

25/6/23

Module - IV

TOC
Date

Pushdown Automata

According to Chomsky hierarchy

R.G \rightarrow Type 3 \rightarrow FSM \rightarrow Finite amount of Info
CFG \rightarrow Type 2 \rightarrow PSD \rightarrow Infinite amount of Info

\downarrow
Stack.

\downarrow operations $\begin{cases} \text{Push} \\ \text{pop} \end{cases}$

3 Components

Input tape \rightarrow Input string
finite control \rightarrow push/pop.

Stack \rightarrow elements

Push Down Automata = finite state

Machine + stack.

Definition of Pushdown automata:

5 Tuple

2 Tuple

\Leftrightarrow 7 Tuple.

7 Tuple Notation

$(Q, \Sigma, \delta, \Gamma, q_0, z_0, f)$

$Q \rightarrow$ No. of states. $\Sigma =$ Alphabet with input symbols

$\delta \rightarrow$ Transition function (Triple Tuple) $\rightarrow \{(q, a, x) \dots\}$

$\Gamma \rightarrow$ Stack symbols

$\delta(q, a, x)$ $q \rightarrow$ current state

$q_0 \rightarrow$ Initial state

$a \rightarrow$ input to be processed
 $x \rightarrow$ Top of stack

$z_0 \rightarrow$ Initial top of stack. z0

Instantaneous
Descriptions (IDP)

$q_n \rightarrow$ new state

$f \rightarrow$ final state

$\alpha \rightarrow$ Top of stack to be
(replaced of x)
otherwise string of
stack symbols

Example of PDA

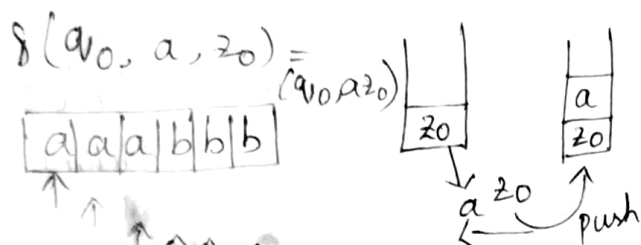
(Q) Construct PDA for language = $\{a^n b^n / n \geq 1\}$

Sol $L = \{ab, aabb, aaabbb, \dots\}$

Example 2

Sol.

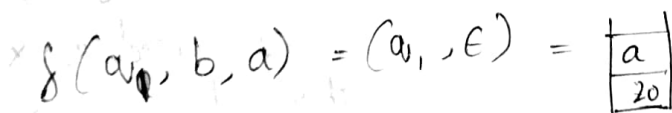
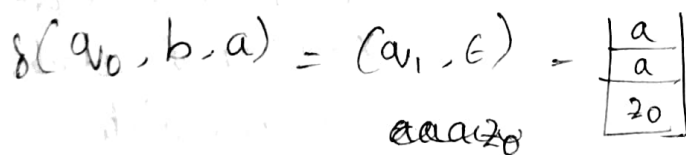
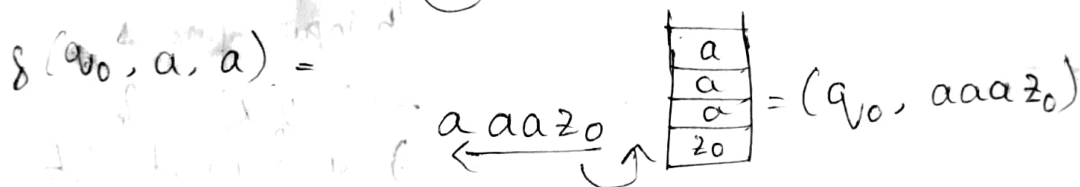
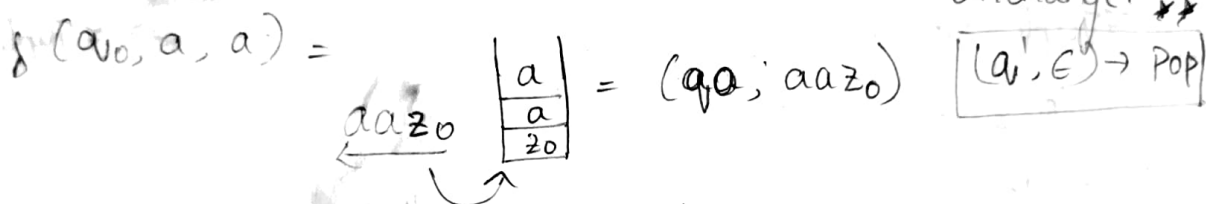
$\delta(q, a, y)$
 \downarrow L \rightarrow Top of stack.
 \downarrow current state \rightarrow Input to Proc
 \downarrow string of stack symbols in stack
 \downarrow New state



