Bloch Equations Revisited: New Analytical Solutions for the Generalized Bloch Equations

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ABSTRACT

The generalized Bloch equations in the rotating frame are solved in Cartesian space by an approach that is different from the earlier Torrey solutions. The solutions are cast into a compact and convenient matrix notation, which paves the way for a direct physical insight and comprehension of the evolution of various magnetization components. The solutions are expressed as a sum of two terms: One describes the decay of the initial state; the other describes the growth of the steady state. The representative trajectories of each component of the above terms plotted separately describe the complete time evolution of each magnetization component. © 1997 John Wiley & Sons, Inc.

INTRODUCTION

In 1946, soon after the experimental discovery of magnetic resonance, Felix Bloch gave phenomenological equations of motion for various magnetization components (1). These have played a central role in elucidating magnetic resonance ever since. The generalized form of the Bloch equations contains an off-resonance radio frequency (rf) field, which couples all the equations. An analytical solution of the coupled equations was given by Torrey in 1949 (2), which to date is the last word on their solution. Despite the availability of this general solution, ab initio solutions of the coupled equations have been given in the lit-

We have given analytical solution to the generalized Bloch equations in the rotating frame without any approximations (12). We also redefine various constants, which facilitates setting independent limits on various parameters. Another feature of our solution is that it provides clear insight about the development of various magnetization components and their interconversions. This insight is made possible by casting the

erature for various limiting situations, such as steadystate solutions (3, 4), on-resonance solutions (5, 6), solutions neglecting relaxation (7), and those that involve weak rf fields (8). The reasons for these later solutions are that they are easier to interpret and give more physical insight than do the Torrey solutions. Recently, several publications have restated and completed Torrey's solutions—and remedied typographical errors (9, 10). Alternatively, the generalized coupled equations are solved numerically (11).

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Table 1 Matrix Elements of A

$$\begin{split} A_{11} &= [U_1 e^{\lambda_1 t} + e^{\mu_2 t} ((1 - U_1) \cos \mu_3 t + U_2 \sin \mu_3 t)] \\ A_{12} &= -A_{21} = [N_1 e^{\lambda_1 t} - e^{\mu_2 t} (N_1 \cos \mu_3 t - N_2 \sin \mu_3 t)] \\ A_{13} &= A_{31} = [N_3 e^{\lambda_1 t} - e^{\mu_2 t} (N_3 \cos \mu_3 t - N_4 \sin \mu_3 t)] \\ A_{22} &= [V_1 e^{\lambda_1 t} + e^{\mu_2 t} ((1 - V_1) \cos \mu_3 t + V_2 \sin \mu_3 t)] \\ A_{23} &= -A_{32} = [N_5 e^{\lambda_1 t} - e^{\mu_2 t} (N_5 \cos \mu_3 t - N_6 \sin \mu_3 t)] \\ A_{33} &= [Z_1 e^{\lambda_1 t} + e^{\mu_2 t} ((1 - Z_1) \cos \mu_3 t + Z_2 \sin \mu_3 t)] \end{split}$$

solution into a compact matrix notation as a sum of two terms—one describes the interconversion of the various magnetization components of the initial state and their decay to zero, and the other describes the independent growth of the steady state. Such a separation is extremely useful, particularly because it provides physical insight about the development of the various magnetization components. It may also be pointed out that these two terms can be separated by the use of two-dimensional (2D) experiments.

From our solution, we have earlier extracted the time development of each magnetization component, which is a sum of the contribution from the initial state, interconversion of various components, and the growth of the steady state (12). It turns out that it is also quite illustrative to monitor separately the time development of each of the above elements of each magnetization component—to monitor the time development of the various elements of the above matrices. In this article, we discuss the time development of various elements of the above matrices to illustrate in a pedagogical manner the new solution of the Bloch equations.

BLOCH EQUATIONS AND THEIR SOLUTION

The phenomenological Bloch equations in vector notation in the laboratory frame are given by [1]

$$\frac{d\mathbf{M}}{dt} = \gamma \mathbf{M} \times \mathbf{H} - \frac{\mathbf{M}_{x}}{T_{2}} \overrightarrow{i} - \frac{\mathbf{M}_{y}}{T_{2}} \overrightarrow{j} - \frac{\mathbf{M}_{z} - \mathbf{M}_{0}}{T_{1}} \overrightarrow{k}$$
[1]

where **M** is the total magnetization vector having components M_x , M_y and M_z ; M_0 is the equilibrium z magnetization in the absence of an rf field; γ is the magnetogyric ratio; and T_1 and T_2 are, respectively, the spin-lattice and spin-spin relaxation time con-

Table 2 Elements of Vector B

$$\begin{aligned} & \pmb{B}_{11} = [1 - \pmb{M}_1 e^{\lambda_1 t} - e^{\mu_2 t} ((1 - \pmb{M}_1) \cos \mu_3 t - \pmb{M}_2 \sin \mu_3 t)] \\ & \pmb{B}_{22} = [1 - \pmb{M}_3 e^{\lambda_1 t} - e^{\mu_2 t} ((1 - \pmb{M}_3) \cos \mu_3 t - \pmb{M}_4 \sin \mu_3 t)] \\ & \pmb{B}_{33} = [1 - \pmb{M}_5 e^{\lambda_1 t} - e^{\mu_2 t} ((1 - \pmb{M}_5) \cos \mu_3 t - \pmb{M}_6 \sin \mu_3 t)] \end{aligned}$$

