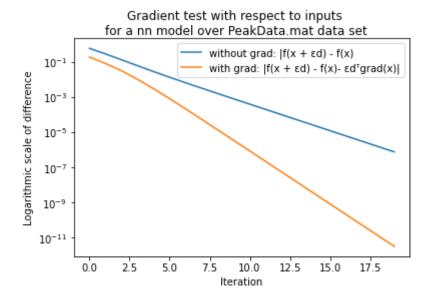
In this section we will check the validity of the network as a whole model by examining the gradient test of all it's variants.

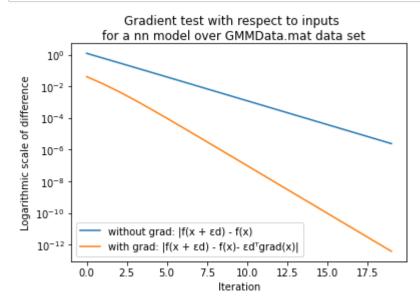
We will start by testing the gradient with respect to the inputs, since we test the entire network, we need to create a list of random vectors d where each of those vector will be in the size of the input of the next layer, and then multiply all those vector with the corrospanding gradients and sum the result  $e*d*grad=e\sum_i d_i^T*grad_i$ . In order to change the input of all the layers , we will define a new function activate with matrix, which will add the vector d to all the inputs.

```
In [62]: def activate_with_matrix(model, d, X):
    new_X = np.array(X, copy=True)
    for i, layer in enumerate(model.layers()):
        new_X = layer(new_X + d[i])
    return new_X
```

```
In [63]: def model gradient test with respect to inputs(loss, model, X, Y):
             without_jacobian = []
             with_jacobian = []
             layers = model.layers()
             lay_len = len(layers)
             d_{array} = []
             for j in range(lay len):
                 d_array.append(create_random_vector(layers[j].dim_in(), 1))
             for k in range(20):
                 e = np.power(0.5, k)
                 predictions = model(X)
                 grad = list(map(lambda x : x[2], model.gradient(Y)))
                 vec = list(map(lambda x: x * e, d_array))
                 loss_predictions = loss(Y, predictions)
                 loss_predictions_d = loss(Y, activate_with_matrix(model, vec, X))
                 diff f = loss predictions d - loss predictions
                 without_jacobian.append(np.abs(diff_f))
                 with_jacobian.append(np.abs(diff_f - sum([vec[i - 1].T.dot(grad[-i]).
                                              reshape(1) for i in range(1, lay len + 1)])))
             return without jacobian, with jacobian
```

```
In [69]: model = sequential_model(
                 linear_layer(2, 4, activation=tanh()),
                 linear_layer(4, 8, activation=tanh()),
                 linear_layer(8, 16, activation=tanh()),
                 linear_layer(16, 5, activation=softmax())
                 )
         without_grad, with_grad = model_gradient_test_with_respect_to_inputs(
                 cross_entropy_loss, model, X[:, 0].reshape(2,1), Y[:, 0].reshape(5,1))
         plt.suptitle('Gradient test with respect to inputs \nfor a nn model over PeakData.ma
         plt.plot(without_grad, label='without grad: |f(x + u03B5d) - f(x)|)
         plt.plot(with_grad, label='with grad: |f(x + u03B5d) - f(x) - u03B5d^{T}grad(x)|')
         plt.xlabel('Iteration')
         plt.ylabel('Logarithmic scale of difference')
         plt.yscale('log')
         plt.legend()
         plt.show()
```

