Lie Theory

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1 Background

1.1 Topology

Definition 1.1.1. A topological space is *locally connected* at point x if everyneighborhood of x contains a connected open neighborhood.

2 Topologcial Groups

2.1 Introduction

Definition 2.1.1. A $topological\ group$ is a group such that

- 1. he product $p: G \times G \to G, p(g,h) = gh$, is a continuous map if $G \times G$ has the product topology;
- 2. The map $\iota: G \to G, \iota(g) = g^{-1}$, is continuous (hence, a homeomorphism, as $\iota^{-1} = \iota$).

Each element $g \in G$ defines the following maps.

- left translation: $L_q: G \to G, L_q(h) = gh;$
- right translation: $R_g: G \to G, R_g(h) = hg;$
- conjugation: $C_q: G \to G, C_q(h) = ghg^{-1}$.

2.2 Neighborhoods of Identity

An (open) neighborhood of $x \in X$, where X is a topological space, is an open set U that cointains x.

Let G be a topological group, and $1 \in G$ is the identity. V(1) refers to the set of all neighborhoods of 1.

Proposition 2.2.1 (Proposition 2.2). Let G be a t.g. (topological group), V = V(1). Then we'll have

- 1. (T1)for all $u \in V, 1 \in u$;
- 2. $(T2)u, v \in V \implies u \cap v \in V;$
- 3. (TG1) for all $u \in V$, there exists $v \in V$ s.t. $v^2 \subseteq u$;
- 4. $(TG2) u \in V \implies u^{-1} \in V$;
- 5. (TG3) $u \in V, g \in G \implies gug^{-1} \in V$.

Definition 2.2.2. Let G be a group, not necessarily topological group. A system of neighborhood of $1 \in G$ is a family of sets sastisfying (T1) to (TG3).

Definition 2.2.3. Let X be a topological space and $x \in X$. A fundamental system of neighborhoods of x is a family F of open sets containing x s.t. for all open u that contains x, there exists $v \in F$ s.t. $v \subseteq u$.

Theorem 2.2.4 (Proposition 2.5). Let G be an abstract group, V be a system of neighborhoods of 1. There exists a unique topology on G making G into a topological group and s.t. V is a fundamental system of neighborhoods of 1.

idea of proof. \Box

Proposition 2.2.5. Let G be a topological group. TFAE

- 1. topology of G is a Hausdorff
- 2. $\{1\}$ is closed in
- 3. $\bigcap_{U \in \mathcal{V}(1)} U = \{1\}$

2.3 Metrizable Groups

Definition 2.3.1. Let G be a topological group. G is metrizable if it has a left-(or right-) invariant distance which defines the tooplogy left-invariant for all $g \in G$ and d(gx, gy) = d(x, y) for all $x, y \in G$.

Theorem 2.3.2. A topological group G is metrizable iff it has a countable system of neighborhoods of 1.

2.4 Homomorphisms

We need to talk about $G \to H$ continuous homomorphisms.

Example 2.4.1. The determinant homomorphism det : $GL_n(\mathbb{R}) \to \mathbb{R}^* = GL(1,\mathbb{R})$ is continuous.

Theorem 2.4.2. Let G, H be topological group. A group homomorphism $\phi : G \to H$ is continuous iff ϕ is continuous at $1 \in G$.

Proof. \implies is obvious. Let's look at the other direction.

Note that $\phi \circ L_g = L_{\phi(g)} \circ \phi$ as maps $G \to H$ because

$$(\phi \circ L_q)(g') = \phi(gg') = \phi(g)\phi(g') = (L_{\phi(q)} \circ \phi)(g').$$

Then

$$\phi = L_{\phi(g)} \circ \phi \circ L_{g^{-1}}$$

is continuous at g, as $L_{g^{-1}}$ is continuous at g, ϕ continuous at 1, and $L_{\phi(g)}$ continuous everywhere.

Theorem 2.4.3. A map $\phi: G \to H$ is a group homomorphism (G, H are just groups) iff

$$gr(\phi) := \{(g, \phi(g)) \mid g \in G\} \subseteq G \times H.$$

Proposition 2.4.4. Let X and Y be topological spaces, such that Y is Hausdorff. A map $\phi: X \to Y$ is continuous if and only if its graph $gr(\phi)$ is closed and the projection $p(x, \phi(x)) = x$ is a homeomorphism.

Proof. Suppose ϕ is continuous. Then

$$gr(\phi) = \theta^{-1}(\Delta y)$$
 w.r.t. $\theta: X \times Y \to Y \times Y$

is closed, since tehta is continuous and Δy is closed.