Table 3 Expressions for U, V, Z, N, and M Characterizing the Elements of A and B

$$\begin{split} U_1 &= \mu_3 L [\mu_2^2 + \mu_3^2 + \beta^2 - \delta^2 + 2\beta\mu_2] \\ U_2 &= -L[\lambda_1^2(\beta + \mu_2) + (\beta + \lambda_1)(\mu_3^2 - \mu_2^2) \\ &+ (\beta^2 - \delta^2)(\lambda_1 - \mu_2)] \\ V_1 &= \mu_3 L [\mu_2^2 + \mu_3^2 + \beta^2 - \delta^2 - \omega_1^2 + 2\mu_2\beta] \\ V_2 &= -L[\lambda_1^2(\beta + \mu_2) + (\beta + \lambda_1)(\mu_3^2 - \mu_2^2) \\ &+ (\beta^2 - \delta^2 - \omega_1^2)(\lambda_1 - \mu_2)] \\ Z_1 &= \mu_3 L [\mu_2^2 + \mu_3^2 + \alpha^2 - \omega_1^2 + 2\mu_2\alpha] \\ Z_2 &= -L[\lambda_1^2(\alpha + \mu_2) + (\alpha + \lambda_1)(\mu_3^2 - \mu_2^2) \\ &+ (\alpha^2 - \omega_1^2)(\lambda_1 - \mu_2)] \\ N_1 &= 2\delta\mu_3 L(\beta + \mu_2) \\ N_2 &= -\delta L [2\beta(\lambda_1 - \mu_2) + (\lambda_1^2 + \mu_3^2 - \mu_2^2)] \\ N_3 &= \delta\omega_1\mu_3 L \\ N_4 &= -\delta\omega_1 L(\lambda_1 - \mu_2) \\ N_5 &= \omega_1\mu_3 L(\alpha + \beta + 2\mu_2) \\ N_5 &= \omega_1\mu_3 L(\alpha + \beta + 2\mu_2) \\ N_6 &= -\omega_1 L [(\alpha + \beta)(\lambda_1 - \mu_2) - (\mu_2^2 - \mu_3^2 - \lambda_1^2)] \\ M_1 &= \mu_3 L (\mu_2^2 + \mu_3^2) \\ M_2 &= \lambda_1 L(\lambda_1\mu_2 + \mu_3^2 - \mu_2^2) \\ M_3 &= \mu_3 L [(\mu_2^2 + \mu_3^2)(\beta + \lambda_1)]/\beta \\ M_4 &= \lambda_1 L [\beta(\lambda_1\mu_2 + \mu_3^2 - \mu_2^2) + (\lambda_1 - \mu_2)(\mu_2^2 + \mu_3^2)]/\beta \\ M_5 &= -\mu_3 (\mu_2^2 + \mu_3^2) L[\lambda_1(\alpha + 2\mu_2) - (\beta^2 + \delta^2)]/(\beta^2 + \delta^2) \\ M_6 &= \lambda_1 L \{(\beta^2 + \delta^2)(\lambda_1\mu_2 + \mu_3^2 - \mu_2^2) - [(\lambda_1 - \mu_2)\alpha - (\mu_2^2 - \mu_3^2 - \lambda_1^2)](\mu_2^2 + \mu_3^2)]/(\beta^2 + \delta^2) \\ \text{where } L &= 1/\mu_3 [(\mu_2 - \lambda_1)^2 + \mu_3^2] \end{aligned}$$

Here λ_1 , $\lambda_2 = \mu_2 + i\mu_3$, and $\lambda_3 = \mu_2 - i\mu_3$ are the roots of the cubic Eq. [3-1] (obtained from text Eqs. [3]–[5]).

$$\lambda^3 + a\lambda^2 + b\lambda + c = 0$$
 [3-1]

where

$$\begin{aligned} a &= \alpha + 2\beta \\ b &= \beta^2 + \delta^2 + \omega_1^2 + 2\alpha\beta \\ c &= \alpha\beta^2 + \alpha\delta^2 + \beta\omega_1^2 \end{aligned} [3-2]$$

with λ_1 and μ_2 real and negative. The roots of Eq. [3–1] are contained in standard textbooks (13, 14) and reproduced in Refs. 9, 10, and 12.

stants. **H** describes the applied magnetic field, which, in the presence of a steady field along the z axis and an rf field along the x axis, is given by

$$H_x = H_1 \cos \omega t$$

$$H_y = -H_1 \sin \omega t$$

$$H_z = H_0$$
 [2]

Table 4 Steady-State Values of Each Magnetization Component

$$u^{\infty} = \frac{\gamma H_1 \delta T_2^2 M_o}{1 + \delta^2 T_2^2 + (\gamma H_1)^2 T_1 T_2}$$
$$v^{\infty} = -\frac{\gamma H_1 T_2 M_o}{1 + \delta^2 T_2^2 + (\gamma H_1)^2 T_1 T_2}$$
$$M_z^{\infty} = \frac{(1 + \delta^2 T_2^2) M_o}{1 + \delta^2 T_2^2 + (\gamma H_1)^2 T_1 T_2}$$

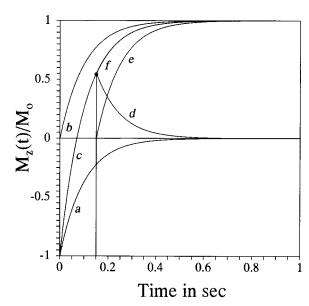


Figure 1 Recovery of inverted magnetization in the absence of an rf field from Eq. [9] for $T_1 = 0.1$ s. Curve (a) shows the decay of the inverted initial state to zero, curve (b) shows the growth of the steady state from zero to unity, curve (c) shows the sum of curves (a) and (b) showing the recovery of the total magnetization. Equation [9] is valid at all points of time. For example, assuming this experiment is interrupted (in a thought experiment) at t = 0.15 s, the total magnetization at that point (indicated by \bullet) then becomes the initial state, which, according to Eq. [9], decays to zero, given by curve (d). Again, the steady state grows from zero, indicated by curve (e); the total is given by curve (f), which is identical to curve (c).