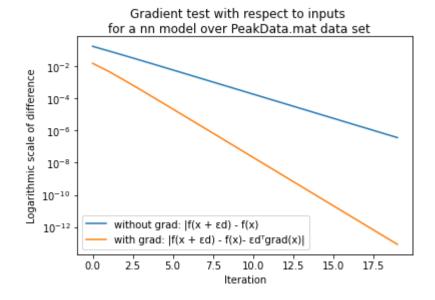


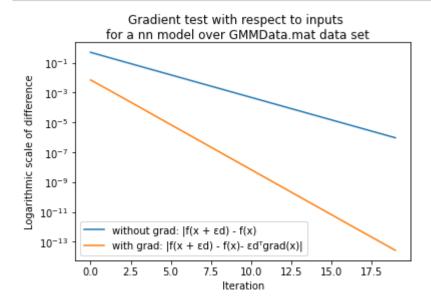


For the gradient test with respect to the weigths, we will define the function activate\_with\_weigths\_matrix, which will add the random vector d to the weigths of each layer before activating it just like we did with the inputs just for the weigths, the test itself is all the same, just the random vectors d will have diffrent dimension, they will be in the size of W in each layer.

```
In [71]: def activate_with_weigths_matrix(model, d, X):
    new_X = np.array(X, copy=True)
    for i, layer in enumerate(model.layers()):
        new_X = layer.activate_with_weigths_change(d[i], new_X)
    return new_X
```

```
In [72]:
         def model_gradient_test_with_respect_to_weigths(loss, model, X, Y):
             without jacobian = []
             with jacobian = []
             layers = model.layers()
             lay len = len(layers)
             d_array = []
             for j in range(lay_len):
                 d array.append(create random vector(layers[j].dim out(), layers[j].dim in()
             for k in range(20):
                 e = np.power(0.5, k)
                 predictions = model(X)
                 grad = list(map(lambda x : x[0], model.gradient(Y)))
                 vec = list(map(lambda x: x * e, d_array))
                 loss_predictions = loss(Y, predictions)
                 loss_predictions_d = loss(Y, activate_with_weights_matrix(model, vec, X))
                 diff_f = loss_predictions_d - loss_predictions
                 without_jacobian.append(np.abs(diff_f))
                 with_jacobian.append(np.abs(diff_f - sum([(np.ravel(vec[i - 1]) @
                             np.ravel(grad[-i])).reshape(1) for i in range(1, lay_len + 1)])
             return without_jacobian, with_jacobian
```

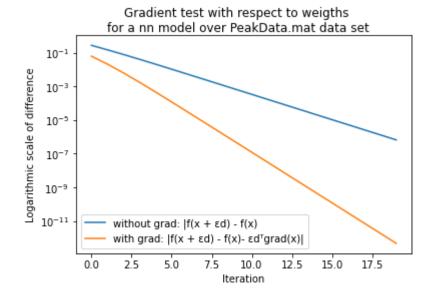


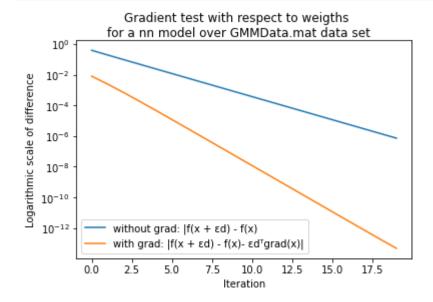


Again we will define new function activate\_with\_biases\_matrix, which will add the random vector d to the biases before activating the layer.

```
In [76]: def activate_with_biases_matrix(model, d, X):
    new_X = np.array(X, copy=True)
    for i, layer in enumerate(model.layers()):
        new_X = layer.activate_with_biases_change(d[i], new_X)
    return new_X
```

```
In [77]:
         def model_gradient_test_with_respect_to_biases(loss, model, X, Y):
             without jacobian = []
             with jacobian = []
             layers = model.layers()
             lay len = len(layers)
             d_{array} = []
             for j in range(lay_len):
                 d array.append(create random vector(layers[j].dim out(), 1))
             for k in range(20):
                 e = np.power(0.5, k)
                 predictions = model(X)
                 grad = list(map(lambda x : x[1], model.gradient(Y)))
                 vec = list(map(lambda x: x * e, d_array))
                 loss_predictions = loss(Y, predictions)
                 loss_predictions_d = loss(Y, activate_with_biases_matrix(model, vec, X))
                 diff_f = loss_predictions_d - loss_predictions
                 without_jacobian.append(np.abs(diff_f))
                 with_jacobian.append(np.abs(diff_f - sum([(vec[i - 1].T.dot(grad[-i])).
                                                  reshape(1) for i in range(1, lay_len + 1)])
             return without_jacobian, with_jacobian
```