Theorem 2.4.5. Suppose G, H are topological groups, H is Hausdorff. The map $G \to H$ is a continuous homomorphism iff $gr(\phi)$ is a closed subgroup and $p: gr(\phi) \to G$ is a homeomorphism.

2.5 Subgroups

Let G be a topological group. $H \subseteq G$ is a topological subgroup if H is a topological group w.r.t. the induced topology.

Proposition 2.5.1. Let G be a topological group. If $H \subseteq G$ a subgroup, which is open. Then H is also closed.

Proof. Consider

$$Y = \bigcup_{g \in G - H} gH.$$

Y is open, as it is a union of open sets. H is also closed, as G-Y=H. Hence, H is closed. \square

Proposition 2.5.2. G a topological group, $H \subseteq G$ a subgroup. Then \overline{H} is also a subgroup of G.

Proof. Note that $A \subseteq X$ (subset of a topological space), $x \in \overline{A}$ iff for all open U that contains $x, U \cap A \neq \emptyset$. Then we check the followings.

1. \overline{H} is closed under $m: G \times G \to G$.

2.6 Connected Components of Topological Groups

A connected space cannot be written as the union of two disjoint open sets.

A *connected component* of a point $x \in X$ is the union of all connected sets containing x, which is also the maximal connected set containing x.

A *connected component* of X is a maximal connected subset.

If $A\subseteq X$ is connected, then the closure \overline{A} is connected. Thus, every connected component is closed.

Let G be a topological group, G_0 is the connected component of $1 \in G$.

Proposition 2.6.1. G_0 is a closed normal subgroup of G. The connected components of G are exactly gG_0 for $g \in G$.

A neighborhood N of $x \in X$ is a subset $N \subseteq X$, $x \in N$ and there exists an open $U \subseteq X$ s.t $x \in U \subseteq N$.

A space is *locally connected* if for every open neighborhood of every point contains a connected open neighborhood.

Proposition 2.6.2. If G is locally conencted, then G_0 is open.

Proposition 2.6.3. If G connected, $U \in \mathcal{V}(1)$, then $G = \bigcup_{n \geq 1} U^n$.

2.7 Group Action

Suppose G a group, X a set.

Definition 2.7.1. A *left action* of a group G on a set X is a function that associates to $g \in G$ a map $a(g) : X \to X$ which satisfies the properties: 1. $a(1) = \mathrm{id}_X$, that is, a(1)(x) = x, for every $x \in X$; 2. $a(gh) = a(g) \circ a(h)$.

Definition 2.7.2. Let $\phi_x: G \times X \to X, \phi_y: G \times Y \to Y$. A map $f: X \to Y$ is G-equivariant if

$$\phi_y(g, f(x)) = f(\phi_x(g, x)).$$

Same stroy for topological groups.

Definition 2.7.3. Let G be a topological group, X a topological space, an *action* G on X should be continuous. In other words, G acts on X by homeomorphisms ϕ_g .

Action is *transitive* if X = Gx for some $x \in X$. We define the *orbit* of x to be $Gx = \{gx \mid g \in G\}$. A *stabilizer* or *isotropy subgroup* of x is $G_x = \{g \in G \mid gx = x\}$.

An action is an *effective action* or *faithful* if $gx = x, \forall x \in X \implies g = 1$, equivalently, $\bigcap_{x \in X} G_x = \{1\}$.

Proposition 2.7.4.

$$G/G_x \to X$$
 where $gG_x \mapsto gx$.

This map is equivariant.

Proposition 2.7.5. Suppose that the action of G on X is continuous and that X is a Hausdorff space. Then, any isotropy subgroup $G_x, x \in X$, is closed.

2.8 Homogeneous Spaces

Let G be a topological group.

Definition 2.8.1. A homogeneous G-space is just G/H for a subgroup H of G.

Definition 2.8.2. A topological space X without regards to group is *homogeneous* if for all $x, y \in X$, there exists a homeomorphism $\phi : X \to X$ s.t. $\phi(x) = y$.

Topology on G/H is that of a quotient: $\pi:G\to G/H$. In other words, $U\subseteq G/H$ open if $\pi^{-1}(U)\subseteq G$ open.

Note: action of G on G/H is continuous:

$$G \times G/H \to G/H$$
 where $(x, gH) \mapsto xgH$.

Proposition 2.8.3. We have the following facts.

1. G/H is a homogeneous space in the sense of topology.

- 2. $\pi: G \to G/H$ is an open map (it takes open sets to open sets).
- 3. H compact implies that π is a closed map.
- 4. G/H is Hausdorff iff H is closed.
- 5. G/H discrete iff H open. (HW2)
- 6. If G is compact, G/H discrete and finite iff H is open.
- 7. $H \triangleleft G$ implies G/H is a topological group.
- 8. $H := \overline{\{1\}}$. Then H is a normal subgroup of G, and G/H is Hausdorff topological group.