These equations, when transformed into a rotating frame at an angular velocity ω about the z axis, become

$$\frac{du}{dt} + \beta u + \delta v = 0$$
 [3]

$$\frac{dv}{dt} + \beta v - \delta u + \omega_1 M_z = 0$$
 [4]

$$\frac{d\mathbf{M}_z}{dt} + \alpha \mathbf{M}_z - \omega_1 v = \alpha \mathbf{M}_0$$
 [5]

where the x and y components of \mathbf{M} in the laboratory frame are related to u and v in the rotating frame, for positive γ , by (1)

$$M_x = u\cos\omega t - \upsilon\sin\omega t$$
 [6]

$$\mathbf{M}_{v} = -(v\cos\omega t + u\sin\omega t)$$
 [7]

Equations [3]-[5] have been written by using the parameters

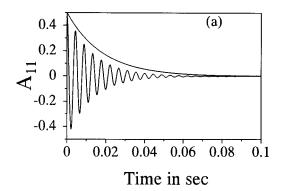
$$\alpha = \frac{1}{T_1}$$

$$\beta = \frac{1}{T_2}$$

$$\delta = \gamma H_0 - \omega$$

$$\omega_1 = \gamma H_1$$
 [8]

Note that the definitions, Eq. [8] are different from those of Bloch (1), Torrey (2), and Morris and Chilvers (10). They define the constants in dimensionless units by dividing each of the above by γH_1 . The above definitions facilitate independent variation of



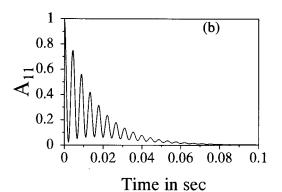
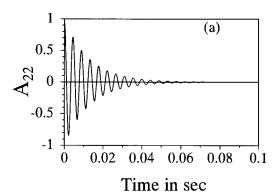


Figure 2 Oscillatory and nonoscillatory parts of A_{11} (Table 1). (a) Separately and (b) added together, for $\omega_1=1$ KHz, $\delta=1$ KHz, $T_1=0.1$ s, and $T_2=0.01$ s. For these values, the parameters U_1 and U_2 are obtained as $U_1=0.50$ and $U_2=0.024$. A_{11} has large nonoscillatory and oscillatory cosine parts and a small oscillatory sine part.



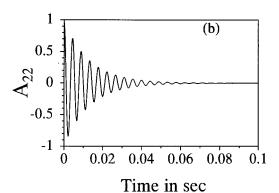


Figure 3 Oscillatory and nonoscillatory parts of A_{22} (Table 1). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values, the parameters V_1 and V_2 are obtained as $V_1 = -0.0011$ and $V_2 = -0.0159$. A_{22} contains mainly the cosine part.

each parameter, including the independent setting of $\gamma \mathbf{H}_1$, $1/T_1$, or $1/T_2 \rightarrow 0$.

These coupled, inhomogeneous differential equations (Eqs. [3]–[5]) have been solved by a direct method, expressed in compact matrix notation as follows (12):

$$\mathbf{M}(t) = \mathbf{A}\mathbf{M}_0 + \mathbf{B}\mathbf{M}^{\infty}$$
 [9]

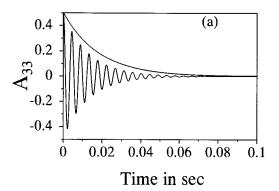
where

$$\mathbf{M}(t) = \begin{pmatrix} u(t) \\ v(t) \\ M_z(t) \end{pmatrix}$$

$$\mathbf{M}_0 = \begin{pmatrix} u_0 \\ v_0 \\ m_0 \end{pmatrix}$$

$$\mathbf{M}^{\infty} = \begin{pmatrix} u^{\infty} \\ v^{\infty} \\ M^{\infty} \end{pmatrix}$$
 [10]

The vector \mathbf{M}_0 describes a general initial state and \mathbf{M}^{∞} the steady state. A and B are 3×3 matrices, with B turning out to be a diagonal matrix. The various elements of A and B are listed in Tables 1 and 2; the parameters of Tables 1 and 2 are given in Table 3. The values of the various components of M^{∞} are given in Table 4, and they match the well-known steady-state solutions of the Bloch equation (3, 4). (The brackets in the numerator of the expression for M_z^{∞} in Eq. [17] of Ref. 12 are missing.) The general characteristics of the A and B matrices are that the A matrix decays from unity to zero, and the **B** matrix grows from zero to unity. The solutions, however, depend on the eigenvalues λ_1 , λ_2 , and λ_3 of the cubic equation (Table 3; Eq. [3-1]), which in general yields one real negative root λ_1 , and two complex, conjugate roots, λ_2 and λ_3 . Expressing $\mu_2 = (\lambda_2 + \lambda_3)/2$ and $\mu_3 = (\lambda_2 - \lambda_3)/2i$, one sees from Tables 1–3 that, while λ_1 and μ_2 govern, respectively, the time evolution of the nonoscillatory and the oscillatory parts of **A** and **B**, μ_3 governs the frequency of the oscillatory parts. The solutions given in Tables 1–3 are the most general solutions.