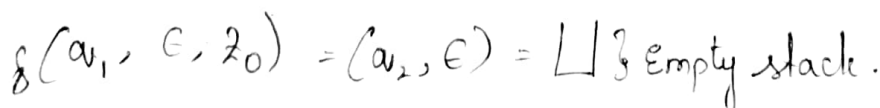
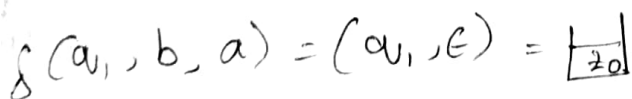
a → Push

b → Pop

unchange. **



$a | a | a | b | b | b | \epsilon$



$F = \{q_2\}$ $Q = \{q_0, q_1, q_2\}$ $\Sigma = \{a, b\}$ $q_0 \rightarrow$ Initial state
 $\Gamma = \{z_0, a\}$ $z_0 \rightarrow$ Top of stack.

$$P = \{ \overset{①}{\{q_0, q_1, q_2\}}, \overset{②}{\{a, b\}}, \overset{③}{\{z_0, a\}}, \overset{④}{\delta}, \overset{⑤}{\{q_0\}}, \overset{⑥}{\{z_0\}}, \overset{⑦}{\{q_2\}} \}$$

Example 2 Give a PDA to accept the following language
 $L = \{a^n, b^{2n} / n \geq 1\}$ by final state

Sol: $L = \{aa, bbbb, \dots\}$

$L = \{abb, aabbbb, \dots\}$

$$\delta(q_0, a, z_0) = \begin{array}{|c|} \hline \\ \hline z_0 \\ \hline \end{array} \rightarrow \begin{array}{|c|} \hline a \\ \hline z_0 \\ \hline \end{array} = (q_0, a z_0)$$

\swarrow
 $a z_0$ push

$$\delta(q_0, a, a) = \begin{array}{|c|} \hline \\ \hline a \\ \hline z_0 \\ \hline \end{array} \rightarrow \begin{array}{|c|} \hline a \\ \hline a \\ \hline z_0 \\ \hline \end{array} \Rightarrow (q_0, aa z_0)$$

\swarrow
 $a z_0$ push

$$\delta(q_0, b, aa z_0) = (q_1, a z_0)$$

$$\delta(q_1, b, a) = (q_2, \epsilon)$$

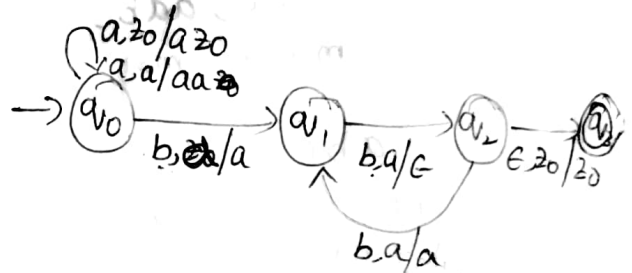
$$\delta(q_2, b, a) = (q_1, a z_0)$$

$$\delta(q_1, b, a) = (q_2, \epsilon)$$

$$\delta(q_2, \epsilon, z_0) = (q_3, z_0)$$



1st b No change
 2nd b pop a
 3rd b No change
 4th b pop a
 ϵ



$$P = (\{q_0, q_1, q_2, q_3\}, \{a, b\}, \{a, z_0\}, \delta, q_0, z_0, q_3)$$

$$G_1, 3, 6, 9$$

$$H_0, 3, 4, 5, 8, 9$$

$$J_0, 1, 2, 3, 5, 6, 8$$

$$K_0, 2, 5, 9$$

$$L_2, 9$$

$$M_4, 7$$

$$N_1, 2, 3, 5, 7$$

$$P_2, 8$$

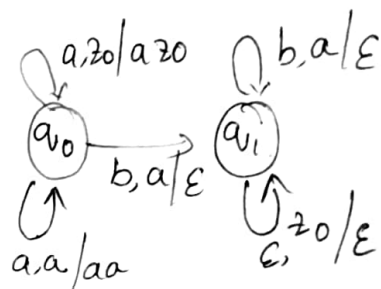
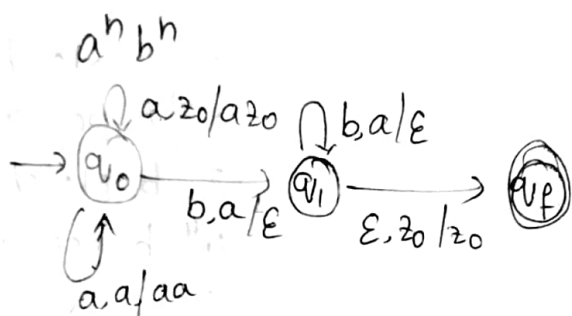
$$L_5, 15, 17$$

Push Down Automata Acceptance.

Example

There are two different ways to define PDA acceptance.