Proof of 1. Consider left translation

$$L_x: gH \mapsto xgH.$$

This is a homeomorphism since $L_{x^{-1}}$ is an inverse and both are continuous. \square

Proof of 2. We need to show that $\pi^{-1}\pi(U)$ is open. (Omitted, just do image preimage and write it as union of right cosets).

Proof of 3. Take $F \subseteq G$ closed, if H is a compact subset, then $FH \subseteq G$ is closed. (From a proposition from textbook).

Notice that $\pi(F)$ closed iff $\pi^{-1}\pi(F)$ closed, and the latter equals to FH. \square

Proof of 4. We first show \implies . Note that $H=\pi^{-1}(H)$, which is a point of G/H, so it's closed. Thus H is closed.

Then we show \Leftarrow . Consider the homeomorphism

$$f: G/H \times G/H \to G \times G/H \times H$$
 where $(g_1H, g_2H) \mapsto (g_1, g_2)H \times H$.

Denote $\Delta = \{(gH, gH)\}$. Then $f(\Delta) = \{(g, g)H \times H\}$ is closed iff $\pi_{G \times G}^{-1} f(\Delta)$ is closed, which equals to $\{(g_1, g_2) \mid g_1 H = g_2 H\} = \{(g_1, g_2) \mid g_1^{-1} g_2 \in H\}$. \square

Let G be a topological group, $H \subseteq G$ a subgroup.

Proposition 2.8.4. If H and G/H are compact, then so is G.

Proof.

$$\pi:G\to G/H$$

is a *perfect map*, i.e., a continuous subjective closed map with compact fibers $\pi^{-1}(x), \forall x \in G/H$.

Proposition 2.8.5. If G/H and H are connected, then so is G.

Proof. Suppose G is not connected, then there exists $A \bigsqcup B = G$, $A, B \neq \emptyset$ open, disjoin $\subseteq G$. Then $\pi(A), \pi(B) \neq \emptyset$, open because π is always open, $\pi(A) \cup \pi(B) = G/H$, which is connected. Therefore $\pi(A) \cap \pi(B) \neq \emptyset$. Thus there exists $gH \in G/H$ s.t. $gH \cap A \neq \emptyset$ and $gH \cap B \neq \emptyset$.

2.9 Orbits and Homogeneous Spaces

Homogeneous space G/G_x , we hav ea bijection:

$$G/G_x \to G \cdot x$$
 where $gG_x \mapsto gx$.

Proposition 2.9.1. Let $G \times X \to X$ be a continuous and transitive action of G on X. Fix $x \in X$ and consider the bijection

$$\xi_x: G/G_x \to X \text{ given by } \xi_x(gG_X) = gx.$$

Then ξ_x is continuous with respect to the quotient topology in G/G_x .

Proposition 2.9.2. Let $G \times X \to X$ be a topological transitive group action. Suppose G is locally compact and spearable (i.e., has a countable dense subset) and X is Hausdorff and locally compact, Then

$$\xi_x: G/G_x \to X = G \cdot x \quad \forall x \in X$$

is a homeomorphism.

2.10 Examples

We have

$$O(N) = \{ g \in GL(n, \mathbb{R}) \mid gg^T = I_n(\det g = 1) \}.$$

O(n) acts on \mathbb{R}^n with orbits being $S_r^{n-1} - \{x \in \mathbb{R}^n \mid |x| = r\}, r \geq 0$.

Induction implies that O(n), SO(n) are compact, SO(n) connected.

Also $SL(n,\mathbb{R})$ is connected, as it has for n > -2 has 2 orbits on $\mathbb{R}^n : \{0\}, \mathbb{R}^n - \{0\}$. Also $SL(n,\mathbb{C})$ is connected.

Consider unitary groups

$$U(n) = \{ q \in GL(n, \mathbb{C}) \mid qq^{-T} - I_n(\det q = 1) \}.$$

 $GL(n,\mathbb{F})$ acts on \mathbb{F}^{n-1} , which is the set of lines through 0 in \mathbb{F}^n .

 $Gr_k(n, \mathbb{F})$ is the set of k-dimensional subspaces of \mathbb{F}^n , which is the quotient of the set of $n \times k$ -matrices of rank k by $GL(k, \mathbb{F})$ acting on the right.

3 Lie Group

3.1 Basics

Definition 3.1.1. A Lie group G is a group and a manifold such that

$$m: G \times G \to G$$

is smooth.

The composition of two smooth maps is smooth.

Proposition 3.1.2. The inverse map $\iota: G \to G$ is a diffeomorphism with

$$d\iota_q = -(dL_{q^{-1}})_1 \circ (dR_{q^{-1}})_q.$$

Particularly, $\iota_1 = -\operatorname{id}$.