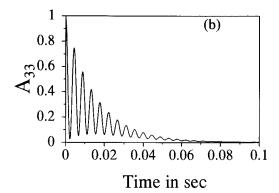
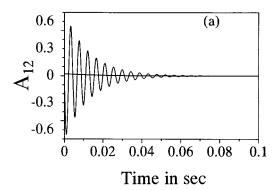


Figure 4 Oscillatory and nonoscillatory parts of A_{33} (Table 1). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values, the parameters Z_1 and Z_2 are obtained as $Z_1 = 0.5024$ and $Z_2 = 0.0398$. The sine part is small and A_{33} behaves similarly to A_{11} (Fig. 2).



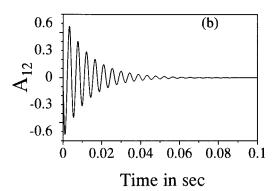


Figure 5 Oscillatory and nonoscillatory parts of A_{12} (Table 1). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values the parameters N_1 and N_2 are obtained as $N_1 = -0.0225$ and $N_2 = 0.7092$. A_{12} has a large oscillatory sine part only.

Equation [9] expresses the solution of the generalized Bloch equations in a compact, convenient form and clearly separates the time development of the initial state and that of the steady state.

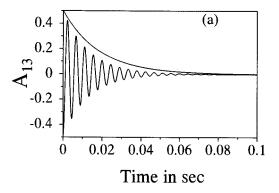
DISCUSSION

From the form of the various matrix elements, it is seen that **A** is a magnitude symmetric matrix, $|A_{ij}| = |A_{ji}|$, such that the amounts of u_0 and m_0 , which contribute to v are equal and opposite to the contribution of v_0 to u and M_z ($A_{12} = -A_{21}$ and $A_{23} = A_{32}$). Also, the amount of m_0 that contributes to u is equal to the contribution of u_0 to M_z ($A_{13} = A_{31}$).

Each diagonal element of **A** is in general a biexponential oscillatory decay from one to zero. Each off-diagonal element of **A** is in general a biexponential oscillatory term, which starts from zero, grows to a maximum, and decays to zero. The off-diagonal elements represent the coupling and interconversion of each magnetization component and are the most crucial parts of the solution. In the absence of these

off-diagonal elements, each initial magnetization component will decay independent of others. Each element of the diagonal matrix ${\bf B}$ represents a biexponential oscillatory growth from zero to one. Because ${\bf B}$ is diagonal, each steady-state component grows independently of others. This is a consequence of the fact that the inhomogeneous term is contained only in one of the Bloch equations, that is, in the ${\bf M}_z$ equation. If the inhomogeneities were present in other equations as well, ${\bf B}$ would be nondiagonal and the steady state also would evolve in a coupled manner. These features of the various matrix elements lead to the following interpretation of the solutions of the Bloch equations.

Because **A** and **B** are not coupled, the initial state and the steady state evolve independently. The various initial magnetization components oscillate, interconvert among one another and decay biexponentially to zero; this is represented by the matrix **A**. The steady-state values also grow independently of the initial state and are independent of one another



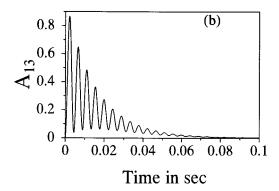
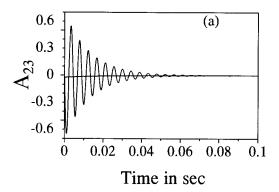


Figure 6 Oscillatory and nonoscillatory parts of A_{13} (Table 1). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values, the parameters N_3 and N_4 are obtained as $N_3 = 0.5014$ and $N_4 = -0.008$. A_{13} has large nonoscillatory and oscillatory cosine parts. The oscillatory sine part is small.



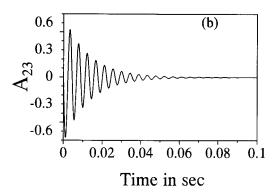


Figure 7 Oscillatory and nonoscillatory parts of A_{23} (Table 1). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values, the parameters N_5 and N_6 are obtained as $N_5 = 0.0226$ and $N_6 = 0.7085$. A_{23} thus has a large oscillatory sine part only, similar to A_{12} (Fig. 5).

(**B** is diagonal); they grow from zero to their final values.

The above separation of the solutions of the Bloch equation into two terms not only provides a clear insight about the time development of various magnetization components, but it is also achievable in 2D experiments. This is best illustrated by the simplest experiment, involving inversion-recovery of z magnetization in the absence of an rf field (Fig. 1). One should interpret this experiment as one in which the inverted magnetization decays to zero and a new magnetization grows from zero to one. In a onedimensional (1D) transient nuclear Overhauser effect (NOE) experiment, both components are inseparable and contribute to the total NOE. In a 2D NOE spectroscopy (NOESY) experiment only the former (A part) contributes to the diagonal and cross-peaks; the latter (B part) contributes to the axial peaks. Therefore, the magnitude of the observed NOE in a 1D transient NOE experiment is twice that in 2D NOESY (B. D. Nageswara Rao, personal communication).