- ① Final state acceptability:
- ② Empty stack acceptability:



Example 3

$$L = \{a^n b^m c^n / n \geq 1, m \geq 1\}$$

$$L = \{abc, aabcc, aabbcc, aaabbbccc, \dots\}$$

$m, n=1$ $m=1, n=2$ $m=2, n=2$ $m=3, n=3$

abc

no. of a's = no. of c's

a a b c c | ε

a → push (a)

b → unchange

c → pop (a)

$$\delta(q_0, a, z_0) = \delta(q_0, a z_0)$$

$$\delta(q_0, a, a) = \delta(q_0, a a z_0)$$

$$\delta(q_0, b, a) = \delta(q_1, a a z_0)$$

$$\delta(q_1, c, a) = \delta(q_2, \epsilon)$$

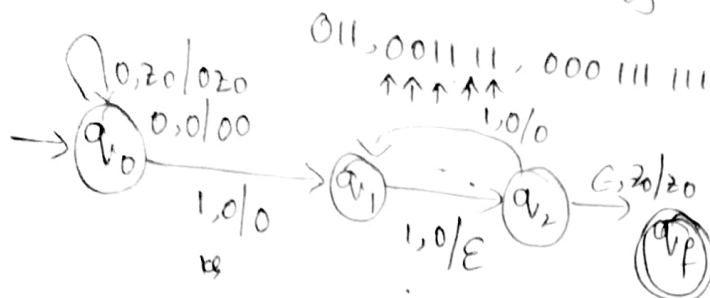
$$\delta(q_2, c, a) = \delta(q_2, \epsilon) \quad | \underline{z_0}$$

$$\delta(q_2, \epsilon, z_0) = \delta(q_3, \epsilon) \rightarrow \text{end.}$$

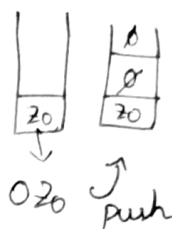
$$Q = \{q_0, q_1, q_2, q_3\}, \Sigma = \{a, b, c\} \quad \Gamma = \{a, z_0\} \quad q_0, z_0, q_3$$

Example 4

$$L = \{0^n, 1^{2n}, n \geq 0\}$$



10 x
01 x



$$\delta(q_0, 0, z_0) \vdash^{a_0} 0z_0$$

$$\delta(q_0, 0, 0) \vdash^{a_0} 00$$

$$\delta(q_0, 1, 0) \vdash q_1, 0$$

$$\delta(q_1, 1, 0) \vdash q_2 \epsilon$$

$$\delta(q_2, 1, 0) \vdash q_1, 0$$

$$\delta(q_2, \epsilon, z_0) \vdash q_f, z_0$$

Equivalence of Acceptance by Final and acceptance by Empty stack for push down automata.

* PDA's that accept by final state

PDA = P

Language accepted by P.

denoted by $L(P)$ by final state

$$* \{w / (q_0, w, z_0) \vdash^* (q, \epsilon, A)\} \text{ s.t., } q \in F$$

Check List

- Entire i/p should be exhausted?
- in a final state

* PDA's that accept by Empty stack:

Language accepted by is denoted by P

by $N(P)$ is .

$\{w \mid (q_0, w, z_0) \xrightarrow{*} (q, \epsilon, \epsilon)\}$ for any $q \in Q$.

check List

- input exhausted?
- is stack empty.

(Q) Does a PDA that accepts by Empty stack. need any final state Specified in the design.

PDA that accepts by final state when 'C' is popped by 'if we get ')'

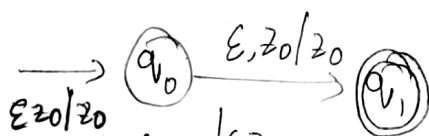
PA: $C, z_0 / C z_0$

$C, C / C C$

$), C / \epsilon$

PDA = $\{Q, \Sigma = \{C,)\}, \Gamma, z_0, q_0, q_f\}$

C
C
z ₀



$C, z_0 / C z_0$

$C, C / C C z_0$

$), C / \epsilon z_0$

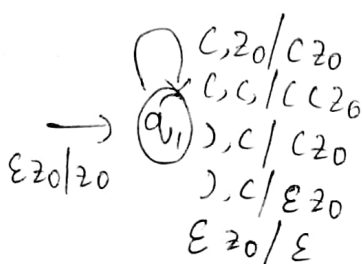
$), C / \epsilon z_0$

$C(C))$

An Equivalent PDA that accepts by Empty stack.