3.2 Tangent Bundle to a Manifold

A fiber bundle is a structure (E, B, π, F) , where E, B, and F are topological spaces and $\pi: E \to B$ is a continuous surjection satisfying a local triviality condition outlined below. The space B is called the base space of the bundle, E the total space, and F the fiber. The map π is called the projection map (or bundle projection). We shall assume in what follows that the base space B is connected.

We require that for every $x \in B$, there is an open neighborhood $U \subseteq B$ of x (which will be called a trivializing neighborhood) such that there is a homeomorphism $\varphi: \pi^{-1}(U) \to U \times F$ (where $\pi^{-1}(U)$ is given the subspace topology, and $U \times F$ is the product space) in such a way that π agrees with the projection onto the first factor. That is, the following diagram should commute:

ADD THIS!

Denote the tangent bundle

$$TM = \bigcup_{x \in M} T_x M$$
 $T_x M = \{ m(t) \mid m(0) = x \} / \sim .$

3.3 Lie Groups

Let TG be the tangent bundle to a Lie group G. We define

$$d(L_q)_h: T_hG \to T_{qh}G$$
 where $h'(t) \mapsto (gh)'(t)$.

Notice that then

$$d(L_q)_1: T_1G \simeq T_qG.$$

Moreover,

$$G \times T_1 G \simeq TG$$
 where $(g, v) \mapsto (g, d(L_q)_1 v)$.

Thus, TG is trivial as a vector bundle for a Lie group G. i.e. G is parallelizable.

3.4 Lie Algebra

Proposition 3.4.1.

$$[\phi*X,\phi*Y] = \phi*([X,Y]).$$

Definition 3.4.2. Let G be a Lie group. A vector field X on G is said to be

• right invariant if, for every $g \in G, (R_g)_* X = X$. In detail,

$$d(R_a)_k(X(h)) = X(hg)$$

for every $g, h \in G$;

• left invariant if, for every $g \in G, (L_g)_* X = X$, that is,

$$d(L_q)_h(X(h)) = X(gh).$$

Definition 3.4.3. We define Maurer-Cartan forms, which are differential 1 forms on G with values in T_1G . They are defined by right or left translations by

$$\omega_g^r(v) = d\left(R_{g^{-1}}\right)_g(v) \quad \text{ and } \quad \omega_g^l(v) = d\left(L_{g^{-1}}\right)_g(v)$$

for $g \in G$ and $v \in T_aG$.

Proposition 3.4.4. If $X \in Vect(G)$ is right-invariant, then $\omega^r(X) = X(1)$, the constant T_1G -valued function. Similarly, if X is left-invariant, then $\omega^l(X) = X(1)$.

Definition 3.4.5. We define the set of right invariant fields as

$$Inv_r = \bigcap_{g \in G} ker\left((R_g)_* - Id_{vect(G)}\right) \subseteq Vect(G).$$

Theorem 3.4.6. Let $Inv_r \cong T_1G \cong Inv_e$

Definition 3.4.7. $\mathfrak{g} = (Inv_r, [,])$ is the *Lie algebra* of a Lie group G.

Proposition 3.4.8. This bracket gives the following bracket on T_1G :

$$A \in T_1G \to A^r(g) = d(R_q)_1A.$$

Moreover

$$[A, B] := [A, B]_r = [A^r, B^r](1).$$

Proposition 3.4.9. Let $A, B \in T_1G$. Then, $[A, B]_r = -[A, B]_l$.

$$[A, B] = -[A, B]_e = BA - AB.$$

3.5 Exponential Map

Remarks on flows on manifolds.

Let X be a vector field on manifold $M, X \in C^{\infty}(M, TM)$. A flow ϕ_t^x defined by $\phi_t^x(x) = x(t), t \in (-\epsilon, \epsilon)$, and $\frac{dx}{dt} = X(x), x(0) = x$.

Another notation is $X_t = \phi_t^x$.

WTS

$$X_{s+t} = X_s \circ X_t = X_t \circ X_s.$$

3.6 Back to Lie Groups

Take $X \in \mathfrak{g} = Inv^r$ right invariant vector field

Then $X_t(g)$ the flow equals to g(t) and is given by

$$\frac{dg}{dt} = X(g), \quad g(0) = g.$$

For $g \in G$, $g(t) : (-\epsilon, \epsilon) \to G$.

Lemma 3.6.1. For $X \in Inv^r$, we have

$$X_t(gh) = X_t(g)h \quad \forall g, h \in G.$$

Theorem 3.6.2. A right-invariant vector field X is complete, i.e., defined for all $t \in \mathbb{R}$.