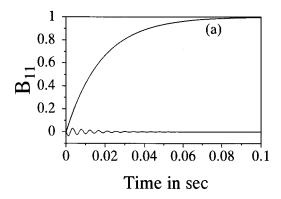
RESULTS

For illustration, the time development of the various elements of **A** and **B** are shown for a specific value of the off-resonance rf field and representative values of T_1 and T_2 . The values chosen in Figs. 2–12 are $\omega_1 = 1$ KHz, $\delta = 1$ KHz, $T_1 = 0.1$ s, and $T_2 = 0.01$ s. For these parameters one obtains the following eigenvalues of the solution: $\lambda_1 = -55.04$ s⁻¹; $\mu_2 = -32.48$ s⁻¹; and $\mu_3 = -1413.30$ s⁻¹.

In Fig. 2(a), the oscillatory and nonoscillatory parts of A_{11} are shown separately, and the total value of A_{11} is shown in Fig. 2(b). Because, for the above parameters, U_2 is very small, and $U_1 = 0.5$, there is a significant nonoscillatory part and an oscillatory part that is mainly a cosine term.

In Fig. 3, A_{22} is shown, and, because V_1 and V_2 are both very small, the nonoscillatory part and the sine part are small; A_{22} contains mainly the decaying cosine part. A_{33} as shown in Fig. 4 has a behavior similar to A_{11} ; because Z_2 is very small.

The off-diagonal term A_{12} shows (Fig. 5) mainly



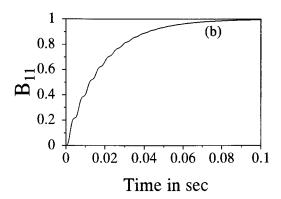
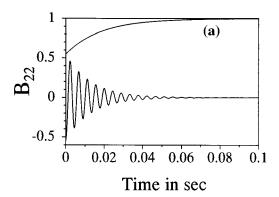


Figure 8 Oscillatory and nonoscillatory parts of \boldsymbol{B}_{11} (Table 2). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values, the parameters \boldsymbol{M}_1 and \boldsymbol{M}_2 are obtained as $\boldsymbol{M}_1 = 1.0021$ and $\boldsymbol{M}_2 = 0.039$. Thus \boldsymbol{B}_{11} has a large nonoscillatory part and a small oscillatory sine part.



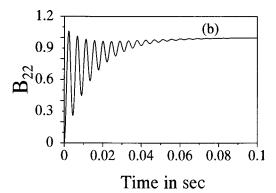


Figure 9 Oscillatory and nonoscillatory parts of B_{22} (Table 2). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values, the parameters M_3 and M_4 are obtained as $M_3 = 4.5139$ and $M_4 = 0.0491$. Thus B_{22} has a large nonoscillatory part, a large oscillatory cosine part, and a small oscillatory sine part.

the oscillatory sine part because N_1 is very small: The term A_{13} (Fig. 6) has a very small sine part (N_4 is small). The term A_{23} (Fig. 7) has a behavior similar to A_{13} . Because for the above parameters $M_1 \approx 1$ and M_2 is small, the term B_{11} has a large nonoscillatory growth and a small decaying oscillatory part that is mainly a sine term (Fig. 8). Because M_3 is large and M_4 is small, B_{22} has a large nonoscillatory part that grows from $(1 - M_3)$ to unity, compensated for by a large oscillatory cosine part, which decays from (M_3) - 1) to zero, and a small oscillatory sine part, which decays from M_4 to zero (Fig. 9). The value of B_{22} oscillates beyond unity even though its value at $t = \infty$ is unity. At first, this could look nonphysical, but the value of B_{22} is multiplied by v^{∞} such that $B_{22} \cdot v^{\infty}$ never goes beyond unity. B_{33} has a behavior similar to \boldsymbol{B}_{11} (Fig. 10). Although \boldsymbol{B}_{11} and \boldsymbol{B}_{33} show mainly a monotonic growth from 0 to 1, \mathbf{B}_{22} has a nonmonotonic growth from zero to unity for the chosen parameters.

The phase trajectories of the decay of initial magnetization components for a general initial state given by $u_0 = v_0 = m_0 = 0.1$ are shown in Fig. 11; which show that u_0 , v_0 , and m_0 decay in a coupled manner. The decay of u_0 , v_0 , and m_0 and the growth of u^{∞} , v^{∞} , and M^{∞} are given, respectively, by Eqs. [11]–[16]:

$$u_0(t) = A_{11}(t)u_0 + A_{12}(t)v_0 + A_{13}(t)m_0$$
 [11]

$$v_0(t) = A_{21}(t)u_0 + A_{22}(t)v_0 + A_{23}(t)m_0$$
 [12]

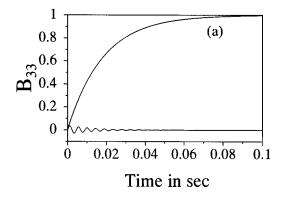
$$m_0(t) = A_{31}(t)u_0 + A_{32}(t)v_0 + A_{33}(t)m_0$$
 [13]

$$u^{\infty}(t) = \mathbf{B}_{11}(t)u^{\infty}$$
 [14]

$$\mathbf{v}^{\infty}(t) = \mathbf{B}_{22}(t)\mathbf{v}^{\infty}$$
 [15]

$$M_z^{\infty}(t) = \boldsymbol{B}_{33}(t)M_z^{\infty}$$
 [16]

They are shown in Fig. 12. Figure 12 shows that $u_0(t)$, $v_0(t)$, and $m_0(t)$ decay in an oscillatory manner from their respective initial values to zero and that



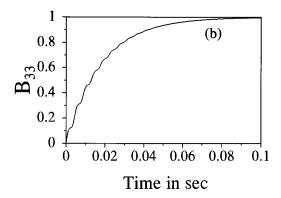


Figure 10 Oscillatory and nonoscillatory parts of B_{33} (Table 2). (a) Separately and (b) added together, for the same values of constants as in Fig. 2. For these values, the parameters M_5 and M_6 are obtained as $M_5 = 1.004$ and $M_6 = -0.039$. B_{33} has a behavior similar to B_{11} (Fig. 9).