C
C
z ₀

$C(C))$



eg. a) 1 symbol (2') = 2

push
pop

((C C)) () () => Example 2

$P_f \Leftarrow$ PDA accepting by final state

$$P_f = (Q_f, \Sigma, \Gamma, \delta, q_0, z_0, F)$$

$P_N \Leftarrow$ PDA accepting by empty stack

$$P_N = (Q_N, \Sigma, \Gamma, \delta, q_0, z_0)$$

Theorem

$(P_N \Rightarrow P_f)$ for every P_N there exists a P_f st

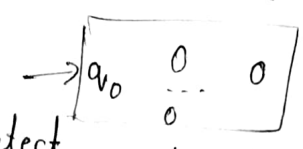
$$L(P_f) = L(P_N)$$

$(P_f \Rightarrow P_N)$ for every P_f there exists a P_N st

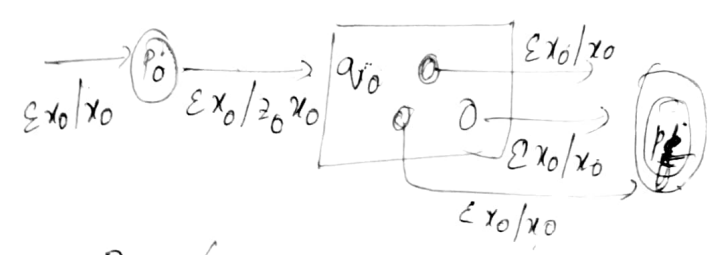
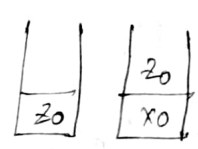
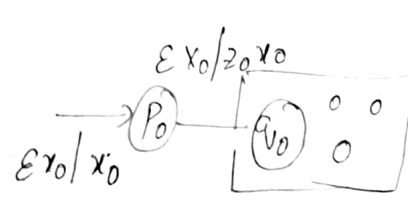
$$L(P_f) = L(P_N)$$

$P_N \Rightarrow P_f$ Construction

* Whenever P_N 's stack becomes empty, make P_f go to a final state without consuming any additional symbol



* To detect empty stack in P_N : P_f pushes a new stack symbol x_0 (not in Γ of P_N) initially before simulating P_N



$$P_f = (Q_N \cup \{P_0, P_f\}, \Sigma, \Gamma \cup \{x_0\}, \delta, P_0, x_0 \{P_f\})$$

Example. "{" "}" Matching Parenthesis

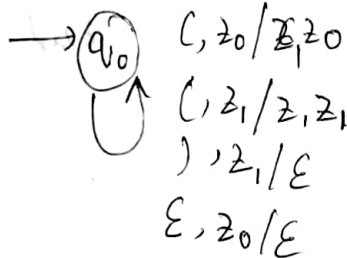
$P_N = \{ \{q_0\}, \{(\cdot)\}, \{z_0, z_1\}, \delta, q_0, z_0 \}$ Empty stack.

$$P_N: \delta(q_0, \{z_0\}) = \{(q_0, z_1, z_0)\}$$

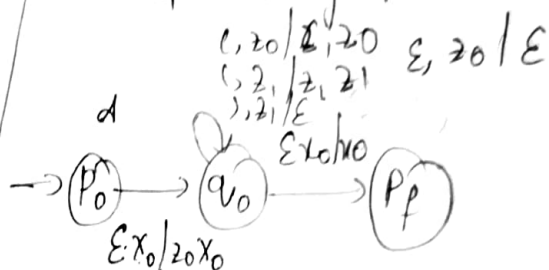
$$\delta(q_0, \{z_1\}) = \{(q_0, z_1, z_1)\}$$

$$\delta(q_0, \cdot, z_1) = \{(q_0, \epsilon)\}$$

$$\delta(q_0, \epsilon, z_0) = \{(q_0, \epsilon)\}$$



Acceptance by final state



$$\delta(p_0, \epsilon, x_0) = \{(q_0, z_0)\}$$

$$\delta(q_0, C, z_0) = \{(q_0, z_1, z_0)\}$$

$$\delta(q_0, C, z_1) = \{(q_0, z_1, z_1)\}$$

$$\delta(q_0, \cdot, z_1) = \{(q_0, \epsilon)\}$$

$$\delta(q_0, \epsilon, z_0) = \{(q_0, \epsilon)\}$$

$$\delta(q_0, \epsilon, x_0) = \{(p_f, z_0)\}$$

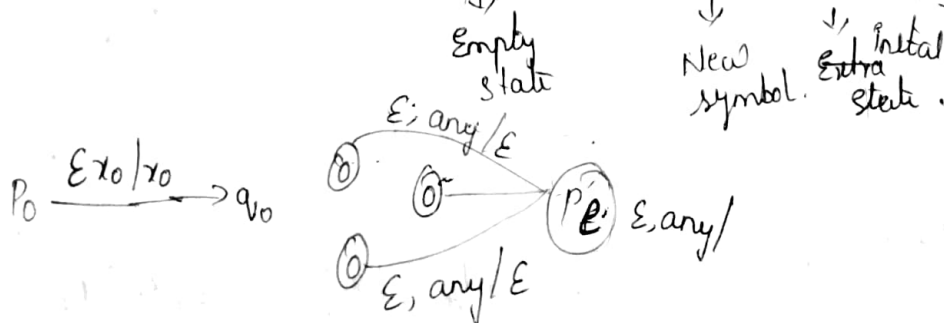
How to Convert an Final state PPA into an Empty stack PDA?