As we can see our code suffice the requirement, passes the tests and can be used to train a NN.

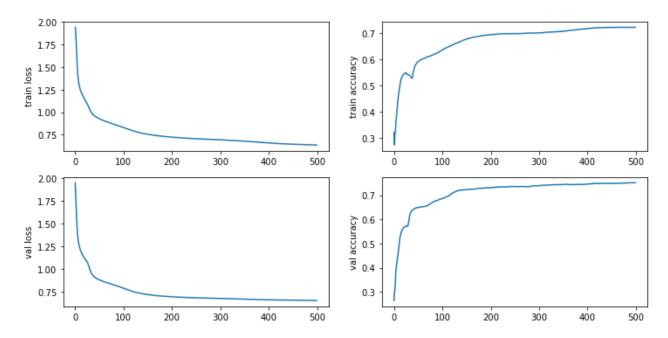
## **Subsection III - Training a Neural Network**

In this section we try to train a neural network with multiple layers in order to achieve higher accuracy values compared to the single softmax layer. For this end we wrote the SGD function code compatible with any model. The following code is just a toy example of what we are going to do in the next section.

We will train this model which consits of 4 layers, with tanh activation and softmax in the end. In the previos section of the SGD we said that the model wasn't expresive enought beacuse he only reached  $\sim 60\%$  accuracy, we expect that this model will reach higher accuracy.

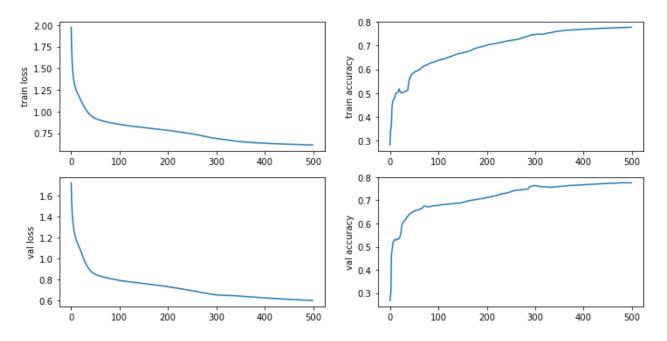
```
In [85]:
         model = sequential_model(
                 linear_layer(2, 4, activation=tanh()),
                 linear_layer(4, 8, activation=tanh()),
                 linear_layer(8, 16, activation=tanh()),
                 linear_layer(16, 5, activation=softmax())
         )
         loss_train, accuracy_train, loss_val, accuracy_val =
                 SGD(model, X, Y, X_val, Y_val, 500, 0.1, cross_entropy_loss, 2500)
         fig, axs = plt.subplots(2, 2, figsize=(12,6))
         fig.suptitle('loss and accuracy function as a function of iteration for PeakData.ma
         axs[0][0].plot(loss_train)
         axs[0][0].set_ylabel('train loss')
         axs[0][1].plot(accuracy_train)
         axs[0][1].set_ylabel('train accuracy')
         axs[1][0].plot(loss_val)
         axs[1][0].set_ylabel('val loss')
         axs[1][1].plot(accuracy_val)
         axs[1][1].set_ylabel('val accuracy')
         plt.show()
```