 $u^{\infty}(t)$, $v_0^{\infty}(t)$, and $M_z^{\infty}(t)$ grow from zero to their respective final values also in an oscillatory manner.

The behavior of the various elements of **A** and **B** for various limiting cases such as on-resonance rf field, weak rf field, or neglect of T_1 or T_2 are extremely useful and illustrative. These have been discussed in detail in Ref. 12 and are discussed briefly here.

Case 1: On-Resonance rf Field

The solution of Bloch equations for the on-resonance case ($\delta=0$) becomes simple, as u is not coupled to υ and M_z . Therefore, u_0 decays with a single exponential given by $\exp(-t/T_2)$ (Table 5–7). This follows from the facts that in this limit, $A_{12}=A_{21}=A_{13}=A_{31}=0$; A_{11} is reduced to $\exp(-t/T_2)$; and, because in this limit $u^\infty=0$, B_{11} is not relevant. The solution of υ and M_z remains coupled, yielding simple roots of the cubic equation (Table 3, Eq. [3-1]) as

$$\lambda_1 = -\beta$$

$$\lambda_{2,3} = \frac{1}{2} \left[-(\alpha + \beta) \pm i \sqrt{\Delta} \right]$$
[17]

with

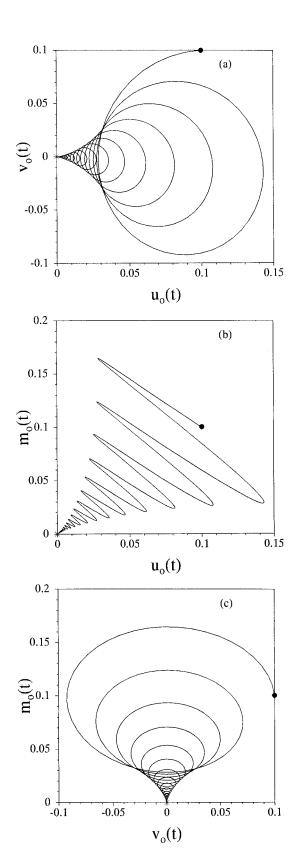
$$\Delta = 4\omega_1^2 - (\alpha - \beta)^2$$
 [18]

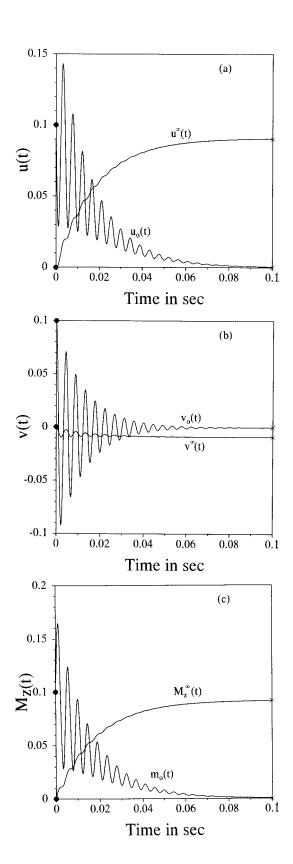
The behavior of v and M_z further depends on the strength of the rf field (ω_1) with respect to the difference of $1/T_1$ and $1/T_2$. Three cases can be distinguished.

(a) Radio Frequency Field Strong Compared to Relaxation, such that $2\omega_1 > |1/T_1 - 1/T_2|$. In this case Δ is positive, yielding oscillatory solutions of v and M_z . A_{22} , A_{33} , and A_{23} (Table 5) remain oscillatory but become single-exponentially-decaying functions. B_{22} and B_{33} also remain oscillatory but become single-exponentially-growing functions from zero to 1.

(b) Radio Frequency Field Comparable to Relaxation, such that $2\omega_1 = |1/T_1 - 1/T_2|$. In this case Δ

Figure 11 Phase trajectories of the decay of the initial magnetization components for $u_0 = v_0 = m_0 = 0.1$; $\delta = 1$ KHz; $\omega_1 = 1$ KHz; $T_1 = 0.1$ s; and $T_2 = 0.01$ s. (a) $u_0(t) - v_0(t)$; (b) $u_0(t) - m_0(t)$; and (c) $v_0(t) - m_0(t)$, where $u_0(t)$, $v_0(t)$, and $m_0(t)$ are given by Eqs. [11]–[13]. All the initial values decay to zero. The filled circles represent the initial state; crosses represent the final state. The **B** part is not included in these diagrams.





= 0. This means that the rf field is equal to linewidth for $T_2 \ll T_1$. This yields simple exponential evolution of v^{∞} and M_z^{∞} as well as a simple exponential uncoupled evolution of v_0 and m_0 with a rate constant that is an average of $1/T_1$ and $1/T_2$ (Table 6). For $T_1 = T_2$, this solution is also the on-resonance solution of Bloch equations in the absence of rf fields.

(c) Radio Frequency Field Weak Compared to Relaxation, such that $2\omega_1 < |1/T_1 - 1/T_2|$. In this case Δ is negative, making all three roots of Eq. [11] real. The various elements of **A** and **B** matrices (Table 7) do not oscillate and show biexponential behavior. However, v and M_z are coupled ($A_{23} \neq 0$) and interconvert.