Main idea:

Whenever p_f reaches a final state, just make ϵ -transition into a new end state. Clear out the stack and accept

→ to address this, add a new Start symbol x_0 (NOT in Γ of P_N)

$$P_N = (Q \cup \{p_0, p_e\}, \epsilon, \Gamma \cup \{x_0\}, \delta, p_0, x_0)$$



Conversion of CFG to PDA

@ Bharu Priya.

Ex:

$$\left. \begin{array}{l} S \rightarrow asa \\ S \rightarrow bsb \\ S \rightarrow c \end{array} \right\} \text{CFG}$$

$S \Rightarrow NT$
 $a, b, c \Rightarrow \text{Terminal.}$

Design push Down automata.

\hookrightarrow Push & pop to accept string

Sol: Procedure: write production rules.

then pop elements

- ① $\delta(q_0, \epsilon, \epsilon) = (q_0, \epsilon)$
- ② $\delta(q_0, \epsilon, s) \Rightarrow (q_0, asa)$
- ③ $\delta(q_0, \epsilon, s) \Rightarrow (q_0, bsb)$
- ④ $\delta(q_0, \epsilon, s) \Rightarrow (q_0, c)$

* write all productions \uparrow

- ⑤ $\delta(q_0, a, a) \Rightarrow (q_1, \epsilon)$
- ⑥ $\delta(q_1, b, b) \Rightarrow (q_2, \epsilon)$
- ⑦ $\delta(q_2, c, c) \Rightarrow (q_3, \epsilon)$

Transition table

S.No.	state	in read i/p	Stack.	transition No.
1.	q_0	abbcbbba	ϵ	1
2.	q_0	abbcbbba	s	1
3.	q_0	abbcbbba	asa	2
4.	q_1	bcbba	sa	5
5.	q_0	bcbba	bsba	3
6.	q_2	bcbba	sb a	6
7.	q_0	bcbba	bsbba	3

8.	q_1	cbba	sbba	6
9.	q_0	cbba	fbba	4
10	q_3	bba	bba	7
11	q_2	ba	ba	6
12.	q_1	a	a	5

abba

abbcbba

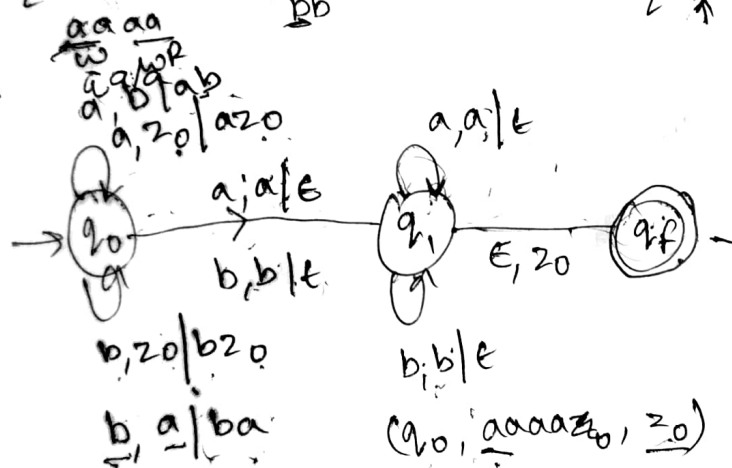
1 2 3

$L = \{w^k \mid k \geq 1\}$ ϵzab

$L = \{abbbba, aaaaab, bb\}$

$L = \{abba, baab\}$

NOPDA



aa | aa

$\vdash(q_0, aaaa z_0, a z_0)$

$\vdash(q_0, aa, aa z_0)$

$\vdash(q_1, aa z_0, a \epsilon)$

$(q_0, a, aa z_0)$

(q_1, a, ϵ)

$(q_0, \epsilon, aaaa z_0)$

(q_1, ϵ, z_0)

$(q_1, \epsilon, aa z_0)$

(q_1, ϵ, z_0)



Pushdown Automata (PDA)

ϵ -NFA + Stack

Input \rightarrow Finite State Control \rightarrow Accept/Reject



Definition:

$$PDA P = (Q, \Sigma, \Gamma, \delta, q_0, z_0)$$

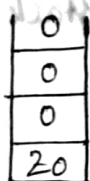
δ - Transition function

$$\delta(q, a, x) = (p, y)$$

Construct a PDA for $L = \{0^n 1^n \mid n \geq 1\}$

Sol: $L = \{01, 0011, 000111, \dots\}$

000111 ϵ



$$\delta(q_0, 0, z_0) = (q_0, 0z_0)$$

$$\delta(q_0, 0, 0) = (q_0, 00)$$

No Need to write a transition (0 should be in stack)

$$\delta(q_0, 1, 0) = (q_1, \epsilon)$$

$$\delta(q_1, 1, 0) = (q_1, \epsilon)$$

~~$\delta(q_1, 1, 0)$~~ = No Need to write a transition.