loss and accuracy function as a function of iteration for PeakData.mat data set



```
In [81]: model2 = sequential_model(
                 linear_layer(5, 5, activation=tanh()),
                 linear_layer(5, 8, activation=tanh()),
                 linear_layer(8, 16, activation=tanh()),
                 linear_layer(16, 5, activation=softmax())
         )
         loss_train, accuracy_train, loss_val, accuracy_val =
                 SGD(model2, X2, Y2, X2_val, Y2_val, 500, 0.1, cross_entropy_loss, 2500)
         fig, axs = plt.subplots(2, 2, figsize=(12,6))
         fig.suptitle('loss and accuracy function as a function of iteration for GMMData.mat
         axs[0][0].plot(loss_train)
         axs[0][0].set_ylabel('train loss')
         axs[0][1].plot(accuracy_train)
         axs[0][1].set_ylabel('train accuracy')
         axs[1][0].plot(loss_val)
         axs[1][0].set_ylabel('val loss')
         axs[1][1].plot(accuracy_val)
         axs[1][1].set_ylabel('val accuracy')
         plt.show()
```

## loss and accuracy function as a function of iteration



This model reached ~80% accuracy, which is just what we hoped for.

The following code will create a grid search which will also optimize the number of layers in the network, starting from 2 to 6 where the layer i will have shape of  $(2^{i+1} * X_{dim})x(2^i * X_{dim})$ , the last layer will allways have output dimension of 5 but the input dimension will change based on the previos layer.

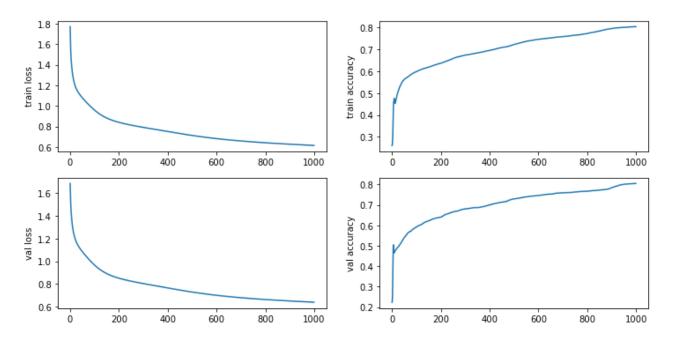
In this section we won't optimize the number of iterations, we will just assume that after 1000 ephocs the network wont learn anymore.

```
In [88]: def model_init(num_layers, dim_in, dim_out):
             return sequential model(
                     *[linear_layer(dim_in * pow(2, i), dim_in * pow(2, i+1),
                                    activation=tanh()) for i in range(num_layers - 1)],
                     linear_layer(dim_in * pow(2, num_layers - 1), dim_out, activation=softm
                 )
         def nn_grid_search(X, Y, X_val, Y_val, num_layers_values, learning_rate_values, bat
             train_accuracy = []
             val_accuracy = []
             val_loss = []
             train_loss = []
             for learning_rate in learning_rate_values:
                     for batch_size in batch_size_values:
                         for num layers in num layers values:
                             model = model_init(num_layers, X.shape[0], Y.shape[0])
                             loss_train, accuracy_train, loss_val, accuracy_val =
                                     SGD(model, X, Y, X_val, Y_val, 1000, learning_rate,
                                         cross_entropy_loss, batch_size)
                             train_accuracy.append(accuracy_train)
                             val accuracy.append(accuracy val)
                             train_loss.append(loss_train)
                             val_loss.append(loss_val)
             return train_accuracy, train_loss, val_accuracy, val_loss
```

```
In [112]:
          max_values = list(map(lambda x : max(x), val_accuracy))
          index = np.argmax(max_values)
          print('the best val accuracy is obtained using learning rate = {}, batch size = {},
                .format( learning_rates[int(index / 25)],
                        batch_sizes[int(index / 5) % 5], num_layers[index % 5]))
          print('best accuracy : {}'.format(np.max(max_values)))
          fig, axs = plt.subplots(2, 2, figsize=(12,6))
          fig.suptitle('loss and accuracy function as a function of iteration for PeakData.ma
          axs[0][0].plot(train_loss[index])
          axs[0][0].set_ylabel('train loss')
          axs[0][1].plot(train_accuracy[index])
          axs[0][1].set_ylabel('train accuracy')
          axs[1][0].plot(val_loss[index])
          axs[1][0].set_ylabel('val loss')
          axs[1][1].plot(val_accuracy[index])
          axs[1][1].set_ylabel('val accuracy')
          plt.show()
```