In the presence of rf, the coupled evolution of transverse and longitudinal magnetization in Bloch equations also leads to a coupled relaxation of these components. Although the general result is contained in Tables 1 and 2, the specific case of $\delta = 0$ (Tables 5-7) demonstrates this explicitly. In the three cases (a), (b) and (c) (Tables 5–7), the v and M_z components have exponential behavior governed by $(\alpha + \beta)/2$, $(\alpha$ $-\beta$)/2 and $2\omega_1/\sqrt{\Delta}$. For decay of υ_0 and m_0 in (a) and (c) when the rf field is strong or weak compared to relaxation (Tables 5 and 7), this is not surprising; because their evolution is also coupled $(A_{23} \neq 0)$. On the other hand, it is interesting that, when the rf field is comparable to relaxation (Table 6), the rates continue to be coupled, given by $(\alpha + \beta)/2$, even when $A_{23} = 0$. Similarly, because the growth of the steady state is not coupled (B is diagonal), the rate of growth of B_{22} and B_{33} being coupled is interesting. Although these magnetization components grow in an uncoupled manner, their growth rates are a mixture of T_1 and T_2 . The rates are equal mixtures for the first two cases, (a) and (b) but in the third case, (c) the mixture is governed by the factors $(\alpha + \beta)/\sqrt{\Delta'}$ and $(\beta^2 - \alpha\beta)$ $-2\omega_1^2$)/ $\beta\sqrt{\Delta'}$ (Table 7). In the limit $\omega_1 \to 0$, \boldsymbol{B}_{22} is not relevant because $v^{\infty} = 0$, and the growth rate of M_z^{∞} becomes $1/T_1$, as it should. The growth rates of $u^{\infty}(t)$ and $\mathbf{M}^{\infty}(t)$ in Fig. 12, which has $\delta \neq 0$, are more complex (given by Tables 2 and 3). However, it can be clearly seen that the rates are between $1/T_1$ and $1/T_{2}$.

Figure 12 Time evolution of the initial and final state of each of the magnetization components for the parameters of Fig. 11. Time evolution of (a) $u_0(t)$ and $u^{\infty}(t)$; (b) $v_0(t)$ and $v^{\infty}(t)$; and (c) $m_0(t)$ and $M_z^{\infty}(t)$. The filled circles represent the initial state and crosses the state at t=0.1 s. For the above parameters, the steady-state values are $u^{\infty}=-0.0908$, $v^{\infty}=-0.0091$, and $M_z^{\infty}=0.0917$.

Case 2: Off-Resonance, Weak rf Field

For small values of rf fields, retaining terms proportional to ω_1 , and neglecting terms of the order of ω_1^2 in Table 3, Eq. [3-2], one obtains simpler definitions for the constants a, b, and c of the cubic equation (Table 3, Eq. [3-1]), which on substitution yield a straightforward factorization of Eq. [3-1] to give

$$\lambda_1 = -\alpha$$

$$\mu_2 = -\beta$$

$$\mu_3 = \delta$$
[19]

The various elements of **A** and **B** are listed in Table 8. The expressions of M_1 , M_2 , M_3 , and M_4 can be obtained from Table 3 by making use of Eq. [13].

Here, all the elements of the **A** matrix are nonzero, and hence u_0 , v_0 , and m_0 decay in a coupled manner. The elements oscillate at the frequency of off-resonance value. All the diagonal elements of **A**, the off-diagonal element A_{12} , and B_{33} have single-exponential behavior; the off-diagonal elements A_{13} and A_{23} of **A**, B_{11} , and B_{22} have biexponential behavior. This solution is more general than the solution for weak rf fields given by Slichter (8).

Table 6 Elements of A and B for $\delta = 0$ and $\Delta = 0$

$$A_{11} = e^{-\frac{t}{T_2}}$$

$$A_{12} = A_{21} = A_{13} = A_{31} = A_{23} = A_{32} = 0$$

$$A_{22} = e^{\frac{-(\alpha+\beta)}{2}t}$$

$$A_{33} = e^{\frac{-(\alpha+\beta)}{2}t}$$

$$B_{22} = B_{33} = 1 - e^{\frac{-(\alpha+\beta)}{2}t}$$

In addition to assuming a weak rf field, Slichter assumes that $M_z(t) = M_0(8)$. This has the following consequences; first, it assumes that at t = 0 the z magnetization is nearly at equilibrium and the x and y components have small values, u_0 and v_0 . Table 8, on the other hand, describes evolution of any arbitrary initial condition. The second consequence is that the evolution of M_z is decoupled from that of u and v. This condition $M_z(t) = M_0$ is not a parametric condition and cannot be substituted in the general solution of Table 8. One must ab initio solve the Bloch equations with the condition, $M_z(t) = M_0$, decoupling the equations, as has been done by Slichter (8, 12).

For $\omega_1=0$, the solution of Table 8 reduces to an off-resonance rotating-frame solution of Bloch equations, such that u_0 and v_0 decay in a coupled manner $(A_{12} \neq 0)$ and m_0 decays independently $(A_{13} = A_{23} = 0)$. In this limit, $u^{\infty} = v^{\infty} = 0$ and hence B_{11} and B_{22} are not relevant. $M_z^{\infty}(t)$ shows single-exponential growth, at the same rate as the decay of m_0 , described by the curves b, e and a, d, respectively, of Fig. 1.