(0 will be popped)

$$\delta(q_1, \epsilon, z_0) = (q_2, z_0)$$

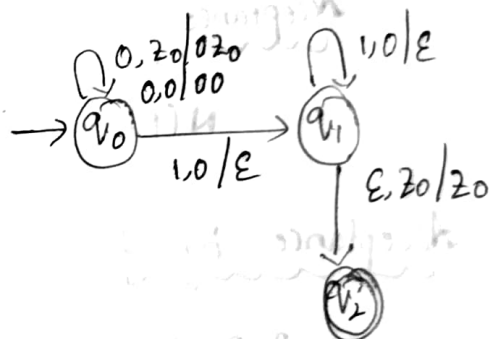
$$PDA P = (\{q_0, q_1, q_2\}, \{0, 1\}, \{0, z_0\}, \delta, q_0, z_0, \{q_2\})$$

Instantaneous Description of PDA

$$\text{If } \delta(q, a, x) = (p, \alpha)$$

$$(q, aw, x\beta) \vdash (p, w, \alpha\beta)$$

$$\delta(q_0, 0, z_0) = (q_0, 0z_0)$$



$$(q_0, 0011, z_0) \vdash (q_0, 011, 0z_0)$$

$$\vdash (q_0, 11, 00z_0)$$

$$\vdash (q_1, 1, 0z_0) \text{ pop } *$$

$$\vdash (q_1, \epsilon, z_0)$$

$$\vdash (q_2, \epsilon, z_0)$$

Acceptance by final state

$$L(P) = \{w \mid (q_0, w, z_0) \vdash^* (q_f, \epsilon, \alpha)\}$$

\hookrightarrow any thing

Acceptance by empty stack.

$$N(P) = \{w \mid (q_0, w, z_0) \vdash^* (q, \epsilon, \epsilon)\}$$

\hookrightarrow empty stack.

Acceptance by final state:

$$L = \{a^n, 2^n \mid n \geq 1\}$$

Sol: $\{abb, aabbbb, \dots\}$

$$\delta(q_0, a, z_0) = (q_0, az_0)$$

$$\delta(q_0, a, a) = (q_0, aa)$$

$$\delta(q_0, b, a) = (q_1, a)$$

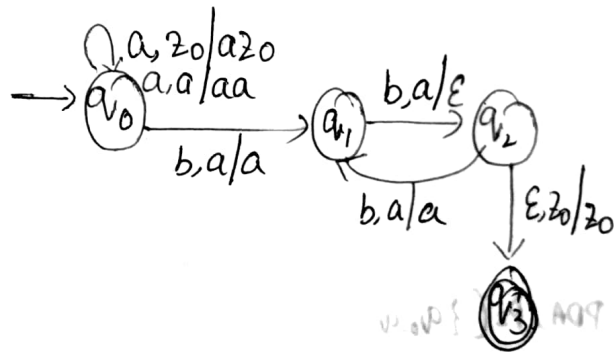
$$\delta(q_1, b, a) = (q_2, \epsilon)$$

$$\delta(q_2, b, a) = (q_1, a)$$

$\delta(q_1, \epsilon, a)$ No Need to do

$$\delta(q_2, \epsilon, z_0) = (q_3, z_0)$$

aabbbb

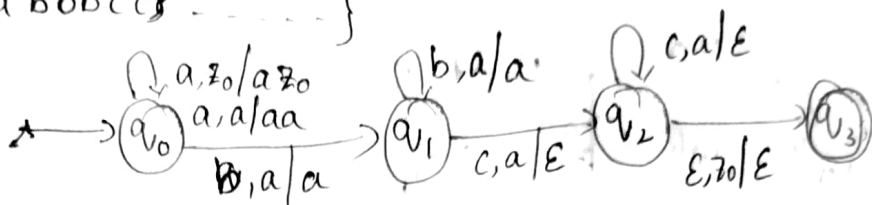


$$PDA \ P = \{(q_0, q_1, q_2, q_3), \{a, b\}, \{z_0, a\}, \delta, q_0, z_0, q_3\}.$$

$$L = \{a^n, b^m, c^n / n \geq 1, m \geq 1\}$$

No. of a's & c's should be equal.