the best val accuracy is obtained using learning rate = 0.001, batch size = 100, n umber of layers = 3 best accuracy : 0.80496

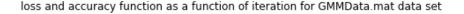
loss and accuracy function as a function of iteration for PeakData.mat data set

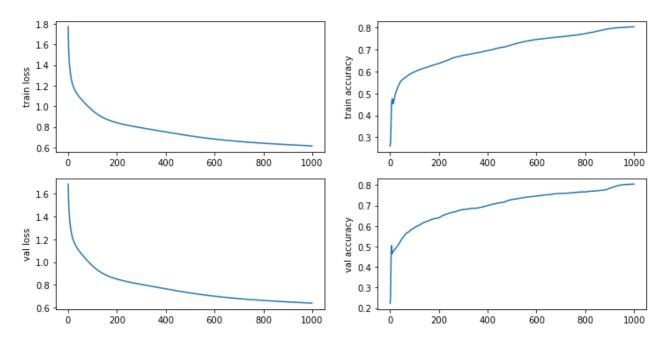


We can see that the loss is still decreasing, so we will use the chosen hyper parameters in order the train this model with a little more iterations.

```
max_values = list(map(lambda x : max(x), val_accuracy))
In [113]:
          index = np.argmax(max_values)
          print('the best val accuracy is obtained using learning rate = {}, number of iterat
                 .format(learning_rates[int(index / 25)],
                        batch_sizes[int(index / 5) % 5], num_layers[index % 5]))
          print('best accuracy : {}'.format(np.max(max_values)))
          fig, axs = plt.subplots(2, 2, figsize=(12,6))
          fig.suptitle('loss and accuracy function as a function of iteration for GMMData.mat
          axs[0][0].plot(train_loss[index])
          axs[0][0].set_ylabel('train loss')
          axs[0][1].plot(train_accuracy[index])
          axs[0][1].set_ylabel('train accuracy')
          axs[1][0].plot(val_loss[index])
          axs[1][0].set_ylabel('val loss')
          axs[1][1].plot(val_accuracy[index])
          axs[1][1].set_ylabel('val accuracy')
          plt.show()
```

the best val accuracy is obtained using learning rate = 0.001, number of iteration s = 100, number of layers = 3 best accuracy : 0.80496

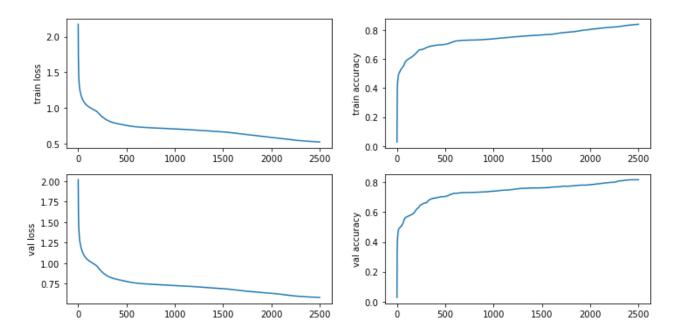




In class we've learned that a network created from too many layer or with too many variables can create a case of overfitting and though the accuracy of the train data will get better the validation data will not show the same upward trend. Though we've tested more networks with more layers, the best results were provided by a network with only 3 layers as expected from this theory. Knowing this information will show a training example of a network with this structure