Case 3: Neglecting Relaxation

For this case, $1/T_1 = 1/T_2 = 0$. In this limit, one obtains nondecaying oscillatory behavior for all the elements of the **A** matrix. All the elements of the **B** matrix are zero (Table 9). If, in addition, one assumes on-resonance ($\delta = 0$), then v_0 and m_0 show coupled oscillations since $A_{23} \neq 0$ with u_0 remaining unchanged ($A_{11} = 1, A_{12} = A_{13} = 0$) and spin locked along the rf field. However, if $\omega_1 = 0$, then u_0 and v_0 show coupled oscillations ($A_{12} \neq 0$), and m_0 remains unchanged because $A_{33} = 1$ and $A_{13} = A_{23} = 0$.

Table 7 Elements of A and B for $\delta = 0$ and $\Delta < 0$

$$\begin{split} &A_{11} = e^{-\frac{t}{T_2}} \\ &A_{12} = A_{21} = A_{13} = A_{31} = 0 \\ &A_{22} = e^{\frac{-(\alpha+\beta)}{2}t} \left(\cosh\frac{\sqrt{\Delta'}}{2}t + \cosh\phi'\sinh\frac{\sqrt{\Delta'}}{2}t\right) \\ &A_{23} = -A_{32} = -e^{-\frac{(\alpha+\beta)}{2}t} \sinh\phi'\sinh\frac{\sqrt{\Delta'}}{2}t \\ &A_{33} = e^{-\frac{(\alpha+\beta)}{2}t} \left(\cosh\frac{\sqrt{\Delta'}}{2}t - \cosh\phi'\sinh\frac{\sqrt{\Delta'}}{2}t\right) \\ &B_{22} = \left(1 - e^{-\frac{(\alpha+\beta)}{2}t} \left(\cosh\frac{\sqrt{\Delta'}}{2}t + \frac{(\alpha+\beta)}{\sqrt{\Delta'}}\sinh\frac{\sqrt{\Delta'}}{2}t\right)\right) \\ &B_{33} = \left(1 - e^{-\frac{(\alpha+\beta)}{2}t} \left(\cosh\frac{\sqrt{\Delta'}}{2}t + \frac{\beta^2 - \alpha\beta - 2\omega_1^2}{\beta\sqrt{\Delta'}}\sinh\frac{\sqrt{\Delta'}}{2}t\right)\right) \\ &\text{where } \tanh\phi' = 2\omega_1/(\alpha-\beta) \text{ and } \Delta' = -\Delta \end{split}$$

Table 8 Elements of A and B for weak rf Field

$$\begin{split} &A_{11} = A_{22} = e^{-t/T_2} \cos\delta t \\ &A_{12} = -A_{21} = -e^{-t/T_2} \sin\delta t \\ &A_{13} = A_{31} = \frac{\omega_1}{\sqrt{(\alpha - \beta)^2 + \delta^2}} [\cos\theta e^{-t/T_1} - e^{-t/T_2} (\cos\theta \cos\delta t - \sin\theta \sin\delta t)] \\ &A_{23} = -A_{32} = \frac{\omega_1}{\sqrt{(\alpha - \beta)^2 + \delta^2}} [\sin\theta e^{-t/T_1} - e^{-t/T_2} (\sin\theta \cos\delta t + \cos\theta \sin\delta t)] \\ &A_{33} = e^{-t/T_2} \\ &B_{11} = [1 + M_1 e^{-t/T_1} - e^{-t/T_2} ((1 + M_1) \cos\delta t - M_2 \sin\delta t)] \\ &B_{22} = [1 + M_3 e^{-t/T_1} - e^{-t/T_2} ((1 + M_3) \cos\delta t - M_4 \sin\delta t)] \\ &B_{33} = 1 - e^{-t/T_2} \end{split}$$
 where $\tan\theta = \frac{\alpha - \beta}{\delta}$

Table 9 Elements of A and B Neglecting Relaxation

$$\begin{split} A_{11} &= 1 - 2 \mathrm{sin}^2(\theta_e) \mathrm{sin}^2 \bigg(\frac{\omega_e}{2} \, t \bigg) \\ A_{12} &= -A_{21} = -\, \mathrm{sin}(\theta_e) \mathrm{sin}(\omega_e t) \\ A_{131} &= A_{31} = \mathrm{sin}(2\theta_e) \mathrm{sin}^2 \bigg(\frac{\omega_e}{2} \, t \bigg) \\ A_{22} &= \mathrm{cos}(\omega_e t) \\ A_{23} &= -A_{32} = -\, \mathrm{cos}(\theta_e) \mathrm{sin}(\omega_e t) \\ A_{33} &= 1 - 2 \mathrm{cos}^2(\theta_e) \mathrm{sin}^2 \bigg(\frac{\omega_e}{2} \, t \bigg) \\ B_{11} &= B_{22} = B_{33} = 0 \\ \end{split}$$
 where $\omega_e = \sqrt{\delta^2 + \omega_1^2}$ and $\tan \theta_e = \frac{\delta}{\omega_1}$

CONCLUSIONS

The solutions of the Bloch equations presented here show that, in general, every initial state decays in a biexponential oscillatory manner while the steady state independently grows from zero—also in an oscillatory, biexponential manner. The decay of the initial state takes place independently of the growth of the steady state, and each component of the steady state grows independently of the other components. The decay of the initial state and the growth of the steady state can be separated by 2D experiments, where the former gives the diagonal and cross-peaks and the latter gives the axial peaks.

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