Sol: $L = \{aa bbb ccc \dots\}$



$$\delta(q_0, a, z_0) = (q_0, a z_0)$$

$$\delta(q_0, a, a) = (q_0, aa)$$

$$\delta(q_0, b, a) = (q_1, a) \text{ No change because of } b.$$

$$\delta(q_1, b, a) = (q_1, a)$$

$$\delta(q_1, c, a) = (q_2, \epsilon)$$

$$\delta(q_2, c, a) = (q_2, \epsilon)$$

$$\delta(q_2, \epsilon, z_0) = (q_3, \epsilon)$$

→ Empty stack.

$$PDA \ P = \{ (q_0, q_1, q_2, q_3), \{a, b, c\}, \{a, z_0\}, \delta, q_0, z_0, q_3 \}$$

$$G_0, G_3, G_5, 6, 7, \dots$$

$$3, 5, 7, 9, \dots$$

$$1, 7, 3, 45, 6, \dots$$

$$K_0, 5, 8, 9, \dots$$

$$L_2, 9$$

$$M_3, 4, 5, 8, 9, \dots$$

$$N_2, 3, 4, 5, 6, \dots$$

$$P_0, 7, 4, \dots$$

$$L_{11}, 16, 18, 19, \dots$$

Construct non-deterministic PDA for

$$L = \{ww^R / w \text{ is in } (0+1)^+\}$$



$$\delta(q_0, 0, z_0) = (q_0, 0z_0)$$

$$\delta(q_0, 1, z_0) = (q_0, 1z_0)$$

$$\delta(q_0, \epsilon, 0) = (q_0, 10z_0)$$

$$\delta(q_0, 0, 0) = (q_0, 00z_0)$$

$$\delta(q_0, 0, 1) = (q_0, 01z_0)$$

$$\delta(q_0, 1, \epsilon) = (q_0, 11z_0)$$

$$\delta(q_0, \epsilon, 0) = (q_1, \epsilon)$$

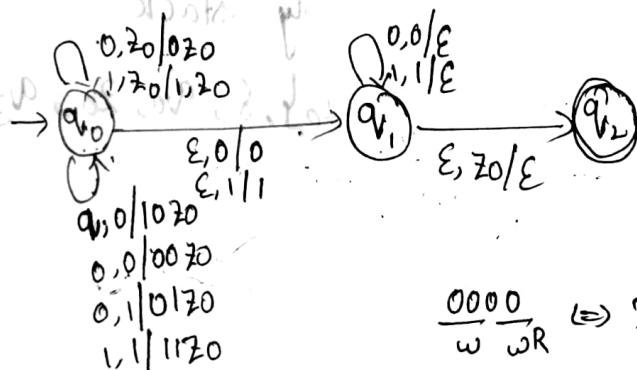
$$\delta(q_0, \epsilon, 1) = (q_1, \epsilon)$$

$$3) \delta(q_1, 0, 0) = (q_1, \epsilon)$$

$$\delta(q_1, 1, 1) = (q_1, \epsilon)$$

$$4) \delta(q_1, \epsilon, z_0) = (q_2, \epsilon)$$

$$PAD P = \{(q_0, q_1, q_2) (0, 1), \{0, 1, z_0\}, \delta, q_0, z_0, \{q_2\}\}$$



$$\frac{0000}{w} \frac{0000}{w^R} \Rightarrow TDP$$

$$(q_0, 0000, z_0) \vdash (q_0, 000, 0z_0)$$

$$(q_0, 00, 00z_0) (q_1, 000, 0z_0)$$

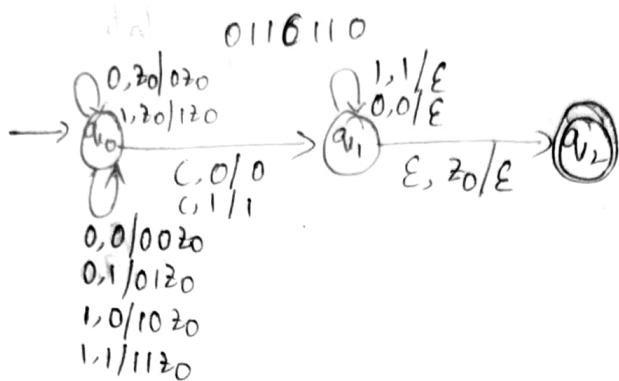
$$(q_0, 00, 000z_0) (q_1, 00, 0z_0)$$

$$(q_0, \epsilon, 0000z_0) (q_1, 0, 000z_0) (q_1, 0, 0z_0) (q_2, 00, \epsilon)$$

$$(q_1, \epsilon, 0000z_0) (q_1, \epsilon, 00z_0) (q_1, \epsilon, z_0) (q_2, \epsilon, \epsilon)$$

Deterministic Pushdown Automata

$$L = \{w c w^R / w \text{ is in } (0+1)^+\}$$



$H_5, J_0, J_1, J_5, J_8, K_0, K_2, K_5, L_9, M_4, P$

$G_3, 6, 9,$

$2, 3, 4, 5,$

$1, 3, 5,$

$K_0, 2, 5,$

$2,$

M

N_2

$P_0, 4$

L_e

Conversion of CFG to PDA

$$S \rightarrow AB$$

$$A \rightarrow 0S/0$$

$$B \rightarrow 1S/1$$

$$A \rightarrow \epsilon$$

$$\delta(q, \epsilon, A) = (q, \epsilon)$$

$$\delta(q, a, a) = (q, \epsilon)$$

Sol: ① $S \rightarrow AB, \delta(q, \epsilon, S) = \delta(q, AB)$

$$A \rightarrow 0S, \delta(q, \epsilon, A) = (q, 0S)$$

$$A \rightarrow 0, \delta(q, \epsilon, 0) = (q, 0)$$

$$B \rightarrow 1S, \delta(q, \epsilon, B) = (q, 1S)$$

$$B \rightarrow 1, \delta(q, \epsilon, 1) = (q, 1)$$

Convert PDA to CFG

Def $M = (Q, \Sigma, \Gamma, \delta, q_0, z_0, \emptyset)$
 \hookrightarrow final state