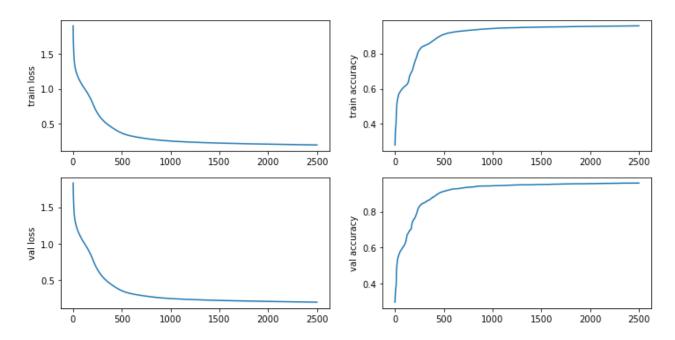
```
In [106]: model = sequential_model(
                  linear_layer(2, 4, activation=tanh()),
                  linear_layer(4, 8, activation=tanh()),
                  linear_layer(8, 5, activation=softmax())
                  )
          loss_train, accuracy_train, loss_val, accuracy_val =
                  SGD(model, X, Y, X_val, Y_val, 2500, 0.001, cross_entropy_loss, 100)
          fig, axs = plt.subplots(2, 2, figsize=(12,6))
          fig.suptitle('loss and accuracy function as a function of iteration')
          axs[0][0].plot(loss_train)
          axs[0][0].set_ylabel('train loss')
          axs[0][1].plot(accuracy_train)
          axs[0][1].set_ylabel('train accuracy')
          axs[1][0].plot(loss_val)
          axs[1][0].set_ylabel('val loss')
          axs[1][1].plot(accuracy_val)
          axs[1][1].set_ylabel('val accuracy')
          plt.show()
```

## loss and accuracy function as a function of iteration



```
In [107]: model2 = sequential_model(
                  linear_layer(5, 8, activation=tanh()),
                  linear_layer(8, 16, activation=tanh()),
                  linear_layer(16, 5, activation=softmax())
                  )
          loss_train, accuracy_train, loss_val, accuracy_val =
                  SGD(model2, X2, Y2, X2_val, Y2_val, 2500, 0.001, cross_entropy_loss, 100)
          fig, axs = plt.subplots(2, 2, figsize=(12,6))
          fig.suptitle('loss and accuracy function as a function of iteration')
          axs[0][0].plot(loss_train)
          axs[0][0].set_ylabel('train loss')
          axs[0][1].plot(accuracy_train)
          axs[0][1].set_ylabel('train accuracy')
          axs[1][0].plot(loss_val)
          axs[1][0].set_ylabel('val loss')
          axs[1][1].plot(accuracy_val)
          axs[1][1].set_ylabel('val accuracy')
          plt.show()
```

## loss and accuracy function as a function of iteration



To conclude, we can see the impact of using hidden layers in our model as the accuracy for both data sets rises for the training data as well as for the validation data. By adding hidden layers we've reached ~80% accuracy for PeakData.mat data set and even ~90% for GMMData.mat data set. we've managed to build and train a neural network from scratch.

For full access to the code please visit <a href="https://github.com/danikv/DeepLearningEx1">https://github.com/danikv/DeepLearningEx1</a> (<a href="https://github.com/danikv/DeepLearningEx1">https://github.com/danikv/DeepLearningEx1</a>)



```
In [61]: | # Appendix
         def relu_der (x):
             if x > 0:
                 return 1
             else :
                 return 0
         relu_der2 = np.vectorize(relu_der)
         class relu:
             def gradient(self, X, Y, error, W):
                 a = relu_der2(Y)
                 error2 = error * a
                 grad_theta = error2 @ X.T
                 grad_b = np.sum(error2, axis=1)
                 grad_data = W.T @ error2
                 return grad_theta, grad_b, grad_data
             def __call__(self, x):
                 return (abs(x)+x)/2
```