$$M = (\{q_0, q_1\}, \{a, b\}, \{a, z_0\}, \delta, q_0, z_0, \emptyset)$$

$$\delta(q_0, a, z_0) = (q_0, a z_0) \quad \delta(q_0, a, a) = (q_0, a a)$$

$$\delta(q_0, b, a) = (q_1, a) \quad \delta(q_1, b, a) = (q_1, a)$$

$$\delta(q_1, a, a) = (q_1, \epsilon) \quad \delta(q_1, \epsilon, z_0) = (q_1, \epsilon)$$

$$G = (V, T, P, S)$$

Sol: $V = \{S, [q_0, a q_0], [q_0, a q_1], [q_1, a q_0], [q_1, a q_1],$

$$[q_0, z_0 a_0], [q_0, z_0 a_1], [q_1, z_0 a_0], [q_1, z_0 a_1]$$

$$T = \{a, b\} \quad S \rightarrow [q_0, z_0 a_0]$$

$$S \rightarrow [q_0, z_0 a_1]$$

$$\delta(q_0, a, z_0) = (q_0, a z_0) \xrightarrow{2 \text{ symbols}}$$

4 productions

$$\begin{cases} [q_0, z_0 a_0] \rightarrow a [q_0, a q_0] [q_0, z_0 a_0] \\ [q_0, z_0 a_0] \rightarrow a [q_0, a q_1] [q_1, z_0 a_0] \\ [q_0, z_0 a_1] \rightarrow a [q_0, a a_0] [q_0, z_0 a_1] \\ [q_0, z_0 a_1] \rightarrow a [q_0, a a_1] [q_1, z_0 a_1] \end{cases}$$

$$\delta(q_0, a, a) = (q_0, a a) \xrightarrow{2 \text{ symbols}}$$

productions

$$\begin{cases} [q_0, a q_0] \rightarrow a [q_0, a q_0] [q_0, a q_0] \\ [q_0, a q_0] \rightarrow a [q_0, a q_1] [q_1, a q_0] \\ [q_0, a q_1] \rightarrow a [q_0, a a_0] [q_0, a q_1] \\ [q_0, a q_1] \rightarrow a [q_0, a a_1] [q_1, a q_1] \end{cases}$$

$$\delta(q_0, b, a) = \delta(q_1, a) \xrightarrow{1 \text{ symbol } (2') = 2}$$

$$[q_0 a q_0] \rightarrow b [q_1 a q_0]$$

$$[q_0 a q_1] \rightarrow b [q_1 a q_1]$$

$$\delta(q_1, b, a) = (q_1, a)$$

$$[q_1 a q_0] \rightarrow b [q_1 a q_0]$$

$$[q_1 a q_1] \rightarrow b [q_1 a q_1]$$

$$\delta(q_1, a, a) = (q_1, \epsilon) \xrightarrow{\text{when } \epsilon \text{ only one production}}$$

$$[q_1, a, q_1] \xrightarrow{a} [q_1, \epsilon, q_1]$$

$$\delta(q_1, \epsilon, z_0) = (q_1, \epsilon)$$

$$[q_1, z_0, q_1] \xrightarrow{\epsilon} \epsilon$$

$$S \rightarrow AA/a$$

$$A \rightarrow SA/b$$

CFG to PDA.

NT: S, A

T: a b

$$\delta(q_0, \epsilon, S) = (q_0, AA)$$

$$\delta(q_0, \epsilon, S) = (q_0, SA)$$

$$\delta(q_0, \epsilon, A) = (q_0, SA)$$

$$\delta(q_0, \epsilon, A) = (q_0, b)$$

$$\delta(q_0, a, a) = (q_0, \epsilon)$$

$$\delta(q_0, b, b) = (q_0, \epsilon)$$

abbabb

$$(q_0, abbabb, S) \vdash (q_0, abbabb, AA)$$

$$\vdash (q_0, abbabb, SAA)$$

$$\vdash (q_0, abbabb, SA A)$$

$$\vdash (q_0, abbabb, b A)$$

$$\vdash (q_0, babb, SA)$$

$$\vdash (q_0, babb, AA)$$

$$\vdash (q_0, babb, b A A)$$

$$\vdash (q_0, abb, S A A)$$

$$\vdash (q_0, abb, A A A)$$

$$\vdash (q_0, bb, A A)$$

$$\vdash (q_0, \epsilon, \epsilon)$$